Appendix C

MATLAB's Simulink Tutorial

Figure C.1
MATLAB Command
Window showing how
to access Simulink.
The Simulink Library
Browser button is
shown circled

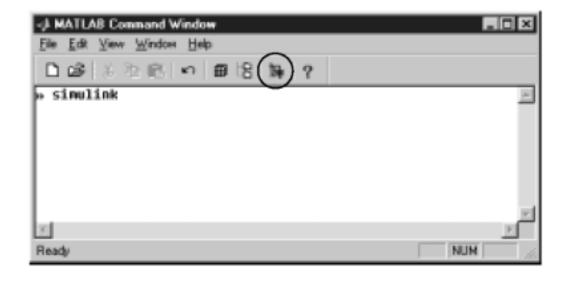


Figure C.2 **Simulink Library Browser** window showing: a. the Create a new model button encircled; **b.** resulting untitled model window

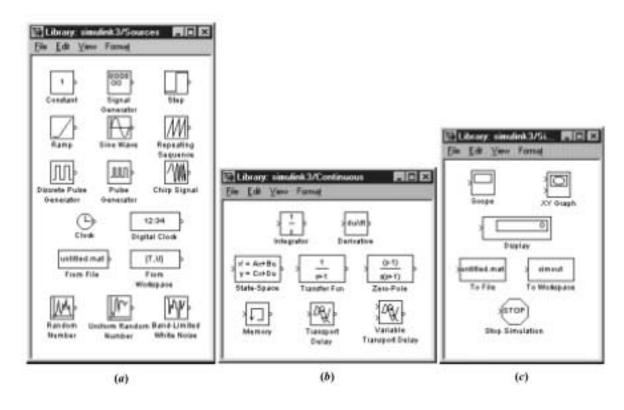




Figure C.3

Simulink libraries:

- a. sources;
- **b.** continuous systems;
- c. sinks



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Figure C.4 Simulink Block Library window

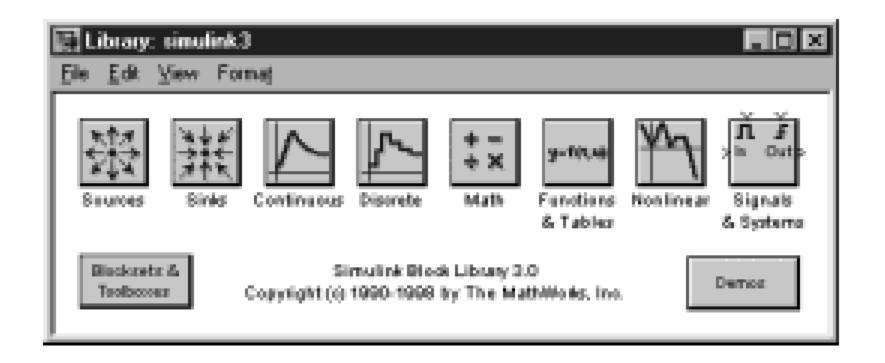


Figure C.5
Simulink block
diagram for
Example C.1

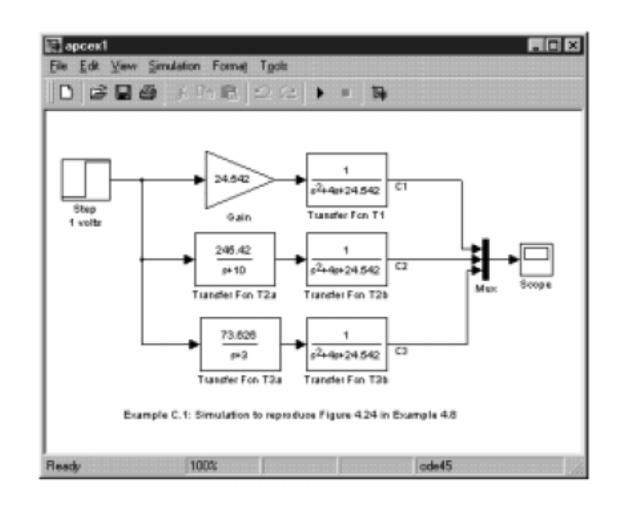
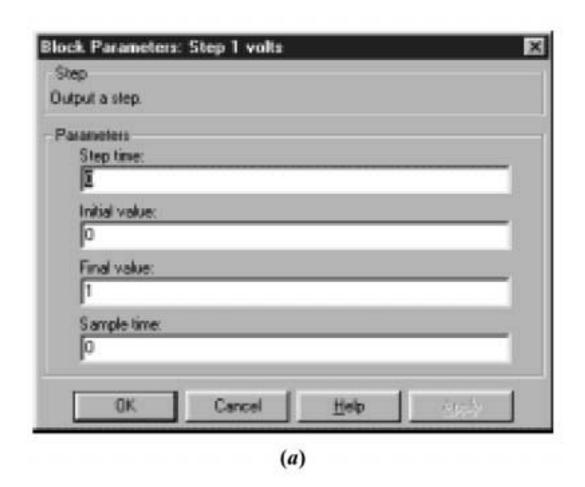


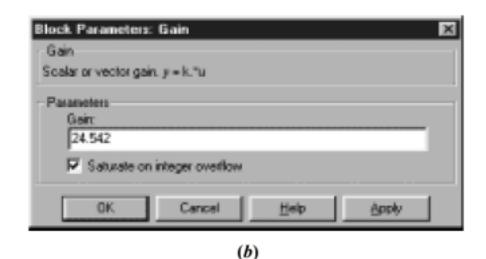
Figure C.6
Block Parameters
windows for:
a. 1 volt step source;
(figure continues)



Appendix C: MATLAB's Simulink Tutorial

Figure C.6 *(continued)*

- **b.** gain;
- **c.** transfer function 1;



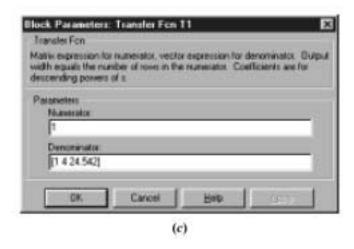
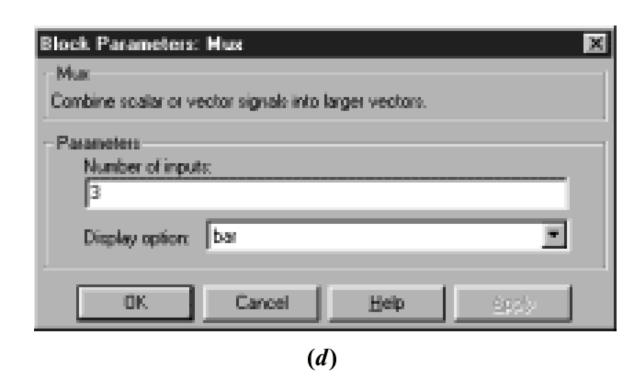


Figure C.6 (continued) d. mux



Appendix C: MATLAB's Simulink Tutorial

Figure C.7 Windows for the scope: a. Scope; b. 'Scope' properties, General tab; c. 'Scope' Properties, **Data history** tab; d. 'Scope' properties: axis 1

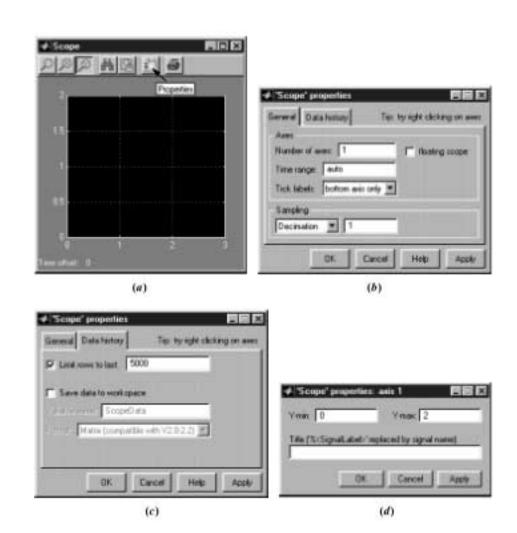


Figure C.8
Simulation
Parameters
window
for Solver
tab



Figure C.9
Scope window
after Example C.1
simulation stops

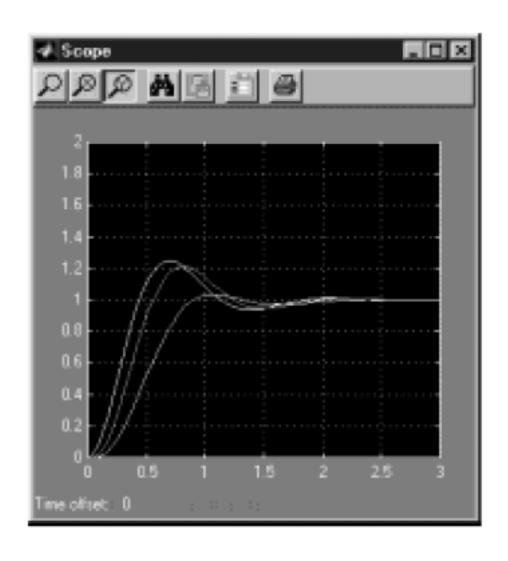


Figure C.10
Simulink block
diagram for
Example C.2

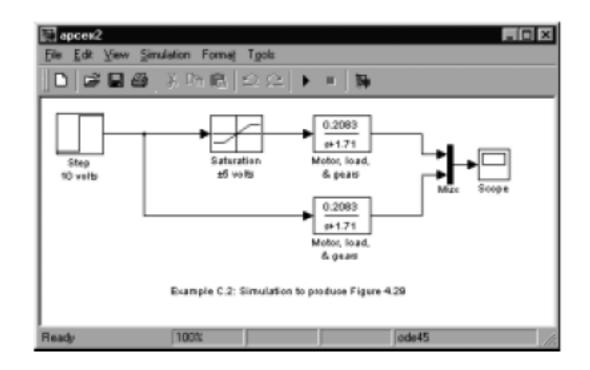
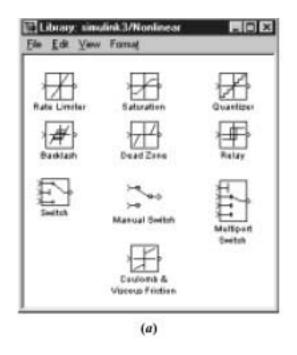


Figure C.11

- **a.** Simulink library for nonlinearities;
- **b.** parameter settings for saturation



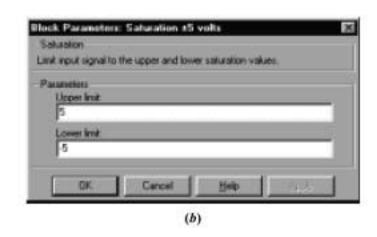


Figure C.12
Scope window after simulation of Example C.2 stops. The bottom curve is the output with saturation

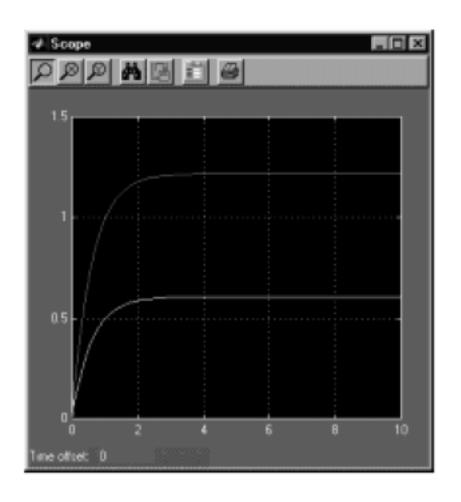
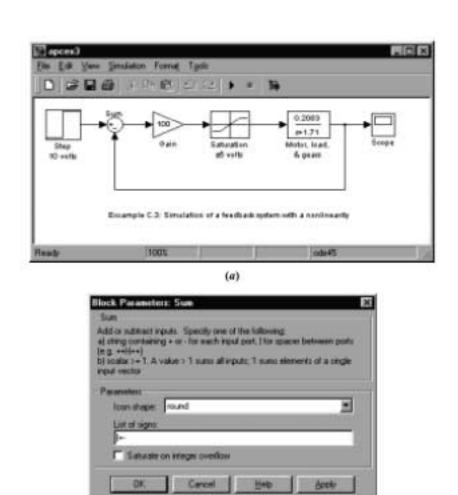


