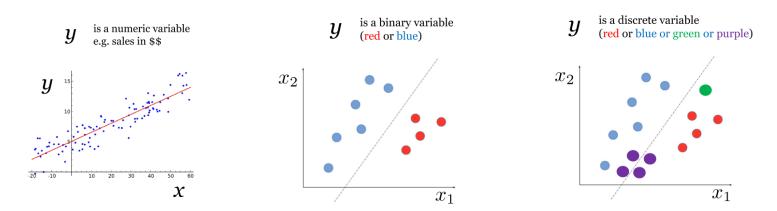
# Classification

Machine Learning and Computational Statistics (DSC6135)

#### 1. Introduction to Classification



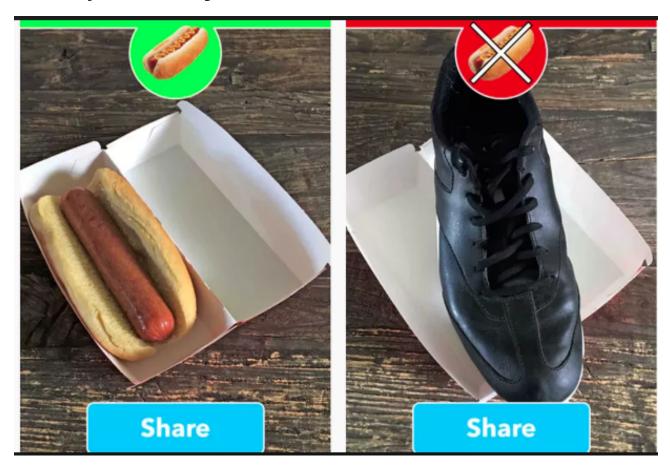
#### From left to right:

- linear regression
- binary classification
- multi-class classification

# **Example: Binary Classification**



# **Example: Binary Classification**



#### **Example: Multi-class Classification**

## Predict words from keyboard trajectories



Many possible letters: *Multi-class* classification

#### Classification overview

- Steps for classification
  - 1. What is prediction? --> hard binary vs. probabilities
  - 2. What is training? --> we need a model
  - 3. How to evaluate --> we need performance metrics
- Possible methods for classification
  - 1. Logistic Regression
  - 2. K-Nearest Neighbors
  - 3. Decission Tree Regression
  - 4. Boosting
  - 5. Suppor Vector Classifiers (SVCs), Support Vector Machines (SVMs)

### **Binary Prediction Step**

Goal: Predict label (o or 1) given features x

```
• Input: x_i \triangleq [x_{i1}, x_{i2}, \dots x_{if} \dots x_{iF}] "features" Entries can be real-valued, or other numeric types (e.g. integer, binary) "predictors" "attributes"
• Output: y_i \in \{0,1\} Binary label (0 or 1) "responses" "labels"
```

```
>>> yhat_N = model.predict(x_NF)
>>> yhat_N[:5] # peek at predictions
[0, 0, 1, 0, 1]
```

### **Probability Prediction Step**

Goal: Predict probability p(Y=1) given features x

• Input: 
$$x_i \triangleq [x_{i1}, x_{i2}, \dots x_{if} \dots x_{iF}]$$

"features" Entries can be real-valued, or other numeric types (e.g. integer, binary)

"predictors" "attributes"

• Output:  $\hat{p}_i$  Probae.e.g. o.

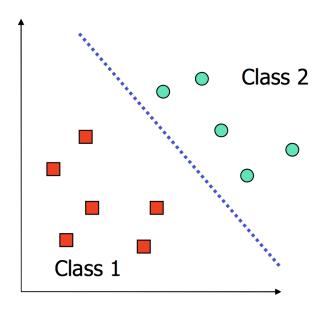
Probability between 0 and 1 e.g. 0.001, 0.513, 0.987

### **Probability Prediction Step**

Logistic Regression: Linear Decision Boundary

We can try to model the **probability** of a data point being from a particular class by

- 1. which side of the decision boundary it's on
- 2. how far it is away from the boundary. Intuitively, the farther a data point is from the decision boundary, the more 'certain' we should be of it's classification.



