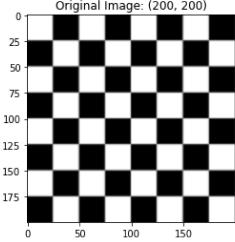
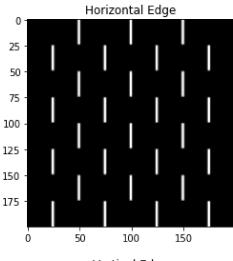
```
import matplotlib.pyplot as plt
import cv2
import numpy as np
import skimage.data as data
```

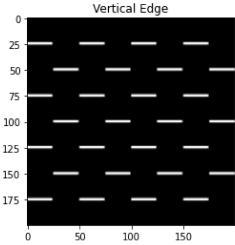
## 6.1

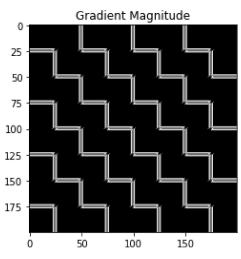


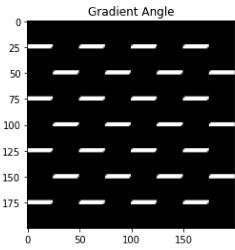
```
In [ ]:
         def sobel_edge_detection(image, filter, verbose=False):
             G_dx = cv2.filter2D(image, -1, filter)
             if verbose:
                 plt.imshow(G_dx, cmap='gray')
                 plt.title("Horizontal Edge")
                 plt.show()
             G_dy = cv2.filter2D(image,-1, np.flip(filter.T, axis=0))
             if verbose:
                 plt.imshow(G_dy, cmap='gray')
                 plt.title("Vertical Edge")
                 plt.show()
             gradient_magnitude = np.sqrt(np.square(G_dx) + np.square(G_dy))
             gradient_magnitude *= 255.0 / gradient_magnitude.max()
             gradient angle = np.arctan2(G dy, G dx)
             if verbose:
                 plt.imshow(gradient_magnitude, cmap='gray')
                 plt.title("Gradient Magnitude")
                 plt.show()
                 plt.imshow(gradient_angle, cmap='gray')
                 plt.title("Gradient Angle")
                 plt.show()
             return gradient_magnitude, gradient_angle
         filter = np.array([[0, 0, 0],
                             [-1, 0, 1],
                             [0, 0, 0]
```

gradient\_magnitude, gradient\_angle = sobel\_edge\_detection(img\_org, filter=filter, verbose=True)









```
6.2
In [ ]:
         img_org = data.moon()
         plt.imshow(img_org, cmap='gray')
         plt.title(f'Original Image: {img_org.shape}')
        Text(0.5, 1.0, 'Original Image: (512, 512)')
Out[]:
                 Original Image: (512, 512)
          0
         100
         200
         300
         400
         500
                 100
                        200
                                    400
                                          500
In [ ]:
         def normalize(img):
              return (img - img.min())/(img.max() - img.min())
        Laplacian
In [ ]:
         def laplacian(img, diagonal=True, ddepth=cv2.CV_64F, default=False, Normalize=True):
              # https://aishack.in/tutorials/sobel-laplacian-edge-detectors/
              if diagonal:
                  filter = np.array((
                                       [-1, -1, -1],
                                       [-1, 8, -1],
                                       [-1, -1, -1]))
              else:
                  filter = np.array((
                                       [0, -1, 0],
                                       [-1, 4, -1],
                                       [0, -1, 0])
              if default:
                  lap = cv2.Laplacian(img, ddepth=ddepth)
             else:
                  lap = cv2.filter2D(img, ddepth=ddepth, kernel=filter)
              # Normalize
              if Normalize:
                  #lap = cv2.convertScaleAbs(lap)
                  lap = normalize(lap)
                  lap = (lap * 255).astype(np.uint8)
```

```
uint8
Out[ ]: Text(0.5, 1.0, 'Laplacian Image: (512, 512), 0, 255')
```

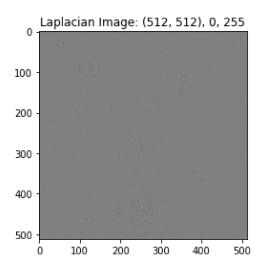
plt.title(f'Laplacian Image: {lap.shape}, {lap.min()}, {lap.max()}')

return lap

print(lap.dtype)

lap = laplacian(img\_org)

plt.imshow(lap, cmap='gray')



## **Sharpening**

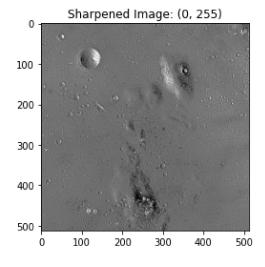
```
def sharpen(img):
    lap_img = laplacian(img, Normalize=False)
    out = img + lap_img
    out = cv2.convertScaleAbs(out)
    out = out.astype(np.uint8)

    return out

sharpened_image = sharpen(img_org)

plt.imshow(sharpened_image, cmap='gray')
    plt.title(f'Sharpened Image: {sharpened_image.min(), sharpened_image.max()}')
```

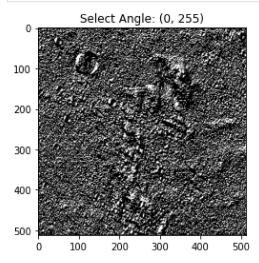
Out[ ]: Text(0.5, 1.0, 'Sharpened Image: (0, 255)')



## 45 degree sharpening

```
plt.imshow(select_angle, cmap='gray')
plt.title(f'Select Angle: {select_angle.min(), select_angle.max()}')
plt.show()

plt.imshow(sharpened_image, cmap='gray')
plt.title(f'Sharpened Image: {sharpened_image.min(), sharpened_image.max()}')
```



Out[ ]: Text(0.5, 1.0, 'Sharpened Image: (0, 255)')

