

## Ishaan Mehta E18CSE069 EB02 LabWEEK4

```
In [1]: import numpy as np
import cv2
from google.colab.patches import cv2_imshow
from sklearn.metrics import mean_squared_error
from PIL import Image
```

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In [2]: img_path='./8bitimg.jpg'
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```
In [3]: img=cv2.imread(img_path)
```

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In [4]: img = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
```

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In [5]: img.shape
```

```
Out[5]: (256, 256)
```

```
In [6]: cv2_imshow(img)
```



```
In [7]: def quantizer(g_img,level):
g_img_flatten=g_img.reshape((1,-1))
f_max=np.max(g_img_flatten)
f_min=np.min(g_img_flatten)
b=(f_max-f_min)/level
res=[]
for i in g_img_flatten:
res.append(np.floor((i-f_min)/b)*b + b/2+ f_min)
results=np.array(res).reshape((256,256))
mse=mean_squared_error(g_img,results)
return (results,mse)
```

```
In [8]: levels=[4,16,32,64]
for level in levels:
res,mse=quantizer(img,level)
cv2_imshow(res)
print('Mean squared Error for ',level,' Level is : ',mse,'using custom function')
print()
```



Mean squared Error for 4 Level is : 307.36312103271484 using custom function



Mean squared Error for 16 Level is : 20.87488603591919 using custom function



Mean squared Error for 32 Level is : 5.112407922744751 using custom function



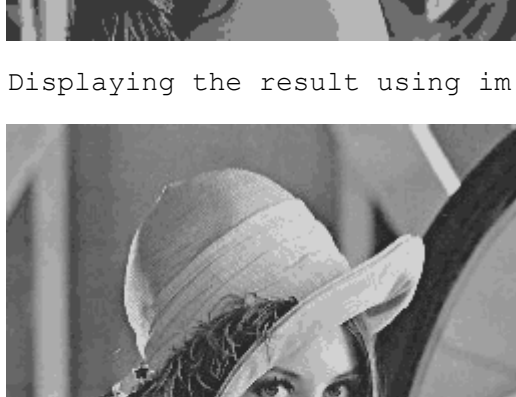
Mean squared Error for 64 Level is : 1.2792555689811707 using custom function

```
In [9]: for level in levels:
im=Image.open(img_path)
pil_img=im.quantize(colors=level)
print('Displaying the result using im.quantize ')
display(pil_img)
print()
```

Displaying the result using im.quantize



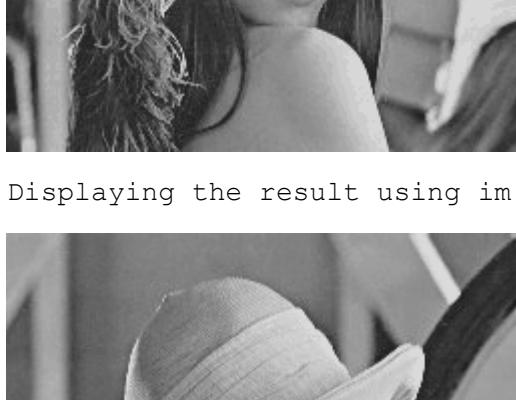
Displaying the result using im.quantize



Displaying the result using im.quantize



Displaying the result using im.quantize



```
In [10]: from scipy import ndimage
```

```
In [11]: img=cv2.imread(img_path)
img = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
r ,bw_img = cv2.threshold(img,127,255,cv2.THRESH_BINARY)
```

```
In [12]: dst_euc = cv2.distanceTransform(bw_img,cv2.DIST_L1, 3)
print('Euclidean TRANSFORM')
print(dst_euc)
```

```
Euclidean TRANSFORM
[[30. 29. 28. ... 2. 2. 1.]
 [30. 29. 28. ... 2. 1. 0.]
 [30. 29. 28. ... 1. 0. 0.]
 ...
 [ 0.  0.  0. ...  0.  0.  0.]
 [ 0.  0.  0. ...  0.  0.  0.]
 [ 0.  0.  0. ...  0.  0.  0.]
```

