# **CECS 229 Programming Assignment #3**

#### Due Date:

Sunday, 10/22 @ 11:59 PM

#### **Submission Instructions:**

Complete the programming problems in the file named pa4.py . You may test your implementation on your Repl.it workspace by running main.py . When you are satisfied with your implementation,

- 1. Submit your Repl.it workspace
- 2. Download the file pa4.py and submit it to the appropriate CodePost auto-grader folder.

# **Objectives:**

- 1. Apply vector operations to translate, scale, and rotate a set of points representing an image.
- 2. Perform various operations with or on vectors: addition, subtraction, dot product, norm.

#### **NOTES:**

- 1. Unless otherwise stated in the FIXME comment, you may not change the outline of the algorithm provided by introducing new loops or conditionals, or by calling any built-in functions that perform the entire algorithm or replaces a part of the algorithm.
- 2. You may import and use the Python 'math' module to obtain the value for e and to calculate sine, cosine, and tangent functions, if needed.

#### Problem 1:

Create a function translate(S, z0) that translates the points in the input set S by  $z_0=a_0+b_0i$ . The function should satisfy the following:

- 1. INPUT:
  - S set S
  - z0 complex number
- 2. OUT:
  - T set T consisting of points in S translated by  $z_0$

```
In [ ]: def translate(S, z0):
    """
    translates the complex numbers of set S by z0
    INPUT:
        * S - set of complex numbers
```

```
* z0 - complex number

OUT:

* a set consisting of points in S translated by z0

"""

# FIXME: Implement this function

# FIXME: Return correct output

return None
```

## Problem 2:

Create a function scale(S, k) that scales the points in the input set S by a factor of k:

- 1. INPUT:
  - S set S
  - k positive float, raises ValueError if  $k \le 0$ .
- 2. OUTPUT:
  - a set consisting of points in S scaled by k.

```
In [ ]: def scale(S, k):
    """
    scales the complex numbers of set S by k.
    INPUT:
        * S - set of complex numbers
        * k - positive float, raises ValueError if k <= 0
OUT:
        * T - set consisting of points in S scaled by k

"""
    # FIXME: Implement this function.
    # FIXME: Return correct output
    return None</pre>
```

#### Problem 3:

Create a function rotate(S, tau) that rotates the points in the input set S by  $\tau$  radians:

- 1. INPUT:
  - S set S
  - tau float. If negative, the rotation is clockwise. If positive the rotation is counterclockwise. If zero, no rotation.
- 2. OUT:
  - a set consisting of points in S rotated by au

```
OUT:
    * a set consisting of points in S rotated by tau radians

"""

# FIXME: Implement this function.

# FIXME: Return correct output
return None
```

## Problem 4:

Finish the implementation of class Vec which instantiates row-vector objects with defined operations of addition, subtraction, scalar multiplication, and dot product. In addition, Vec class overloads the Python built-in function abs() so that when it is called on a Vec object, it returns the Euclidean norm of the vector.

```
class Vec:
In [ ]:
            def __init__(self, contents = []):
                Constructor defaults to empty vector
                INPUT: list of elements to initialize a vector object, defaults to empty list
                self.elements = contents
                return
            def __abs__(self):
                Overloads the built-in function abs(v)
                returns the Euclidean norm of vector v
                # FIXME: Implement this method
                # FIXME: Return correct output
                return None
            def __add__(self, other):
                overloads the + operator to support Vec + Vec
                RAISES ValueError if vectors are not same length
                RETURNS a Vec object that is the sum vector of this Vec and 'other' Vec
                # FIXME: Finish the implementation
                # FIXME: Return correct output
                return None
            def __sub__(self, other):
                overloads the - operator to support Vec - Vec
                RAISES ValueError if vectors are not same length
                RETURNS a Vec object that is the difference vector of this Vec and 'other' Vec
                # FIXME: Finish the implementation
                # FIXME: Return correct output
                return None
            def mul (self, other):
```

```
Overloads the * operator to support
       - Vec * Vec (dot product) raises ValueError if vectors are not
         same length in the case of dot product; returns scalar
       - Vec * float (component-wise product); returns Vec object
       - Vec * int (component-wise product); returns Vec object
    0.00
   if type(other) == Vec: #define dot product
       # FIXME: Complete the implementation
       # FIXME: Return the correct output
       return None
   elif type(other) == float or type(other) == int: #scalar-vector multiplication
       # FIXME: Complete the implementation
       # FIXME: Return the correct output
       return None
def rmul (self, other):
   """Overloads the * operation to support
       - float * Vec; returns Vec object
       - int * Vec; returns Vec object
   # FIXME: Complete the implementation
   # FIXME: Return the correct output
   return None
return str(self.elements) # does NOT need further implementation
```