Figure C.13 a. Simulation block diagram for a feedback system with saturation; **b.** block parameter window for the

summer



(b)

Figure C.14
Simulation output
for Example C.3

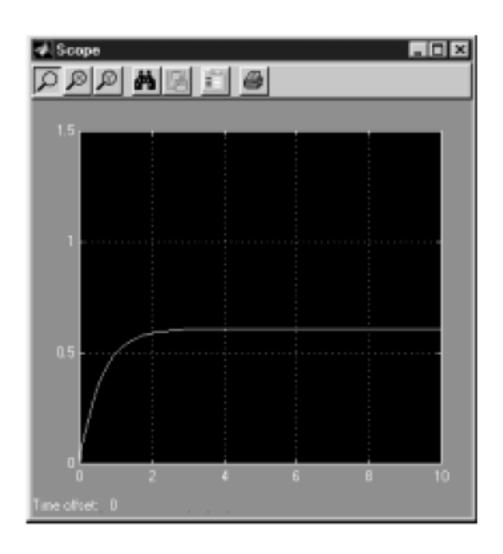


Figure C.15
Simulink block
diagram for
simulating
digital systems
two ways

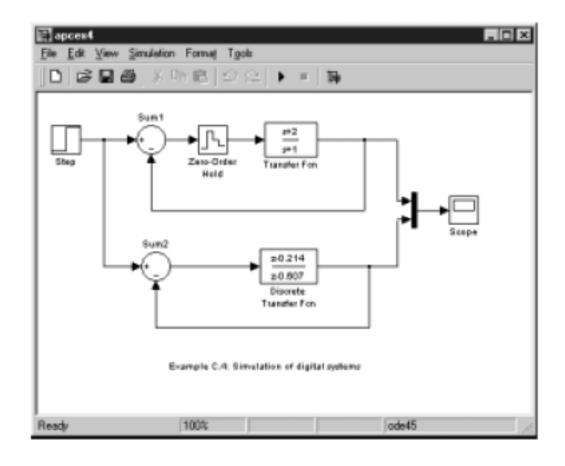


Figure C.16
Simulinks library of discrete parts

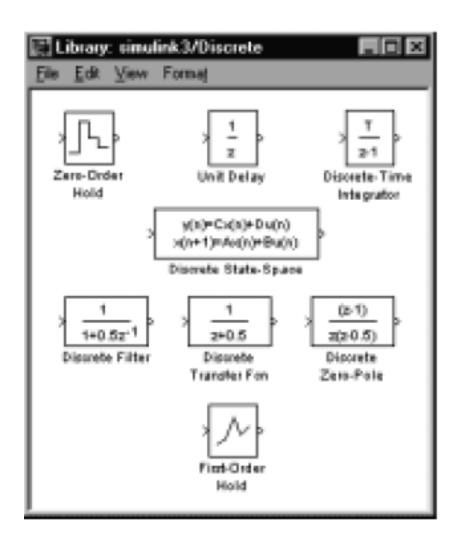
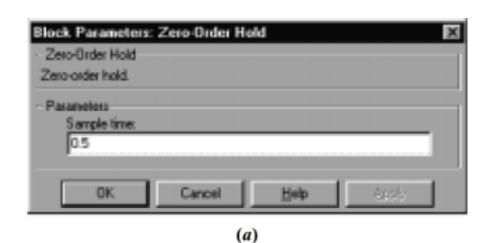


Figure C.17
Block Parameter
windows for:
a. Zero-Order Hold
block;
b. Discrete Transfer
Fcn block



	the number of rows powers of z	in the numerator.	Loencers ae for
Numer	loc		
[1 -0.2	4]		
Denom [1 -0.6			-
Sample 0.5	ine		

Figure C.18
Outputs of the digital systems

