

Q1)

a) $v = \alpha/x$ we want $F(x)$

we know $\frac{dv}{dt} = \alpha$ but we want $\frac{dv}{dx} = \alpha$
as a function of x

so we can use the chain rule

$$\therefore \alpha = \frac{dv}{dt} = \frac{dv}{dx} \cdot \frac{dx}{dt} = v \frac{dv}{dx}$$

$$\text{now: } \frac{dv}{dx} = \frac{\alpha}{x^2} = -\frac{\alpha}{x^2}$$

$$\therefore v \frac{dv}{dx} = \frac{\alpha}{x} \cdot \left(-\frac{\alpha}{x^2}\right) \text{ where } F(x) = \frac{-\alpha x^2}{x^3}$$

b) $F = -kx + kx^3/2^2$

where $F = \frac{-2V}{2x}$

$$\therefore -kx + kx^3/2^2 = \frac{-2V}{2x}, \text{ take the negative sign out}$$

$$kx - kx^3/2^2 = \frac{2V}{2x} \Rightarrow S kx dx - S kx^3/2^2 dx = 2V$$

$$\Rightarrow S kSx dx - \frac{k}{2^2} Sx^3 2x = 2V$$

$$\frac{kx^2}{2} + C_1 - \frac{kx^4}{4^2} + C_2 = V$$

$$\frac{kx^2}{2} - \frac{kx^4}{4^2} + C = U(x) \text{ where } C = \text{constant}$$

$$\text{so, } U(x) = \frac{kx^2}{2} - \frac{kx^4}{4^2}$$

D E

$$\frac{dU}{dx} =$$

equ.

R2

2) a)

→ 1/2

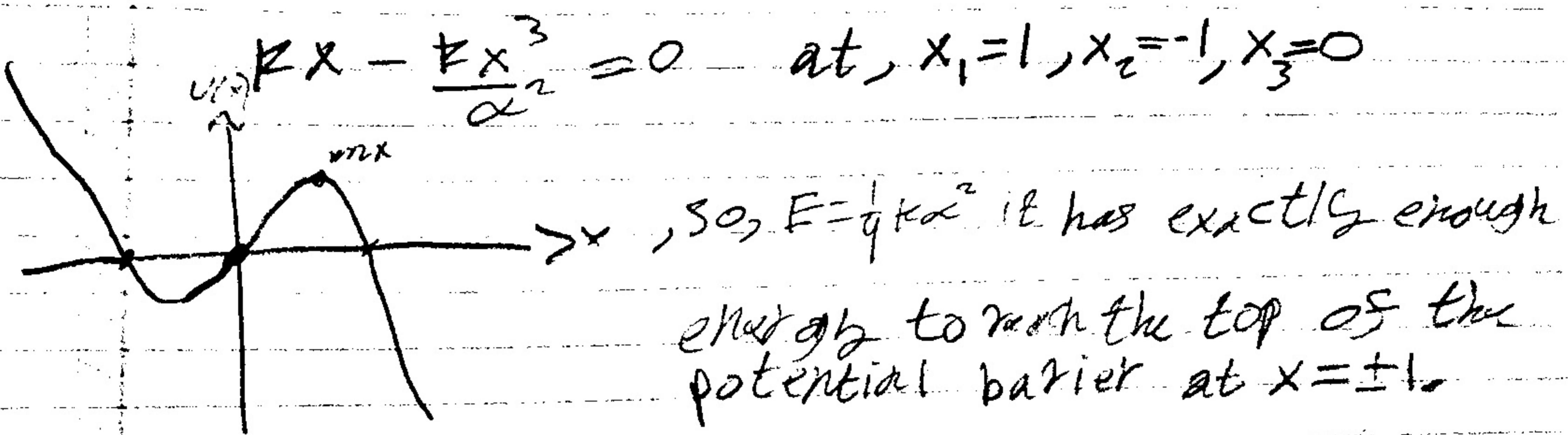
1/2

S

$$D) E = (\gamma q) k \alpha^2, V(x) = \frac{kx^2}{2} - \frac{kx^4}{4\alpha^2}$$

$\frac{dV}{dx} = kx - \frac{kx^3}{\alpha^2}$ solving the cubic equation we find

$$kx - \frac{kx^3}{\alpha^2} = 0 \text{ at } x_1=1, x_2=-1, x_3=0$$



so, $E = qk\alpha^2$ it has exactly enough energy to reach the top of the potential barrier at $x=\pm 1$.

