Week 5. Linking, Loading and Code Optimization

18-342: Fundamentals of Embedded Systems

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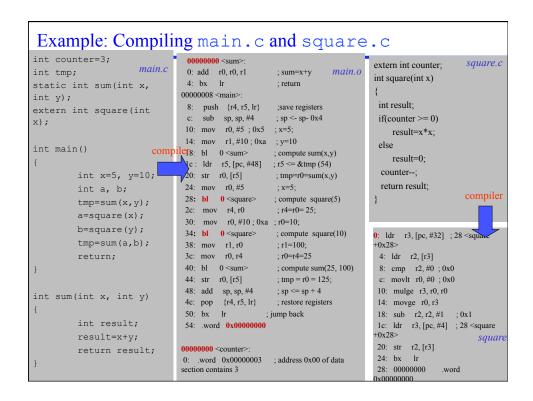


Overview of this Week

- · Linking and Loading
 - Statically linked executable
 - Dynamically linked executable
- ELF File Format
- Code Optimization
 - Processor independent code optimization techniques
 - ARM specific code optimization techniques
- Announcement:
 - Quiz next Thursday
 - Same policies as Quiz 1
 - Syllabus will include everything covered up to next Tuesday's lecture from Friday's lecture after Quiz 1

Linkers

- Compilers and assemblers generate re-locatable object files
 - References to external symbols are not resolved
 - Compilers generate object files in which code starts at address 0
 - Cannot execute a compiler produced object file
- Executable files are created from individual object files and libraries through the linking process
- Linker performs two tasks
 - Symbol resolution: Object files define and reference symbols, linker tries to resolve each symbol reference with one symbol definition
 - Relocation: Linker tries to relocate code and data from different object files so that different sections start at different addresses and all the references are updated



```
Example: After Linking main.o and square.o
00008338 <sum>:
 8338: add r0, r0, r1
                                                      8390: ldr r3, [pc, #32]; r3 = &counter (83b8)
 833c: bx lr
                                                      8394 ldr r2, [r3]; r2 = counter
00008340 <main>:
                                                      8398 cmp r2, #0; 0x0; counter > 0?
 8340:
        push {r4, r5, lr}
                                                      839c: movlt r0, #0; 0x0; if(counter < 0) then
 8344: sub sp, sp, #4 ; 0x4
                                                    r0 <= 0x0
               xQ, #5 ; 0x5
 8348: mov
                                                      83a0: mulge r3, r0, r0 ; else r3 = r0*r0
 834c:
       mov r1, #10; 0xa
                                                      83a4: movge r0, r3 ; else r0 = r3 = r0 * r0
        bl 8338 <sum>
 8350:
                                                     83a8: sub r2, r2, #1 ; counter--
 8354:
        ldr r5, [pc, #48]; x5 \le 0x0001056c = &tmp
                                                      83ac:
                                                             ldr r3, [pc, #4]; r3 = 0x00010564 =
        str r0, [r5] ; *0x0001056c = tmp = 15
 8358:
                                                    &counter (83b8)
                                                      83b0: str r2, [r3] ; counter = r2 = counter-1
 835c:
        mov r0, #5; 0x5
 8360: bl 8390 < square> ;
                                                      83b4: bx lr ; return back
                                                      83b8: .word 0x00010564
 8364: mov r4, r0
       mov r0, #10, 0xa
                                                    00010564 <counter>:
 836c: bl 8390 < square
                                                      10564: .word 0x00000003
 8370:
        mov r1, r0
 8374:
        mov r0 r4
 8378:
        bl 8338 <sum>
        str r0, [r5] ; *0x00010566 = tmp = 125
 837c:
                                                     0001056c <tmp>:
                                                      1056e; .word 0x00000000
        add sp, sp, #4 ;
 8384:
         pop {r4, r5, lr}
                                                                  linker relocates the code to a different
        bx lr
 8388:
                                 linker adds the actual address of
 838c:
        .word 0x0001056c
                                                                  location
                                 symbol square
```

Library Functions

- What happens when the source files use library functions like printf, scanf, etc.?
- Compiler produces a symbol (in the same way as the square function in the previous example) in the object file
- Linker
 - Attempts to resolve these references by matching them to definitions found in other object files
 - If the symbol is not resolved, the linker searches for the symbol definition in library files
- What are library files?
 - Collection of object files that provide related functionality
 - Example: The standard C library libc.a is a collection of object files printf.o, scanf.o, fprintf.o, fscanf.o...

