Dynamics of feedbacks in nonequilibrium biodiversity organizational scale

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HTTPS://GITHUB.COM/MELIANOO9/ECOEVON/TREE/MASTER/CCSS2024

References

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Where are we now

Nonequilibrium

Feedbacks

Where are we gonna go

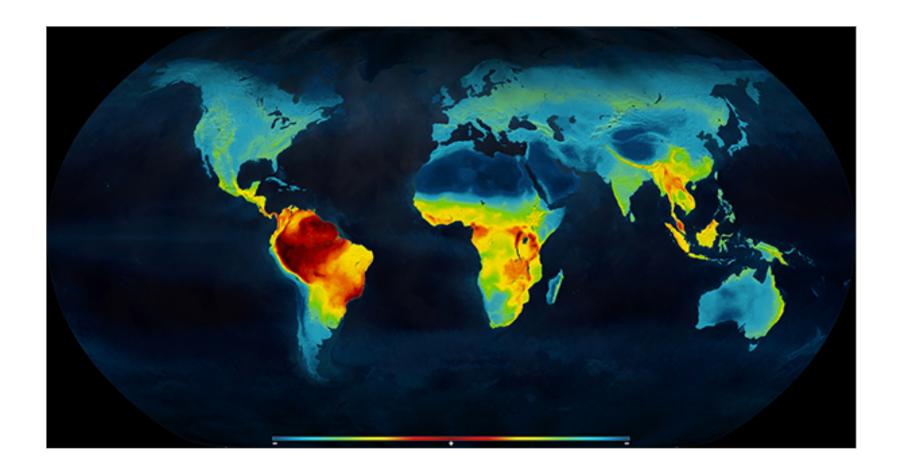
Biodiversity organizational scale

Route to dimensionality