2)
a) $k(x) + U(x) = E_{tot}$

$$\rightarrow \frac{1}{2}mv^2 + \frac{1}{2}kx^2 = \frac{1}{2}kA^2$$

$$\cancel{\frac{1}{2}mv^2} = \cancel{\frac{1}{2}kA^2} - \cancel{\frac{1}{2}kx^2} \Rightarrow \cancel{\frac{1}{2}mv^2} = k(A^2 - x^2)$$

$$\Rightarrow V(x) = \sqrt{\frac{k(A^2 - x^2)}{m}} \text{ where } \frac{k}{m} = w$$

$$\text{so } V(x) = \pm w\sqrt{A^2 - x^2}$$

b) We know $V(x) = \sqrt{\frac{k(A^2 - x^2)}{m}}$

where $v(x) = \frac{dx}{dt}$, so $\frac{dx}{dt} = \sqrt{\frac{k(A^2 - x^2)}{m}}$

$$dx = \sqrt{\frac{k(A^2 - x^2)}{m}} dt \Rightarrow \frac{dx}{\sqrt{\frac{k(A^2 - x^2)}{m}}} = dt$$

so, $\int_0^x \frac{dx}{\sqrt{\frac{k(A^2 - x^2)}{m}}} = \int_0^t dt$ we know $x=0$

$$\Rightarrow \int_0^x \frac{dx}{\sqrt{\frac{k(A^2 - x^2)}{m}}} = \int_0^t dt$$

$$\Rightarrow \sqrt{\frac{m}{k}} \int_0^x \frac{dx}{\sqrt{A^2 - x^2}} = t \text{ using wolfram alpha}$$

we get:

$$t = \sqrt{\frac{m}{k}} \sin^{-1}\left(\frac{x}{A}\right)$$

or we can solve it by hand

let $x=0$ when, $\theta=0$

$$x' = x \text{ when } \theta = \sin^{-1}\left(\frac{x}{A}\right)$$

let $x' = A \sin \theta$, $dx' = A \cos \theta d\theta$ where x' is some variable

our integral becomes $t = \sqrt{\frac{m}{k}} \int_0^{\sin^{-1}\left(\frac{x}{A}\right)} \frac{A \cos \theta}{\sqrt{A^2 - A^2 \sin^2 \theta}} d\theta$

Solving it, $t = \sqrt{\frac{m}{k}} \int_0^{\sin^{-1}\left(\frac{x}{A}\right)} \frac{A \cos \theta}{\sqrt{A^2 - A^2 \sin^2 \theta}} d\theta = \sqrt{\frac{m}{k}} \int_0^{\sin^{-1}\left(\frac{x}{A}\right)} \frac{1}{\sqrt{1 - \sin^2 \theta}} d\theta$

so, $t = \sqrt{\frac{m}{k}} \sin^{-1}\left(\frac{x}{A}\right)$, so $x(t) = A \sin\left(\sqrt{\frac{k}{m}} t\right)$

from T

$$\sqrt{\frac{m}{k}} T = 2\pi$$

$$\sqrt{\frac{m}{k}} \cdot 2\pi$$

3)

a)

$$OB = 0$$

$$BC = h$$

now AB

CA =

ΔCAE ,

so H

$H(\theta) =$

b) U:

So T note the sine function goes from $0 \rightarrow 2\pi$ for a full cycle

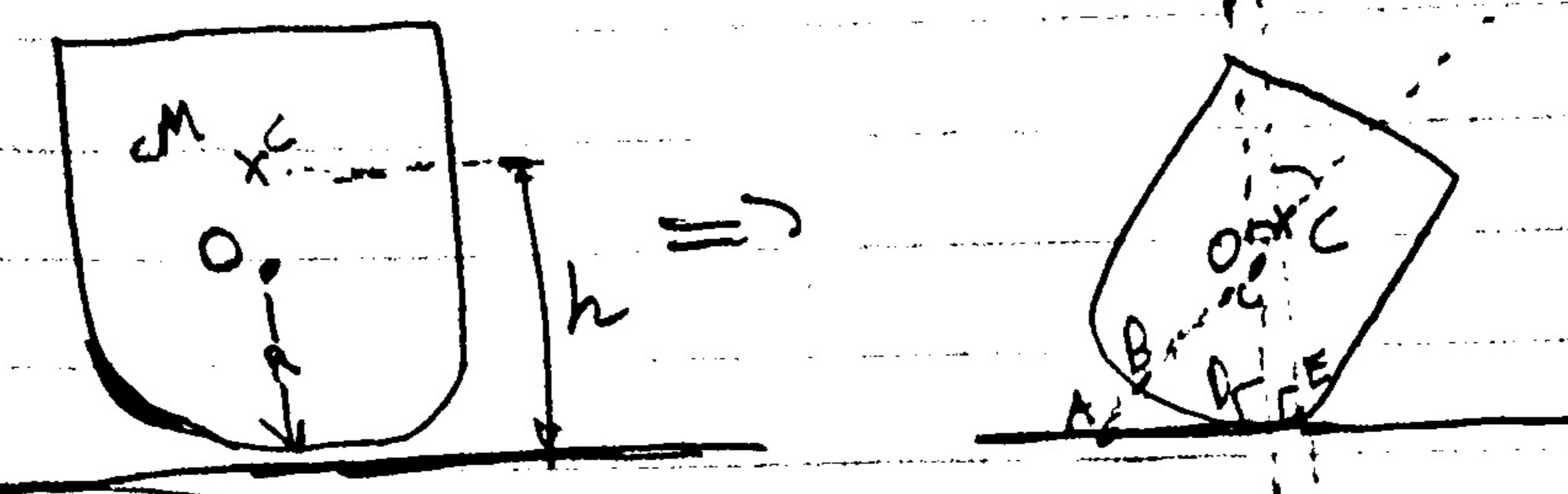
$$\sqrt{\frac{F_k}{m}} T = 2\pi$$

$$\sqrt{\frac{m}{F_k}} \cdot 2\pi = T$$

3)

a)

main sig



$$OB = OD = R \quad \text{from } \triangle OAD; \quad OA \cos \theta = OD = R$$

$$BC = h$$

$$OA = \frac{R}{\cos \theta}$$

$$\text{now } AB = OA - OB = \frac{R}{\cos \theta} - R = R \left(\frac{1}{\cos \theta} - 1 \right)$$

$$CA = AB + BC = R \left(\frac{1}{\cos \theta} - 1 \right) + h$$

$$\Delta CAE, CA \cos \theta = CE \Rightarrow CE = \left(R \left(\frac{1}{\cos \theta} - 1 \right) + h \right) \cos \theta$$

so $H(\theta)$ the height is: $CE = H(\theta) = h \cos \theta + R(1 - \cos \theta)$

$$H(\theta) = h \cos \theta + R(1 - \cos \theta), \text{ so } U = mg H(\theta) - D$$

$$b) U = mg [h \cos \theta + R(1 - \cos \theta)]$$

b) continued, simplifying $V(\theta)$

we get $mg[R+h-R]\cos\theta$)