Library Functions

- How does the linker know where to find the library?
 - User defined libraries can be specified as a command line argument
 - The environment variable LD_LIBRARY_PATH holds the path that is searched to find the specific library
- Linker does a search to see whether the symbol is defined in the specified libraries
 - The order in which this search is performed is determined by the order in which the libraries are specified
 - If the symbol is defined in more than 1 library, the first library in the path is selected
 - Linker then extracts the specific .o file that defines the symbol in the library and processes
 this .o file with all the other object files
 - If the symbol is not defined in any of the library, linker throws an error

Kinds of Linking Models

- Different kinds of linking models
 - Static: Set of object files, system libraries and library archives are statically bound, references are resolved, and a self-contained executable file is created
 - Problem: If multiple programs are running on the processor simultaneously, and they require some common library module (say, printf.o), multiple copies of this common module are included in the executable file and loaded into memory (waste of memory!)
 - Dynamic: Set of object files, libraries, system shared resources and other shared libraries are linked together to create an executable file
 - When this executable is loaded, *other shared resources and dynamic libraries must be made available* in the system for the program to run successfully
 - If multiple programs running on a processor need the same object module, only one copy of the module needs to be loaded in the memory

Dynamic Linking

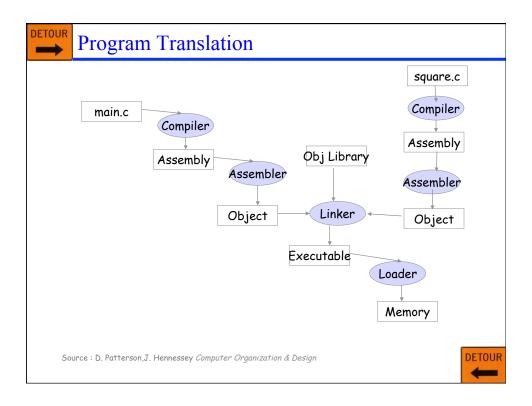
- Dynamically linked executable or shared object undergoes final linking when
 - Loaded into memory by a program loader
- An executable or shared object to be linked dynamically might
 - List one or more shared objects (shared libraries) with which it should be linked
- Other advantages of dynamic linking
 - Updating of libraries
- The size on disk of an executable that uses dynamically linked modules may be less than its size in memory (during run-time)
 - Why?

