EXPERIMENT 8

AIM: Implement 8086 based Assembly programs.

THEORY:

Intel 8086 is built on a single semiconductor chip and packaged in a 40-pin IC package. The type of package is DIP (Dual Inline Package). Intel 8086 uses 20 address lines and 16 data- lines. It can directly address up to 220 = 1 Mbyte of memory. 8086 is designed to operate in two modes, i.e., Minimum and Maximum mode.

Main registers								
	АН	AL		AX (primary accumulator)				
	ВН	BL		BX (base, accumulator)				
	СН	CL		CX (counter, accumulator)				
	DH	DL		DX (accumulator, extended acc				
Index registers	}							
0000	5	SI		Source Index				
0000	[DI .		Destination Index				
0000	В	P		Base Pointer				
0000	S	P		Stack Pointer				
Program count	ter							
0000	1	Р		Instruction Pointer				
Segment regist	ters							
	CS	0	000	Code Segment				
	DS	0	000	Data Segment				
	ES	0	000	Extra Segment				
	SS	0	000	Stack Segment				
Status register								
	O D I T	S Z - A - I	P - C	Flags				

It consists of a powerful instruction set, which provides operation like division and multiplication very quickly.

8086 microprocessor supports 8 types of instructions:

- Data Transfer Instructions
- Arithmetic Instructions
- Bit Manipulation Instructions
- String Instructions
- Program Execution Transfer Instructions (Branch & Loop Instructions)
- Processor Control Instructions
- Iteration Control Instructions
- Interrupt Instructions

CODE:

1) Program to add two word length numbers

OPR1: DW 0x6969 ; declare first number
OPR2: DW 0x0420 ; declare second number
RESULT: DW 0 ; declare place to store result

; actual entry point of the program

start:

MOV AX, word OPR1; move first number to AX MOV BX, word OPR2; move second number to BX

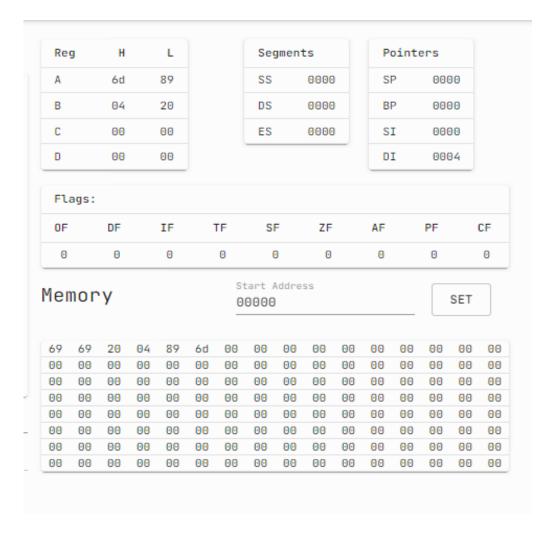
CLC ; clear the carry flag ADD AX, BX ; add BX to AX

MOV DI, OFFSET RESULT ; move offset of result to DI

MOV word [DI], AX; store result

print reg ; print result

OUTPUT:



2) A Program to move data from one segment to another

SET 0 ; set address for segment 1

src:DB 0x3; store data

DB 0x5 DB 0x7

SET 0x1 ; set addresss for segment 2

dest:DB [0,3]; store data

; actual entry point of the program

start:

print mem 0:8 ; print initial state of segment 1 ; print initial state of segment 2

MOV AX, 0 ; move address of seg1

MOV DS,AX; to ds

MOV AX, 0x1; move address of seg2

MOV ES,AX ; to es

MOV SI, OFFSET src ; move offset of source data MOV SI, OFFSET dest ; move offset of destination data

MOV CX, 0x3; move number of data items

print reg ; print state of registers

_loop:

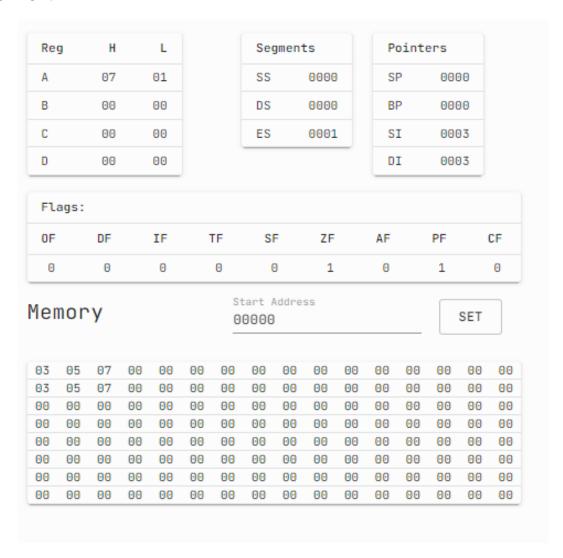
mov AH, byte DS[SI] ; move one byte from source to ah

mov byte ES[DI],AH ; move ah to destination

inc SI inc DI

dec CX ; decrement count

jnz_loop ; if count is not zero jump back print mem 0:8 ; print final state of segment 1 print mem 0x10:8 ; print final state of segment 2



3) Program to calculate factorial using looping

NUM: DW 0x6 ; calculate factorial of 6 RESULT: DW 0 ; place to store the reult

; actual entry point of the program

start:

MOV CX,word NUM ; move number into cx
MOV AX, 0x1 ; initialize accumulator with 1
NOTZEROLOOP: ; label to jump back to
MUL CX ; multiple by the number

