

# Mellon M. Zhang

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 Mellon (Meilong) Zhang |  meilongzhang |  Mellon M. Zhang |  meilongzhang

Atlanta, Georgia - Citizenship: US

## RESEARCH INTERESTS

My research aims to improve the reliability and trustworthiness of perception-based robotic algorithms and foundation models in safety-critical and dynamic scenarios. I am particularly interested in multimodal and spatiotemporal reasoning, vision-language-action models (VLAs), and video understanding (Vid-LLMs).

## EDUCATION

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|--|---|
| • <b>Georgia Institute of Technology</b><br><i>Ph.D. in Machine Learning, advised by Prof. Glen Chou</i> | <i>Aug 2023 - Current</i><br>Atlanta, USA   |
| • <b>University of California, Berkeley</b><br><i>B.A. in Computer Science</i>                           | <i>Aug 2019 - May 2023</i><br>Berkeley, USA |

## PAPERS

C=CONFERENCE, W=WORKSHOP, S=IN SUBMISSION, P=IN PREPARATION

- [S.2] M. M. Zhang, G. Chou, and S. Mukhopadhyay. **Polar Hierarchical Mamba: Streaming LiDAR Object Detection with Point Clouds as Egocentric Sequences**, 2025. *Under review.* [[pdf](#)]
- [W.1] M. M. Zhang and G. Chou. **Towards Streaming LiDAR Object Detection with Point Clouds as Egocentric Sequences**, 2025. *Workshop on 4D Vision: Modeling the Dynamic World @ CVPR 2025.* [[pdf](#)]
- [S.1] M. M. Zhang, H. Kumawat, and S. Mukhopadhyay. **DFDNet: Directional Feature Diffusion for Efficient Fully-Sparse LiDAR Object Detection**. 2024. *Under review.* [[pdf](#)]
- [P.1] M. M. Zhang. **spkan: Sparse Convolutions with Kolmogorov-Arnold Networks**, 2024. *In preparation.* [[github](#)]

## EXPERIENCE

- |  |   |
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| • <b>Trustworthy Robotics Lab</b><br><i>Graduate Research Assistant - Advisor: Prof. Glen Chou</i>                                     | <i>Jul 2025 - Current</i><br>Atlanta, USA   |
| ◦ Projects: 3D perception (LiDAR), Foundation model reliability (VLA, VLM, Vid-LLM)  |   |
| • <b>Gigascale Reliable Energy-Efficient Nanosystem Lab</b><br><i>Graduate Research Assistant - Advisor: Prof. Saibal Mukhopadhyay</i> | <i>Aug 2023 - Jul 2025</i><br>Atlanta, USA  |
| ◦ Projects: Efficient perception   |   |
| • <b>Knight Lab</b><br><i>Undergraduate Research Assistant - Advisor: Prof. Robert Knight</i>  | <i>Aug 2021 - May 2023</i><br>Berkeley, USA |
| ◦ Projects: LLM interpretability   |   |

## HONORS AND AWARDS

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|---|-----------------|
| • <b>Lambda Labs Research Grant</b><br><i>Compute funding for research on active uncertainty mitigation in autonomous driving.</i>                                  | <i>Jul 2025</i> |
| • <b>UC Berkeley Rose Hills Fellowship</b><br><i>Merit-based fellowship for independent summer research funding. One of 45 recipients selected university-wide.</i> | <i>May 2022</i> |
| • <b>Georgia Tech SURE Fellowship</b><br><i>Merit-based summer research internship. One of 50 recipients selected nationally.</i>                                   | <i>May 2021</i> |

## SERVICE AND TEACHING

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| • <b>Teaching:</b> Graduate Teaching Assistant, AE 2610 Intro Experimental Methods in Aerospace, Fall 2025 |           |
| • <b>Program Committee:</b> CoRL ('25)   |           |
| • <b>Project ENGAGES</b> , one-on-one research mentorship with high school student from Atlanta area.      | 2025-2026 |
| • <b>Computer Science Mentors</b> , undergraduate tutor for CS61B: Data Structures                         | 2020-2022 |

## SKILLS

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| • <b>Programming:</b> Python (PyTorch, Tensorflow, Scikit-learn etc.), C++, CUDA, LaTeX, Java, Javascript, C, RISC-V |  |
| • <b>Development:</b> Linux, bash, Git, SLURM, HPC   |  |