Where are we now

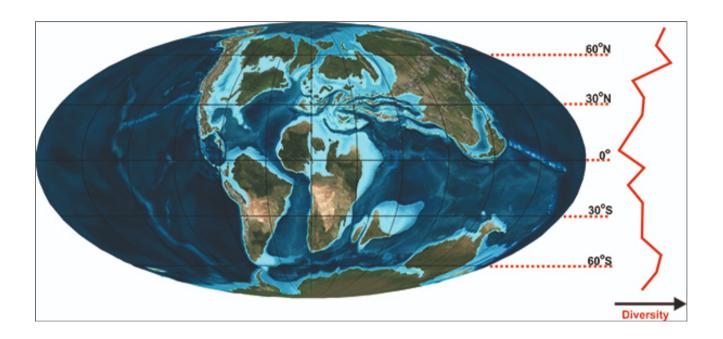


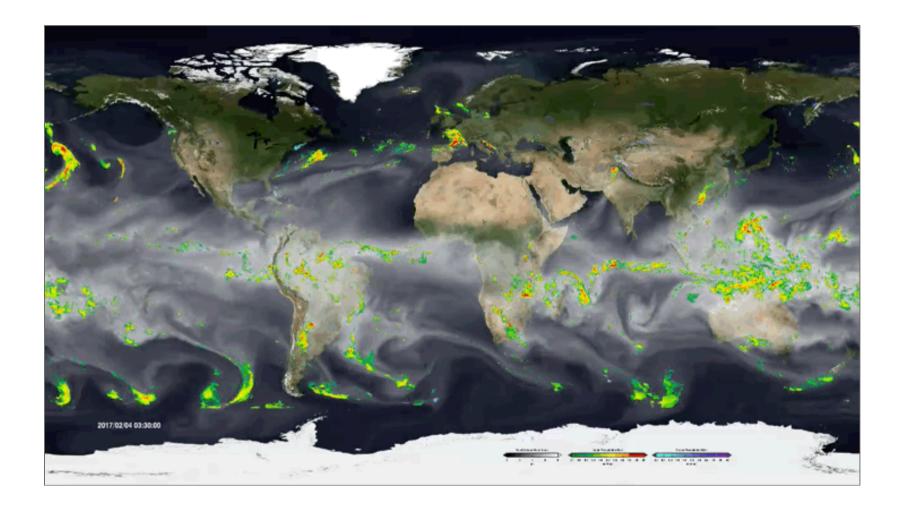
Nonequilibrium



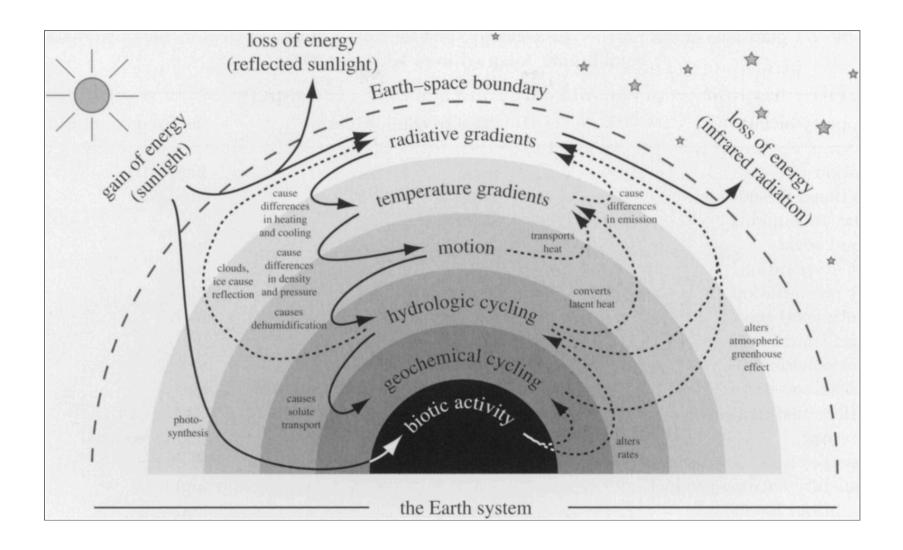
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In [1]: from IPython.display import Video
    Video("./CCSS2024Fig/ContinentalDrift2.mp4", width=1058, height=508)
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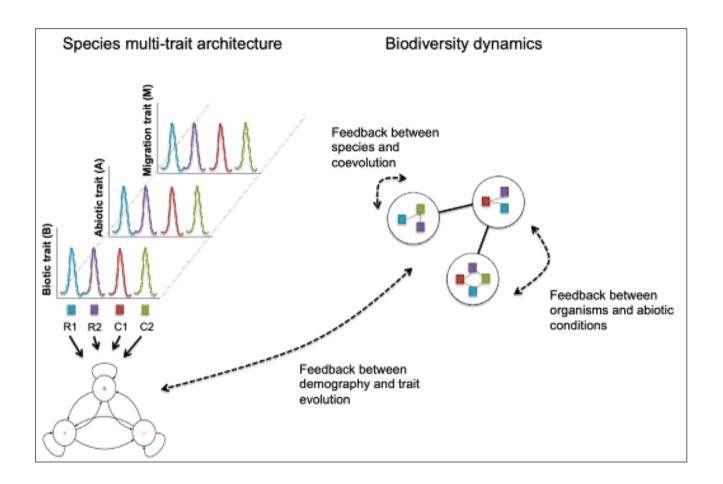
Out[1]:



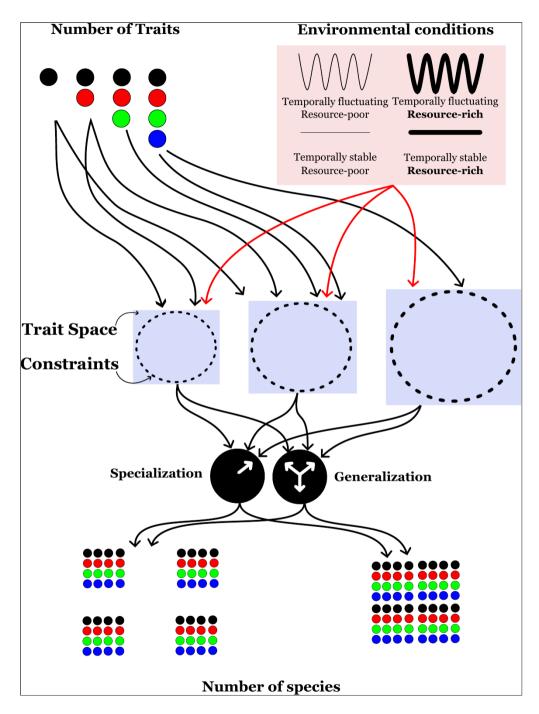


Feedback

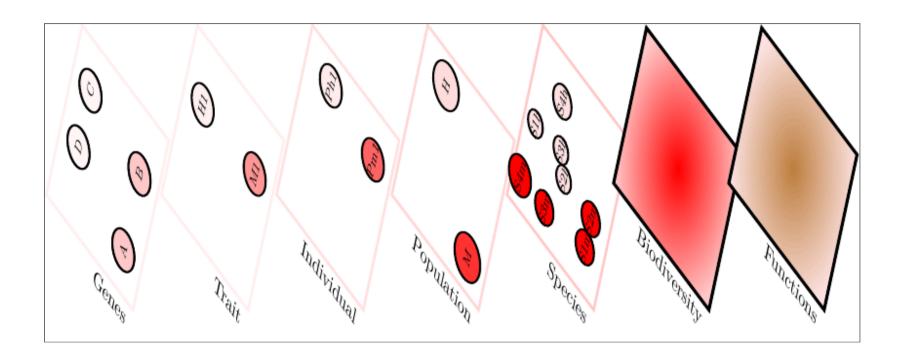


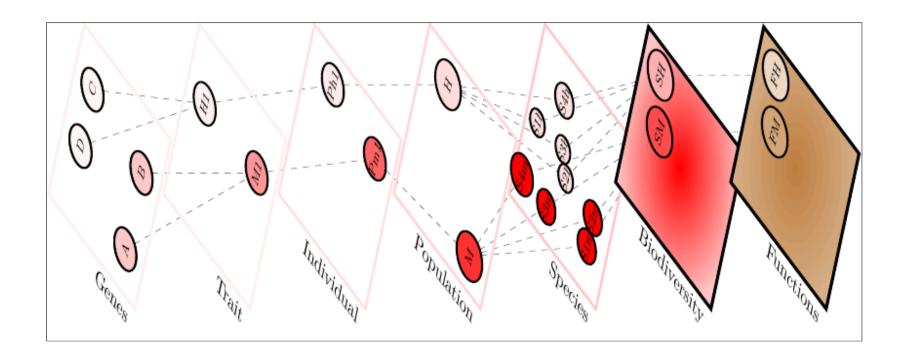


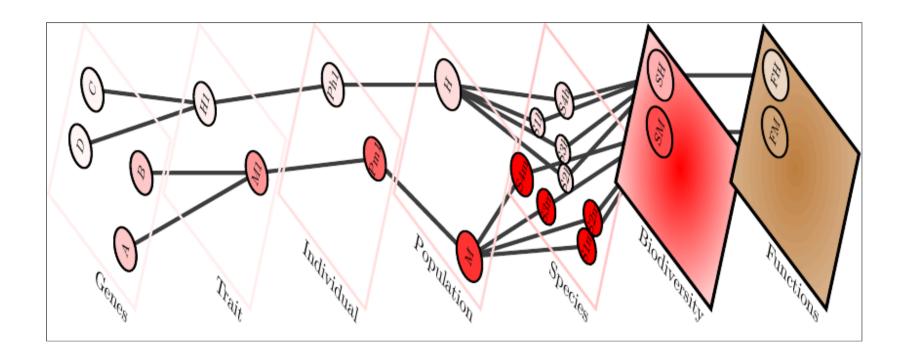
Where are we gonna go

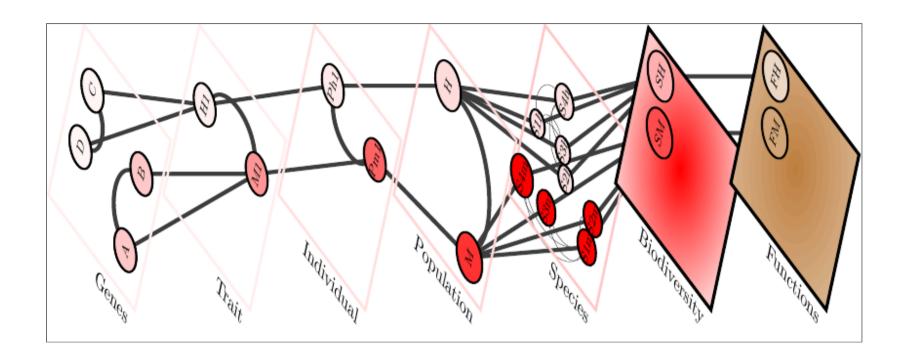


$$\Omega_{\text{BAM}} = \begin{bmatrix} V_B & C_{BA} & C_{BM} \\ C_{AB} & V_A & C_{AM} \\ C_{MB} & C_{MA} & V_M \end{bmatrix} \\
\mathbf{W}(\mathbf{z})_{ix}^t = exp[-\gamma([\mathbf{z}_{ix}^t - \theta^t_{ix}]^T \mathbf{\Omega_{BAM}}^{-1}[\mathbf{z}_{ix}^t - \theta^t_{ix}])] \\
\begin{bmatrix} W(\mathbf{z_B}_{ix}^t) \\ W(\mathbf{z_A}_{ix}^t) \\ \vdots \\ W(\mathbf{z_M}_{ix}^t) \end{bmatrix} = \begin{bmatrix} W(B_{ix}^t)^* \\ W(A_{ix}^t)^* \\ \vdots \\ W(M_{ix}^t)^* \end{bmatrix} \underbrace{\begin{bmatrix} V_B & C_{BA} & \dots & C_{BM} \\ C_{AB} & V_A & \dots & C_{AM} \\ \vdots & \vdots & \vdots & \vdots \\ C_{MB} & C_{MA} & \dots & V_M \end{bmatrix}}_{\mathbf{\Omega_{BAM}}} \underbrace{\begin{bmatrix} W(B_{ix}^t)^* \\ W(A_{ix}^t)^* \\ \vdots \\ W(M_{ix}^t)^* \end{bmatrix}}_{\mathbf{W}}$$



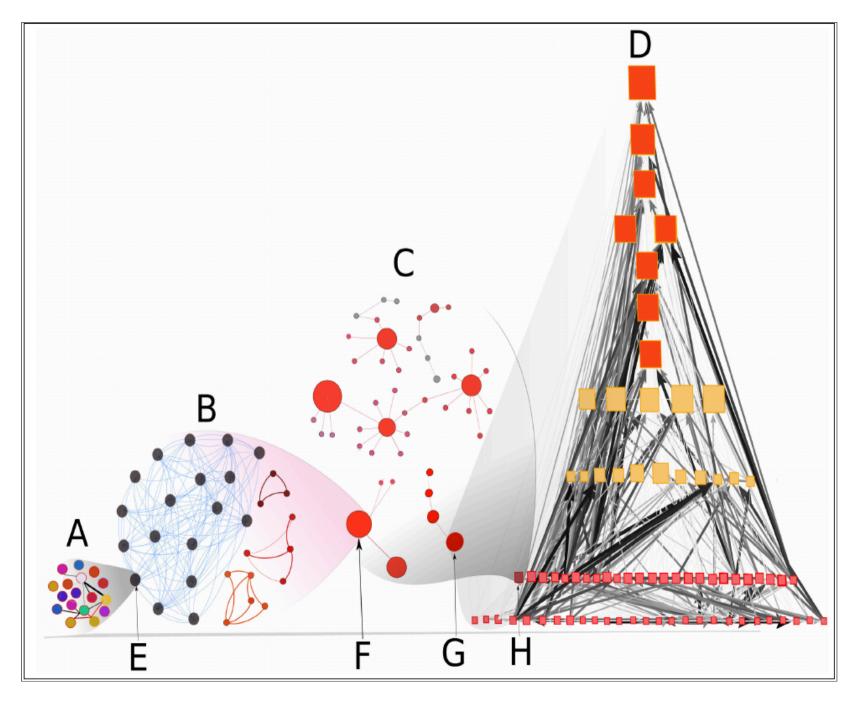


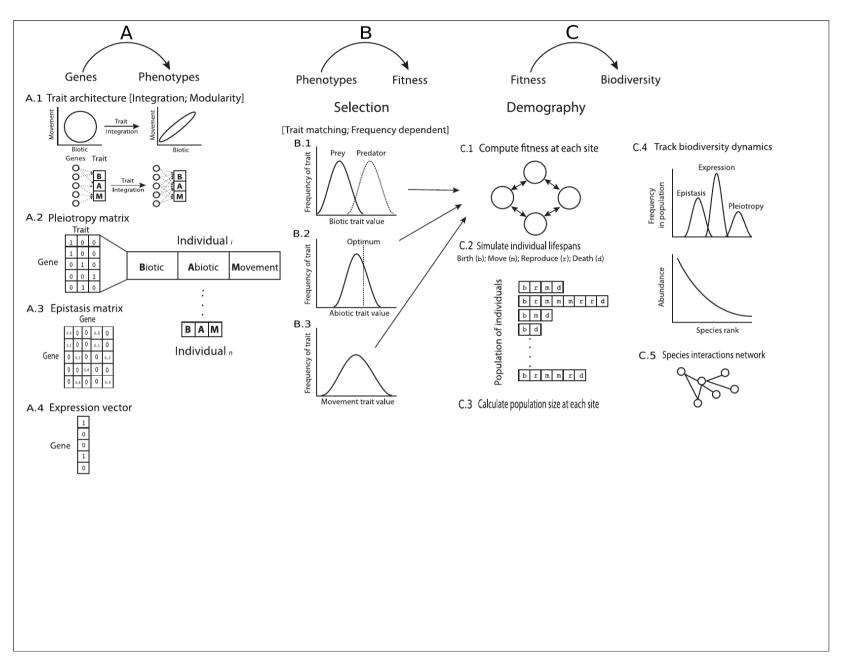




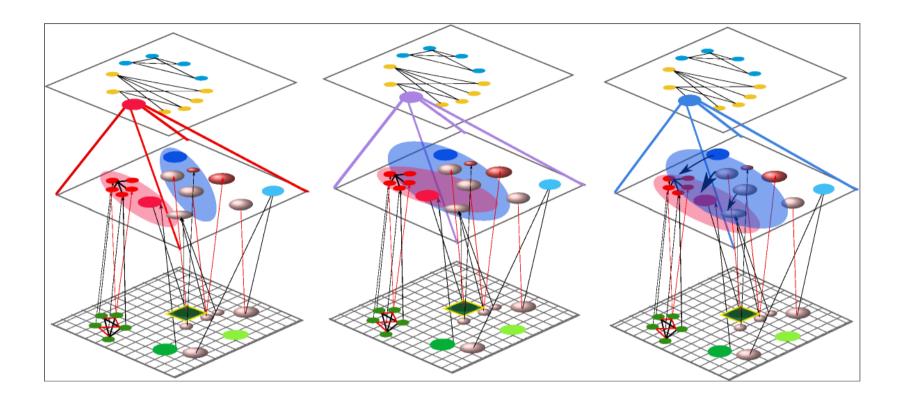
$$egin{aligned} \partial_t
ho(\mathbf{z}, \mathbf{t}) &= -
abla_{\mathbf{z}} ig[
abla_{\mathbf{z}} \mathbf{F}(\mathbf{z}, \mathbf{y_t})
ho(\mathbf{z}, \mathbf{t}) ig] - r(\mathbf{z}, \mathbf{y_t})
ho(\mathbf{z}, \mathbf{t}) \\ &+ \int_{\Omega} \int_{\Omega} M(\mathbf{z} | \mathbf{z}', \mathbf{z}'') \mathbf{B}(\mathbf{z}', \mathbf{z}'')
ho(\mathbf{z}', \mathbf{t})
ho(\mathbf{z}'', \mathbf{t}) \mathrm{d}^{\mathbf{d}} \mathbf{z}' \mathrm{d}^{\mathbf{d}} \mathbf{z}'' \end{aligned}$$