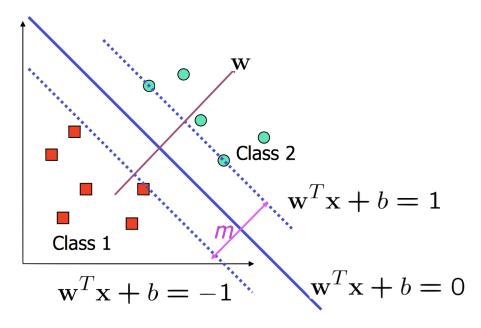
# Logistic Regression: Linear Decision Boundary

When the decision boundary is linear, it is defined by the equation

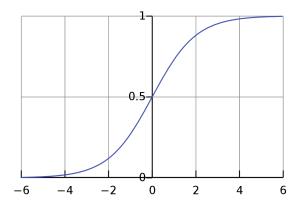
$$\mathbf{w}^{\mathsf{T}}\mathbf{x} = w_0 x_0 + w_1 x_1 + \dots + w_D x_D = 0$$

where  $x_0 = 1$ .

The vector  $\mathbf{w}$  allow us to gauge the 'distance' of a point from the decision boundary



To model the probability of labeling a point a certain class, we have to convert distance,  $\mathbf{w}^{\mathsf{T}}\mathbf{x}$  (which is unbounded) into a number between 0 and 1, using the *sigmoid function*:



$$\sigma(z) = \frac{1}{1 + e^{-z}},$$

$$Prob[y = 1 | \mathbf{x}] = \sigma(\mathbf{w}^{\mathsf{T}} \mathbf{x})$$

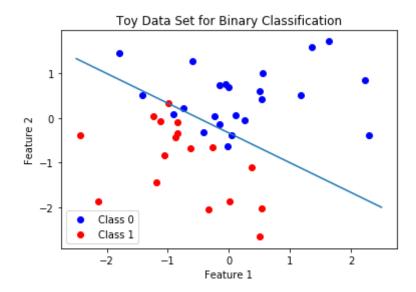
If  $Prob[y = 1 | \mathbf{x}] \ge 0.5$  we label  $\mathbf{x}$  class 1, otherwise we label it class 0.

To fit our model, we need to learn the parameters of  ${\bf w}$  that maximizes the likelihood of our training data.

#### How to generate data from logistic model?

```
In [4]: x1 = np.random.randn(40, 1) # some continuous features
    x2 = np.random.randn(40, 1)
    X = np.hstack((x1, x2))
    z = 1 + 2*x1 + 3*x2 # linear combination with a bias
    pr = 1/(1+np.exp(-z)) # pass through an inv-logit function
    y = np.random.binomial(1, pr).reshape(-1) # bernoulli response variable
    xspan = np.linspace(-2.5, 2.5, 100)
    boundary = -(1+2*xspan) / 3.0

plot_logistic(X,y)
```



#### **Logistic Loss**

- We are given training data  $X=(x_1,\ldots,x_N),y=(y_1,\ldots,y_N)$ , where  $x_i\in\mathbb{R}^p$  and  $y_i\in\{1,0\}$ .
- We assign a probability based on the logistic function to each data point for belonging to a specific class:

$$p = \text{Prob}[y = 1 | x] = \frac{1}{1 + e^{-\mathbf{w}^T x}},$$
 and  $\text{Prob}[y = 0 | x] = 1 - \text{Prob}[y = 1 | x].$ 

• We employ a Bernoulli random variable with probability mass function:

$$J(X, y, \mathbf{w}) = \prod_{i=1}^{N} \text{Prob}[y = y_i | x] = \prod_{i=1}^{N} p^{y_i} (1 - p)^{1 - y_i}$$

- J is the maximum likelihood estimator we want to minimize, given the model.
- For optimization purposes, we maximize the log-likelihood:

$$\max_{\mathbf{w}} \log \left[ \prod_{i=1}^{N} p^{y_i} (1-p)^{1-y_i} \right]$$

$$\max_{\mathbf{w}} \sum_{i=1}^{N} \left[ y_i \log(1 + e^{-(\mathbf{w}^T x_i)}) + (1 - y_i) \log(1 + e^{(\mathbf{w}^T x_i)}) \right]$$

