

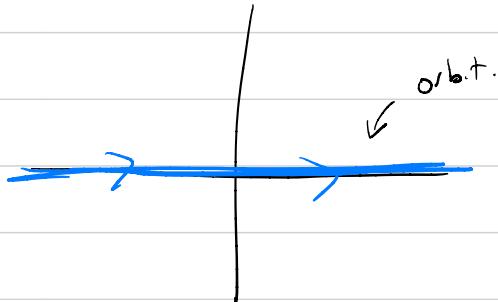
Hw7 Soln

1) a) Will show x -axis is an orbit so nothing can cross it.

let $y=0$

$$\frac{dx}{dt} = 1+x^2 \rightarrow \text{always } > 0$$

$$\frac{dy}{dt} = 0 + \tan(0) = 0 \rightarrow \text{no } y \text{ movement}$$



b) Will show $y=x$ is made up of orbits that cannot be crossed.

Equl Points : $\begin{cases} y+x^2=0 \\ x-y^2=0 \end{cases}$ $\begin{cases} y=-x^2 \\ x=-y^2 \end{cases}$ $\begin{cases} (0,0), (-1,-1) \\ x=-x^2 \end{cases}$

$$\boxed{y=x}$$

$$\frac{dx}{dt} = x + x^2 = x^3$$

So if on line $y=x$, orbit moves in direction

$$\frac{dy}{dt} = x + x^2 = x^3$$

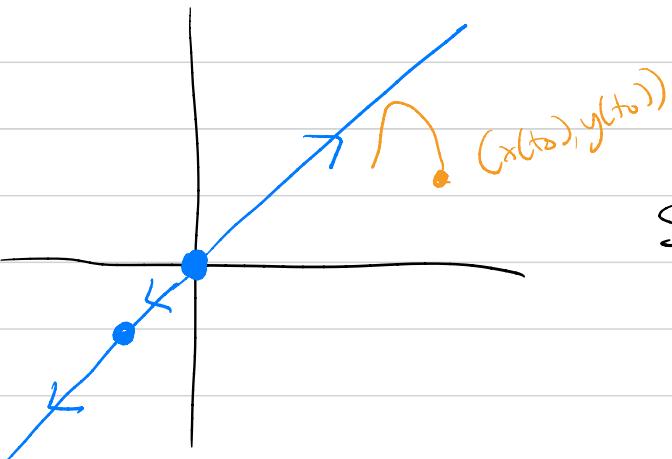
$$\begin{bmatrix} x^3 \\ x^3 \end{bmatrix}$$

which is still on line!

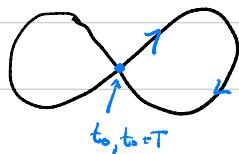
$$x > 0, x^3 > 0$$

$$x < 0, x^3 < 0$$

So if $x(t_0) \neq y(t_0)$, orbit can never intersect
 $y=x$.



c) No, this can't happen.



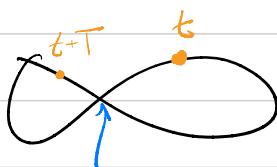
Let's say we start at intersection point at t_0 .

We return to this point at $t = t_0 + T$. (traveling along right loop only)

$$\text{So } Q(t_0) = Q(t_0 + T).$$

By Property 2, Q is periodic with $Q(t) \equiv Q(t+T) \quad \forall t$.

But this isn't true : Take $t_0 < t < t_0 + T$



$Q(t)$ is on RHS,

$Q(t+T)$ must be on LHS

$$\text{as } t_0 + T < t + T < t_0 + 2T$$

$$t_0, t_0 + T, t_0 + 2T$$

\therefore Contradiction.

