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(http://cocl.us/pytorch_link_top)



Deeper Neural Networks with nn.ModuleList()

Table of Contents

In this lab, you will create a Deeper Neural Network with nn.ModuleList()

- Neural Network Module and Function for Training
- Train and Validate the Model

Estimated Time Needed: 25 min

Preparation

We'll need the following libraries

In [1]:

```
import the libraries we need for this lab

import matplotlib.pyplot as plt
import numpy as np
import torch
import torch.nn as nn
import torch.nn.functional as F
from matplotlib.colors import ListedColormap
from torch.utils.data import Dataset, DataLoader

torch.manual_seed(1)
```

Out[1]:

<torch. C.Generator at 0x11c408610>

Function used to plot:

In [2]:

```
# Define the function to plot the diagram
def plot decision regions 3class(model, data set):
    cmap light = ListedColormap(['#FFAAAA', '#AAFFAA', '#00AAFF'])
    cmap bold = ListedColormap(['#FF0000', '#00FF00', '#00AAFF'])
    X = data set.x.numpy()
    y = data set.y.numpy()
    h = .02
    x_{min}, x_{max} = X[:, 0].min() - 0.1, X[:, 0].max() + 0.1
    y \min_{x \in X} y \max_{x \in X} = X[:, 1].\min() - 0.1, X[:, 1].\max() + 0.1
    xx, yy = np.meshgrid(np.arange(x_min, x_max, h), np.arange(y_min, y_max, h))
    XX = torch.Tensor(np.c_[xx.ravel(), yy.ravel()])
    , yhat = torch.max(model(XX), 1)
    yhat = yhat.numpy().reshape(xx.shape)
    plt.pcolormesh(xx, yy, yhat, cmap=cmap_light)
    plt.plot(X[y[:] == 0, 0], X[y[:] == 0, 1], 'ro', label = 'y=0')
    plt.plot(X[y[:] == 1, 0], X[y[:] == 1, 1], 'go', label = 'y=1')
    plt.plot(X[y[:] == 2, 0], X[y[:] == 2, 1], 'o', label = 'y=2')
    plt.title("decision region")
    plt.legend()
```

Create Dataset Class

```
In [3]:
```

```
# Create Data Class
class Data(Dataset):
   # modified from: http://cs231n.github.io/neural-networks-case-study/
   # Constructor
    def __init__(self, K=3, N=500):
        D = 2
        X = np.zeros((N * K, D)) # data matrix (each row = single example)
        y = np.zeros(N * K, dtype='uint8') # class labels
        for j in range(K):
          ix = range(N * j, N * (j + 1))
          r = np.linspace(0.0, 1, N) # radius
          t = np.linspace(j * 4, (j + 1) * 4, N) + np.random.randn(N) * 0.2 # theta
          X[ix] = np.c_[r * np.sin(t), r*np.cos(t)]
          y[ix] = j
        self.y = torch.from_numpy(y).type(torch.LongTensor)
        self.x = torch.from_numpy(X).type(torch.FloatTensor)
        self.len = y.shape[0]
   # Getter
   def __getitem__(self, index):
        return self.x[index], self.y[index]
   # Get Length
    def __len__(self):
        return self.len
    # Plot the diagram
   def plot stuff(self):
        plt.plot(self.x[self.y[:] == 0, 0].numpy(), self.x[self.y[:] == 0, 1].numpy
(), 'o', label="y = 0")
       plt.plot(self.x[self.y[:] == 1, 0].numpy(), self.x[self.y[:] == 1, 1].numpy
(), 'ro', label="y = 1")
        plt.plot(self.x[self.y[:] == 2, 0].numpy(), self.x[self.y[:] == 2, 1].numpy
(), 'go', label="y = 2")
       plt.legend()
```

Neural Network Module and Function for Training

Neural Network Module using ModuleList()

```
In [4]:
```

```
# Create Net model class
class Net(nn.Module):
    # Constructor
    def __init__(self, Layers):
        super(Net, self).__init__()
        self.hidden = nn.ModuleList()
        for input_size, output_size in zip(Layers, Layers[1:]):
            self.hidden.append(nn.Linear(input_size, output_size))
    # Prediction
    def forward(self, activation):
        L = len(self.hidden)
        for (1, linear_transform) in zip(range(L), self.hidden):
            if 1 < L - 1:
                activation = F.relu(linear_transform(activation))
            else:
                activation = linear_transform(activation)
        return activation
```

