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Flexible Automation of Quantified Multi-Modal Logics with Interactions

Melanie Taprogge and Alexander Steen

Special thanks to:



FACHBEREICH
KÜNSTLICHE INTELLIGENZ

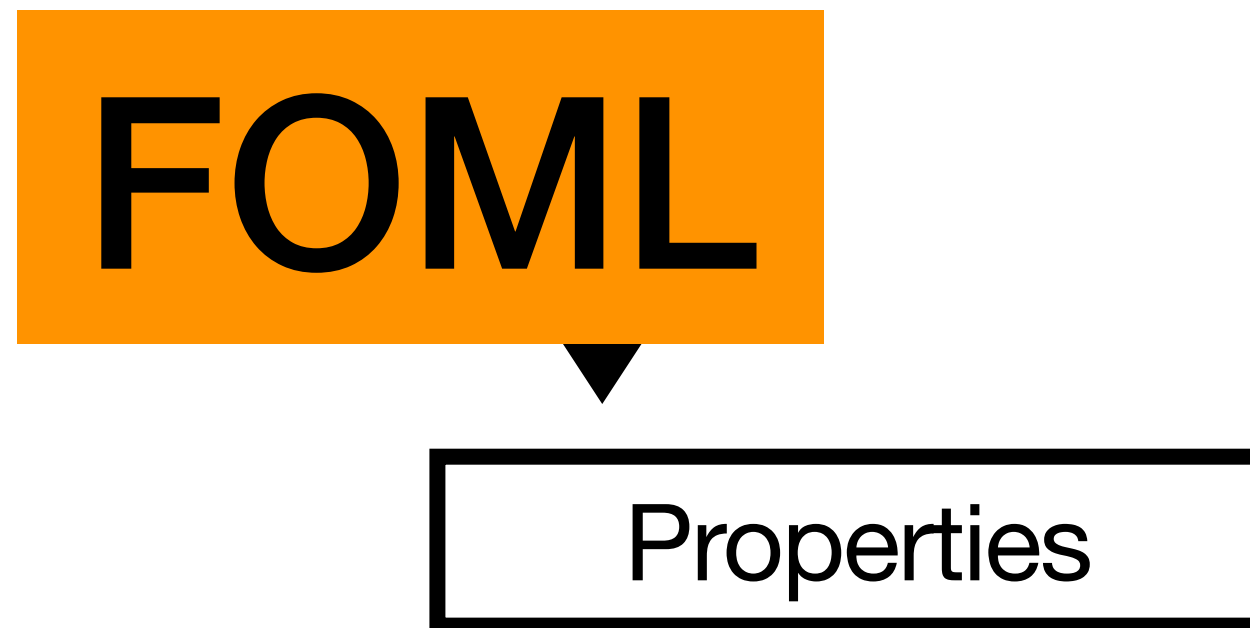
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Agenda

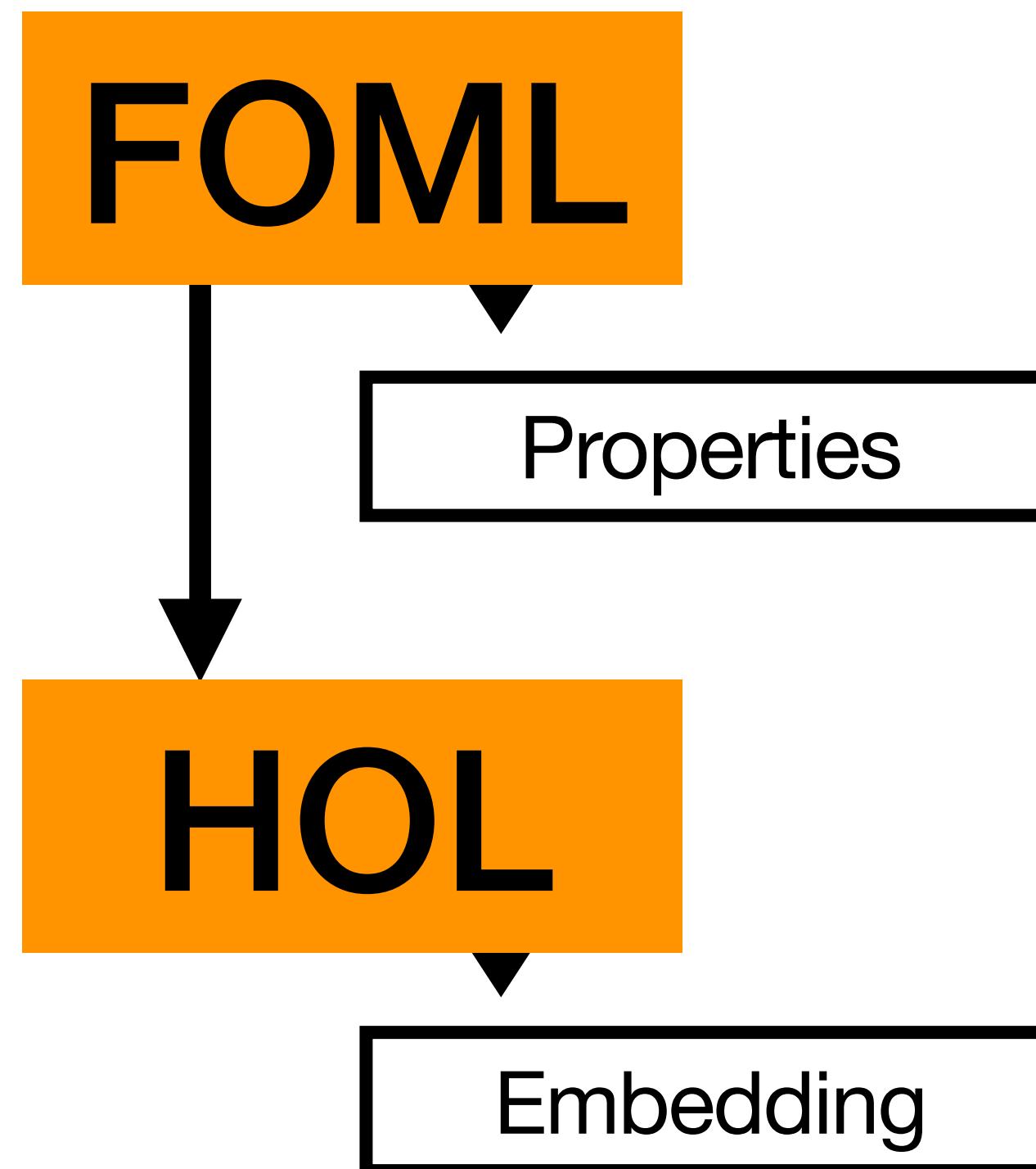
- First-Order Multi-Modal Logics
 - Introduction
 - Characterisation



ATP Systems

Agenda

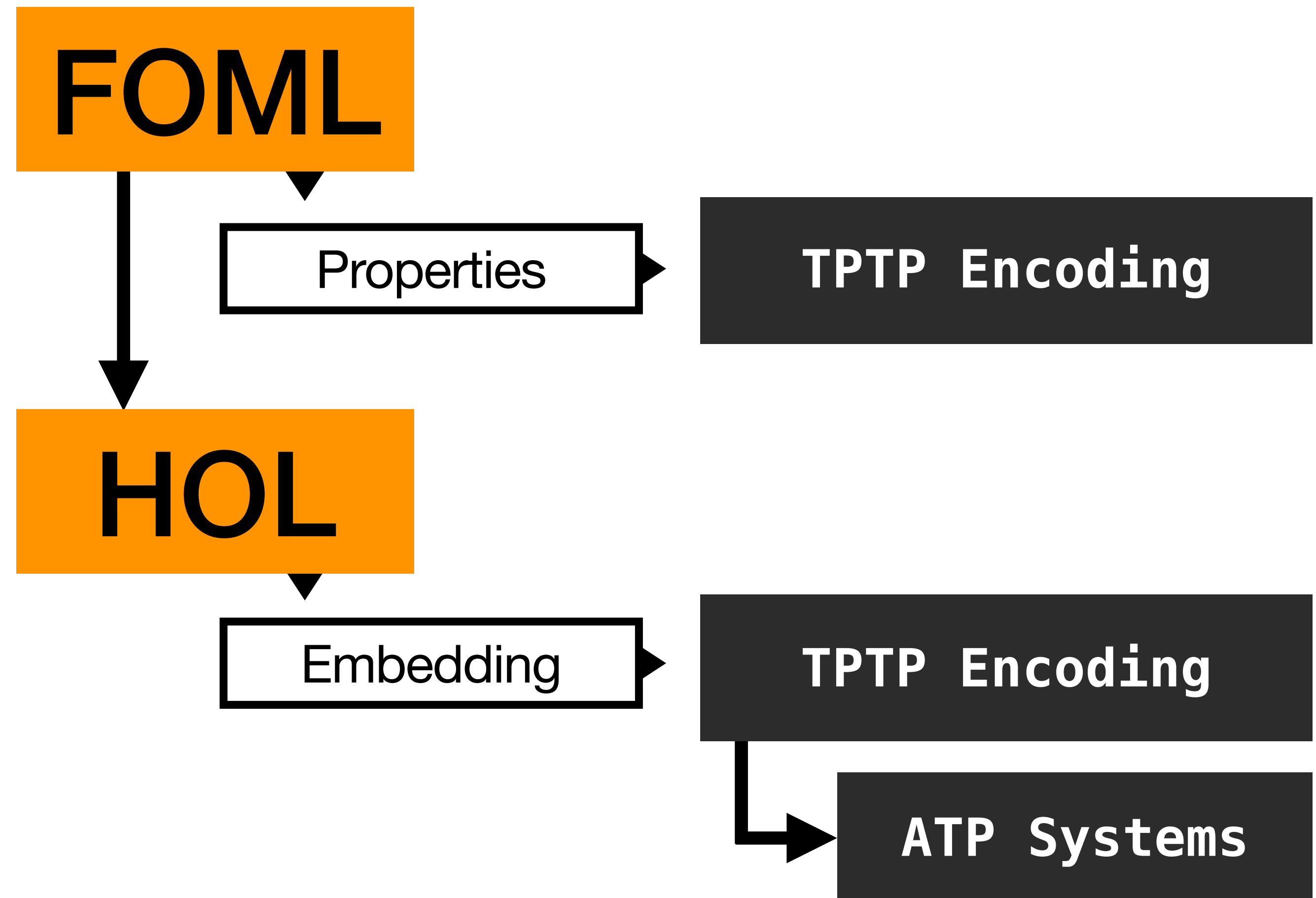
- First-Order Multi-Modal Logics
 - Introduction
 - Characterisation
- Higher-Order Logic
 - Introduction
 - Embedding of FOML