at $\theta=0$ $V(0)=mgh$

at $\theta=\pi$ $V(\pi)=mg(2R-h)$

so it oscillate between the two above

c) $\frac{dV}{d\theta} = mg[-h\sin\theta + R\sin\theta]$

at $\theta=0$ $V'(0)=0$ so it stable at 0

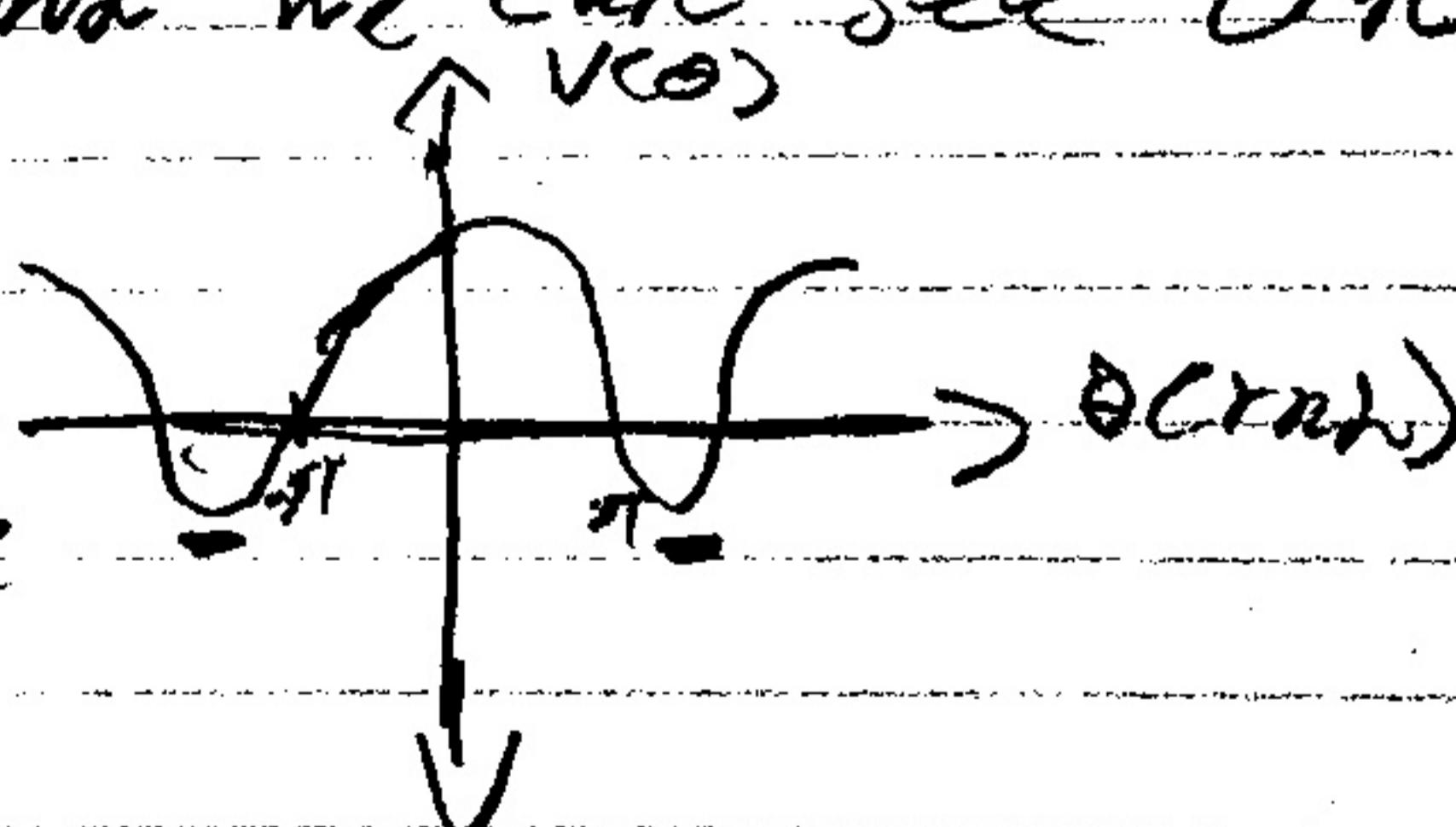
$\frac{d^2V}{d\theta^2} = mg\cos\theta[-h+R]$, at $\theta=0$

$mg[-h+R]$, now for stable equilibrium $\theta=0$

$\frac{d^2V}{d\theta^2} > 0$ which true if $R > h$

now it make sense, and we can see that from graph $V(\theta)$

so it actually oscillate, and it stable when it's concave up



4)

$$\frac{dx}{dt} = \frac{2}{2}$$

$$\Rightarrow |v| = *$$

$$= \frac{ds}{dt}$$

thus

$$c) F_{||} =$$

$$a_{||} =$$

so,

$$d) F_{||} =$$

thus

a) and b)

1)

$$\Rightarrow |V| = \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2}$$

$$\frac{dx}{dt} = \frac{2x}{2S} \frac{2S}{2t}, \frac{dy}{dt} = \frac{2y}{2t} \frac{2S}{2t}$$

$$\Rightarrow |V| = \sqrt{\left(\frac{2x}{2t} \frac{2S}{2t}\right)^2 + \left(\frac{2y}{2t} \frac{2S}{2t}\right)^2}$$

$$= \frac{2S}{2t} \sqrt{\left(\frac{dx}{2S}\right)^2 + \left(\frac{dy}{2S}\right)^2}, \text{ so, } 2S = \sqrt{\left(\frac{dx}{2S}\right)^2 + \left(\frac{dy}{2S}\right)^2}$$