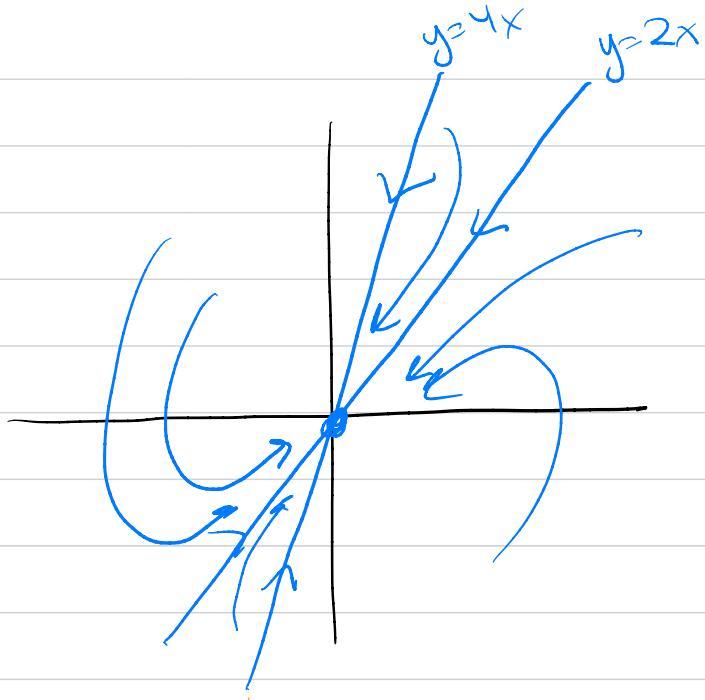
$$2) \text{ a) } \lambda_1 = -2$$

$$\vec{v}_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

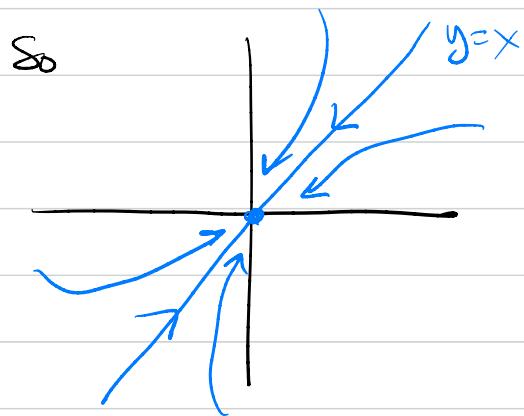
$$\lambda_2 = -4$$

$$\vec{v}_2 = \begin{bmatrix} 1 \\ 4 \end{bmatrix}$$

$$\lambda_2 < \lambda_1 < 0$$



b) $\lambda_1 = -5$ $\vec{v}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ ← only one eigenvector.



c) $\lambda = \pm i$
 $(\alpha = 0)$

At $(x, 0)$ w.t.h $x > 0$

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2x + 1(0) \\ -5x - 2(0) \end{bmatrix} = \begin{bmatrix} 2x \\ -5x \end{bmatrix}$$

\uparrow y goes ↓

$$3) \text{ a)} \quad x = z \quad \Rightarrow \quad \frac{dx}{dt} = z' = y$$

$$y = z' \quad \frac{dy}{dt} = z'' = -\frac{c}{m}z' - \frac{k}{m}z = -\frac{c}{m}y - \frac{k}{m}x.$$

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -\frac{k}{m} & -\frac{c}{m} \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\text{b)} \quad \det(A - \lambda F) = -\lambda \left(-\lambda - \frac{c}{m} \right) - \left(-\frac{k}{m} \right) = 0$$

$$\lambda^2 + \frac{c}{m}\lambda + \frac{k}{m} = 0$$

$$\lambda = \frac{-\frac{c}{m} \pm \sqrt{\left(\frac{c}{m}\right)^2 - 4\frac{k}{m}}}{2} = -\frac{c \pm \sqrt{c^2 - 4km}}{2m}$$

$$-C \pm \sqrt{C^2 - 4km}$$

$\frac{2m}{}$

Case I: $C^2 - 4km > 0 \Rightarrow$ Then as $C > \sqrt{C^2 - 4km}$
 both eigenvalues $< 0.$

Case II: $C^2 - 4km = 0$

$$\lambda = -\frac{C}{2m} : 1 \text{ or } 2 \text{ eigenvectors?}$$

$$\begin{bmatrix} \frac{C}{2m} & 1 \\ -\frac{C}{2m} & -\frac{C}{2m} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow \vec{v} = \begin{bmatrix} 1 \\ -\frac{C}{2m} \end{bmatrix}$$

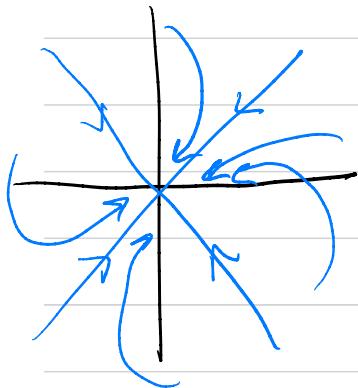
Only 1.

Case III: $C^2 - 4km < 0$

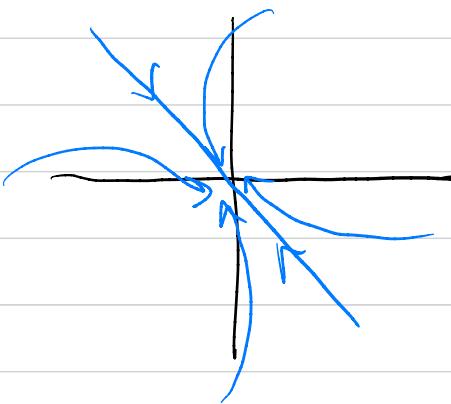
$$\lambda = -\frac{C}{2m} \pm i \frac{\sqrt{4km - C^2}}{2m}$$

negative real part.