ATP Systems

Agenda

- First-Order Multi-Modal Logics
 - Introduction
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- Higher-Order Logic
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 - Embedding of FOML
- Automation via TPTP Encoding
 - Encoding of HOL and FOML
 - Encoding of FOML Characterisation
- Summary



First-Order Multi-Modal Logics (FOML)

Multi-Modal Logic [5]

Syntax:

Propositions
Bottom

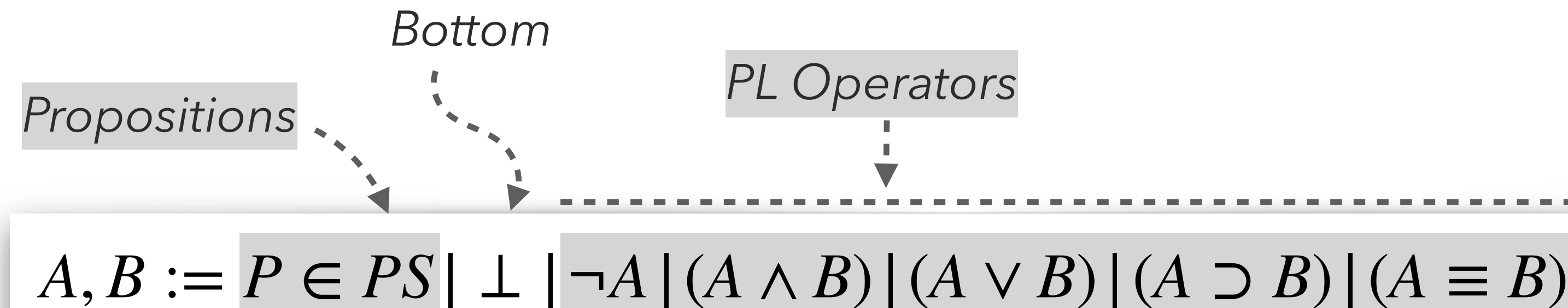


$A, B := P \in PS \mid \perp$

First-Order Multi-Modal Logics (FOML)

Multi-Modal Logic [5]

Syntax:



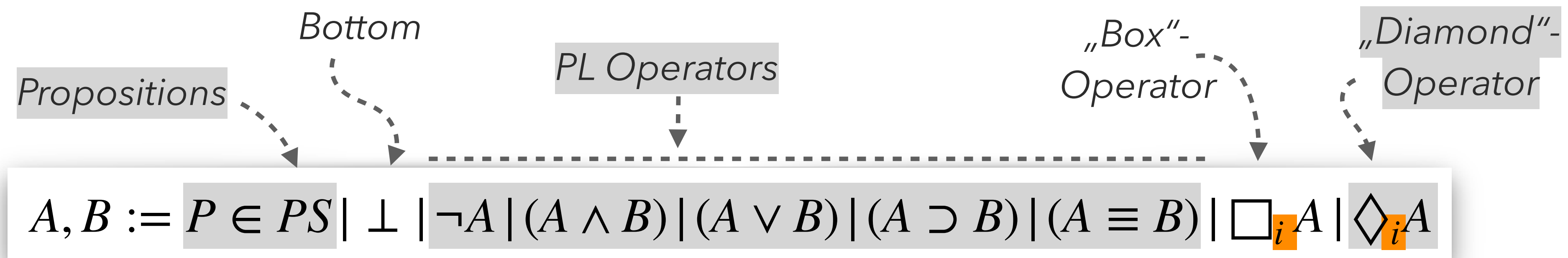
Sample formula:

$A \wedge B$

First-Order Multi-Modal Logics (FOML)

Multi-Modal Logic [5]

Syntax:



With index set I , e.g. $I = \{alice, bob\}$

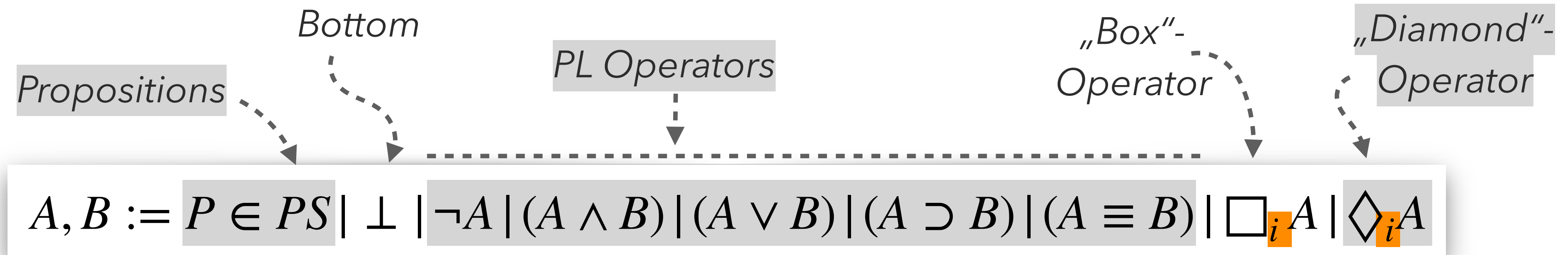
Sample formula:

$\Box_{alice} (A \wedge B)$

First-Order Multi-Modal Logics (FOML)

Multi-Modal Logic [5]

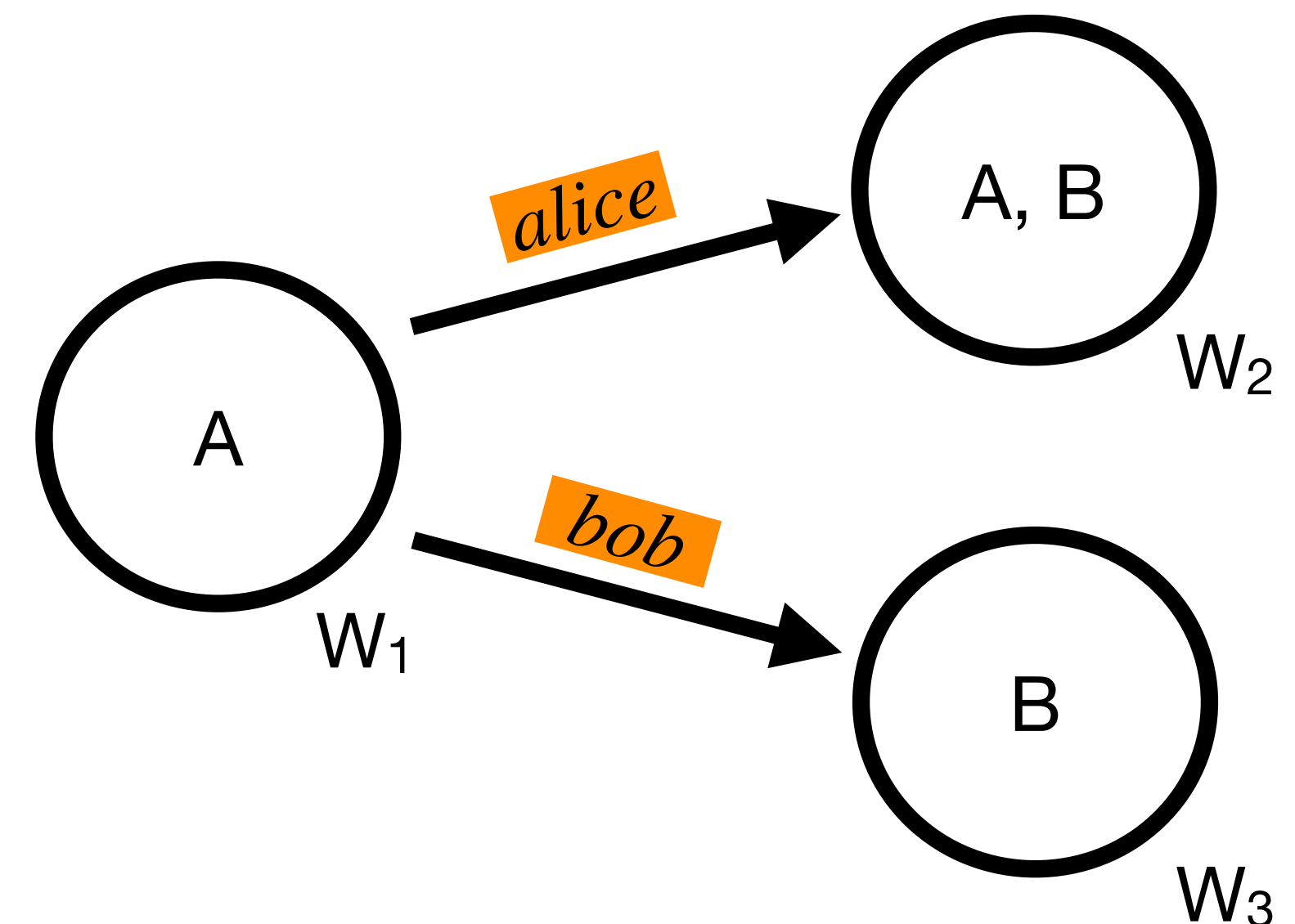
Syntax:



With index set I , e.g. $I = \{alice, bob\}$

Sample formula: $M, W_1 \models \Box_{alice} (A \wedge B)$

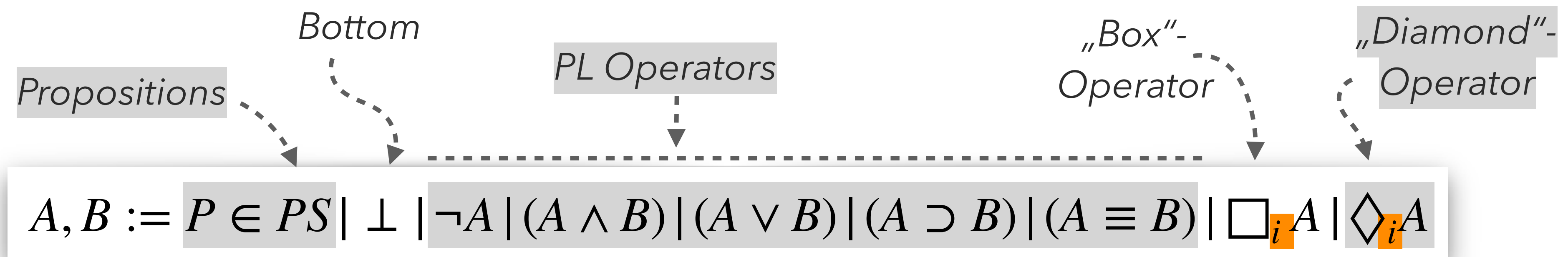
Semantics: Evaluation relative to possible worlds using Kripke-Structures:
 $M = (W, \{R_i\}_{i \in I}, V)$