#### **Example with sklearn:**

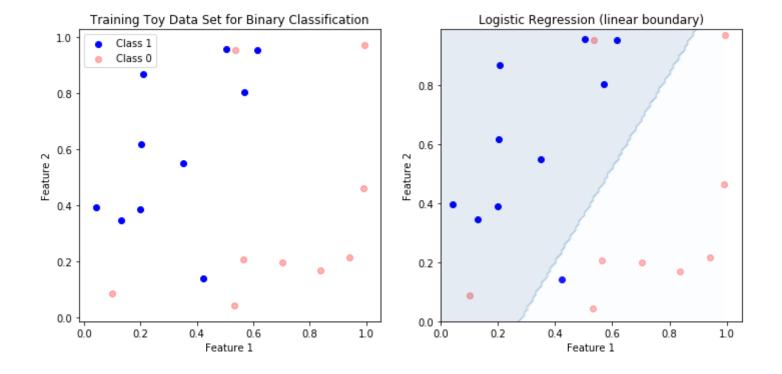
tol=0.0001, verbose=0, warm start=False)

n jobs=None, penalty='l2', random state=None, solver='lbfgs',

```
In [7]: # plot data and decision boundary of logistic regression
    plot_fig(X_train,y_train)

# plot decision boundary
    ax[1] = plot_decision_boundary(X_train, y_train, logreg, 'Logistic Regression (linear boundary)', ax[1])

plt.tight_layout()
    plt.show()
```



# Out [8]: logistic regression train score 0.842105

test score 0.759494

**Questions:** Why does the model do worse on testing data rather than training data?

## Optimization of the logistic loss

- Summary of variables:
  - Feature vector:

$$\mathbf{x} = [1 \ x_1 \ x_2 \ \dots \ \mathbf{x}_F]^T$$

Weight vector:

$$\mathbf{w} = [b \ w_1 \ w_2 \ \dots \ \mathbf{w}_F]^T$$

Score:

$$z_i = \mathbf{w}^T \mathbf{x}$$

Loss (minimization):

$$\sum_{i=1}^{N} -[y_i \log(1 + \exp^{-(\mathbf{w}^T x_i)}) + (1 - y_i) \log(1 + \exp^{(\mathbf{w}^T x_i)})]$$

• Gradient of the sigmoid:

$$\frac{\partial \sigma(z)}{\partial z} = \frac{\partial}{\partial z} (1 + e^{-z})^{-1} = e^{-z} (1 + e^{-z})^{-2} = \frac{1}{1 + e^{-z}} \frac{e^{-z}}{1 + e^{-z}} = \sigma(z)$$

• Gradient of the log sigmoids:

$$\frac{\partial \log \sigma(z_i)}{\partial \omega^T} = \frac{1}{\sigma(z_i)} \frac{\partial \sigma(z_i)}{\partial \omega^T} = \frac{1}{\sigma(z_i)} \frac{\partial \sigma(z_i)}{\partial z_i} \frac{\partial z_i}{\partial \omega^T} = (1 - \sigma(z_i))x_i$$

$$\frac{\partial \log(1 - \sigma(z_i))}{\partial \omega^T} = \frac{1}{1 - \sigma(z_i)} \frac{\partial (1 - \sigma(z_i))}{\partial \omega^T} = -\sigma(z_i)x_i$$

• Gradient of the logistic loss

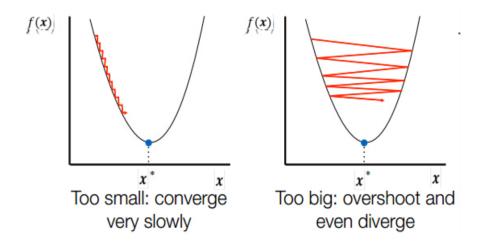
$$\frac{\partial l_i(\omega)}{\partial \omega^T} = -y_i x_i (1 - \sigma(z_i)) + (1 - y_i) x_i \sigma(z_i) = x_i (\sigma(z_i) - y_i)$$