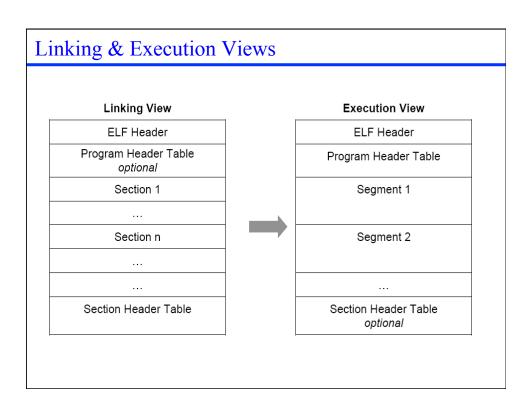
Kinds of Object Files

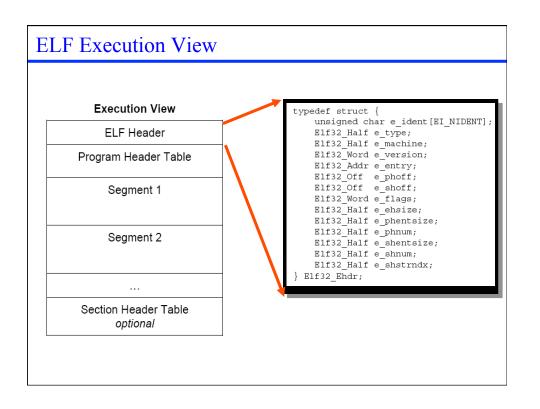
- Three main types of object files
 - Re-locatable file: Code and data suitable for linking with other object files to create an executable or a shared object file
 - Executable file: Program suitable for execution
 - Shared object file (also called "Dynamically linked library"): Special type
 of re-locatable object file that can be loaded into memory and linked
 dynamically
 - First, the linker may process it with other re-locatable and shared object files to create another object file
 - Second, the dynamic linker combines it with an executable file and other shared objects to create a process image
- Compilers and assemblers generate re-locatable object files
- Linkers generate executable object files

Executable and Linking Format (ELF)

- Object files need to be in a specific format to facilitate linking and loading
- Executable and Linkable Format (ELF) is the popular format of an object file
- Supported by many vendors and tools
 - Diverse processors, multiple data encodings and multiple classes
- ELF specifies the layout of the object files and not the corcode or data
- ELF object files consist of
- ELF Header
 - Beginning of ELF file
 - Holds a road map of file's organization
 - How to interpret the file, independent of the processor
- Program header table
 - Tells the system how to create a process image
 - Files used to build a process image (execute a program) must have a program header table
 - Re-locatable files do not need one
- Sections







ELF Header

- All ELF files contain a header in the beginning of the file
 - Determines whether the file is an ELF file, whether it is in big/little endian format, the target processor, offsets to the program header table and/or section header table...
- Format of the ELF header

ELF Sections

Secti

Relocatable files must have a section header table Locations and size of sections are described by the section header table

.rel.text .rel.data .debug .line		ELF header
ions .data .bss .symtab .rel.text .rel.data .debug .line	ions {	.text
.bss .symtab .rel.text .rel.data .debug .line		.rodata
.symtab .rel.text .rel.data .debug .line		.data
.rel.text .rel.data .debug .line		.bss
.rel.text .rel.data .debug .line		.symtab
.debug		.rel.text
.line		.rel.data
		.debug
.strtab		.line
,		.strtab
Section header table	{	Section header table

Source: "Computer Systems: A Programmer's Perspective", R. E. Bryant and D. O'Hallaron

Description of Various Sections

- text: program instructions and literal data
- . rodata: Read-only data such as the format strings in printf statements
- .data: initialized global data
- .bss: un-initialized global data (set to zero when program image is created)
 - This section does not occupy any space in the object file
- . symtab: this section holds the symbol table information
 - All global variables and functions that are defined and referenced in the program
- .rel.text: list of locations in the .text section that will need to be modified when linker combines this object files with others
- .rel.data: relocation information for any global variables that are referenced or defined in a module
- .debug: debugging information (present only if code is compiled to produce debug information)
- .line: mapping between line numbers in C program and machine code instructions (present only if code is compiled to produce debug information)
- .strtab: string table for symbols defined in .symtab and .debug sections

Executable Object Files ELF header Maps file sections to runtime memory Segment header table segments Read-only memory segment .init (code segment) .text .rodata .data Read/write memory segment (data segment) .bss .symtab .debug Symbol table and .line debugging info are not loaded into memory .strtab Describes object file Section header table sections Source: "Computer Systems: A Programmer's Perspective", R. E. Bryant and D. O'Hallaron

ELF Program Header

- Executable ELF files must have a program header table
 - The program header table is used to load the program (called "creating program image")
 - Each segment has its own entry in the program header table
 - e phnum in ELF Header holds the number of program header entries
 - All program header entries have the same size (e_phentsize in ELF header)
- · Program header entry for each segment

- What happens if p_memsz > p_filesz?
 - The remaining bytes (p memsz-p filesz) are initialized with 0