First-Order Multi-Modal Logics (FOML)

Multi-Modal Logic [5]

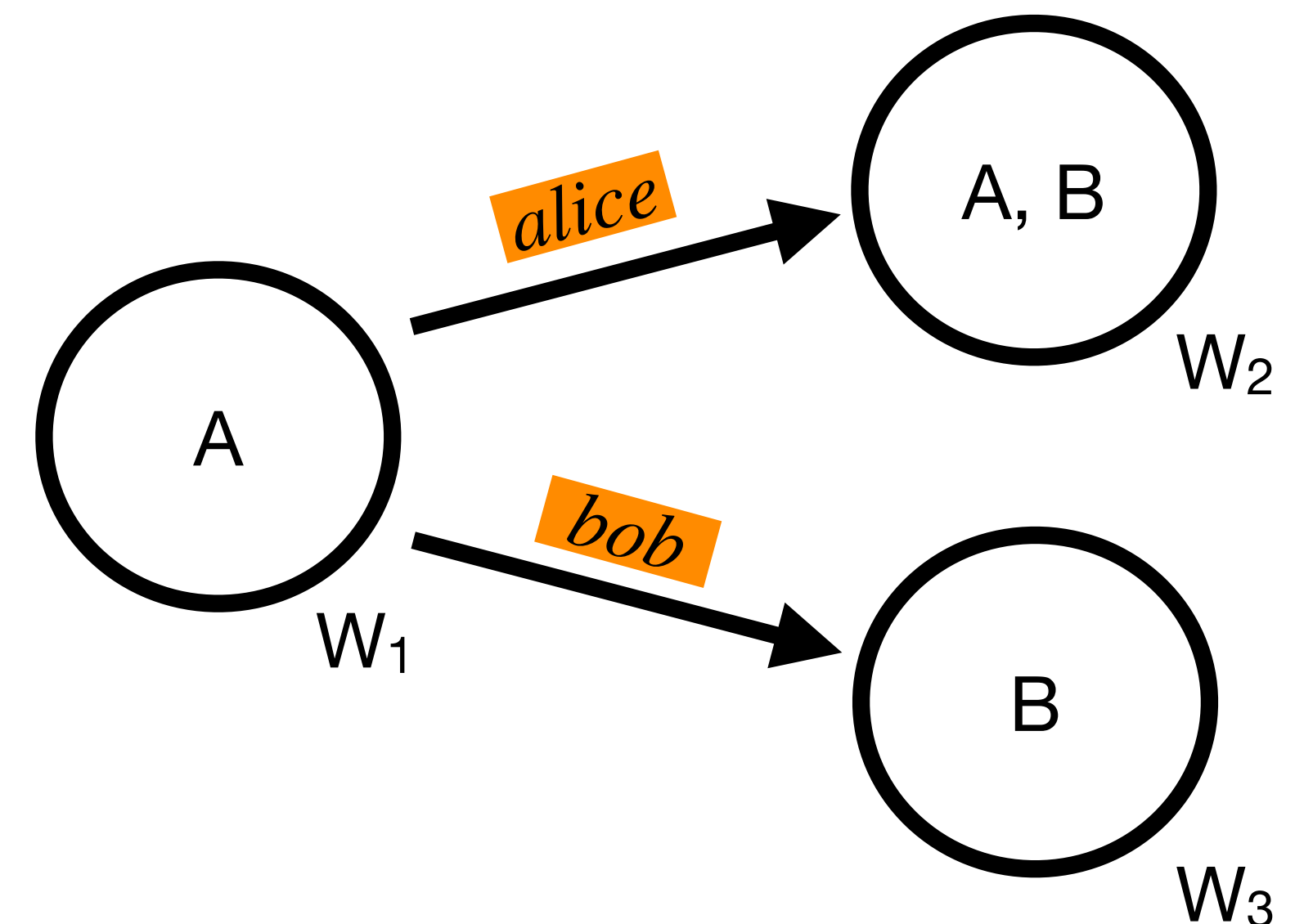
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Sample formula: $M, W_1 \models \Box_{alice} (A \wedge B)$ ✓

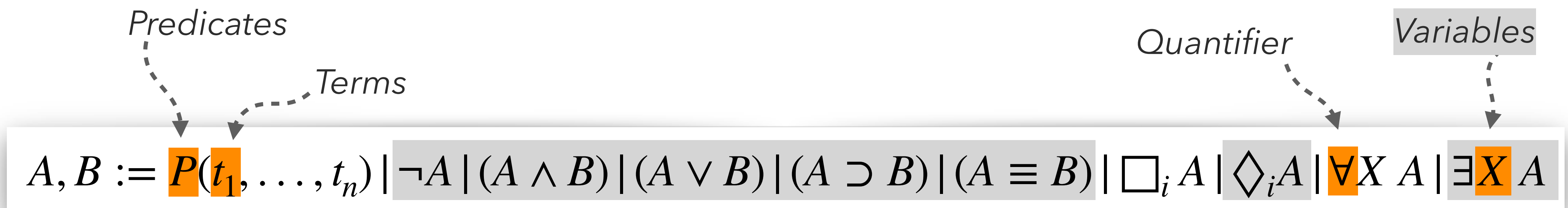
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 $M = (W, \{R_i\}_{i \in I}, V)$



First-Order Multi-Modal Logics (FOML)

First-Order Multi-Modal Logic [5,17]

Syntax:



With index set I , e.g. $I = \{alice, bob\}$

Sample formula: $M, W_1 \models \Box_{alice} (P(c) \wedge \forall X Q(c, X))$

Semantics: Evaluation relative to possible worlds using Kripke-Structures:

$$M = (W, \{R_i\}_{i \in I}, \mathcal{D}, \mathcal{I})$$

with $\mathcal{D} = \{D_w\}_{w \in W}$
and $\mathcal{I} = \{I_w\}_{w \in W}$

First-Order Multi-Modal Logics (FOML)

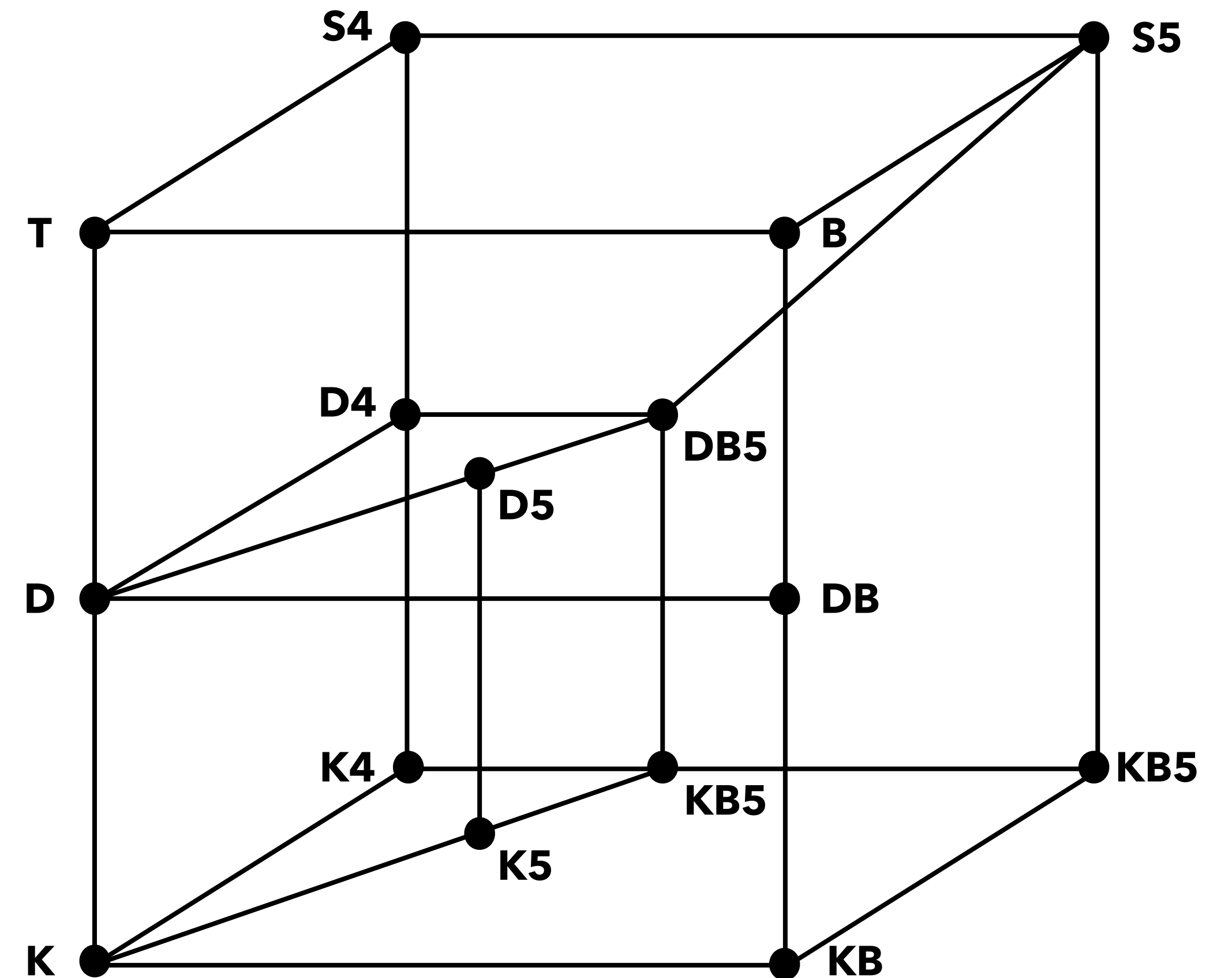
Characterisation [9]

Axiom schemes	
(D)	$\Box A \supset \Diamond A$
(T)	$\Box A \supset A$
(4)	$\Box A \supset \Box \Box A$
(5)	$\Diamond A \supset \Box \Diamond A$
(B)	$A \supset \Box \Diamond A$

First-Order Multi-Modal Logics (FOML)

Characterisation [9]

