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(http://cocl.us/pytorch_link_top)



Logistic Regression and Bad Initialization Value

Table of Contents

In this lab, you will see what happens when you use the root mean square error cost or total loss function and select a bad initialization value for the parameter values.

- [Make Some Data](#)
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- [Train the Model:Batch Gradient Descent](#)

Estimated Time Needed: **30 min**

Preparation

We'll need the following libraries:

In [1]:

```
# Import the libraries we need for this lab

import numpy as np
import matplotlib.pyplot as plt
from mpl_toolkits import mplot3d
import torch
from torch.utils.data import Dataset, DataLoader
import torch.nn as nn
```

Helper functions

The class `plot_error_surfaces` is just to help you visualize the data space and the Parameter space during training and has nothing to do with Pytorch.

In [2]:

```
# Create class for plotting and the function for plotting
```

```
class plot_error_surfaces(object):
```

```
    # Construtor
```

```
    def __init__(self, w_range, b_range, X, Y, n_samples = 30, go = True):
        W = np.linspace(-w_range, w_range, n_samples)
        B = np.linspace(-b_range, b_range, n_samples)
        w, b = np.meshgrid(W, B)
        Z = np.zeros((30, 30))
        count1 = 0
        self.y = Y.numpy()
        self.x = X.numpy()
        for w1, b1 in zip(w, b):
            count2 = 0
            for w2, b2 in zip(w1, b1):
                Z[count1, count2] = np.mean((self.y - (1 / (1 + np.exp(-1*w2 * self
.x - b2)))) * 2)
                count2 += 1
            count1 += 1
        self.Z = Z
        self.w = w
        self.b = b
        self.W = []
        self.B = []
        self.LOSS = []
        self.n = 0
        if go == True:
            plt.figure()
            plt.figure(figsize=(7.5, 5))
            plt.axes(projection='3d').plot_surface(self.w, self.b, self.Z, rstride=
1, cstride=1, cmap='viridis', edgecolor='none')
            plt.title('Loss Surface')
            plt.xlabel('w')
            plt.ylabel('b')
            plt.show()
            plt.figure()
            plt.title('Loss Surface Contour')
            plt.xlabel('w')
            plt.ylabel('b')
            plt.contour(self.w, self.b, self.Z)
            plt.show()
```

```
    # Setter
```

```
    def set_para_loss(self, model, loss):
        self.n = self.n + 1
        self.W.append(list(model.parameters())[0].item())
        self.B.append(list(model.parameters())[1].item())
        self.LOSS.append(loss)
```

```
    # Plot diagram
```

```
    def final_plot(self):
        ax = plt.axes(projection='3d')
        ax.plot_wireframe(self.w, self.b, self.Z)
        ax.scatter(self.W, self.B, self.LOSS, c='r', marker='x', s=200, alpha=1)
```

```

plt.figure()
plt.contour(self.w, self.b, self.Z)
plt.scatter(self.W, self.B, c='r', marker='x')
plt.xlabel('w')
plt.ylabel('b')
plt.show()

# Plot diagram
def plot_ps(self):
    plt.subplot(121)
    plt.ylim
    plt.plot(self.x, self.y, 'ro', label="training points")
    plt.plot(self.x, self.W[-1] * self.x + self.B[-1], label="estimated line")
    plt.plot(self.x, 1 / (1 + np.exp(-1 * (self.W[-1] * self.x + self.B[-1]))),
label='sigmoid')
    plt.xlabel('x')
    plt.ylabel('y')
    plt.ylim((-0.1, 2))
    plt.title('Data Space Iteration: ' + str(self.n))
    plt.show()
    plt.subplot(122)
    plt.contour(self.w, self.b, self.Z)
    plt.scatter(self.W, self.B, c='r', marker='x')
    plt.title('Loss Surface Contour Iteration' + str(self.n))
    plt.xlabel('w')
    plt.ylabel('b')

# Plot the diagram

def PlotStuff(X, Y, model, epoch, leg=True):
    plt.plot(X.numpy(), model(X).detach().numpy(), label=('epoch ' + str(epoch)))
    plt.plot(X.numpy(), Y.numpy(), 'r')
    if leg == True:
        plt.legend()
    else:
        pass

```

Set the random seed:

In [3]:

```

# Set random seed

torch.manual_seed(0)

```

Out[3]:

```

<torch._C.Generator at 0x7f4d52436090>

```

Get Some Data

Create the Data class

In [4]:

```
# Create the data class

class Data(Dataset):

    # Constructor
    def __init__(self):
        self.x = torch.arange(-1, 1, 0.1).view(-1, 1)
        self.y = torch.zeros(self.x.shape[0], 1)
        self.y[self.x[:, 0] > 0.2] = 1
        self.len = self.x.shape[0]

    # Getter
    def __getitem__(self, index):
        return self.x[index], self.y[index]

    # Get Length
    def __len__(self):
        return self.len
```

Make Data object

In [5]:

```
# Create Data object

data_set = Data()
```

Create the Model and Total Loss Function (Cost)

Create a custom module for logistic regression:

In [6]:

```
# Create logistic_regression class

class logistic_regression(nn.Module):

    # Constructor
    def __init__(self, n_inputs):
        super(logistic_regression, self).__init__()
        self.linear = nn.Linear(n_inputs, 1)

    # Prediction
    def forward(self, x):
        yhat = torch.sigmoid(self.linear(x))
        return yhat
```

Create a logistic regression object or model:

In [7]:

```
# Create the logistic_regression result  
  
model = logistic_regression(1)
```

Replace the random initialized variable values with some predetermined values that will not converge:

In [8]:

```
# Set the weight and bias  
  
model.state_dict()['linear.weight'].data[0] = torch.tensor([[ -5]])  
model.state_dict()['linear.bias'].data[0] = torch.tensor([[ -10]])  
print("The parameters: ", model.state_dict())
```

```
The parameters: OrderedDict([('linear.weight', tensor([[ -5.]])), ('linear.bias', tensor([[ -10.]])])
```

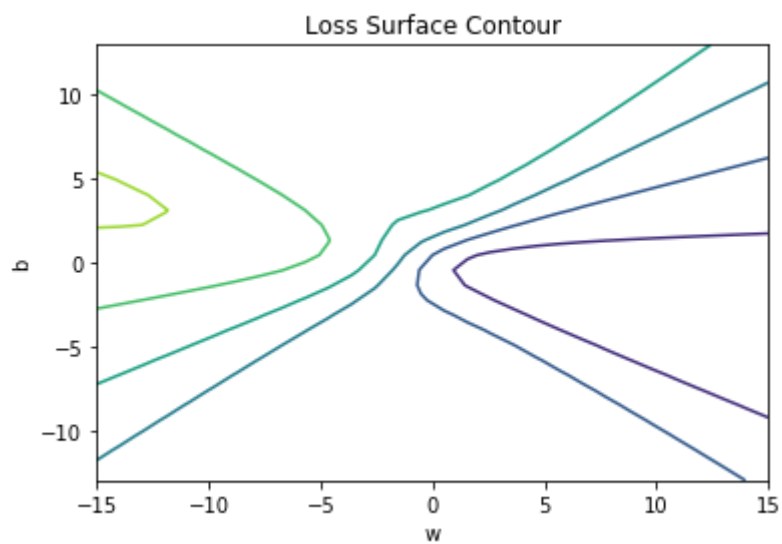
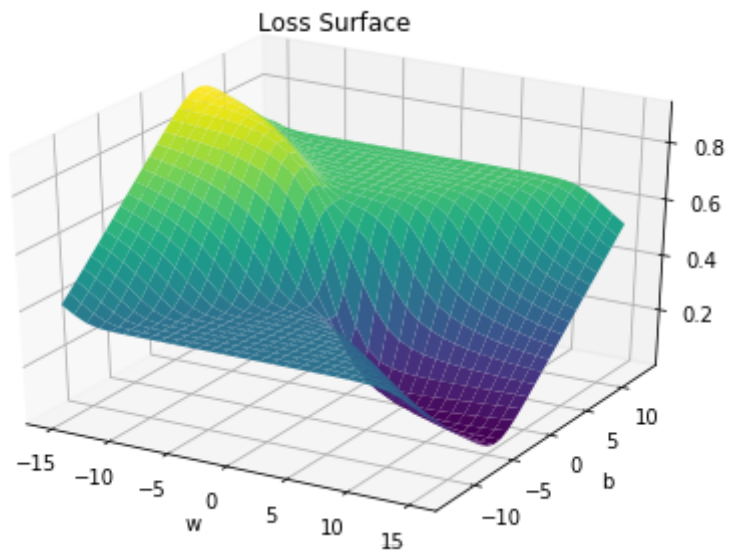
Create a `plot_error_surfaces` object to visualize the data space and the parameter space during training:

In [9]:

```
# Create the plot_error_surfaces object
```

```
get_surface = plot_error_surfaces(15, 13, data_set[:,0], data_set[:,1], 30)
```

<Figure size 432x288 with 0 Axes>



Define the dataloader, the cost or criterion function, the optimizer:

In [10]:

```
# Create dataloader object, criterion function and optimizer.

trainloader = DataLoader(dataset=data_set, batch_size=3)
criterion_rms = nn.MSELoss()
learning_rate = 2
optimizer = torch.optim.SGD(model.parameters(), lr=learning_rate)
```

Train the Model via Batch Gradient Descent

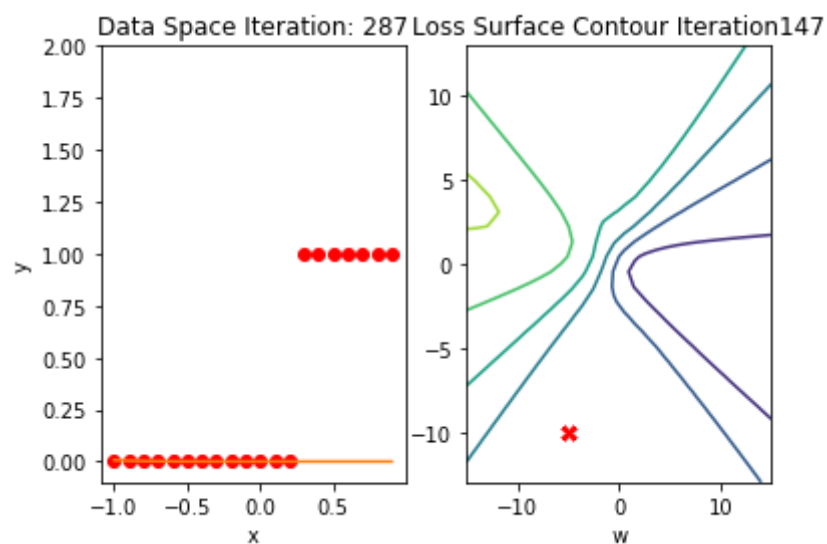
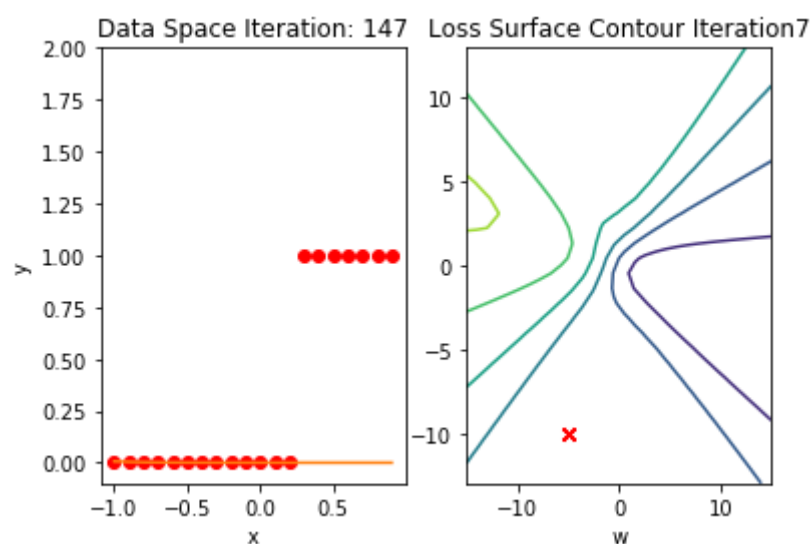
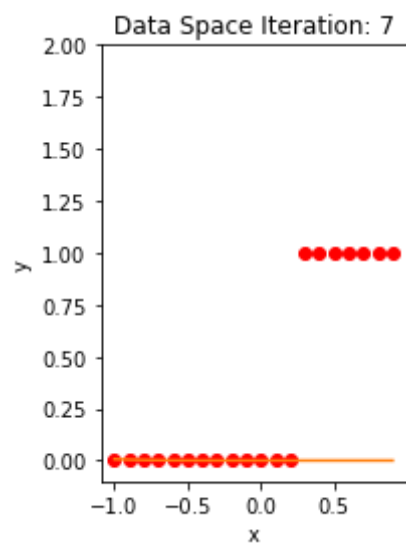
Train the model

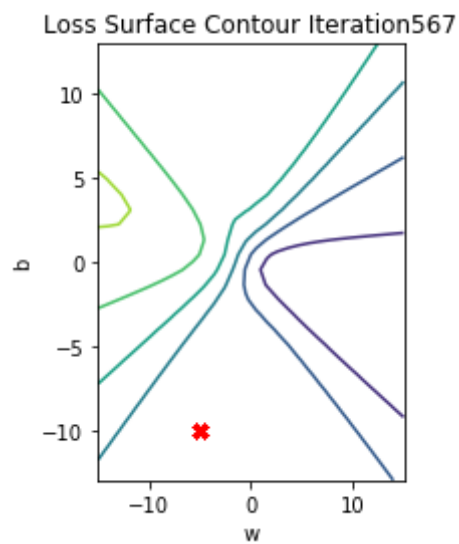
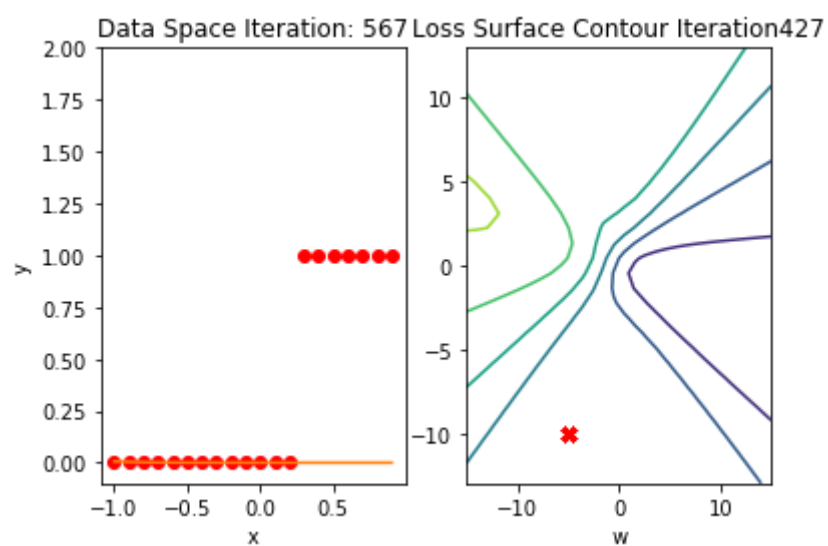
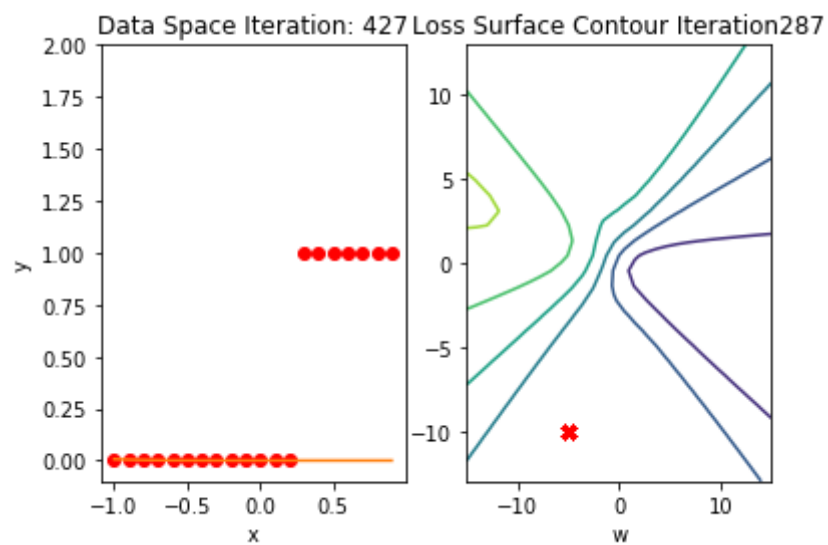
In [11]:

```
# Train the model
```

```
def train_model(epochs):  
    for epoch in range(epochs):  
        for x, y in trainloader:  
            yhat = model(x)  
            loss = criterion_rms(yhat, y)  
            optimizer.zero_grad()  
            loss.backward()  
            optimizer.step()  
            get_surface.set_para_loss(model, loss.tolist())  
        if epoch % 20 == 0:  
            get_surface.plot_ps()
```

```
train_model(100)
```





Get the actual class of each sample and calculate the accuracy on the test data:

In [12]:

```
# Make the Prediction

yhat = model(data_set.x)
label = yhat > 0.5
print("The accuracy: ", torch.mean((label == data_set.y.type(torch.ByteTensor)).type(torch.float)))
```

The accuracy: tensor(0.6500)

Accuracy is 60% compared to 100% in the last lab using a good Initialization value.



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