#### **Gradient descent**

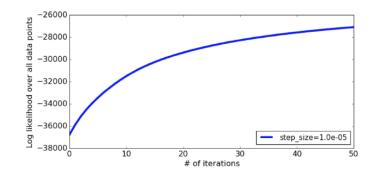
- The gradient of the logistic regression does not have closed form solution!
- We will need to use iterative methods to solve the problem approximately.
- One such simple method, is gradient descent:

$$\min_{\boldsymbol{w},w_0} -\sum_{i} \log p(y_i \mid \boldsymbol{x}_i; \boldsymbol{w}, w_0) + \frac{\lambda}{2} \|\boldsymbol{w}\|_2^2$$
 Start with  $\boldsymbol{w}^0 = 0, w_0^0 = 0$ , step size  $s$  for  $t = 0, ..., (T-1)$  
$$\boldsymbol{w}^{t+1} = \boldsymbol{w}^t - s \nabla J(\boldsymbol{w}^t, w_0^t) - \lambda \boldsymbol{w}^t$$
 
$$w_0^{t+1} = w_0^t - s \nabla J(\boldsymbol{w}^t, w_0^t)$$
 if  $L(\boldsymbol{w}^{t+1}, w_0^{t+1}) - L(\boldsymbol{w}^t, w_0^t) < \delta$  break return  $\boldsymbol{w}^T, w_0^T$ 

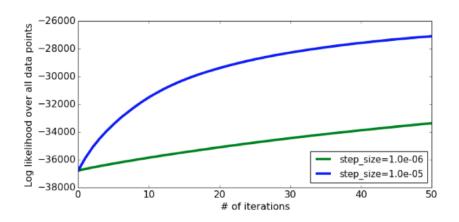
#### Intuition in 1D



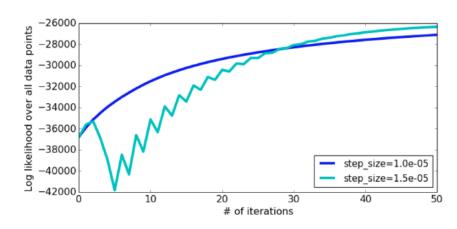
# Step size tuning



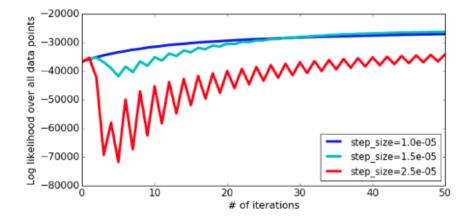
## Step size tuning: too small



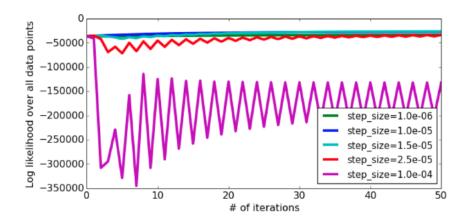
# Step size tuning: large



## Step size tuning: too large



### Step size tuning: way tooo large

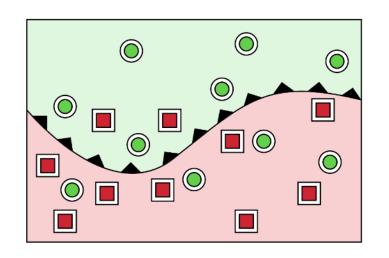


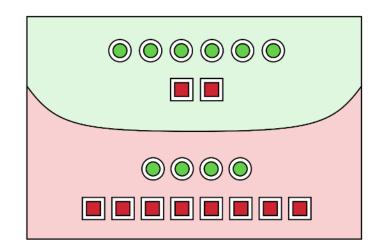
# Logistic Regression: Non-Linear Decision Boundary

Go to external notebook.

Question: What is a good/bad classifier?

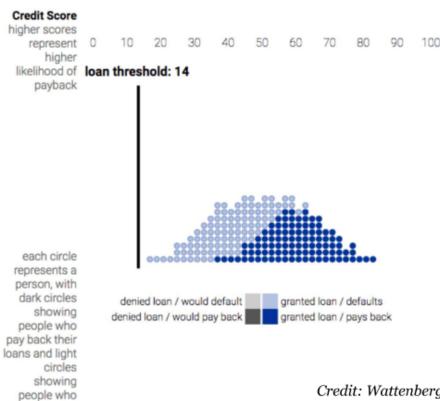
#### 2. Evaluation in Classification Task





What is a good/bad classifier? How can we measure this?

#### Thresholding to get Binary Decisions



default

Credit: Wattenberg, Viégas, Hardt

#### **Evaluation metrics for classification**

Many possibilities in practice.