DEC CX ; decrement the number

JNZ NOTZEROLOOP ; if not zero jump back MOV word RESULT,AX ; store the result in memory

print reg ; print registers

ointers	101		Segmen		L		Н	я	Reg
0000	SP	0000	SS	02 d0			Α		
0000	BP	0000	DS		00		00		В
0000	SI	0000	ES		00		00		С
0000	DI				00		00		D
								ags:	Fla
PF	AF	ZF	SF	TF	IF		DF		0F
1	0	1	0	0	0		0		0
SET		SS	tart Addre				У	nor	1en
SE1	00 0	es			00	θ2	y	nor	
			0000	0		02 00			1en
00 00 00	00 0	00 00	00 00	0 00	00		d0	00	06
00 00 00	00 0	00 00	00 00	0 00	00 00	00	d0 00	00	06 00
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4) Program to show use of interrupts

hello: DB "Hello World"; store string

; actual entry point of the program, must be present

start:

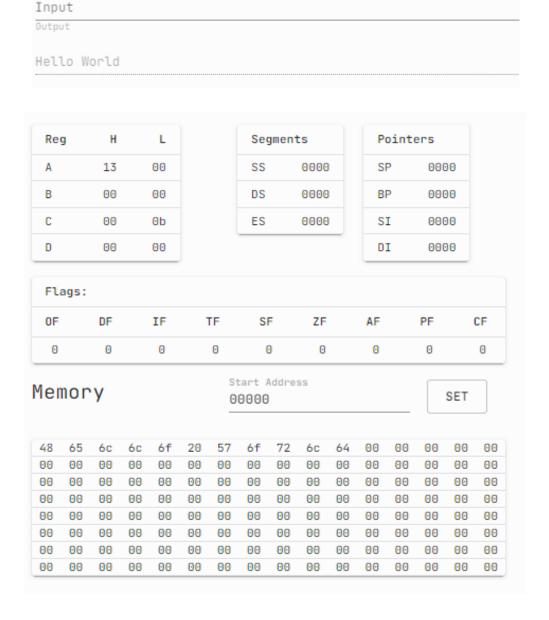
MOV AH, 0x13; move BIOS interrupt number in AH

MOV CX, 11; move length of string in cx

MOV BX, 0; mov 0 to bx, so we can move it to es MOV ES, BX; move segment start of string to es, 0 MOV BP, OFFSET hello; move start offset of string in bp

MOV DL, 0; start writing from col 0

int 0x10 ; BIOS interrupt



5) Program to show use of interrupts

hello: DB "Hello World" ; store string

; actual entry point of the program

start:

MOV AH, 0x13; move BIOS interrupt number in AH

MOV CX, 12; move length of string in cx

MOV BX, 0; mov 0 to bx, so we can move it to es
MOV ES, BX; move segment start of string to es, 0
MOV BP, OFFSET hello; move start offset of string in bp

MOV DL, 0; start writing from col 0

int 0x10 ; BIOS interrupt

Reg	ı	Н		L			Seg	gment	ts		Po	oint	ers		
Α		13		00			SS 000		0000	SP		•	0000		
В		00		00					0000		BP				
C 00 0		0c			ES		0000		SI		0000				
D 00				00							D	I	000	00	
Fla	ıgs:														
0F		DF		IF		TF	SF		ZF		AF		PF		CF
0		0		0		0	(9	0		0		0		0
lemory							0000		ss					SET	
48	65	6c	6c	6f	20	57	6f	72	6c	64	00	00	00	00	00
00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00
00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00
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	00				00	00	00	00	00	00	00	00	00	00	00
00	00 00	00	00	00	00	00	00								

6) Program to calculate LCM and GCD of two numbers

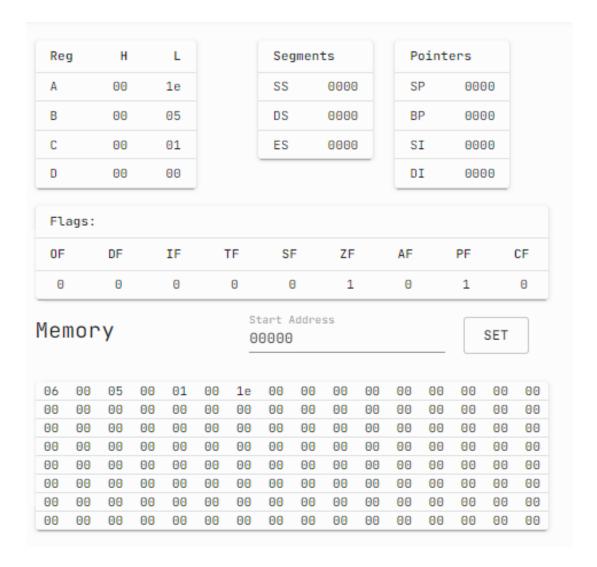
mov word lcm, ax ; store lcm

; print memory

print mem:16

no1: dw 0x6 ; number 1 no2: dw 0x5 ; number 2 gcd: dw 0 ; place to store gcd lcm: dw 0 ; place to store lcm ; actual entry point of the program start: mov ax, word no1; move number 1 in accumulatore mov bx, word no2 ; move number 2 in register BX loop0: mov dx, 0x0; place to loop back ; cannot use 'loop' as label, as loop is an opcode which will give error when used with jumps div bx ; divide accumulator by bx mov ax, bx mov bx, dx cmp bx, 0x0 ; check if bx is 0 jnz loop0 ; if not loop back mov word gcd, ax ; store gcd ; move ax in cx mov cx, ax mov ax, word no1 ; move number 1 in accumulatore mov bx, word no2 ; move number 2 in register BX mul bx ; multiply accumulator by BX div cx ; divide accumulator by CX

OUTPUT:



CONCLUSION: In this experiment, I implemented 8086 microprocessor's assembly language based programs. The codes were run on an online 8086 emulator. The programs were to add two word length numbers, to calculate LCM and GCD of two numbers, to transfer the data, to calculate the factorial using loop in 8086 assembly instruction set and programs to implement interrupts.