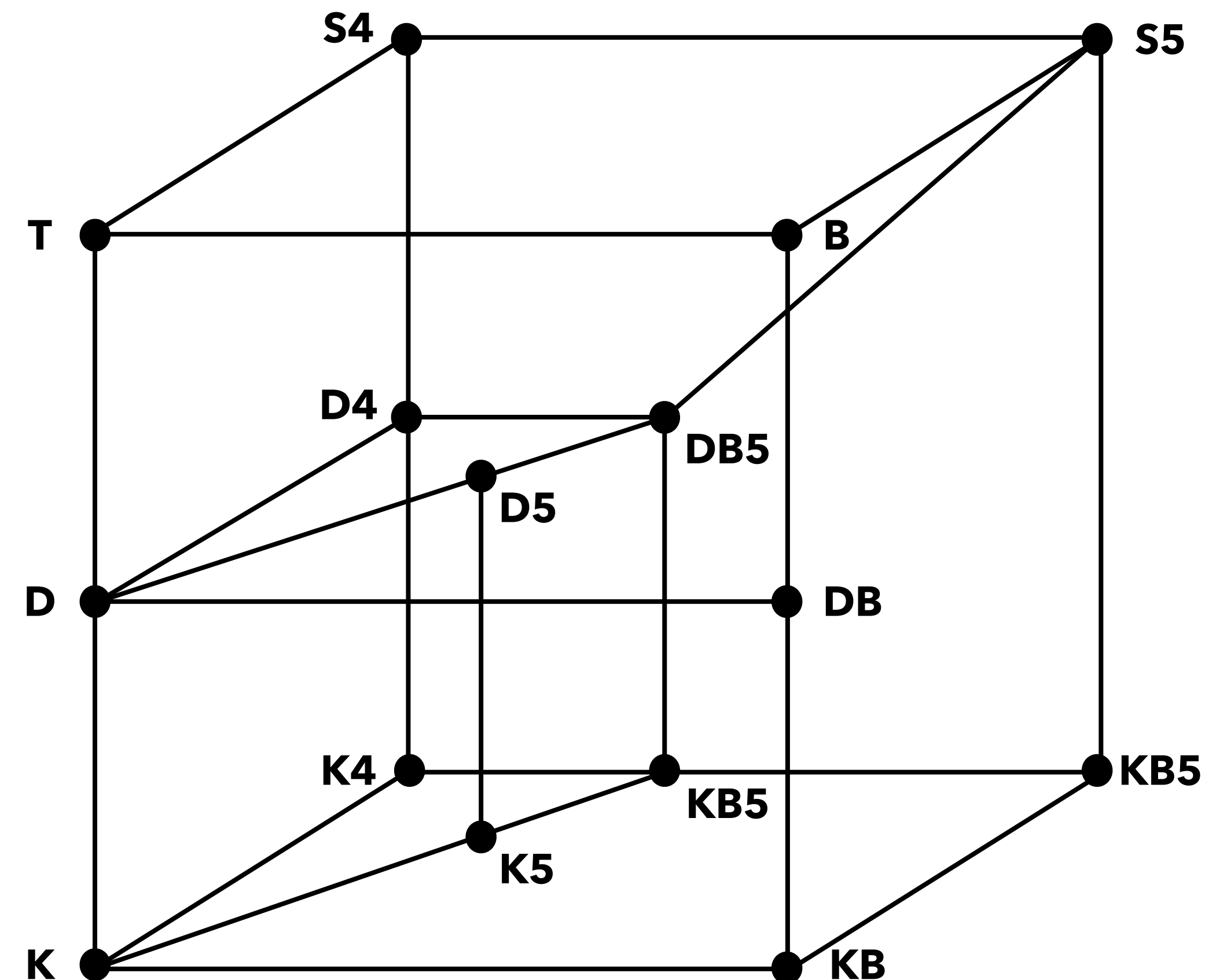
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First-Order Multi-Modal Logics (FOML)

Characterisation [9]

Frame Properties	Axiom schemes
Serial	$(D) \quad \Box A \supset \Diamond A$
Reflexive	$(T) \quad \Box A \supset A$
Transitive	$(4) \quad \Box A \supset \Box \Box A$
Euclidean	$(5) \quad \Diamond A \supset \Box \Diamond A$
Symmetric	$(B) \quad A \supset \Box \Diamond A$

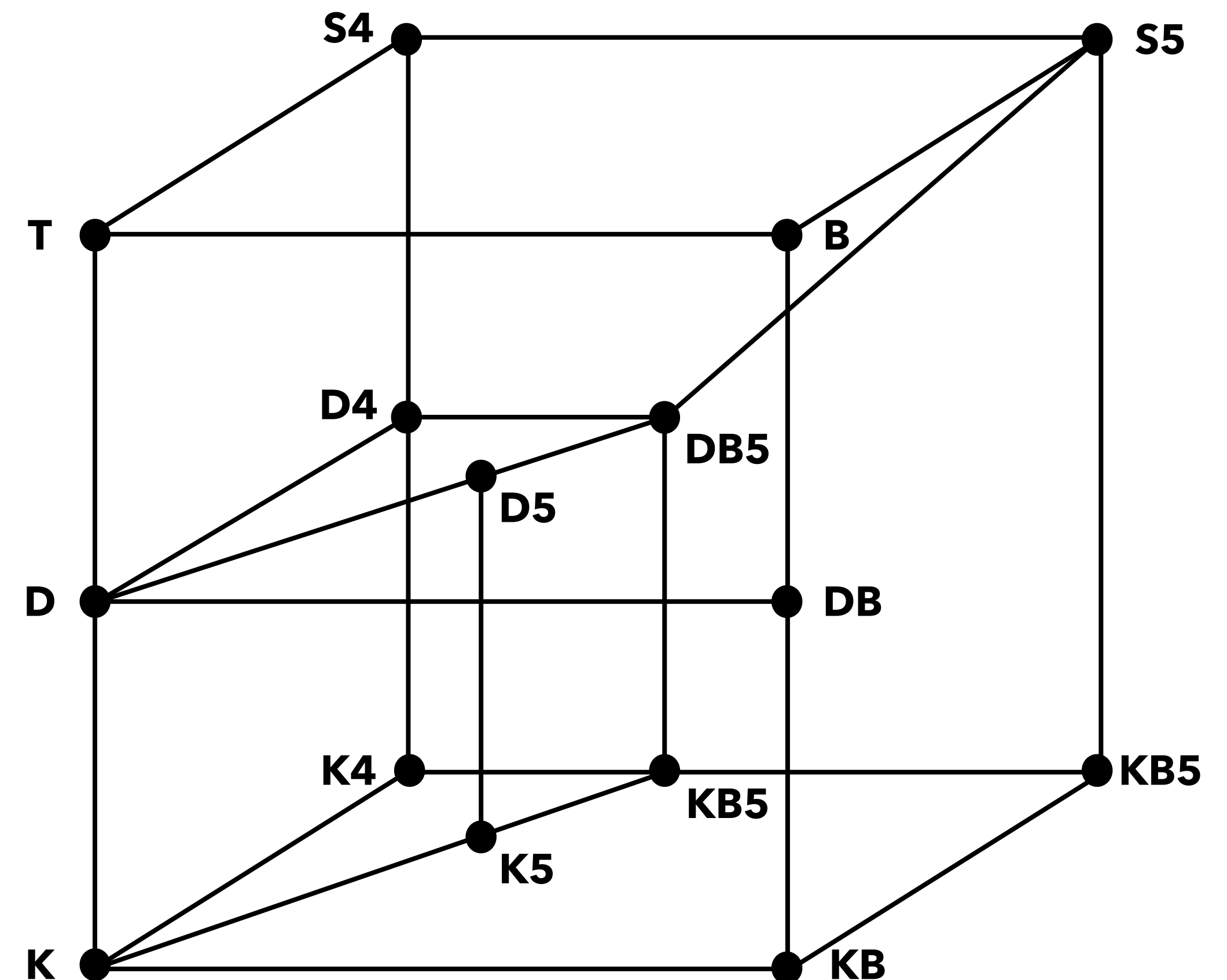


First-Order Multi-Modal Logics (FOML)

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Irreflexive $\neg xRx$	

Frame Properties



First-Order Multi-Modal Logics (FOML)

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Irreflexive

$\neg xRx$

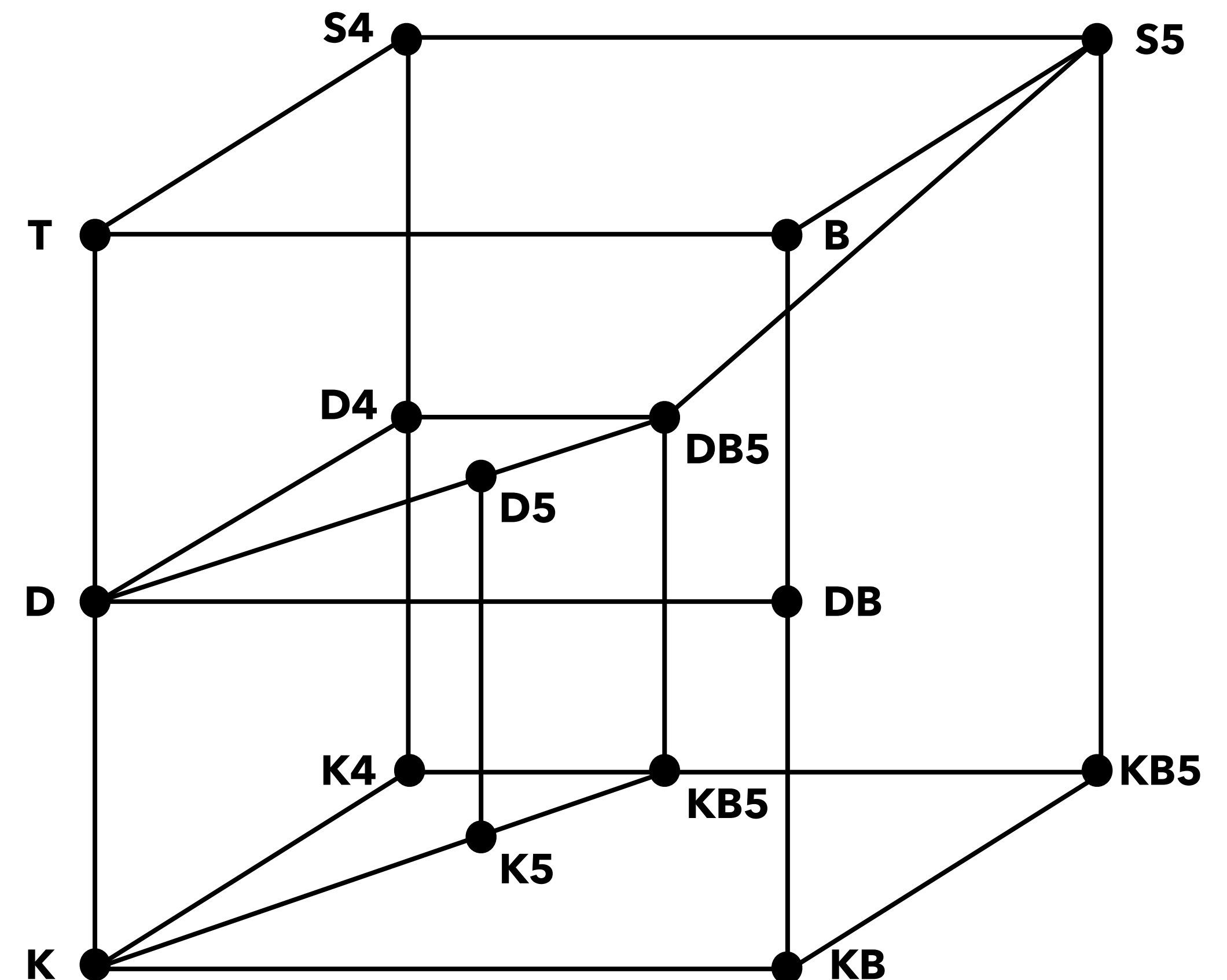
Frame Properties

[11]