```
In [13]: dst_cb = cv2.distanceTransform(bw_img,cv2.DIST_L2, 3)
print('City-Block TRANSFORM')
print(dst_cb)
```

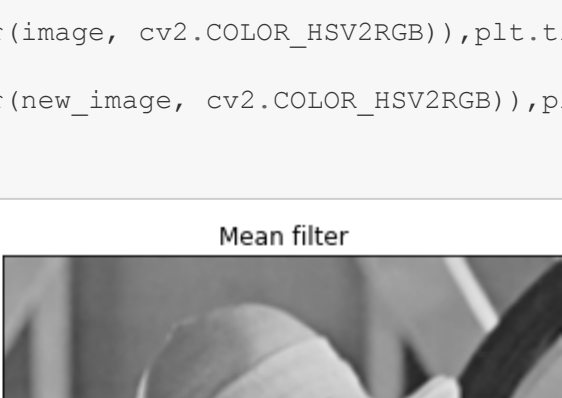
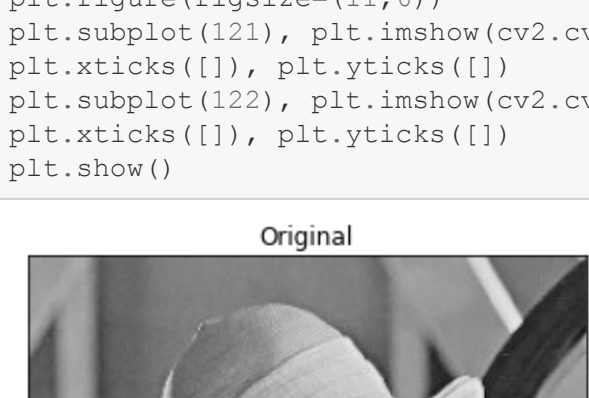
```
City-Block TRANSFORM
[[28.650055 27.695053 26.740051 ... 1.9100037 1.3692932
 0.95500183]
 [28.650055 27.695053 26.740051 ... 1.3692932 0.95500183
 0.]
 [28.650055 27.695053 26.740051 ... 0.95500183 0.
 0.]
 ...
 [ 0. 0. 0. ... 0. 0. 0.]
 [ 0. 0. 0. ... 0. 0. 0.]
 [ 0. 0. 0. ... 0. 0. 0.]
 [ 0. 0. 0. ... 0. 0. 0.]
 [ 0. 0. 0. ... 0. 0. 0.]
```

```
In [14]: dst_chess = cv2.distanceTransform(bw_img,cv2.DIST_C, 3)
print('CHESS TRANSFORM')
print(dst_chess)
```

```
CHESS TRANSFORM
[[28. 28. 28. ... 2. 1. 1.]
 [27. 27. 27. ... 1. 1. 0.]
 [26. 26. 26. ... 1. 0. 0.]
 ...
 [ 0.  0.  0. ...  0.  0.  0.]
 [ 0.  0.  0. ...  0.  0.  0.]
 [ 0.  0.  0. ...  0.  0.  0.]
```

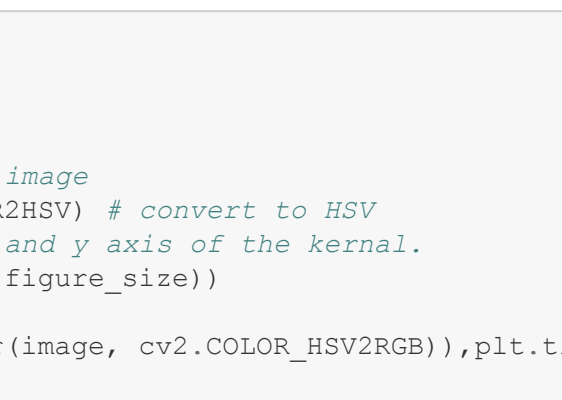
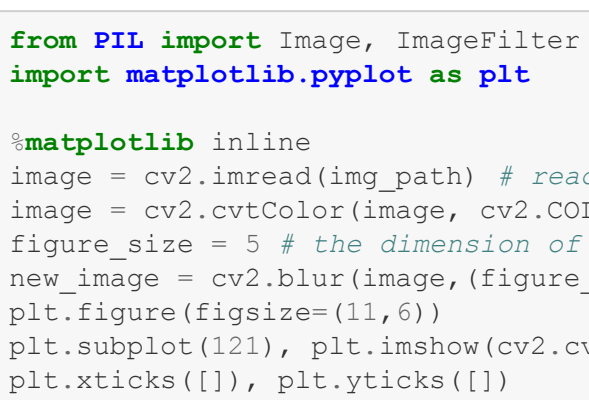
```
In [20]: from PIL import Image, ImageFilter
import matplotlib.pyplot as plt