$$\text{thus } V = \frac{2S}{2t}$$

$$\hookrightarrow F_{11} = m \frac{d^2 S}{2t^2}$$

$$a_{11} = \frac{dV}{dt} = \frac{2S}{2t^2}, F_{11} = ma_{11}$$

$$\text{so, } F_{11} = m \frac{d^2 S}{2t^2}$$

$$\hookrightarrow F_{11} = m \frac{d^2 S}{2t^2} = -\frac{2U}{2S}$$

$$\text{thus, } F_{11} = -\frac{2U}{2S}$$

two above

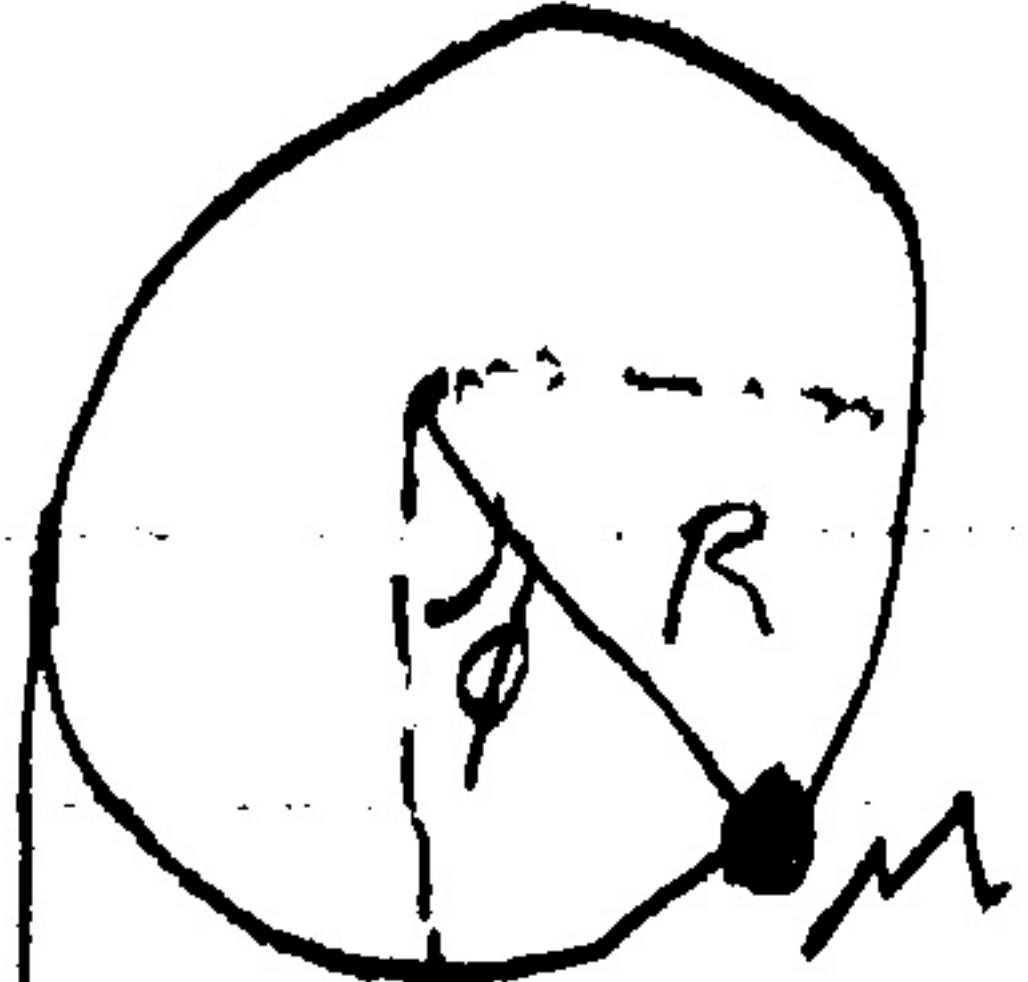
at 0

when $\theta = 0$

that

(crash)

5)



a)

$$V_m = mgR$$

$$V_M = mgR(1 - \cos\phi) = mg[R(1 - \cos\phi)]$$

$$U_m = -mgR\sin\phi = -mgR\phi$$

$$U(\phi)_{\text{tot}} = V_M + U_m = mg[R(1 - \cos\phi)] - mgR\phi$$

$$\frac{dU}{d\phi} = mgR\sin\phi - mgR = 0$$

$$= m\sin\phi = m \quad \text{where } \frac{m}{m} \text{ is } -1 \leq \frac{m}{m} \leq 1$$

