AI Assignment - I!

Of Enplain the concept of realionality in the content of cintelligent agents. How does realionality relate to the behaviour of agents in their environment? Provide examples to illustrate your explanation.

And Pationality requires to the ability of an agent to make decisions that are enjected to manimize its schances of achieving its goals, given the available info and resources.

Hers how rationality related the agent behaviour is goal directed behaviour: Rational agents are driven by goals on objectives they aim to acheine. Their actions are selected based on their assessment of how likely those actions are to bring them closes to their goals.

(ii) decision making under uncertainity: in many real world scenation agents don't have complete information about their environment on the outcome of their action. Rational agents make decision to by weighting the available evidence asserting the possibilities of different outcome.

(iii) Adaptation to changing environments: Environments

are often dynamic and reational agents need to adapt their behaviour accordingly. This adaptarion involves continuously updating their believes and strategies based on new information and experience.

av) Trade effer and resource constraints: Rational agents must often make trade off due to livil de computations power. (v) Learning and improvement? Rational agents can lean prom past enperiences to improve their future decision making. This bearing process involves indentifying pattern in donte, adjusting strategies and refining their their models of the environment. Pationality January Manager A your directed behaviour. rdecision making.

Adaptation

Tradepple and resource construct. Hearing and impron. Q2HAm Characteristics Description Description Enamples was the po whealed ahers Gully access to complete info.
about the estate of observable), self driving can the envisionment (particly) Deterministic Whether the outcome of Chers (determine) action is entirely predilable weather unumber to worth fe 10 forecastice. by suncertainty in (Stochart) The outcome.

epistatic maze navigation dishether each interaction between the agent and 141 . The environment is self contained on if there is a sequence of action and status Dynamic Whether the environments Francial market, change over time with response to agent actions on external factors (dynamic), Robotics (dynamide Spaces are finite or count ably infinite. Piscrete Board game (dort) Robetics (contrue) Enamples of different Environment. Environment type Enample Board game Chess, go Vast search spaces Optimal decision making under un certaining. Marufacturi g Robotics senson perception, poits planning, object manipulation. NEP level speech lenteral understanding, a programme ambiguity. resolution

Is The typical component of Al agent include: Auf is Perception: This component is responsible for sensing and ferceiving the environment. It gathers information from sensor like data inputs on software agent (i) Actuation: The actuation component enables the agent to interact with the environment It consists of effectors which are mechanism through which the agent can evert water or influence ets surboundings. (iii) knowledge Base : This component stones the agents internal representation of the world, including its beliefs, goals, plan and past enperiences. This knowlede base is essent at for Civ Reasoning Decision making : I the reasoning component processes information from the perception module and the knowledge base to make decision and choose actions that are expected to achieve the agents just (v) barning / Adaptation: Intelligent agents can lean from experience and adapt their behaviour our time. Some common types of agents used in the along with their application: (i) Reactive Agents: There agents make decisione based solely on the durent purcept. The don't maistain justical solate or model of the

GI Deliberate Agents: Deliberate agents maintain an internal representation of the world and cuse snasoning and planning to make decision. decision. Whodel based agents: Model based argents maintain an explicit model of the environment which other was to asimulate spassible future states cand out comes. cand out comes. (iv) Utility based agents: Altility based agents make decisions by evaluating the utility of different action and selecting the one that manimises expected utility. (v) Learning agents: Improve their payormara one time by hearing from experience Intelligent Agents 1 Knowledge band Porception Actuation 1 Reactive Agents Reasoning L decision making. bearing ! Adaptation Model based | Agents Deliberate

and the structure of the structure of the RH And Duttine of process of problem solving by searching.

(1) Problem Formulation: Problem solving agents bigin by defining the problem they had to solve. This involves indentifying the initial state, the possible actions on operator available to the agent, good state or slate that the agent aim. (ii) Problem representation: Once the problem is formulated, problem solving agent represent it in a suitable formalism such a a state space a graph on a set of logical proposition (iii) Search strategy selection: Problem solving agents then choose a search strategy to explore the problem space and find a solution. Adution. (iv) Everch process: Begin the search forum the initial state and systemmatically employees the problem space by applying the chosen search strategy. (v) Solution the construction: Once the goal solution is reached. The publican solution bothing agent reconstructs the solution path by tracing back the sequence of actions on states that lead to the goed. Ulustratue Example: (1) Pathfinding in a Maze: · Problem formulation: initial estate (starty position in the waze) action (movement, in Jour direction - up, down, left, right goal state distination in the ward

" search istrategy: Depth first search on breadth search to explore the maze and find a path from the initial state to the good stall

Example solution: The agent implores the maze by moving from one position its another, avoiding obstacles until it reaches the goal position.

Problem formulation!

Problem Representation!

[Search Strategy Selection!

[Search process!

[Solution Reconstruction!