Useful Tools

- You can use many command line tools to parse ELF files
- ARM provides readelf command line utility that can display information about an ELF file
 - You can disassemble ELF files, look at symbol table information, etc.
- Example: readelf main.o

```
** ELF Header Information
File Name: main.c
Machine class: ELFCLASS32 (32-bit)
Data encoding: ELFDATA2MSB (Big endian)
Header version: EV_CURRENT (Current version)
File Type: ET_REL (Relocatable object) (1)
Machine: EM_ARM (ARM)
Header size: 52 bytes (0x34)
Program header entry size: 32 bytes (0x20)
Section header entry size: 40 bytes (0x28)
Program header entries: 0
Section header entries: 25
Program header offset: 0 (0x00000000)
Section header offset: 4512 (0x000011a0)
...and more
```

Useful Tools (contd.)

- Look at the symbol table information in main.o
- Example: nm main.o

D (global, initialized, data) counter
T (global text) main
U (global undefined) square
t (local, static, text) sum
C (global, uninitialized) tmp

 You can also use other switches to print information on each segment, section, print relocation information ...

References

- Linking
 - How linking works
 - Static & Dynamic Linking
- Loading
 - ELF file format
 - Executable & Linking Format Header
 - References:
 - Chapter 7 of "Computer Systems: A Programmer's perspective" by R. E. Bryant and D. R. O' Hallaron
 - Read sections 3.1, 3.2 and 3.7 of the ARM ELF Specification (on Blackboard in Course Documents → Manuals folder)

Improving Program Performance

- Compiler writers try to apply several standard optimizations
 - Do **not** always succeed
 - Have to ensure that the program will produce the same output for *all* cases

- Optimizations based on specific architecture/implementation characteristics can be very helpful
- How can one help?
 - Re-organize code to help compiler find opportunities for improvement

Processor Independent Compiler Optimizations (1)

- Common Sub-expression Elimination
 - Formally, "An occurrence of an expression E is called a *common sub-expression* if E was previously computed, and the values of variables in E have not changed since the previous computation."
 - You can avoid re-computing the expression if we can use the previously computed one.
 - Benefit: less code to be executed

Processor Independent Compiler Optimizations (2)

- Dead-Code Elimination
 - If code is definitely not going to be executed during any run of a program, then it is called dead code and can be removed.
 - Example:

```
debug = 0;
...
if (debug) {
   print .....
}
```

- You can help by using #ifdefs to tell the compiler about dead code
 - It is often difficult for the compiler to identify dead code itself

Processor Independent Compiler Optimizations (3)

- Induction Variables and Strength Reduction
 - A variable X is called an *induction variable* of a loop L if every time the variable X changed value, it is incremented or decremented by some constant
 - When there are 2 or more induction variables in a loop, it may be possible to get rid of all but one
 - It is also frequently possible to perform strength reduction on induction variables
 - the strength of an instruction corresponds to its execution cost
 - Benefit: fewer and less expensive operations

```
j = 0
label_xxx
j = j + 1
t4 = 11 * j
t5 = a[t4]
if (t5 > v) goto label_xxx
```

```
t4 = 0

label_XXX

t4 += 11

t5 = a[t4]

if (t5 > v) goto label_XXX
```

Before

After

Processor Independent Compiler Optimizations (4)

- Loop Unrolling
 - Doing multiple iterations of work in each iteration is called "loop unrolling"
 - Benefit: reduction in looping overheads and opportunity for more code opts.
 - **Danger**: increased code size and *non-integral loop div*.
 - Appropriate when loops are small

```
int checksum(int *data, int N)
{
        int i, sum=0;
        for(i=0;i<N;i++)
        {
            sum += *data++;
        }
        return sum;
}</pre>
```

Before loop unrolling

```
int checksum(int *data, int N)
{
    int i, sum=0;
    for(i=0;i<N;i+=4)
    {
        sum += *data++;
        sum += *data++;
        sum += *data++;
        sum += *data++;
        sum += *data++;
    }
    return sum;
}</pre>
```