A function used to train.

```
# Define the function for training the model
def train(data_set, model, criterion, train_loader, optimizer, epochs=100):
   LOSS = []
    ACC = []
    for epoch in range(epochs):
        for x, y in train_loader:
            optimizer.zero_grad()
            yhat = model(x)
            loss = criterion(yhat, y)
            optimizer.zero_grad()
            loss.backward()
            optimizer.step()
            LOSS.append(loss.item())
        ACC.append(accuracy(model, data_set))
    fig, ax1 = plt.subplots()
    color = 'tab:red'
    ax1.plot(LOSS, color = color)
    ax1.set_xlabel('Iteration', color = color)
    ax1.set_ylabel('total loss', color = color)
    ax1.tick_params(axis = 'y', color = color)
    ax2 = ax1.twinx()
    color = 'tab:blue'
    ax2.set ylabel('accuracy', color = color) # we already handled the x-label wit
h ax1
    ax2.plot(ACC, color = color)
    ax2.tick_params(axis = 'y', color = color)
    fig.tight layout() # otherwise the right y-label is slightly clipped
    plt.show()
    return LOSS
```

A function used to calculate accuracy

```
In [6]:
```

```
# The function to calculate the accuracy

def accuracy(model, data_set):
    _, yhat = torch.max(model(data_set.x), 1)
    return (yhat == data_set.y).numpy().mean()
```

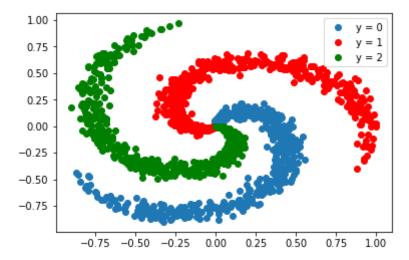
Train and Validate the Model

Crate a dataset object:

In [7]:

```
# Create a Dataset object

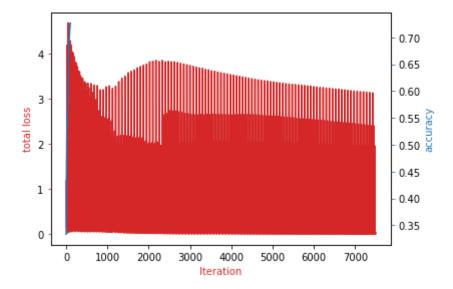
data_set = Data()
data_set.plot_stuff()
data_set.y = data_set.y.view(-1)
```

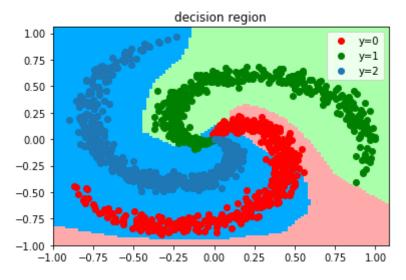


Create a network to classify three classes with 1 hidden layer with 50 neurons

```
# Train the model with 1 hidden layer with 50 neurons

Layers = [2, 50, 3]
model = Net(Layers)
learning_rate = 0.10
optimizer = torch.optim.SGD(model.parameters(), lr=learning_rate)
train_loader = DataLoader(dataset=data_set, batch_size=20)
criterion = nn.CrossEntropyLoss()
LOSS = train(data_set, model, criterion, train_loader, optimizer, epochs=100)
plot_decision_regions_3class(model, data_set)
```





Create a network to classify three classes with 2 hidden layers with 20 neurons in total

```
In [15]:
Net([3,3,4,3]).parameters
Out[15]:
<bound method Module.parameters of Net(</pre>
  (hidden): ModuleList(
    (0): Linear(in_features=3, out_features=3, bias=True)
    (1): Linear(in_features=3, out_features=4, bias=True)
    (2): Linear(in features=4, out features=3, bias=True)
)>
In [ ]:
# Train the model with 2 hidden layers with 20 neurons
Layers = [2, 10, 10, 3]
model = Net(Layers)
learning rate = 0.01
optimizer = torch.optim.SGD(model.parameters(), lr=learning_rate)
train loader = DataLoader(dataset=data set, batch size=20)
criterion = nn.CrossEntropyLoss()
LOSS = train(data_set, model, criterion, train_loader, optimizer, epochs=1000)
```

Practice

Create a network with three hidden layers each with ten neurons, then train the network using the same process as above

```
In [ ]:
```

```
# Practice: Create a network with three hidden layers each with ten neurons.
Layers = [2, 10, 10, 10, 3]
model = Net(Layers)
learning_rate = 0.01
optimizer = torch.optim.SGD(model.parameters(), lr = learning_rate)
train_loader = DataLoader(dataset = data_set, batch_size = 20)
criterion = nn.CrossEntropyLoss()
LOSS = train(data_set, model, criterion, train_loader, optimizer, epochs = 1000)
plot_decision_regions_3class(model, data_set)
```

Double-click here for the solution.

plot decision regions 3class(model, data set)

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