Axiom Schemes

McKinsey Axiom

$\Box \Diamond A \supset \Diamond \Box A$



First-Order Multi-Modal Logics (FOML)

Characterisation [9]

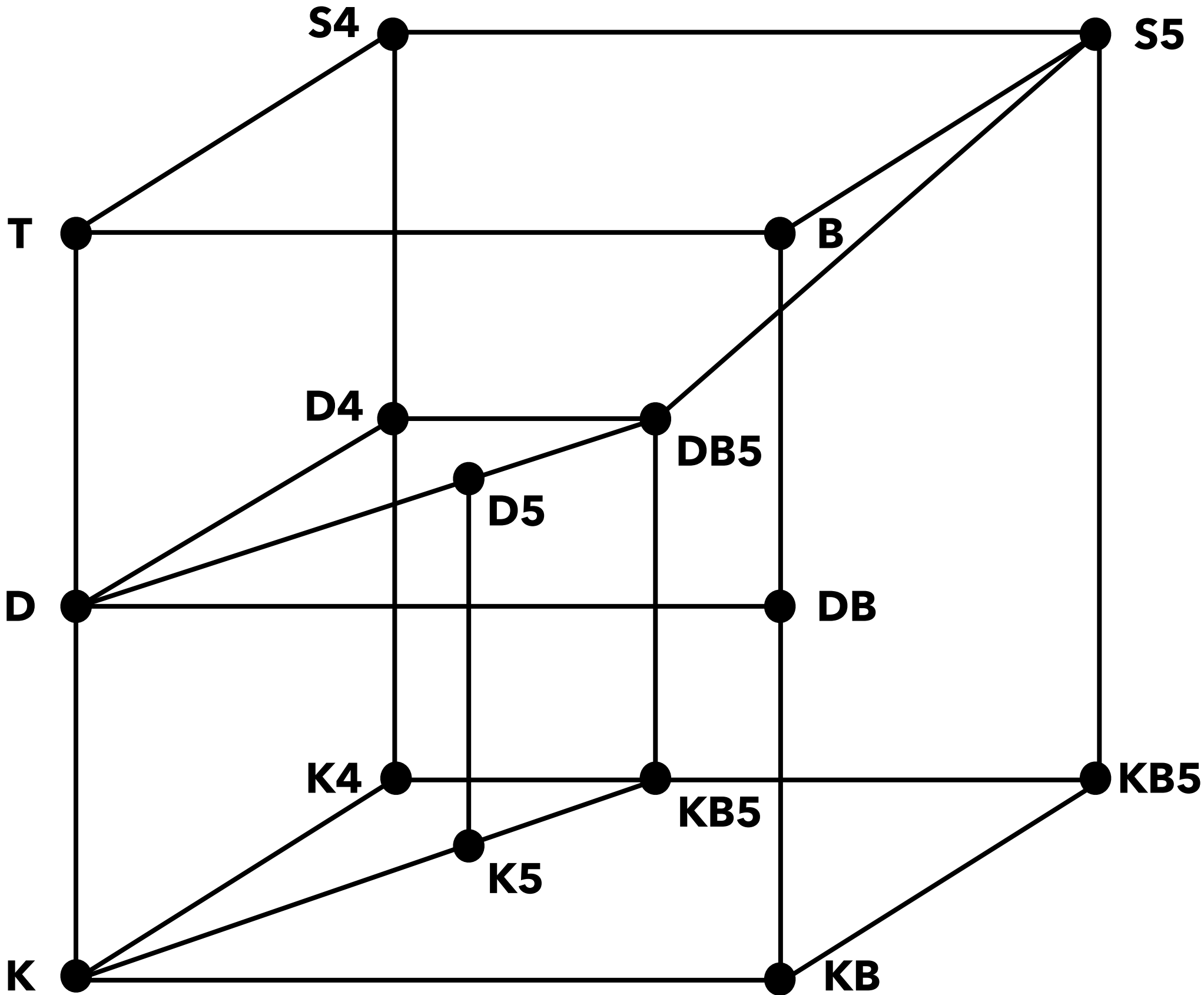
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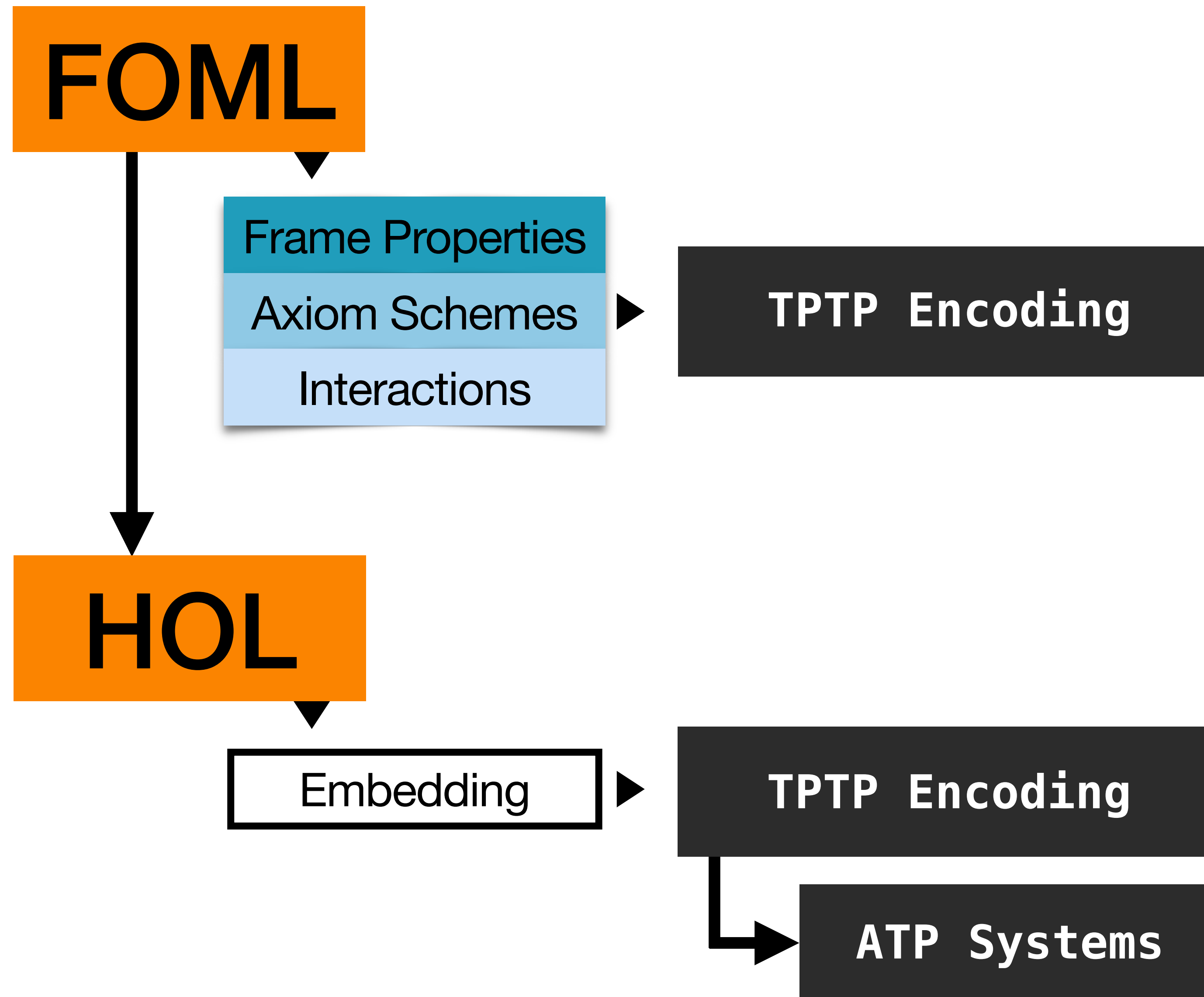
Irreflexive $\neg xRx$

Frame Properties

[11]	Axiom Schemes	McKinsey Axiom $\Box \Diamond A \supset \Diamond \Box A$
------	----------------------	--

[8]	Interactions	$\Box_1 A \supset \Box_2 A$
-----	---------------------	-----------------------------





Higher Order Logic (HOL)

Introduction [4, 6, 12]

Syntax:

Variables

Constants

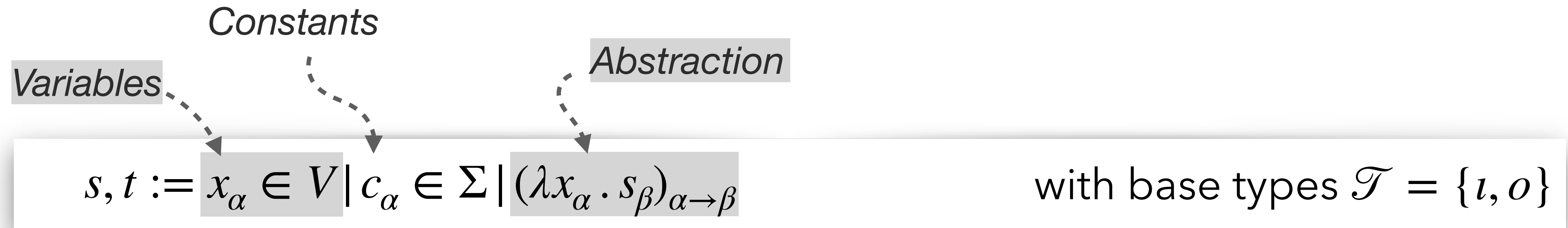
$s, t := x_\alpha \in V \mid c_\alpha \in \Sigma$

with base types $\mathcal{T} = \{\iota, o\}$

Higher Order Logic (HOL)

