**DESCRIPTION OF WORK**

**for**

**BLG 506E**

**COMPUTER VISION**

**COURSE PROJECT**

**Project Title**

**Name and number of the Student**

Date

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# EXECUTIVE SUMMARY

In this project, the aim is to classify vehicles in an image. There are two main objectives in this project which will be represented by CV (computer vision) models. Transfer learning methods will be used; therefore, pre-trained models will be evaluated. In summary, Ali Şentaş will be responsible for training the model that detects the vehicle in an image, draws bounding boxes around them and provide these images to the classifier model. Classifier model will be the responsibility of Melik Buğra Özçelik. This model will be trained to classify vehicles based on their types (car, truck, bus etc.).

# INTRODUCTION

In the domain of autonomous driving, the aim is to train vehicles to learn driving without need of a human driver. To do that, an autonomous vehicle should make decisions itself based on the information that it gathers by observing the environment. Without other actors in traffic, it is a relatively easy task to gather information of surrounding structural objects using sensors. However, considering the road line markings and the other moving traffic actors, sensor capabilities themselves are not sufficient. In this case, CV plays an important role to handle this type of a task [ref]. To detect road line markings and the traffic actors, state-of-the-art deep learning-based CV techniques might be useful [ref]. Focusing on detecting the traffic actors -vehicles in the scope of this project- there are two sub tasks. Firstly, the vehicles around should be detected by a CV model and stored in bounding boxes that draws the borders of the vehicle. Secondly, the detected bounding boxes should be fed into another model that classifies the vehicle in it based on its type. For an autonomous vehicle, having the knowledge about the vehicle types around it is very crucial. Because, these vehicles are also moving and making their own decisions, and these decisions also can be clustered depending on their types. Namely, the autonomous vehicle can predict the next actions of the vehicles around. For instance, if the vehicle in front of it is a heavy truck, the autonomous vehicle should always be cautious. In this project, it is aimed to detect the vehicles in an image and classify them based on their types.

# PROJECT DESCRIPTION

The project is

## Goals of Project

List goals of the project

## Impact of Solution

Impact of the solution and their specific expected benefits to the society, individuals, etc.

## SOTA

Provide a brief overview of the similar works worldwide and state of the art.

### Novel contributions

State key differences of your contribution from already available solutions.

## Risk Assessment

Indicate if there are any risks related to technical issues, e.g. risks related to the development of a proposed algorithm. Also, indicate contingency plans in case the risk materializes.

# PROJECT SCOPE

This SOW shall apply to the tasks, services and terms detailed below:

## Work Breakdown Structure (WBS)

[From Wikipedia] The WBS is a tree structure, which shows a subdivision of effort required to achieve an objective; for example a program, project, and contract. In a project or contract, the WBS is developed by starting with the end objective and successively subdividing it into manageable components in terms of subsystems, components and work packages which include all steps necessary to achieve the objective.

Example:

Figure 1 Example Work Breakdown Structure (WBS)

## Work Packages

[From Wikipedia] Similar to a WBS, a WP is part of a Plan Breakdown Structure, representing a collection of work actions necessary to create a specific result. The work package is the lowest level of the WBS where the duration can be reliably estimated.

Example:

|  |  |  |  |
| --- | --- | --- | --- |
| **WP 1** | **<WP Name>** | | |
| Start Date | <e.g. kickoff, M3> | End Date | <e.g. M5> |
| **Objectives:** This work package will cover ... | | | |
| **Tasks**   * *...* * *...* * *...* | | | |
| **Deliverables and Milestones:**  D1.1: ..  D1.2: ...  D1.3: ... | | | |

## Out of Scope

The following are considered OUT OF SCOPE for this contract:

Indicate any related topics out of scope.

# ASSUMPTIONS

Indicate if the project depends on any external material, e.g. certain data/hardware from some other company is needed to progress in the project.

# MILESTONES and DELIVERABLES

Tabulate milestones and deliverables from all work packages.

## Deliverables and Milestone Tables

Example:

|  |  |  |
| --- | --- | --- |
| **Deliverable (D)** | **Description** | **Date** |
| D1.1 | ... | M2 |
| D1.2 | ... | M2 |
| D1.3 | ... | M3 |
| … | … | … |

Table 2 Deliverable Table

|  |  |  |
| --- | --- | --- |
| **Milestone (MS)** | **Date** | **Deliverables** |
| MS1 | M1 | … |
| MS1 | M5 | … |
| … | … | … |

## Project Schedule (Gantt Chart)

Example:

|  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- |
|  | M1 | M2 | M3 | M4 | M5 | M6 | M7 | M8 | M7 | M8 | M9 | M10 | M11 | M12 |
| WP 1 |  |  | D1.1 | D1.2 |  |  |  |  |  |  |  |  |  |  |
| WP 2 |  |  | D2.1 |  |  |  |  |  |  |  |  |  |  |  |
| WP 3 |  |  |  | D3.1 |  |  |  |  |  |  |  | D3.2 |  |  |
| WP 4 |  |  |  |  |  |  |  | D4.1 | D4.2 | D4.3 |  |  |  |  |
| WP 5 |  |  |  |  |  |  |  |  |  |  |  | D5.1 |  | D5.2 |

Figure 1 Gantt chart

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