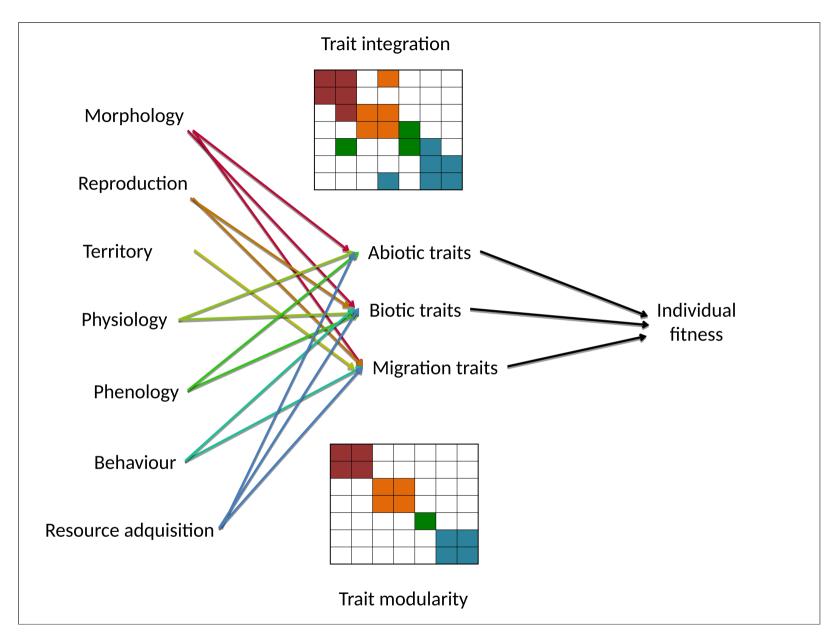
Biodiversity organizational scale





Route to Dimensionality





Complex traits: GPA

$$z_j^i(x,t) = f(\mathbf{L})(x,t), f: \mathbb{R}^m \to \mathbb{R}^z$$
 (1)

In this formulation, an individual's i phenotype in site x and time t is given by

$$\mathbf{Z}^{\mathbf{i}}(x,t) = f(\mathbf{L}) = \mathbf{D}[\mathbf{f}(\mathbf{L})] = \mathbf{BY}, \tag{2}$$

$$\mathbf{Z}^{\mathbf{i}}(x,t) = \mathbf{B}^{\mathbf{T}}\mathbf{E}\mathbf{Y} \tag{3}$$

Abiotic trait

$$D(z_a^i)(x,t) = |0.5 - cdf(\mathcal{N}(\theta_a, \sigma^2), z_a^i)|, \tag{4}$$

where $D(z_a^i)$ is the distance of abiotic trait of individual i to its optimum, θ_a is the optimal value used as the mean of a normal distribution, σ^2 is the variance of the normal distribution, and z_a^i is the value of the abiotic trait i and cdf is cumulative distribution function. The fitness of the abiotic trait of individual i is then given by

$$W(z_a^i)(x,t) = 1 - D(z_a^i)(x,t)$$
 (5)

Biotic trait

$$D(z_b^i z_b^j)(x,t) = |0.5 - cdf(\mathcal{N}(z_b^i, \sigma^2), z_b^j)|. \tag{6}$$

The strength of an interaction is a function of species-species coefficient and the phenotypic distance between the two individuals

