外径 50 [mm]、内径 10 [mm] の円筒内に満たされている水が全て凍結するまでの時間を後退差分法の VTS 法で求めるプログラムをソースコード 1 に示す。各時間ステップを出力したものを実行結果として、図  $1\sim4$  に示す。

ソースコード 1: 円筒状物体が凍結するまでの時間を後退差分法の VTS 法で求めるプログラム

```
1 | #include <stdio.h>
2 #include <math.h>
_4 | #define N 100
5 #define lambda_s 2.22
6 #define cp_s 2067
7 #define rho_s 917
8 #define alpha_s lambda_s / (rho_s * cp_s)
   #define L 334880
10 #define Ta -5
11 #define Tm 0
12 #define A 0.005
13 #define B 0.025
14 #define eps 1e-5
15
16 double dt[N], old_dt[N];
17 double t_s[N][N] = {Tm};
18
   const double dr = (B - A) / N; // drの算出
19
20
   void thomas_init(int n, double a[], double b[], double c[], double d[]){
21
22
   double r_s = (alpha_s * dt[n]) / (dr * dr);
23
    for(int i=0;i<n;i++){</pre>
24
       a[i] = -r_s * (1 - 1 / (2 * (A / dr + i + 1)));
25
      b[i] = 1 + 2 * r_s;
26
      c[i] = -r_s * (1 + 1 / (2 * (A / dr + i + 1)));
27
      d[i] = t_s[i+1][n];
28
29
     d[0] = t_s[1][n] + r_s * (1 - 1 / (2 * (A / dr + 1))) * Ta;
30
     d[n-1] = 0;
31
32 }
33
   void thomas(int n, double a[], double b[], double c[], double d[]){
34
    for(int i=1;i<n;i++){</pre>
35
       double e = a[i] / b[i-1];
36
      b[i] = b[i] - e * c[i-1];
37
      d[i] = d[i] - e * d[i-1];
38
39
40
    d[n-1] = d[n-1] / b[n-1];
    for(int i=n-2;i>=0;i--){
41
      d[i] = (d[i] - c[i] * d[i+1]) / b[i];
42
     }
43
44
45
     for(int i=1;i<=n;i++){</pre>
```

```
t_s[i][n+1] = d[i-1];
46
47
  }
48
49
   int is_convergence(double old_val, double new_val) {
50
     // 収束判定
51
     double e_temp = fabs((new_val - old_val) / old_val);
52
53
     if(e_temp > eps){
       return 1;
54
     } else {
55
       return 0;
56
57
   }
58
59
   int main(){
60
     double t_sum = 0;
61
     for(int i=0;i<N;i++) {</pre>
62
       dt[i] = 0;
63
       old_dt[i] = 0;
64
65
66
     // dt_0
67
     t_s[0][1] = Ta;
68
     dt[0] = ((rho_s * L) / lambda_s) * ((dr * dr) / (Tm - Ta));
69
     printf("\Delta t_0_{\sqcup\sqcup} = \ \%7.31f[s]\n", dt[0]);
70
     t_sum += dt[0];
71
72
     // dt_1
73
     dt[1] = dt[0];
74
     do {
75
       old_dt[1] = dt[1];
76
77
       double r_s = (alpha_s * dt[1]) / (dr * dr);
78
       double q = 1 / (2 * (A / dr + 1)); // t_s1 計算の簡略化変数
79
       t_s[1][2] = 1 / (1 + 2 * r_s) * ((1 + r_s * (1 + q)) * Tm + r_s * Ta * (1 - q)
80
       dt[1] = ((rho_s * L) / lambda_s) * ((dr * dr) / (Tm - t_s[1][2]));
81
     } while(is_convergence(old_dt[1], dt[1]));
82
     printf("\Delta t_1 = \%7.31f[s] n", dt[1]);
83
     t_sum += dt[1];
84
85
     // dt_2 ->
86
     for(int i=2;i<N;i++){</pre>
87
       dt[i] = dt[i-1];
88
       double a[i], b[i], c[i], d[i];
89
90
       do {
91
         old_dt[i] = dt[i];
92
93
         thomas_init(i, a, b, c, d);
94
         thomas(i, a, b, c, d);
95
         dt[i] = ((rho_s * L) / lambda_s) * ((dr * dr) / (Tm - t_s[i][i+1]));
```

```
(Users\s_takahashi\takahashi_workspace\c_workspace\computational_mechanics\kadai4> .\kadai4_2.exe
= 1.107[s]
= 2.274[s]
= 3.477[s]
= 4.720[s]
             6.002[s]
             7.322[s]
             8.678[5
            12.953[s]
\Delta t_{10} = 14.443[s]
Δt_11 = 15.965[s]
Δt_12 = 17.517[s]
Δt_13 = 19.098[s]
\Delta t_1 = 20.708[s]
\Delta t_10 = 24.012[s]

\Delta t_17 = 25.704[s]

\Delta t_18 = 27.423[s]
Δt_19 = 29.166[s]
Δt_20 = 30.935[s]
Δt_21 = 32.728[s]
Δt_22 = 34.545[s]
\Delta t_23 = 36.385[s]
\Delta t_24 = 38.248[s]
Δt_25 = 40.133[s]
Δt_26 = 42.040[s
\Delta t_27 = 43.969[s]
\Delta t_28 = 45.919[s]
\Delta t_29 = 47.889[s]
            49.880[s
```