if $\frac{m}{m}$ holds between -1 and 1 then there exist a critical point

thus it's = 0 at $(\pi/2 + 2\pi n)$ where n is any integer

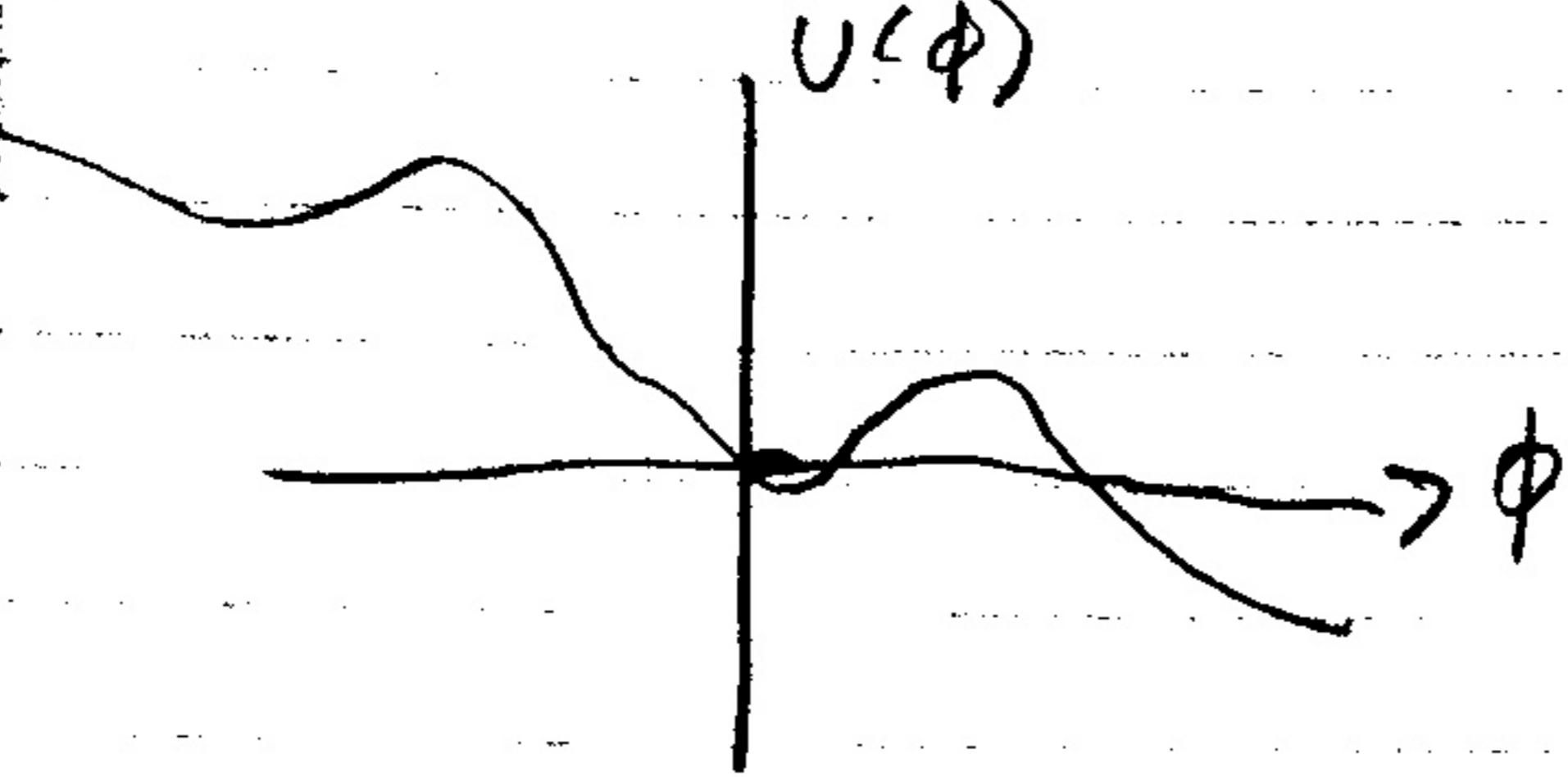
$$\frac{d^2U}{d\phi^2} = mgR\cos\phi, \text{ it's stable}$$