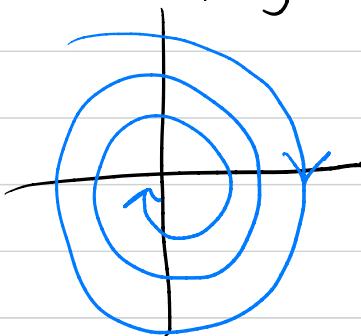
Case I:
(Overdamped)



Case II:
(Crit. Damped)



Case III
(Under damped)



(Look at $(x, 0), x \geq 0$)
 $\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -k/m & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \ll \infty$

c) Recall that motion is $z(t) = x(t)$ (ignore $y(t)$)

I: Can cross y-axis once, spring snaps back to place after 1st oscillation

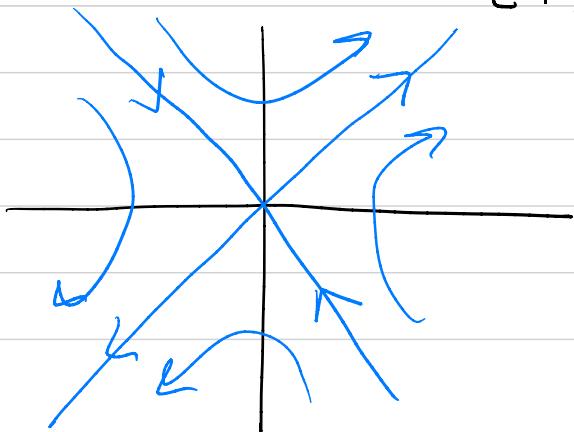
II: Same as I, but not as quickly.

III: Spring oscillates back and forth with oscillations getting smaller.

$$4) \text{ a)} A = \begin{bmatrix} 0 & 1 \\ 1+6x^2 & 0 \end{bmatrix} \Big|_{(0,0)} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$\vec{z}_1 = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \quad \vec{z}$$

$$\text{b)} \lambda = \pm 1 \quad \vec{v} = \begin{bmatrix} \pm 1 \\ 1 \end{bmatrix}$$



$$c) \frac{dy}{dx} = \frac{x+2x^3}{y} \Rightarrow$$

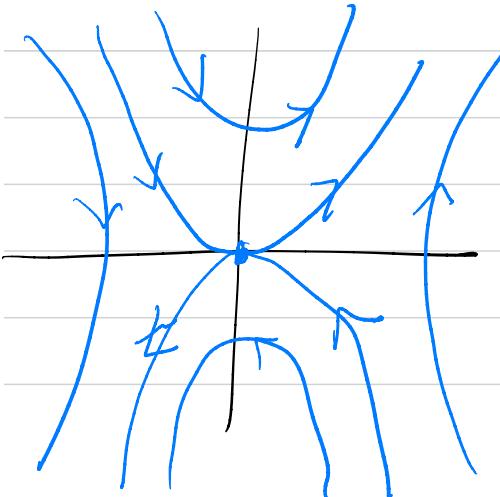
$$\int y \, dy = \int x + 2x^3 \, dx$$

$$\frac{1}{2}y^2 = \frac{1}{2}x^2 + \frac{1}{2}x^4 + C$$

$$y = \pm \sqrt{x^4 + x^2 + C}$$

looks like parabola with C as y intercept.

when $\sqrt{\quad}$ makes sense.



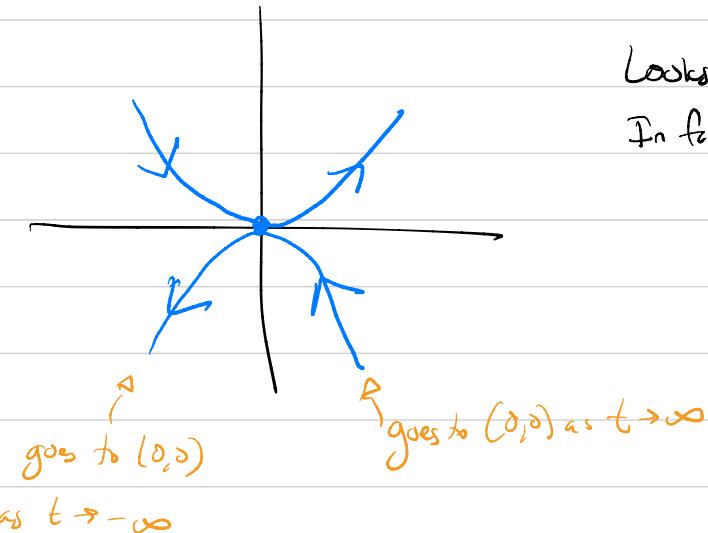
To get signs, take values > and look at eq.

ex: $(0, y)$ ($y > 0$)

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ y \end{bmatrix} > 0$$

d) Can see that there are two orbits toward origin ($C=0$) .

$$y = \pm \sqrt{x^4 + x^2} . \quad \text{From phase portrait:}$$



Looks like lines from linearized phase portrait.

In fact, for small x ,

$$y = \pm \sqrt{x^4 + x^2} \approx \pm \sqrt{x^2} = \pm x$$

which are precisely the lines from (b) .