Loop is unrolled 4 times

After unrolling the loop

Processor Independent Compiler Optimizations (4)

```
int checksum(int *data, int N)
{
    int i, sum=0;
    for(i=0;i<N;i++)
    {
        sum += *data++;
    }
    return sum;
}</pre>
```

```
0x00: MOV r3, #0 ; sum =0
0x04: MOV r2, #0 ; i= 0
0x08: CMP r2, r1 ; (i < N)?
0x0c: BGE 0x20 ; go to 0x20 if i >= N
0x10: LDR r12, [r0], #4 ; r12 <- data++
0x14: ADD r3, r12, r3 ; sum = sum + r12
0x18: ADD r2, r2, #1 ; i=i+1
0x1c: B 0x8 ; jmp to 0x08
0x20: MOV r0, r3 ; sum = r3
0x24: MOV pc, r14 ; return
```

```
Loop Unrolling
                                     ; sum =0
0x00:
                                                                                                    Original loop
0x04:
0x08:
                                     ; (i < N) ? ; go to 0x20 if
           CMP
           BGE
0x10:
                      r12,[r0],#4 ; r12 <- data++
           LDR
                      r3,r12,r3 ; sum = sum + r12
r2,r2,#1 ; i=i+1
0x8 ; jmp to 0x08
0x18:
0x1c:
                                                                                          loop overhead
           ADD
                                                                                          computed N times
0x20:
                      r0,r3
0x24:
           MOV
                      pc,r14
                                    ; return
                                    ; sum = 0
; i = 0
; jmp to 0x30
0x00:
                                                                                                 After unrolling
                     r2,#0
0x30
0x04:
          MOV
0x08:
                                                                                                 the loop 4 times
                     r12,[r0],#4 ; r12 <- data++
0x0c:
                     r3,r12,r3 ; sum = sum + r12
r12,[r0],#4 ; r12 <- data++
0x10:
          ADD
0x14:
          LDR
0x18:
                     r12,[r0],#4 ; r12 <- data++
0x1c:
0x20:
          LDR
                     r3,r12,r3 ; sum = sum + r12
r12,[r0],#4 ; r12 <- data++
          ADD
0x24:
0x28:
                     r3,r12,r3
                                                                                        loop overhead
0x2c:
0x30:
          ADD
CMP
                     r2,r2,#4
r2,r1
                                     ; i = i + 4; (i < N)?
                                                                                        computed N/4 times
                                    ; go to 0x0c if i < N
                               ; r0 <- sum
; return
0x38:
          MOV
                     r0,r3
                     pc, r14
0x3c:
          MOV
```

Processor Independent Compiler Optimizations (5)