when $\frac{d^2U}{d\phi^2} > 0$ and unstable

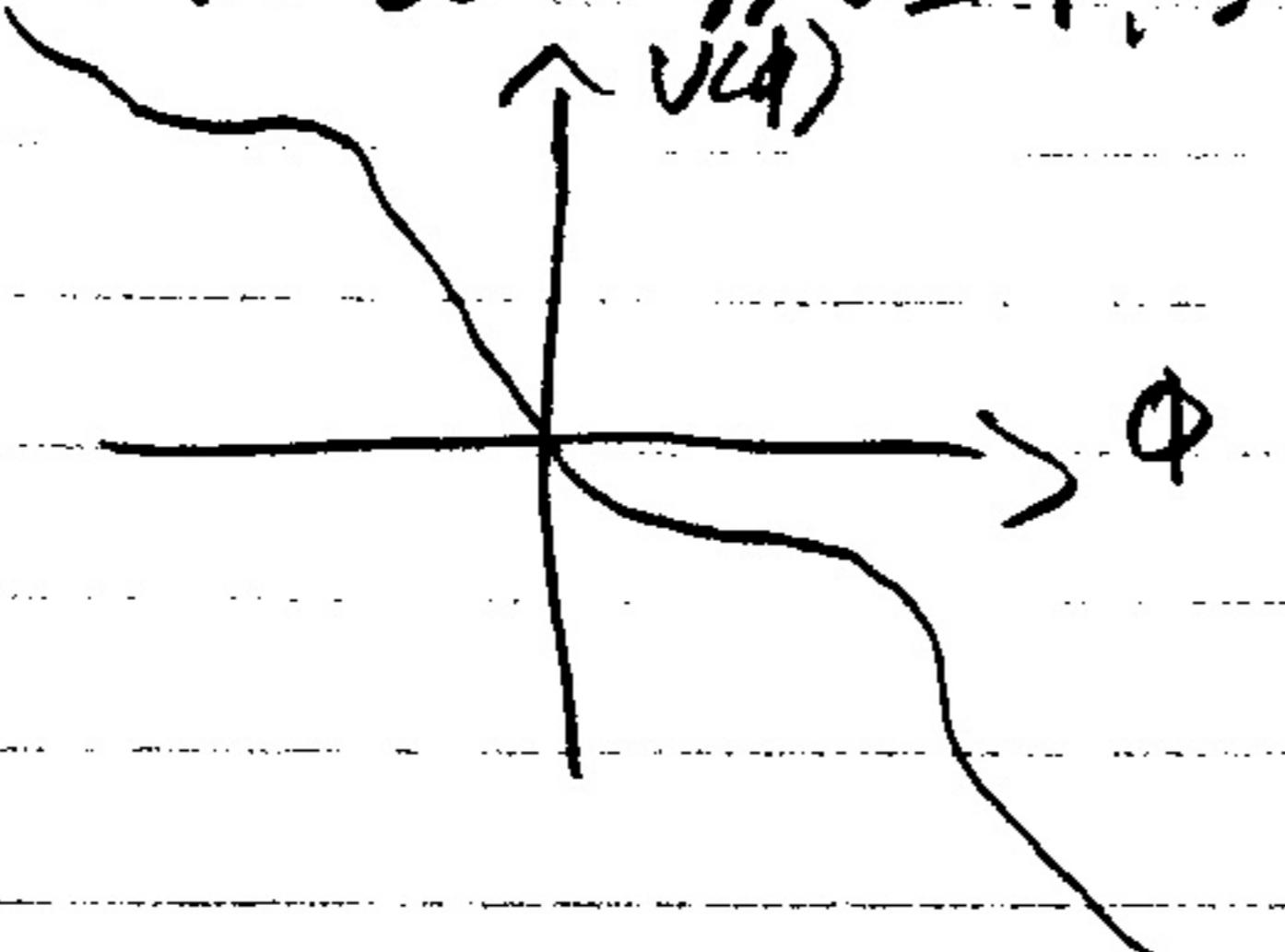
$$\frac{d^2U}{d\phi^2} < 0$$

this make sense since if $\frac{d^2U}{d\phi^2} > 0$
it make a concave up (↑) and the opposite is $\frac{d^2U}{d\phi^2} < 0$ (↓)

d) case 1 $m/M = 0.5$



case 2 $m/M = 1.5$



- Increasing m/M changes the potential, removing stable points and leading to more motion.

(*) 2) $U(\phi) = 0$ to oscillate (it must be stable equilibrium)

the system will exhibit ~~ex~~ oscillation if $\frac{m}{M} < 1$ this value serves as a fixed point this can be reached by

$$\text{solving } \sin\phi = \frac{m}{M}$$