

Assig -1

Q4

~~Assig~~ a) Assuming 'N' microphone array.

∴ We can define

$$Z_t = [(X_1)_t (X_2)_t (X_3)_t \dots (X_N)_t]$$

where ~~$X_{i,t}$~~ $(X_i)_t$ is the data from i th microphone at upto time instant 't'

i.e.

$$Z_t = \begin{bmatrix} x_{10} & x_{20} & \dots & x_{N0} \\ x_{11} & x_{21} & & x_{N1} \\ \vdots & \vdots & & \vdots \\ x_{1t} & x_{2t} & & x_{Nt} \end{bmatrix}_{(t \times N)}$$

where shape of Z_t is $(t \times N)$

Now

$$\text{Cov}(x, y) = E[(X - E(X))(Y - E(Y))]$$

Assuming X, Y are sampled uniformly from a gaussian distribution with $\mu=0$ & $\sigma=1$

$$\text{Cov}(X, Y) = E[XY] = \frac{\sum_{i=0}^N x_i y_i}{N}$$

Furthermore, one can write Covariance Matrix (Cov_M) as

$$\text{Cov}_M(X, Y) = \left(\frac{\begin{bmatrix} X \\ Y \end{bmatrix} \begin{bmatrix} X^T & Y^T \end{bmatrix}}{N} \right)$$

$$\text{Let } A = \begin{bmatrix} X \\ Y \end{bmatrix}$$

$$\therefore \text{Cov}_M(X, Y) = \frac{AA^T}{N} \quad \text{where}$$

$$A = \begin{bmatrix} X \\ Y \end{bmatrix}$$

— (2)

\therefore From (1) & (2)

$$\boxed{\text{Cov}_M(X_1, X_2, X_3, \dots, X_N) = \frac{Z^T Z}{N} \quad \text{where} \quad Z = [X_1, X_2, \dots, X_N]}$$

— (3)

Now using relation

$$R(X_1, X_2, \dots, X_N) = \frac{\text{COV}_M(X_1, \dots, X_N)}{\sigma_{X_1} \dots \sigma_{X_N}}$$

As, we assumed $\sigma = 1$

$$\therefore R(X_1, X_2, \dots, X_N) = \text{COV}_M(X_1, \dots, X_N)$$

Correlation Matrix

$$\therefore \left[R(X_1, X_2, \dots, X_N) \right]_t = \frac{Z_t^T Z_t}{\cancel{t}}$$

where $Z = [X_1, X_2, \dots, X_N]$

(b)

Now, as we know.

$$Z_{tH}^T = \underbrace{(Z_t^T \quad V_{tH}^T)}_{\text{Augment Matrix}} \quad \text{--- (4)}$$

where V_{tH}^T denotes.

$$\begin{bmatrix} x_{1,tH} \\ x_{2,tH} \\ \vdots \\ x_{N,tH} \end{bmatrix}$$

Now for any Augment matrix $a = (b|c)$

$$aa^T = bb^T + cc^T \quad \text{--- (5)}$$

\therefore from (4) (5)

$$Z_{tH}^T Z_{tH} = Z_t^T Z_t + V_{tH}^T V_{tH}$$

--- (6)

$$\therefore R_{t+1}(X_1, \dots, X_N) = \frac{Z_{t+1}^T Z_{t+1}}{t+1}$$

Substituting $Z_{t+1}^T Z_{t+1}$ from (6) above.

$$R_{t+1}(X_1, \dots, X_N) = \frac{Z_t^T Z_t}{t} + \left(\frac{1}{t+1} \right) (V_{t+1}^T V_{t+1})$$

As we know $R_t = \frac{Z_t^T Z_t}{t}$

$$\therefore R_{t+1}(X_1, \dots, X_N) = \frac{t}{t+1} R_t(X_1, \dots, X_N) + \frac{1}{t+1} (V_{t+1}^T V_{t+1})$$

~~$$\therefore R_{t+1}(X_1, \dots, X_N) = \frac{t}{t+1} R_t(X_1, \dots, X_N)$$~~

Ans

$$\therefore R_{t+1}(X_1, \dots, X_N) = \frac{t}{t+1} R_t(X_1, \dots, X_N) + \frac{1}{t+1} (V_{t+1}^T V_{t+1})$$

where

$R_t(X_1, \dots, X_N) \Rightarrow$ Correlation at time 't'

$V_t(X_1, \dots, X_N) \Rightarrow [x_{1,t+1} \ x_{2,t+1} \dots x_{n,t+1}]$