- In-lining of functions
 - Replacing a call to a function with the function's code is called "in-lining"
 - Benefit: reduction in procedure call overheads and opportunity for additional code optimizations
 - Danger: increased code size (possibly)
 - Appropriate when small and/or called from a small number of sites

```
void t(int x, int y)
{
    int al=max(x,y);
    int a2=max(x+1,y);

    return max(al+1,a2);
}
__inline int max(int a, int b)
{
    int x;
    x=(a>b ? a:b);
    return x;
}
```

```
Without Function Inlining
void t(int x, int y)
                                     $a
                                                       r0,r1; (x > y) ?

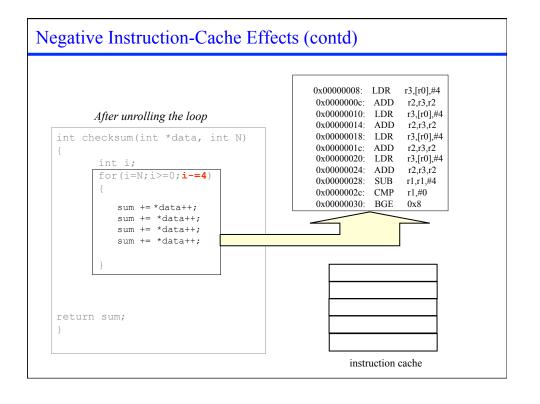
0x0c; return if (x > y)

r0,r1; else r0 <- y

pc,r14 return
                                     0x00:
    int a1=max(x,y);
                                     0x04:
    int a2=max(x+1,y);
                                     0x08:
                                             MOV
                                     0x0c:
                                             MOV
    return max(a1+1,a2);
                                     0x10:
                                              STMFD
                                                       r13!, {r4, r14}; save registers
                                     0x14:
                                                       r2,r0;
                                                                       r2 <- x
int max(int a, int b)
                                     0x18:
                                             MOV
                                                       r3,r1;
                                                                        r3 <- y
                                     0x1c:
                                              MOV
                                                       r1,r3;
                                                                       r1 <- y
    int x;
                                     0x20:
                                              MOV
                                                       r0,r2;
                                                                     r0 <- x
    x=(a>b ? a:b);
                                     0x24:
                                              BL
                                                       max ;
                                                                       r0 <- max(x,y)
    return x;
                                     0x28:
                                             MOV
                                                       r4,r0;
                                                       r1,r3;
r0,r2,#1;
r0 <- x+1
r0 <- max(x+1,y)
                                     0x2c:
                                             MOV
                                     0x30:
                                             ADD
                                                       r0,r4,#1;
                                     0x38:
                                              MOV
                                     0x3c:
                                             ADD
                                                                       r0 <- a1+1
                                             LDMFD
                                     0x40:
                                                       r13!,{r4,r14} ; restore
                                     0x44:
                                                       max ;
```

With Function Inlining void t(int x, int y) $0 \times 00:$ r0,r1 ; (x<= y) ? $0 \times 04:$ 0x10 ; jmp to 0x10 if true BLE 0x08: r2,r0 ; a1 <- x MOV int a1=max(x,y); 0x0c: В 0x14 ; jmp to 0x14int a2=max(x+1,y); 0x10: MOV r2,r1; a1 <- y if x <= yr0,r0,#1; generate r0=x+1 r0,r1 ; (x+1 > y) ? ADD 0x14: return max(a1+1,a2); 0x18: ;jmp to 0x24 if true BGT 0x24 0x1c: _inline int max(int a, int b) 0x20: MOV r0,r1 0x24: r1, r2, #1 ; r1 <- a1+1 CMP r1,r0 ; (a1+1 <= a2) ? 0x28: int x; 0x34 ; jmp to 0x34 if true 0x2c: x=(a>b ? a:b);r0,r1 ; else r0 <- a1+1 MOV 0x30: return x; 0x34: MOV pc,r14

Negative Instruction-Cache Effects • Negative instruction cache effects - Loop unrolling and function in-lining can cause performance degradation in systems with caches 0x0000000c: int checksum(int *data, int N) r3,[r2],#4 LDR 0x00000010: ADD r0,r3,r0 0x0000014: SUB r1, r1, #1 for(i=N;i>=0;i--) 0x00000018: r1,#0 CMP 0x0000001c: 0xc sum += *data++; return sum; 0x0000000C 0x00000010 0x00000014 Before unrolling the loop 0x00000018 0x0000001Cinstruction cache



ARM Specific Code Optimization Techniques

- Often, it is important to understand the architecture's implementation in order to effectively optimize code
- One example of this is the ARM barrel shifter
 - Can convert Y * Constant into series of adds and shifts
 - Y * 9 = Y * 8 + Y * 1
 - Assume R1 holds Y and R2 will hold the result
 ADD R2, R1, R1, LSL #3; LSL #3 is same as * by 8
- Use of conditional execution of instructions can reduce the code size as well as reduce the number of execution cycles

Writing Efficient C for ARM Processors (1)

- Use loops that count down to zero, instead of counting upwards
- Example

```
int checksum(int *data)
{
    unsigned i;
    int sum=0;

    for(i=0;i<64;i++)
        sum += *data++;

    return sum;
}

int checksum(int *data)
{
    unsigned i;
    int sum=0;

    for(i=63;i >= 0;i--)
        sum += *data++;

    return sum;
}
```

Count-up loop

- Count-down loop
- Counting upwards needs an ADD instruction, a CMP to check if index less than 64, and a conditional branch if index is less than 64
 - Counting downwards needs a SUBS instruction (which sets the CPSR flags), and a conditional branch instruction BGE to handle the end of the looping

Count-Down Loops

```
Example
int checksum_v1(int *data)
{
    unsigned i;
    int sum=0;

    for(i=0;i<64;i++)
        sum += *data++;

    return sum;
}

MOV r2, r0; r2=data
    MOV r0, #0; sum=0
    MOV r1, #0; i=0
L1 LDR r3, [r2], #4; r3=*data++
    ADD r1, r1, #1; i=i+1
    CMP r1, 0x40; cmp r1, 64
    ADD r0, r3, r0; sum +=r3
    BCC L1; if i < 64, goto L1
    MOV pc, lr; return sum

int checksum_v2(int *data)
{
    unsigned i;
    int sum=0;

    for(i=63;i >= 0;i--)
        sum += *data++;

    return sum;
}

MOV r2, r0; r2=data
    MOV r2, r0; r2=data
    MOV r0, #0; sum=0
    MOV r1, #0x3f; i=63
    L1 LDR r3, [r2], #4; r3=*data++
    ADD r0, r3, r0; sum +=r3
    SUBS r1, r1, #1; i--, set flags
    BGE L1; if i >= 0, goto L1
    MOV pc, lr; return sum
```

Writing Efficient C for ARM Processors (2)

- These are things you can keep in mind, rather than expecting the compiler to do all the work for you
- ARM processors uses 32-bit data types in their data processing instructions
- Example

```
void t4(void)
    void t3(void)
                                                int c;
            char c;
                                               int x=0;
            int x=0;
                                               for(c=0;c<63;c++)
            for(c=0;c<63;c++)
                                                         x++;
                   x++;
                                        }
                 r0,#0; x=0
r1,#0; c=0
       VOM
       VOM
                r1,#0, cmp c with 63
L2; if c>= 63, goto L2
       CMP
T.1
       BCS
               r0,r0,#1; x++;
r1,r1,#1; c++
r1,r1,#0xff; c=(char) r1
       ADD
        ADD
        AND
       В
                 L1;
                              branch to L1
L2
                 pc,r14
```

Writing Efficient C for ARM Processors (3) – Avoid Divisions or Remainder Operation

- ARM does not have a divide instruction
- Divisions are implemented by calling software routines in C library
- Can take between 20-100 cycles
- In many cases, it might be possible to avoid divisions and/or remainder operation

Example: Circular Buffers (assuming increment <= size)

```
start=(start+increment) % size

start+= increment;
if (start >= size)
    start -= size;
```

 If you cannot avoid a division, try to arrange the numerator and denominator to be unsigned integers

Writing Efficient C for ARM Processors (4)

- Efficiently using global variables: Global variables are stored in memory, load and store instructions are typically used to access the variable when they are used or modified
 - Register accesses are more efficient than memory accesses
- In some cases a global variable is used frequently, it may be better to store it in a local variable
- Example

```
int f(void);
int g(void);
int g(void);
int errs;

void test_v1(void)
{
    errs += f();
    errs += g();
}

int f(void);
int g(void);
int errs;

void test_v2(void)
{
    int local_errs=errs;
    local_errs += f();
    local_errs += g();
    errs=local_errs;
}
```

Efficient Use of Global Variables

```
test v1
 0x00:
              STMFD
                           r13!, {r4, r14} ; save registers
 0x04:
                                                           ; compute f()
                    r4,0x84

r1,[r4,#0] ; r1 <- errs

r0,r0,r1 ; r1 <- r1 + r0

r0,[r4,#0] ; store r1 at mem loc address of errs

; compute g()
 0x08:
             LDR
              LDR
 0x10:
             ADD
 0x14:
             STR
 0x18:
             BL
                          r1,[r4,#0]
             LDR r1,[r4,#U] , r1
ADD r0,r0,r1
STR r0,[r4,#0] ; store r0 in errs
LDMFD r13!,(r4,pc) ; exit from function
 0x20:
 0x24:
 0x28:
test v2
                       r13!, {r3-r5, r14} ; save registers
r5,0x84 ; r5 <- address of
0x00:
             STMFD
0x04:
             LDR
                       r3,0x84
r4,[r5,#0]
f
                                                           ; r5 <- address of errs
                                                         ; r4 = local_errs = errs
; compute f()
; r4 = r4 + f()
0x08:
             LDR
0x0c:
0x10:
             ADD
                         r4,r0,r4
             BL g ; compute g()

ADD r0,r0,r4 ; r0 = r0 + r4;

STR r0,[r5,#0] ; store r0 at mem loc

LDMFD r13!,{r3-r5,pc} ; exit from function
                                                         ; compute g()
; r0 = r0 + r4;
 0x14:
             BL
0x18:
                                                          ; store r0 at mem loc address of errs
0x1c:
 0x20:
```

Writing Efficient C for ARM Processors (5)

- Local variables are typically stored in registers
- In some cases, local variables need to be stored in memory
 - Example when the address of a local variable is taken
- If a local variable is stored in memory, load and store are used to access the variable
- Example

```
int f(int *a);
                                              int f(int *a);
int g(int b);
                                              int g(int b);
                                              void test_v2(void)
void test_v1(void)
  int i=0;
                                                 int dummy=0, i;
                                                 f(&dummy);
  f(&i);
                                                i = dummy;
  i += g(i);
  i += g(i);
                                                i += g(i);
  /* lots of access to i */
                                                i += g(i);
  return i;
                                                 /* lots of access to i */
                                                 return i;
```

Writing Efficient C for ARM Processors (6)

- Avoid register spilling
 - When the number of local variables in use in a function exceeds the number of registers available
 - Causes the compiler to place certain variables in memory
- You should limit the number of live variables in a function
 - Subdividing large functions into multiple small functions may help (keep in mind that there you increase the function call overhead)
 - Use the register keyword to tell the compiler which variables have to be stored in registers in case of register spilling

Optimizing Function Calls

- Can the compiler optimize multiple calls to the same function?
- Example: Will the compiler convert

Writing Efficient C for ARM Processors (7) – Optimizing Function Calls

- Pure functions: Function whose output depends only upon the input parameters (and not the value of any other global variables) and do not have any side-effects
- Can tell a compiler that a function is a pure function by using the keyword pure in the declaration of the function
 - This allows the compiler to optimize calls to pure functions regardless of where the function is defined
- Example:

```
__pure int square(int x);

int test(int x)

{
    return (square(x*x) + square(x*x));
}

int test(int x)

{
    return (2*square(x*x));
}
```

Optimization for Code Size – Optimizing Structures

• Which of the two structures would be better?

```
struct
{
      char a;
      int b;
      char c;
      short d;
}
```

12 bytes

```
char a;
char c;
short d;
int b;
}
```

8 bytes

More Space Optimization

 Can use the __packed key word to instruct the compiler to remove all padding

```
__packed struct
{
    char a;
    int b;
    char c;
    short d;
    8 bytes
```

- · Packed structures are slow and inefficient to access
- ARM Compiler emulates unaligned load and store by using several aligned accesses and using several byte-by-byte operations to get the data
- Use __packed only if space is more important than speed and you cannot reduce padding by rearrangement

Summary of Lecture

- Improving program performance
 - Processor independent compiler optimizations
 - Common sub-expression elimination
 - · Dead-code elimination
 - · Induction variables
 - · In-lining of functions
 - Loop unrolling
- ARM specific optimizations
- Writing efficient C for running programs on ARM processors