Introduction [4, 6, 12]

Syntax:

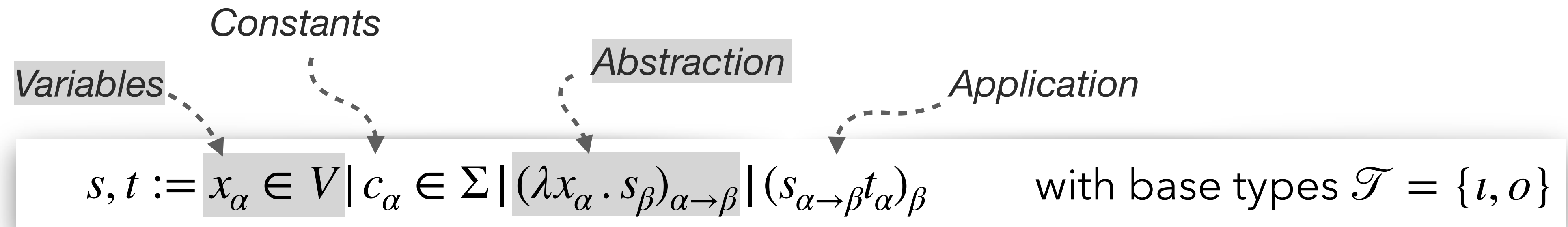


- Abstractions are unnamed functions that return s_β with each free occurrence of x_α replaced with the argument (β -reduction)

Higher Order Logic (HOL)

Introduction [4, 6, 12]

Syntax:

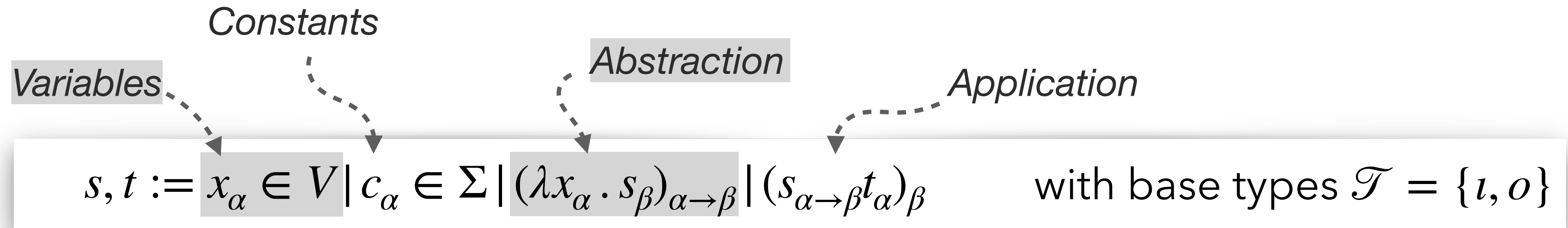


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Higher Order Logic (HOL)

Introduction [4, 6, 12]

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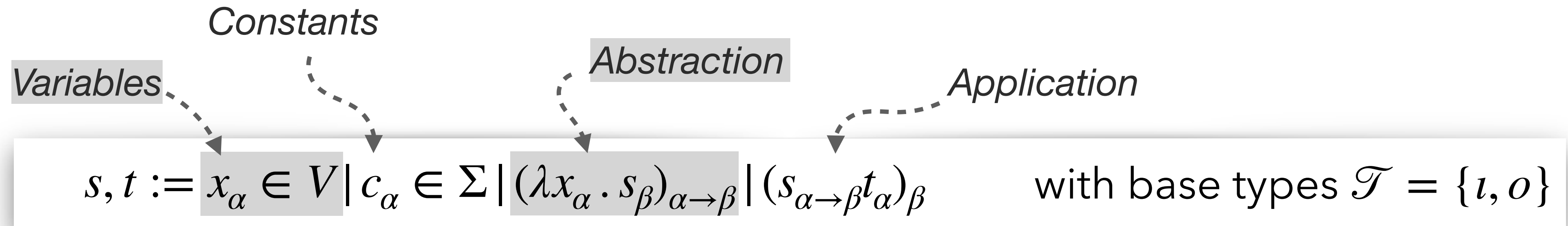


- Abstractions are unnamed functions that return s_β with each free occurrence of x_α replaced with the argument (β -reduction)
- Function types can be constructed using „ \rightarrow “

Higher Order Logic (HOL)

Introduction [4, 6, 12]

Syntax:



- Abstractions are unnamed functions that return s_β with each free occurrence of x_α replaced with the argument (β -reduction)
- Function types can be constructed using „ \rightarrow “

Semantics: General semantics of HOL [1] is assumed

Higher Order Logic (HOL)

Introduction

Syntax:

Variables *Constants* *Abstraction* *Application*

$s, t := x_\alpha \in V \mid c_\alpha \in \Sigma \mid (\lambda x_\alpha. s_\beta)_{\alpha \rightarrow \beta} \mid (s_{\alpha \rightarrow \beta} t_\alpha)_\beta$ with base types $\mathcal{T} = \{\iota, o\}$

Embedding of FOML into HOL [2,3]

- Introduction of new type μ for worlds

Higher Order Logic (HOL)

Introduction

Syntax:

$s, t := x_\alpha \in V \mid c_\alpha \in \Sigma \mid (\lambda x_\alpha. s_\beta)_{\alpha \rightarrow \beta} \mid (s_{\alpha \rightarrow \beta} t_\alpha)_\beta$
 with base types $\mathcal{T} = \{\iota, o\}$

Variables (points to x_α)
Constants (points to c_α)
Abstraction (points to $\lambda x_\alpha. s_\beta$)
Application (points to $(s_{\alpha \rightarrow \beta} t_\alpha)_\beta$)

Embedding of FOML into HOL [2,3]

- Introduction of new type μ for worlds
- Definition of auxiliary structures representing elements from Kripke semantics, eg. :

$$wR_i v \longrightarrow r_{\mu \rightarrow \mu \rightarrow o}^i W_\mu V_\mu$$

Higher Order Logic (HOL)

Introduction

Syntax:

$s, t := x_\alpha \in V \mid c_\alpha \in \Sigma \mid (\lambda x_\alpha. s_\beta)_{\alpha \rightarrow \beta} \mid (s_{\alpha \rightarrow \beta} t_\alpha)_\beta$
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Embedding of FOML into HOL [2,3]

- Introduction of new type μ for worlds
- Definition of auxiliary structures representing elements from Kripke semantics, eg. :

$$\begin{aligned}
 wR_i v &\rightarrow r_{\mu \rightarrow \mu \rightarrow o}^i W_\mu V_\mu \\
 \Box_i A &\rightarrow (\lambda X_{\mu \rightarrow o}. \lambda W_\mu. \forall V_\mu. \neg(r^i W V) \vee (X V)) [A]
 \end{aligned}$$

Higher Order Logic (HOL)

Introduction

Syntax:

Variables
Constants
Abstraction
Application

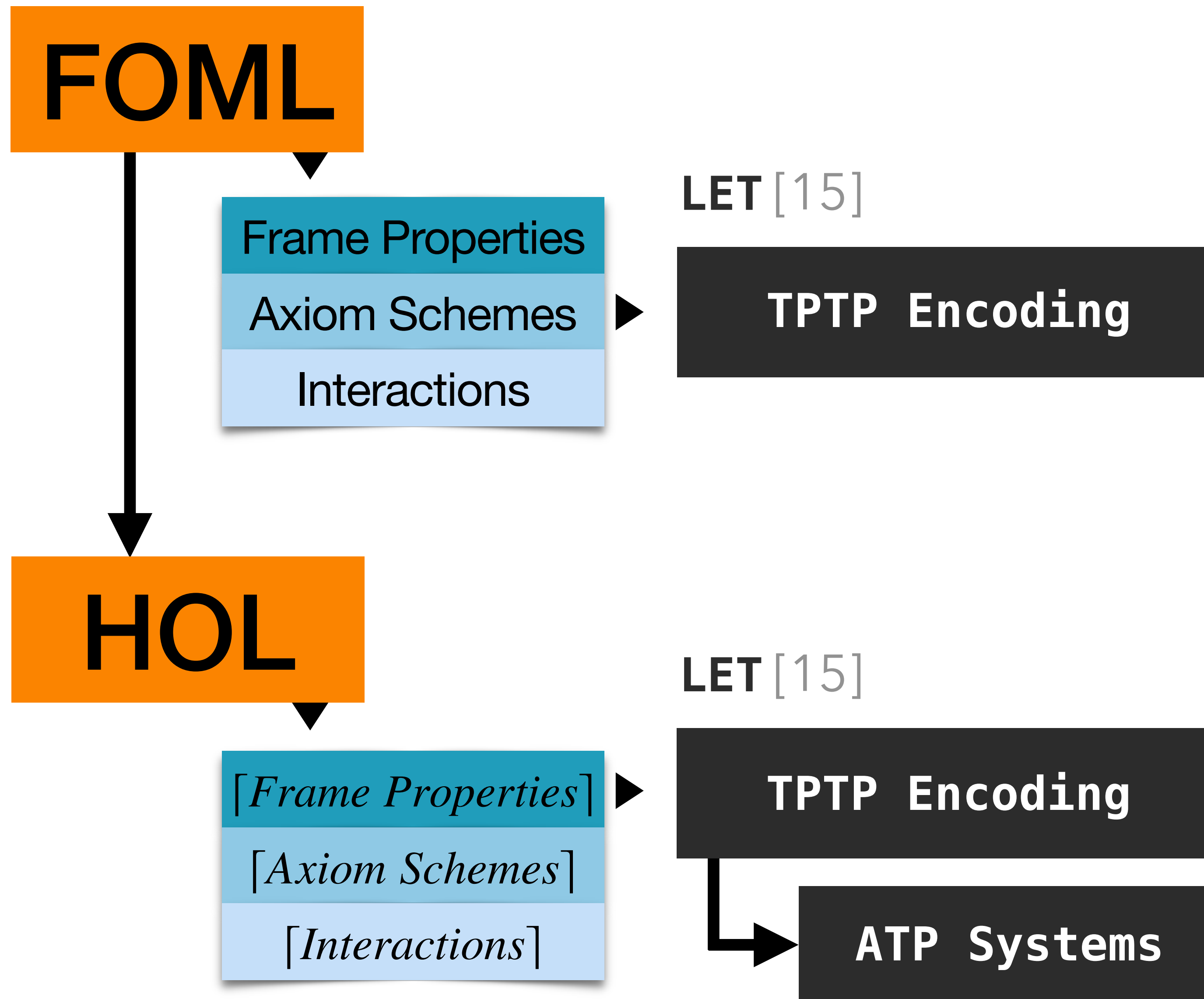
$$s, t := x_\alpha \in V \mid c_\alpha \in \Sigma \mid (\lambda x_\alpha. s_\beta)_{\alpha \rightarrow \beta} \mid (s_{\alpha \rightarrow \beta} t_\alpha)_\beta \quad \text{with base types } \mathcal{T} = \{\iota, o\}$$

Embedding of FOML into HOL [2,3]

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 \end{aligned}$$

- Recursive embedding of formulas



Thousands of Problems for Theorem Provers (TPTP)

Introduction [16]

- community standard platform for ATP development
- Several languages for ATP systems, e.g.
 - THF for classical higher-order logic
 - NXF for first-order non-classical reasoning [15]
- Core building block: annotated formulas of form
`language(name,role,formula).`

TPTP-Syntax

$\neg xRx$

TPTP-Syntax

$\neg xRx$

`(~$ki_accessible(X,X))`

xRx : `$ki_accessible(X,X)`

$\neg A$: `~A`

TPTP-Syntax

$\neg xRx$

$! [X: \$ki_world] :$
 $(\sim \$ki_accessible(X,X))$

xRx : $\$ki_accessible(X,X)$

$\neg A$: $\sim A$

$\forall X A$: $! [X: type] : (A)$

TPTP-Syntax

$\neg xRx$

! [X: \$ki_world] :
(~\$ki_accessible(X,X))

$\Box \Diamond A \supset \Diamond \Box A$

{ \$box } @ ()

$\Box A$: { \$box } @ A

TPTP-Syntax

$$\neg xRx$$

! [X: \$ki_world] :
(~\$ki_accessible(X,X))

$$\Box \Diamond A \supset \Diamond \Box A$$

{ \$box } @ ({ \$dia } @ (A))

$\Box A$: { \$box } @ A

$\Diamond A$: { \$dia } @ A

TPTP-Syntax

$$\neg xRx$$

`! [X: $ki_world] :`
`(~$ki_accessible(X,X))`

$$\Box \Diamond A \supset \Diamond \Box A$$

`{ $box } @ ({ $dia } @ (A))`
`=> { $dia } @ ({ $box } @ (A))`

$$\Box A : \{ \$box \} @ A$$

$$\Diamond A : \{ \$dia \} @ A$$

$$(A \supset B) : A \Rightarrow B$$

TPTP-Syntax

$$\neg xRx$$

`! [X: $ki_world] :
 (~$ki_accessible(X,X))`

$$\Box \Diamond A \supset \Diamond \Box A$$

`{ $box } @ ({ $dia } @ (A))
=> { $dia } @ ({ $box } @ (A))`

$$\Box_1 A \supset \Box_2 A$$

`{ $box(#1) } @ (A)
=> { $box(#2) } @ (A)`

TPTP-Syntax

$\neg xRx$

`! [X: $ki_world] :
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=> { $box(#2) } @ (A)`

Logic Specification [15]

```
thf(logic_spec, logic, $modal == [  
  $designation == $rigid,  
  $domains == $constant,  
    $modalities == [  
      $modal_system_T,  
      { $box(#1) } ==  
        [ $modal_system_D]  
    ]  
  ]).
```

TPTP-Syntax

$\neg xRx$

`! [X: $ki_world] :
 (~$ki_accessible(X,X))`

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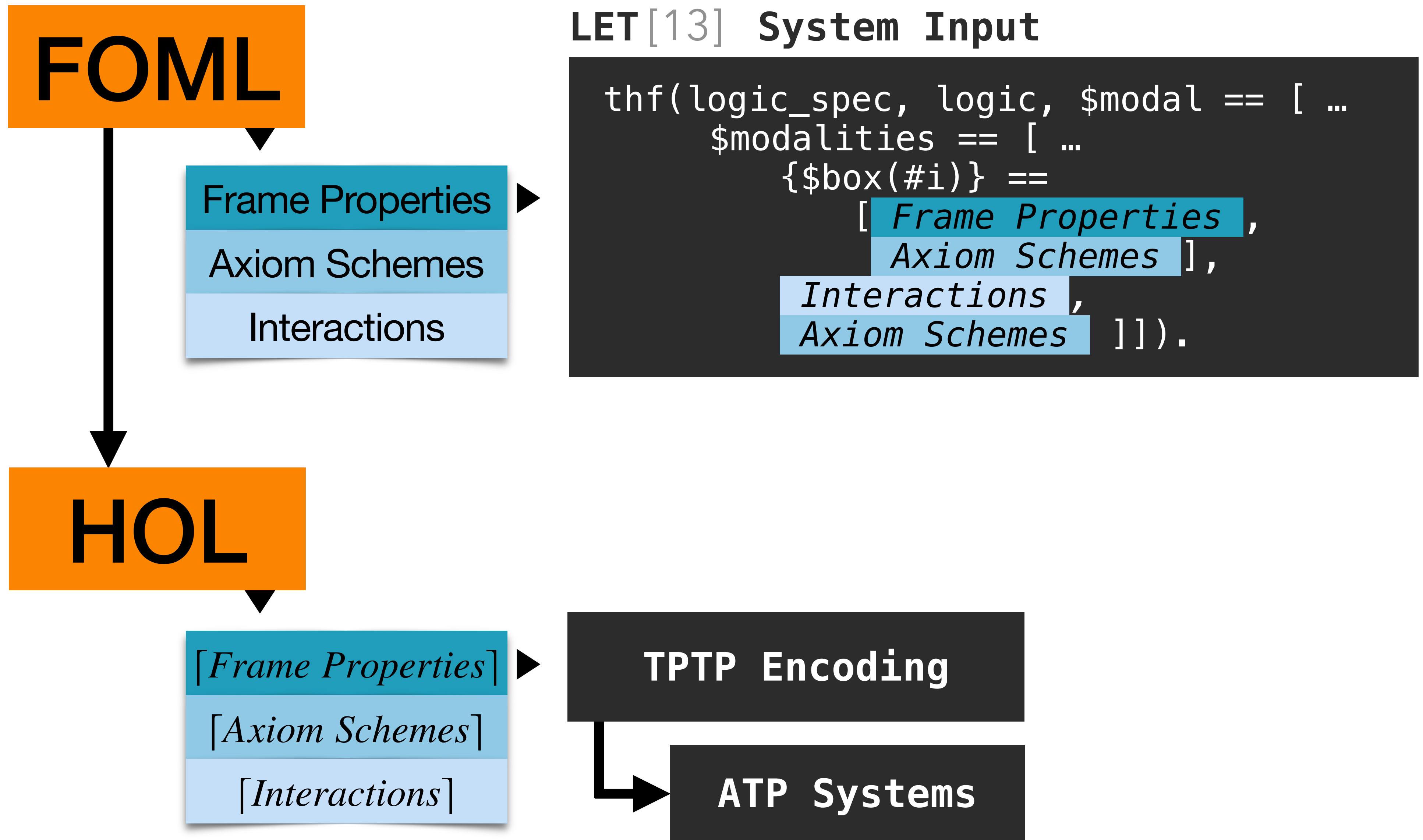
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Logic Specification [15]

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  $domains == $constant,  
  $modalities == [  
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    { $box(#1) } ==  
      [ $modal_system_D  
        ! [X: $ki_world] :  
          (~$ki_accessible(X,X)),  
          { $box } @ ( { $dia } @ (A) )  
            => { $dia } @ ( { $box } @ (A) ) ],  
        .  
        { $box(#1) } @ (A)  
          => { $box(#2) } @ (A),  
        .  
        .  
      ] ] ).
```



FOML-SPEC

$$\neg xRx$$

`! [X: $ki_world] :`
`(~$ki_accessible(X,X))`

$$\Box \Diamond A \supset \Diamond \Box A$$

`{ $box } @ ({ $dia } @ (A))`
`=> { $dia } @ ({ $box } @ (A))`

$$\Box_1 A \supset \Box_2 A$$

`{ $box(#1) } @ (A)`
`=> { $box(#2) } @ (A)`

HOL-EMBEDDING

`! [X:mworld]:`
`~ (mrel @'#1' @ X @ X)`

$$\Box_i A \rightarrow (\lambda X_{\mu \rightarrow o} . \lambda W_{\mu} . \forall V_{\mu} . \neg (r^i W V) \vee (X V)) [A]$$

..... **Embedding**


FOML-SPEC

HOL

$$\Box_i A \rightarrow (\lambda X_{\mu \rightarrow o} . \lambda W_{\mu} . \forall V_{\mu} . \neg (r^i W V) \vee (X V)) [A]$$

`{box(#1)} @ (A)` ^[10] \rightarrow

```
mbox: (mindex > ((mworld > $o) > (mworld > $o)))

mbox = (^ [R:mindex,Phi:(mworld > $o),W:mworld]:
  ! [V:mworld]: ((mrel @ R @ W @ V)
    => (Phi @ V)))
```

`mbox @ '#1' @ A`

..... **Embedding**


FOML-SPEC

HOL-EMBEDDING

FOML-SPEC

$$\neg xRx$$

```
! [X: $ki_world] :  
  (~$ki_accessible(X,X))
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$$\Box \Diamond A \supset \Diamond \Box A$$

```
{ $box } @ ( { $dia } @ (A) )  
=> { $dia } @ ( { $box } @ (A) )
```

$$\Box_1 A \supset \Box_2 A$$

```
{ $box(#1) } @ (A)  
=> { $box(#2) } @ (A)
```

HOL-EMBEDDING

```
! [X:mworld]:  
  ~ (mrel @'#1' @ X @ X )
```

```
mglobal @ ^[W:mworld]:  
  ((mbox @'#2' @(mdia @,#2' @A )@ W)  
=> (mdia @'#2'@(mbox@'#2' @A )@ W))
```

```
mglobal @ ^ [W:mworld]:  
  ((mbox @ '#1' @ A @ W)  
=> (mbox @ '#2' @ A @ W))
```

FOML-SPEC

$$\neg xRx$$

```
! [X: $ki_world] :  
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{ $box } @ ( { $dia } @ (A) )  
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```
{ $box(#1) } @ (A)  
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```

HOL-EMBEDDING

```
! [X:mworld]:  
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```

```
! [A:(mworld > $o)]:  
  (mglobal @ ^[W:mworld]:  
   ((mbox @'#2' @(mdia @,#2' @A )@ W)  
    => (mdia @'#2'@(mbox@'#2' @A )@ W)))
```

```
! [A:(mworld > $o)]:  
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`! [X: $ki_world] :
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$$\Box \Diamond A \supset \Diamond \Box A$$

`{ $box } @ ({ $dia } @ (A))
=> { $dia } @ ({ $box } @ (A))`

$$\Box_1 A \supset \Box_2 A$$

`{ $box(#1) } @ (A)
=> { $box(#2) } @ (A)`

HOL-EMBEDDING

```
thf(mrel_2_semantic1, axiom,  
! [X:mworld]:  
  ~ (mrel @'#1' @ X @ X)).
```

```
thf(mrel_2_syntactic1, axiom,  
! [A:(mworld > $o)]:  
  (mglobal @ ^[W:mworld]:  
    ((mbox @'#2' @(mdia @,#2' @A )@ W)  
     => (mdia @'#2'@(mbox@'#2' @A )@ W))))).
```

```
thf(interaction_scheme_1, axiom,  
! [A:(mworld > $o)]:  
  (mglobal @ ^ [W:mworld]:  
    ((mbox @ '#1' @ A @ W)  
     => (mbox @ '#2' @ A @ W))))).
```

HOL-EMBEDDING

SYSTEM OUTPUT (LET) [13]

.....