%matplotlib inline
image = cv2.imread(img_path) # reads the image
image = cv2.cvtColor(image, cv2.COLOR_BGR2HSV) # convert to HSV
figure_size = 3 # the dimension of the x and y axis of the kernel.
new_image = cv2.blur(image,(figure_size, figure_size))
plt.figure(figsize=(11,6))
plt.subplot(121), plt.imshow(cv2.cvtColor(image, cv2.COLOR_HSV2RGB)),plt.title('Original')
plt.xticks([], plt.yticks([]))
plt.subplot(122), plt.imshow(cv2.cvtColor(new_image, cv2.COLOR_HSV2RGB)),plt.title('Mean filter')
plt.xticks([], plt.yticks([]))
plt.show()
```



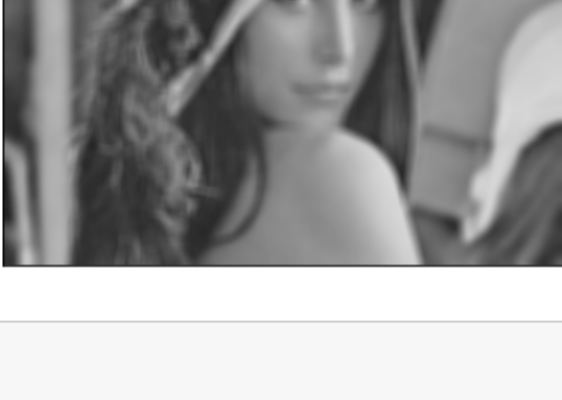
```
In [21]: from PIL import Image, ImageFilter
import matplotlib.pyplot as plt

%matplotlib inline
image = cv2.imread(img_path) # reads the image
image = cv2.cvtColor(image, cv2.COLOR_BGR2HSV) # convert to HSV
figure_size = 5 # the dimension of the x and y axis of the kernel.
new_image = cv2.blur(image,(figure_size, figure_size))
plt.figure(figsize=(11,6))
plt.subplot(121), plt.imshow(cv2.cvtColor(image, cv2.COLOR_HSV2RGB)),plt.title('Original')
plt.xticks([], plt.yticks([]))
plt.subplot(122), plt.imshow(cv2.cvtColor(new_image, cv2.COLOR_HSV2RGB)),plt.title('Mean filter')
plt.xticks([], plt.yticks([]))
plt.show()
```



```
In [22]: from PIL import Image, ImageFilter
import matplotlib.pyplot as plt

%matplotlib inline
image = cv2.imread(img_path) # reads the image
image = cv2.cvtColor(image, cv2.COLOR_BGR2HSV) # convert to HSV
figure_size = 7 # the dimension of the x and y axis of the kernel.
new_image = cv2.blur(image,(figure_size, figure_size))
plt.figure(figsize=(11,6))
plt.subplot(121), plt.imshow(cv2.cvtColor(image, cv2.COLOR_HSV2RGB)),plt.title('Original')
plt.xticks([], plt.yticks([]))
plt.subplot(122), plt.imshow(cv2.cvtColor(new_image, cv2.COLOR_HSV2RGB)),plt.title('Mean filter')
plt.xticks([], plt.yticks([]))
plt.show()
```



```
In [ ]:
```