図 1: 実行結果1

```
At 31 = 51.891[s]
At 32 = 53.922[s]
At 33 = 55.971[s]
At 34 = 58.948[s]
At 35 = 60.127[s]
At 36 = 62.233[s]
At 37 = 64.356[s]
At 38 = 66.497[s]
At 39 = 68.656[s]
At 40 = 70.832[s]
At 41 = 73.025[s]
At 42 = 75.234[s]
At 43 = 77.460[s]
At 44 = 79.702[s]
At 44 = 79.702[s]
At 44 = 79.702[s]
At 44 = 88.827[s]
At 46 = 88.827[s]
At 47 = 86.523[s]
At 48 = 88.827[s]
At 49 = 91.147[s]
At 59 = 93.481[s]
At 59 = 93.481[s]
At 51 = 95.838[s]
At 52 = 98.194[s]
At 53 = 100.571[s]
At 55 = 105.369[s]
At 55 = 107.789[s]
At 56 = 107.789[s]
At 57 = 110.222[s]
At 58 = 112.669[s]
At 59 = 115.128[s]
At 60 = 117.601[s]
At 60 = 117.601[s]
At 61 = 120.987[s]
At 62 = 122.586[s]
At 62 = 122.580[s]
```

図 2: 実行結果 2

```
\Delta t_64 = 127.621[s]
Δt_65 = 130.158[s]
\Delta t_{66} = 132.706[s]
\Delta t_67 = 135.267[s]
\Delta t_{68} = 137.839[s]
\Delta t 69 = 140.424[s]
Δt_70 = 143.020[s]
Δt_71 = 145.628[s]
\Delta t_72 = 148.247[s]
\Delta t_73 = 150.878[s]
\Delta t_74 = 153.519[s]
Δt_75 = 156.172[s]
\Delta t_76 = 158.836[s]
\Delta t_77 = 161.511[s]
\Delta t_78 = 164.197[s]
\Delta t_{79} = 166.893[s]
Δt_80 = 169.600[s]
Δt_81 = 172.318[s]
\Delta t_{82} = 175.046[s]
Δt_83 = 177.784[s]
\Delta t_84 = 180.532[s]
Δt_85 = 183.291[s]
\Delta t_{86} = 186.059[s]
\Delta t_87 = 188.838[s]
Δt_88 = 191.626[s]
Δt_89 = 194.424[s]
\Delta t_{90} = 197.232[s]
\Delta t_{91} = 200.049[s]
\Delta t_{92} = 202.876[s]
\Delta t_{93} = 205.713[s]
```

図 3: 実行結果 3

```
Δt_94 = 208.558[s]
Δt_95 = 211.413[s]
Δt_96 = 214.277[s]
Δt_97 = 217.150[s]
Δt_98 = 220.033[s]
Δt_99 = 222.924[s]

t = 9878.036[s]
```

図 4: 実行結果 4