```
thf(mrel_2_semantic1,axiom,  
! [X:mworld]:  
  ~ (mrel @'#1' @ X @ X )).
```

.....

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thf(mrel_2_syntactic1,axiom,  
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  (mglobal @ ^[W:mworld]:  
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```

.....

```
thf(interaction_scheme_1,axiom,  
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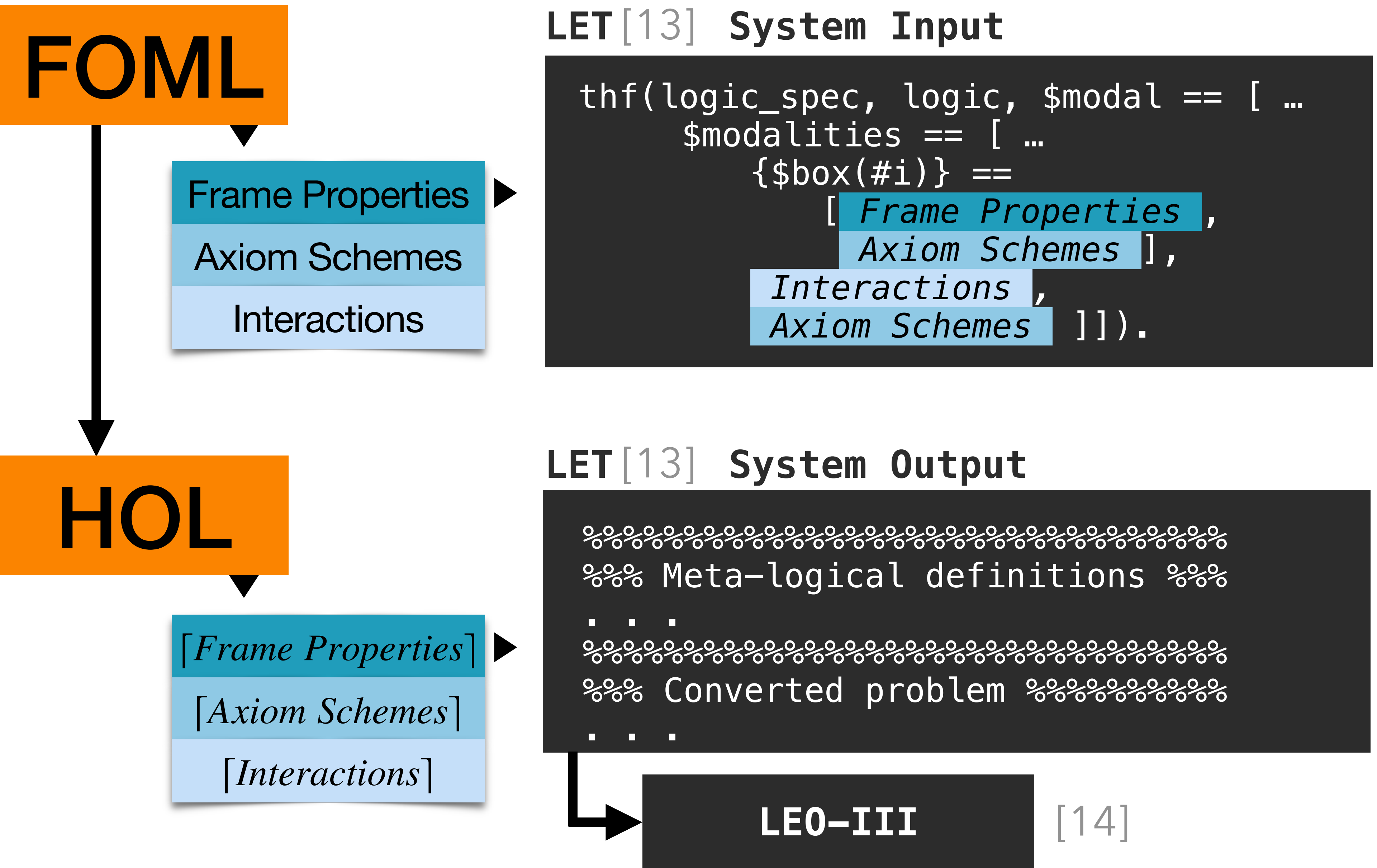
%%
%%% Meta-logical definitions %%%

. . .

. . .

%%
%%% Converted problem %%%%%%%%%%

. . .



References

- [1] Andrews, P.: General models and extensionality. *J. Symbolic Logic* 37(2), 395–397 (1972)
- [2] Benzmüller, C., Paulson, L.: Quantified multimodal logics in simple type theory. *Logica Univ.* 7(1), 7–20 (2013)
- [3] Benzmüller, C., Woltzenlogel Paleo, B.: Higher-order modal logics: automation and applications. In: Faber, W., Paschke, A. (eds.) *Reasoning Web 2015. LNCS*, vol. 9203, pp. 32–74. Springer, Cham (2015)
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Application Example

Simplified Shooting Problem [A1]

- The logic is defined as follows:

$$T: \quad \Box_{always} A \supset A$$

$$4: \quad \Box_{always} A \supset \Box_{always} \Box_{always} A$$

$$B_1: \quad \Box_{always} A \supset \Box_{load} A$$

$$B_2: \quad \Box_{always} A \supset \Box_{shoot} A$$

Application Example

Simplified Shooting Problem [A1]

- The logic is defined as follows:

$$\begin{array}{ll} T: & \Box_{always} A \supset A \\ 4: & \Box_{always} A \supset \Box_{always} \Box_{always} A \\ B_1: & \Box_{always} A \supset \Box_{load} A \\ B_2: & \Box_{always} A \supset \Box_{shoot} A \end{array}$$

- The reasoning problem:

$$\begin{array}{ll} 1: & \Box_{always} \Box_{load} loaded \\ 2: & \Box_{always} (loaded \supset \Box_{shoot} \neg alive) \\ C: & \Box_{load} \Box_{shoot} \neg alive \end{array}$$

Application Example

Simplified Shooting Problem [A1]

QMLTP Version [A2]

- The logic is defined as follows:

$$\begin{array}{ll} T: & \Box_{always} A \supset A \\ 4: & \Box_{always} A \supset \Box_{always} \Box_{always} A \\ B_1: & \Box_{always} A \supset \Box_{load} A \\ B_2: & \Box_{always} A \supset \Box_{shoot} A \end{array}$$

- The reasoning problem:

$$\begin{array}{ll} 1: & \Box_{always} \Box_{load} loaded \\ 2: & \Box_{always} (loaded \supset \Box_{shoot} \neg alive) \\ C: & \Box_{load} \Box_{shoot} \neg alive \end{array}$$

Attempt at including B_1 as regular axioms:

$$\begin{array}{l} \Box_{always} loaded \supset \Box_{load} loaded \\ \Box_{always} \neg loaded \supset \Box_{load} \neg loaded \\ \Box_{always} alive \supset \Box_{load} alive \\ \Box_{always} \neg alive \supset \Box_{load} \neg alive \end{array}$$

➡ Does not result in a provable reasoning problem

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Application Example

Simplified Shooting Problem: LET Version

```
tff(modal_system, logic,  
    $modal ==  
    [ $modalities == [  
        {$box(#always)} == [$modal_axiom_T, $modal_axiom_4],  
        {$box(#load)} == $modal_system_K,  
        {$box(#shoot)} == $modal_system_K,  
        {$box(#always)} @ (P) => {$box(#load)} @ (P),  
        {$box(#always)} @ (P) => {$box(#shoot)} @ (P) ] ] ).  
  
tff(alive_decl, type, alive: $o ).  
tff(loaded_decl, type, loaded: $o ).  
  
tff(axiom_1,hypothesis, {$box(#always)} @ ({$box(#load)} @ (loaded)) ).  
tff(axiom_2,hypothesis, {$box(#always)} @ (loaded => ( {$box(#shoot)} @ (~  
alive) )) ).  
  
tff(conj, conjecture, {$box(#load)} @ ({$box(#shoot)} @ (~ alive)) ).
```

Application Example

Simplified Shooting Problem: LET Version

```
tff(modal_system, logic,  
    $modal ==  
    [ $modalities == [  
        {$box(#always)} == [$modal_axiom_T, $modal_axiom_4],  
        {$box(#load)} == $modal_system_K,  
        {$box(#shoot)} == $modal_system_K,  
        {$box(#always)} @ (P) => {$box(#load)} @ (P),  
        {$box(#always)} @ (P) => {$box(#shoot)} @ (P) ] ] ).  
  
tff(alive_decl, type, alive: $o ).  
tff(loaded_decl, type, loaded: $o ).  
  
tff(axiom_1,hypothesis, {$box(#always)} @ ({$box(#load)} @ (loaded)) ).  
tff(axiom_2,hypothesis, {$box(#always)} @ (loaded => ( {$box(#shoot)} @ (~  
alive) )) ).  
  
tff(conj, conjecture, {$box(#load)} @ ({$box(#shoot)} @ (~ alive)) ).
```

➡ Proven by LEO-III