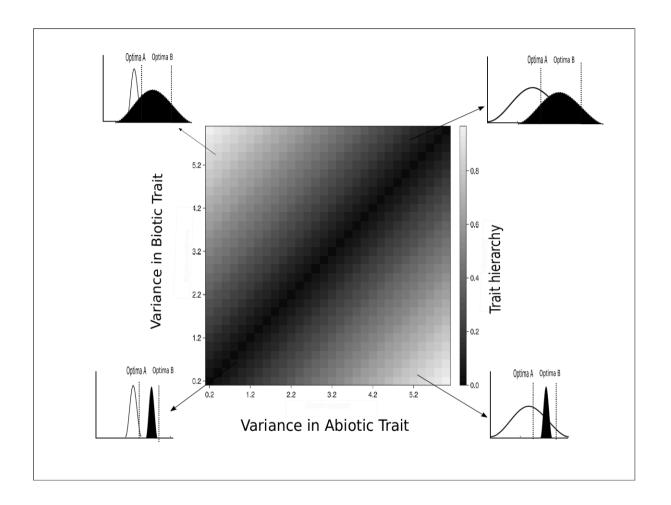
$$s_{z_{b}^{i}z_{b}^{j}}(x,t) = \left(1 - D(z_{b}^{i}z_{b}^{j})(x,t)\right) \times \left|c_{z_{b}^{A}z_{b}^{B}}\right| \times sign(c_{z_{b}^{A}z_{b}^{B}}) \tag{7}$$

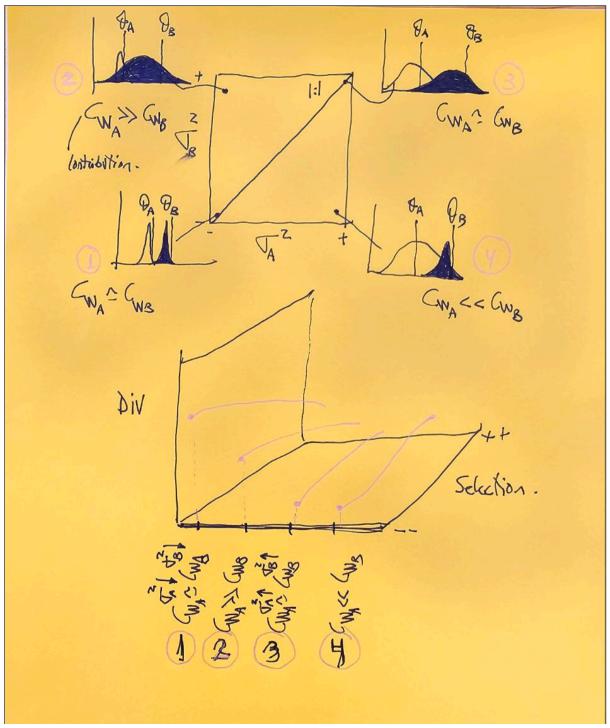
Fitness

$$W(Z^i)(x,t) = W(z_a^i)(x,t) + s_{z_b^i z_b^j}(x,t),$$
 (8)

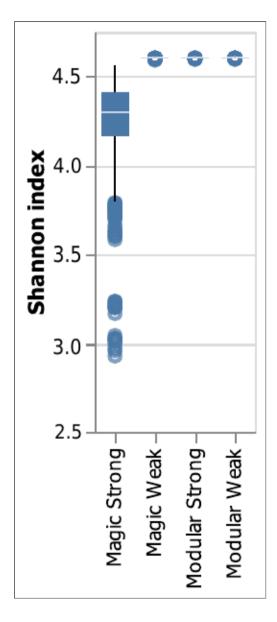
and the fitness function takes into account the selection coefficient as

$$W(Z^i)_{(x,t)} = 1 - ((1 - W(Z^i)_{(x,t)}) \times s_A)$$
 (9)









Take home message

Where are we now

 gap in understanding bb-ba-ab-aa-interactions accounting for nonequilibrium and feedbacks at many spatiotemporal scales

Where are we gonna go

- GPA connecting complex traits to biotic-abiotic feedbacks and diversity patterns
- The route to dimensionality integrating BOS to feedbacks