Mellon M. Zhang

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EDUCATION

Georgia Institute of Technology

Atlanta, GA

PhD in Machine Learning

Aug 2023 - Expected May 2028

o Advisor: Prof. Glen Chou

• Coursework: Advanced Programming Techniques, Mathematical Foundations of Machine Learning, Statistical Machine Learning, Probabilistic Graphical Models, Deep Learning, Conversational AI

University of California, Berkeley

Berkeley, CA

B.A. in Computer Science

Aug 2019 - May 2023

 Coursework: Linear Algebra & Differential Equations, Data Science, Database Systems, Algorithms, Data Structures, Robotics, Optimization, Artificial Intelligence, Computer Architecture, Discrete Mathematics, CS Theory, Operating Systems, Deep Learning, Machine Learning

Refereed Workshop Papers

M. M. Zhang and G. Chou. Polar Hierarchical Mamba: Towards Streaming LiDAR Object Detection with Point Clouds as Egocentric Sequences, Workshop on 4D Vision: Modeling the Dynamic World @ CVPR 2025

PREPRINTS

- M. M. Zhang, G. Chou, and S. Mukhopadhyay. Polar Hierarchical Mamba: Streaming LiDAR Object Detection with Point Clouds as Egocentric Sequences. Under Review at NeurIPS 2025. [arXiv]
- M. M. Zhang, H. Kumawat, and S. Mukhopadhyay. **DFDNet: Directional Feature Diffusion for Efficient Fully-Sparse LiDAR Object Detection**. *Under Review at ICCV 2025*. [Paper]

Research Experience

Georgia Institute of Technology

Atlanta, GA

Graduate Research Assistant - Advisor: Prof. Glen Chou

Aug 2023 - Current

- Visual reasoning of vision-language-action models
- Uncertainty-aware temporal LiDAR perception
- Streaming LiDAR Object Detection
 - * **Keywords:** Pytorch, Mamba, DDP, LiDAR, HPC
 - * Developed a novel streaming neural network for real-time processing of LiDAR sectors, achieving 10% improvement over existing SOTA and 2x throughput
 - * Implemented in Pytorch and trained on HPC SLURM cluster using Distributed Data Parallel (DDP)
 - * Under preparation for NeurIPS 2025, accepted to 4DV @ CVPR 2025
- Efficient Fully-Sparse LiDAR Object Detection
 - * Keywords: Pytorch, convnets, DDP, self-driving, SLURM, HPC
 - * Proposed a novel neural network for efficient point cloud object detection achieving SOTA performance with 2x reduction in computational cost (floating point operations)
 - * Designed and implemented in Pytorch, trained on HPC cluster using SLURM and Distributed Data Parallel (DDP)
 - * First-author manuscript under review at TMLR

Knight Lab Berkeley, CA

Undergraduate Research Assistant - Advisor: Prof. Robert T. Knight

 $Aug \ 2021 - Aug \ 2022$

- Explaining Large Language Models from Neuroscience Perspective
- Keywords: Prompt engineering, fine-tuning, dataset creation, explainable AI

- Designed a novel dataset from neuroscience logic puzzles and finetuned T5 model.
- Awarded UC Berkeley Rose Hills Fellowship for independent research.

Gigascale Reliable Energy-Efficient Nanosystem (GREEN) Lab

Atlanta, GA

Gatech SURE Research Intern - Advisor: Prof. Saibal Mukhopadhyay

May 2021 - Aug 2021

- o Associative Memories for Robust Image Classification
- Keywords: hopfield networks, Tensorflow, image classification, network design
- Novel multilayer perceptron model with an associative memory layer for image retrieval and denoising, outperforms convnets on MNIST dataset with 10x reduction in training samples.
- 2nd place of 50 in Georgia Tech SURE Symposium

Personal Projects

- spkan Sparse Convolutions with Kolmogorov-Arnold Networks: Custom C++/CUDA kernels with Pybind11 for fast sparse convolutions with trainable activation functions inspired by the Kolmogorov-Arnold representation theorem. First sparse Kanvolution PyPI package and features 7x speedup from previous Kanvolution implementation.
- Turtlecups Maze-solving Mobile Robot: Mobile robot designed to traverse mazes constructed from SOLO cups. End-to-end with perception (Canny edge detection), planning (RRT*), control (PID), and intercommunication (ROS).

Honors and Awards

• Berkeley Rose Hills Fellowship (One of 45 recipients selected university-wide)

2022

• Georgia Tech SURE Fellowship (One of 50 recipients selected nationally)

2021

Professional Activities

- Program Committee: CoRL ('25)
- Informal Reviewer: CVPR ('25), ICCV ('25), NeurIPS ('25)
- Project ENGAGES

2025 - 2026

- o One-on-one research mentorship with high school student from Atlanta area.
- Best presentation runner-up at Project ENGAGES summer finale.

INVITED TALKS

• Project ENGAGES Mentor Lecture Series. Securing Modern Robotics.

June 2025

PRESENTATIONS

CVPR Workshop on 4D Vision, 2025. Polar Hierarchical Mamba: Towards Streaming LiDAR Object Detection with Point Clouds as Egocentric Sequences. Poster presentation.

June 2025

Gatech SURE Symposium. Integrating Unsupervised and Supervised Techniques for Robust Image Classification. Oral presentation, Best presentation runner-up (#2/50).

July 2021

SKILLS

Programming: Python (PyTorch, Tensorflow, Scikit-learn etc.), C++, CUDA, LaTeX, Java, Javascript, C, RISC-V

Development: Linux, bash, Git, SLURM, HPC

Hobbies: Volleyball, tennis, hiking, piano