- 1. Evaluate probabilities / scores directly: logistic loss, hinge loss, ...
- 2. Evaluate binary decisions at specific thresholds: accuracy, TPR, TNR, PPV, NPV, etc.
- 3. Evaluate across range of thresholds ROC curve, Precision-Recall curve,

**Libraries:** <a href="https://scikit-learn.org/stable/modules/model">https://scikit-learn.org/stable/modules/m

- 1. log\_loss, hinge\_loss.
- 2. metrics.precision\_score, metrics.recall\_score
- 3. metrics.average\_precision\_score, metrics.roc\_auc\_score

# Types of binary predictions

- TN: True negative - FP: False positive - FN: False negative - TP: True positive

The following table is called the **confusion matrix**.

		classifier calls	
		"negative" C=0	"positive" C=1
true outcome	Y=0	TN	FP
	Y=1	FN	TP

# **Examples**

Hot Dog Not Hot Dog









#### **Evaluating correct predictions:**

Accuracy: fraction of correct predictions

$$\frac{TP + TN}{TP + TN + FN + FP}$$

• Potential problem:

Suppose your dataset has 1 positive example and 99 negative examples.

What is the accuracy of the classifier that always predicts "negative"?

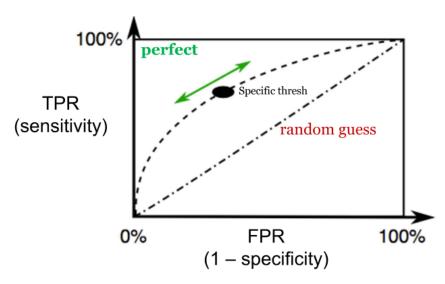
# Other evaluation metrics:

METRIC	FORMULA	IN WORDS	EXPRESSION
		"Probability that" Or "How often the"	
True Positive Rate (TPR) sensitivity recall	TP	subject who is positive will be called positive	Pr( C = 1   Y = 1)
True Negative Rate (TNR) specificity, 1-FPR	TN	subject who is negative will be called negative	Pr( C = 0   Y = 0)
Positive Predictive Value (PPV) precision	TP	subject called positive will actually be positive	Pr( Y = 1   C = 1)
Negative Predictive Value (NPV)	TN TN + FN	subject called negative will actually be negative	Pr( Y = 0   C = 0)

## **Example applications for evaluation choice**

- 1. App to classify cats vs. dogs from images?
- 1. Classifier to find relevant tweets to list on website?
- 1. Detector for tumors based on medical image?

# **ROC Curve (across thresholds)**



#### Area under ROC curve

(also called AUROC or AUC or "C-statistic")

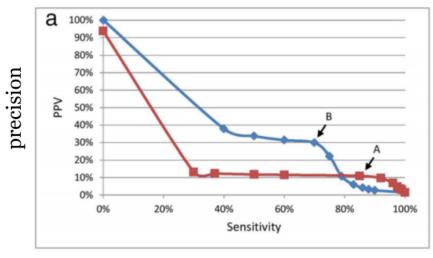
- Area varies from 0.0 to 1.0
- 0.5 is random guess
- 1.0 is perfect

• Probabilistic meaning:

$$AUROC \doteq Pr(\hat{y}_i > \hat{y}_j | y_i = 1, y_j = 0)$$

For random pair of examples, one positive and one negative. What is the probability that the classifier will rank the positive one higher?

#### **Precision-Recall Curve**

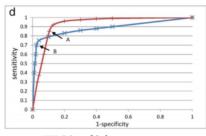


recall (= TPR)

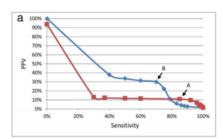
## AUROC not always the best choice

Why the C-statistic is not informative to evaluate early warning scores and what metrics to use

Santiago Romero-Brufau<sup>1,2\*</sup>, Jeanne M. Huddleston<sup>1,2,3</sup>, Gabriel J. Escobar<sup>4</sup> and Mark Liebow<sup>5</sup>



AUROC: red is better



Blue much better for alarm fatigue

# **Summary of Methods**

Methods	Function class flexibility	Knobs to tune	Interpret?
Logistic Regression	Linear	L2/L1 penalty on weights	Inspect weights
Decision Tree Classifier	Axis-aligned, Piecewise constant	Max. depth, Min. leaf size, Goal criteria	Inspect tree
K Nearest Neighbors Classifier	Piecewise constant	Number of Neighbors, distance metric, how neighbors vote	Inspect neighbors

In [ ]: