



Penn  
Engineering  
UNIVERSITY OF PENNSYLVANIA

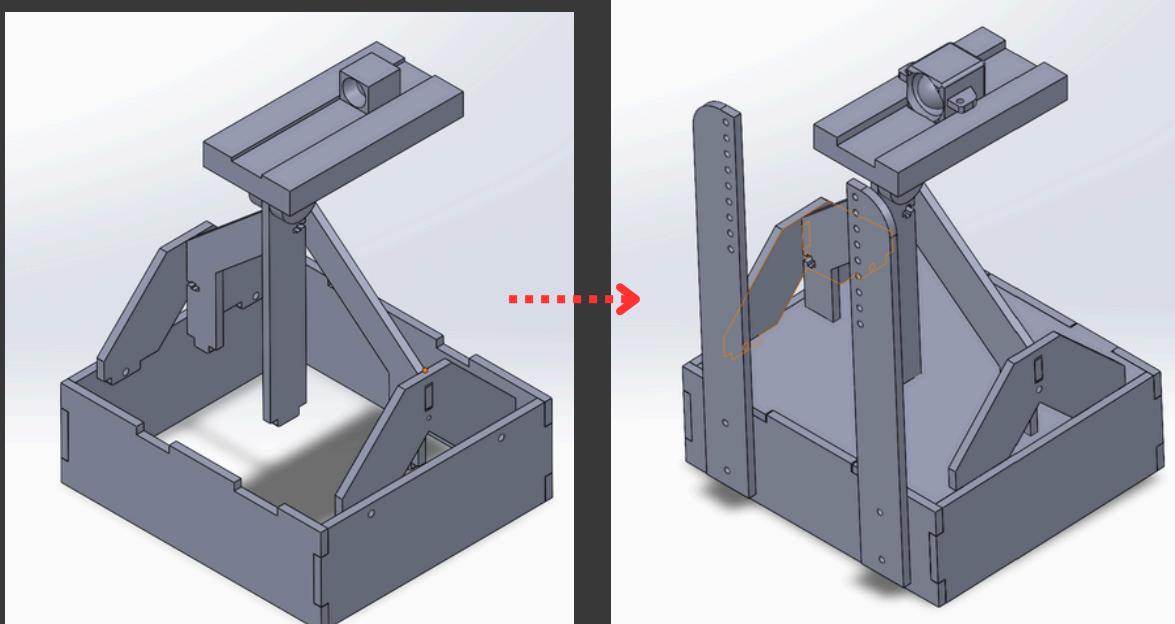
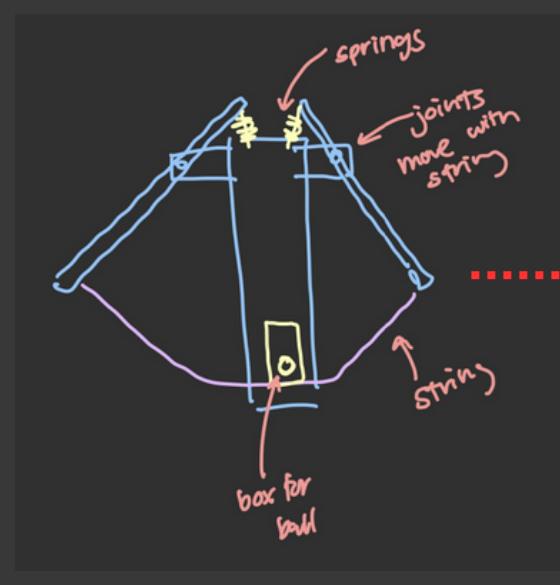
# Undergraduate Lab Projects

Trained in the traditional engineering and experimentation methodology through structured lab projects as a Mechanical Engineering undergraduate. Key projects include: Seige machine, Kinematics Launcher, Bridge, and Bottle Rocket.

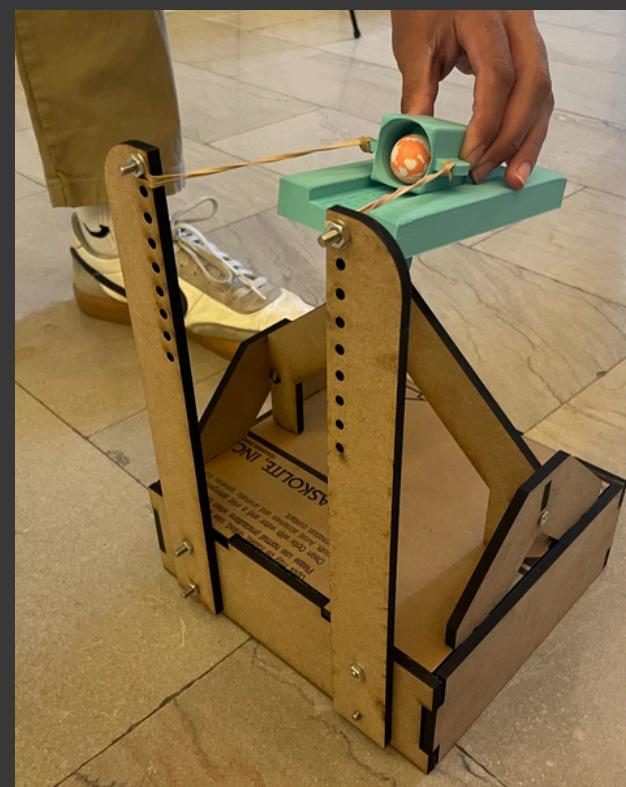
Made use of the school's Rapid Prototyping Lab to laser cut MDF, Acrylic and FDM 3D printers to extrude small PLA structures.

# MEAM 1010: Intro to Mechanical Design

## Seige Machine

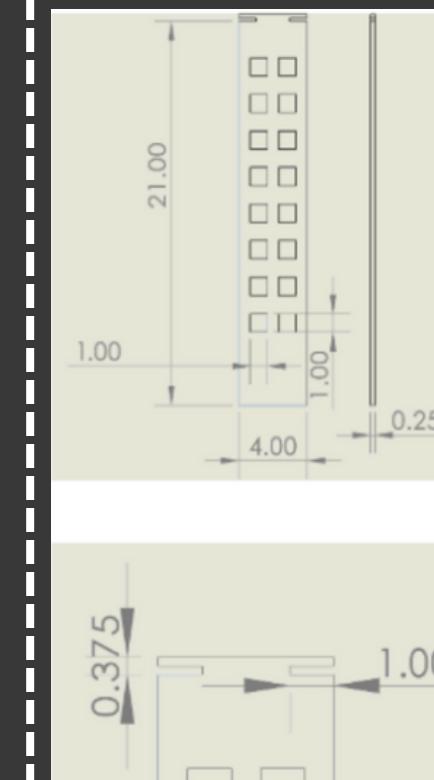
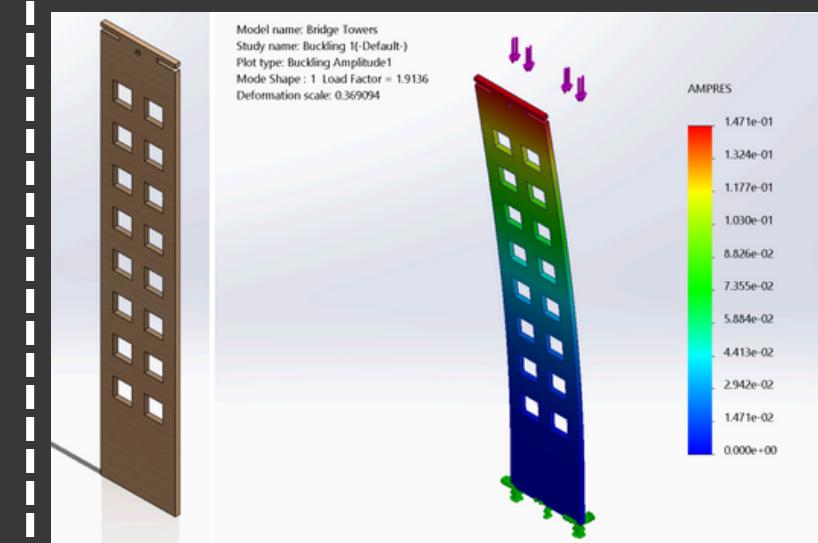


- Inspired by spring-loaded crossbows
- Utilized press fits for crossbow to attach to the large structure
- Fastener t-slot joints at the edges of the large structure
- Fastener lap joints on the crossbow itself
- Iterated on base design to manage reaction force generated by elastic rubber bands



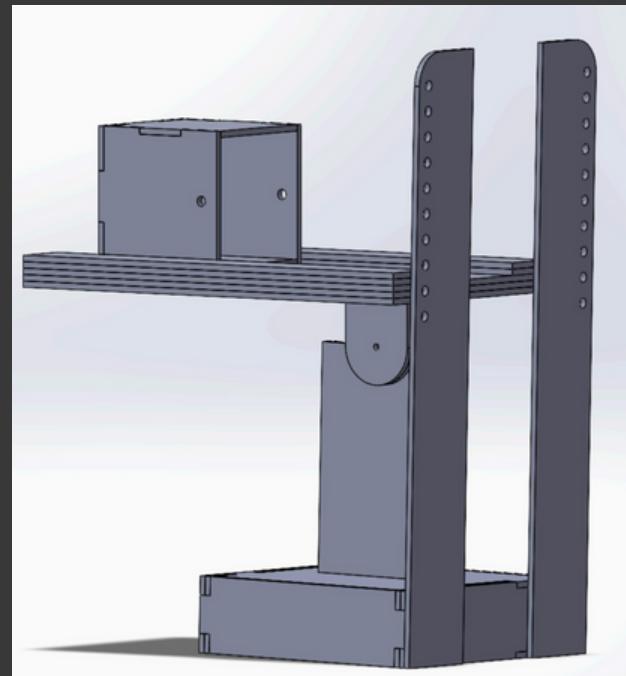
# MEAM 2470: Mechanical Engineering Lab 1

## Bridge Project



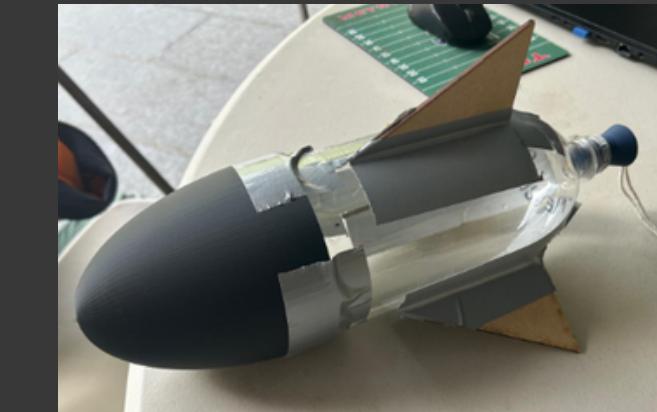
- Designed and built wide-span suspension bridge with 21" MDF towers; FEA validated tower safety factor of 1.91 under 25 N load.
- Modeled cable sag via parabolic arc-length integration, calculated required pre-load cut length (75.7") and hanger tensions (20–25 N range).
- Derived tension–elongation model from MTS tensile tests to predict cable stretch; total elongation measured at 4.7".
- Implemented bowline knots + cleated loops for secure cable anchoring; optimized for cost.
- Final bridge passed test with 7.5" sag clearance (vs. 6" minimum), validating calculations and fabrication.

## Launcher Project



- Designed and manufactured adjustable slingshot-style launcher in SolidWorks; tunable angle ( $0\text{--}40^\circ$ ) and variable pullback energy.
- Iteratively improved design (track extension, kicker mechanism, structural backplate) to reduce friction and stabilize launches.
- Built Python model of projectile motion with drag; optimized launch angle and energy via numerical simulation.
- Calibrated model with experimental testing; derived correction multipliers for angle (0.66) and pullback (2.65).
- Validated energy transfer with onboard acceleration sensors; achieved  $>5$  m launch distance.

## Model Rocket Project



- Designed and fabricated a pressurized water–butane rocket with 3D-printed PLA nosecone (optimized 0.08" wall thickness) and MDF fins (sealed for water resistance) to minimize drag and maximize stability.
- Conducted 7+ experimental launches across varied angles ( $40\text{--}75^\circ$ ) and fill volumes (100–750 mL), recording trajectory outcomes under different wind conditions.
- Simulated two-phase flight (thrust + coasting) using ideal gas law, Antoine equation for butane vapor pressure, and drag modeling, implemented in Python.
- Applied OpenRocket aerodynamic modeling to determine center of pressure (6.76") and center of mass (5.33") for static stability margin analysis.
- Optimized launch parameters via brute-force grid search over angle and water fill volume; trade off accuracy vs. robustness for demo day.