Lecture 2 - Functions and Relations

Functions

A function f from a set A to a set B is an assignment of exactly one element of B to each element of A.

We write:

$$f(a) = b$$

if b is the unique element of B assigned by the function f.

Domain and codomain

If f:A o B we say that A is the domain of f and B is the codomain of f.

Image and preimage

If f(a) = b we say that b is the image of a and that a is the preimage of b.

Range

The range of f is the set of all images of elements of A (the domain).

If we have a subset S of the domain A, we say that the image of S is the set of all images of elements in S. We denote it like this:

$$f(S) = \{f(s)|s \in S\}$$

Properties of a function

Injective (into, one-to-one)

A function f is one-to-one if and only if:

$$\forall x,y \in A \text{ such that if } x=y \text{ then } f(x)=f(y)$$

Surjective (onto)

A function f is onto if and only if for every element $b \in B$ there is an element $a \in A$ such that f(a) = b.

Bijective

A function if bijective if and only if it is injective and surjective.

Graphs

A graph of a function f is the set of ordered pairs:

$$\{(a,b)|a\in A,b\in B\}$$

Relation

A relation R is a subset of:

$$R \subset A \times B$$

Where $A \times B$ is a cartesian product of two sets A and B.

When (a,b) belongs to R, a is said to be related to b.

A graph of a function f is also a subset of $A\times B$, and therefore it is a relation. Graphs of functions are relations where $a\in A$ is the first element of the ordered pair only once.

A relation on a set A is a relation from A to A, or in other words it is a subset of $A\times A$. When n=|A| the set $A\times A$ has exactly n^2 elements, and therefore there are 2^{n^2} distinct relations on A

Reflexive Relations

A relation is said to be reflexive if $(a,a) \in R$ for every element in A.

If n=|A| then the number of different reflexive relations that can be defined on A is equal to $2^{n(n-1)}$

Symmetric Relations

A relation is said to be symmetric if $(b,a)\in R$ whenever $(a,b)\in R$.

Antisymmetric Relations

A relation is said to be antisymmetric if a=b whenever $(a,b)\in R$ and $(b,a)\in R$.

Asymmetric Relations

A relation is said to be asymmetric if $(a,b) \in R$ implies that $(b,a) \notin R$.

Transitive Relations

A relation is said to be transitive if whenever $(a,b) \in R$ and $(b,c) \in R$, then $(a,c) \in R$.

Composite of relations

Let R be a relation from a set A to a set B and S a relation from B to a set C. The composite of R and S is the relation consisting of ordered pairs (a,c), where $a\in A$, $c\in C$, and for which there exists an element $b\in B$ such that $(a,b)\in R$ and $(b,c)\in R$. We denote the composite of R and S by $S\circ R$.

Matrices and relations

If R is a relation from $A=\{a_1,a_2,a_3,\ldots,a_m\}$ to $B=\{b_1,b_2,\ldots,b_n\}$, then R can be represented by the zero-one matrix $M_R=[m_{ij}]$ with:

$$m_{ij}=1 ext{ if } (a_i,b_j) \in R$$

$$m_{ij}=0 ext{ if } (a_i,b_j)
otin R$$

Example

$$R = \{(2,1), (3,1), (3,2)\}$$

$$M_R = \begin{bmatrix} 0 & 0 \\ 1 & 0 \\ 1 & 1 \end{bmatrix}$$

All matrices representing a relation on some set A are square.

All matrices representing a reflexive relation have 1's along the main diagonal.

All matrices representing a symmetric relation are symmetric along the main diagonal.

$$M_R = \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 \\ 1 & 0 & 1 & 1 \end{bmatrix}$$

Directed graphs and relations

Relations can also be represented using a directed graph (graph as in graph theory) or digraphs. An ordered pair $(a,b)\in R$ represents an edge from a vertex

a to a vertex b, where a is called the initial vertex and b is called the terminal vertex.

Equivalence relation

A relation is called an equivalence relation if it is reflexive, symmetric and transitive. Two elements related by an equivalence relation are called equivalent.