

Adversarial Auto-Encoders (AAEs) and Wasserstein Auto-Encoders (WAEs)

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April 5, 2018

Jensen-Shannon divergence

Minimize Jensen-Shannon divergence between true data distribution p_d and generative model p_g :

$$\min_G \mathcal{D}_{JS}(p_d(x) || p_g(x))$$

where

$$\mathcal{D}_{JS}(p_d(x) || p_g(x)) = \frac{1}{2} \mathcal{D}_{KL}(p_d || \frac{p_d + p_g}{2}) + \frac{1}{2} \mathcal{D}_{KL}(p_g || \frac{p_d + p_g}{2})$$

Generative Adversarial Networks (GANs)

Minimizing JSD corresponds to finding best G when D is optimal

$$\min_G \max_D V(D, G) = \mathbb{E}_{p_d(x)}[\log D(x)] + \mathbb{E}_{p_z(z)}[\log(1 - D(G(z)))]$$

Min-max game between 2 neural networks

- generator $G(z)$: prior $p_z(z)$ and likelihood $p(x | z)$
- discriminator $D(x)$: predicts probability x comes from p_d , not p_g

Encoder $q(z | x)$, decoder $p(x | z)$. Prior on latent codes $p(z)$.

$$\begin{aligned} \min_q \mathbb{E}_{q(z | x)}[-\log p(x | z)] + \mathcal{D}_{KL}(q(z | x) || p(z)) \\ = \text{Reconstruction} + \text{Regularization} \end{aligned}$$

Adversarial Auto-encoders (AAEs)

- Aggregated posterior

$$q(z) = \int_x q(z | x) p_d(x) dx$$

- Replaces VAE's $\mathcal{D}_{KL}(q(z | x) || p(z))$ regularizer with $\mathcal{D}_{JS}(q(z) || p(z))$

AAE: Adversarial Networks

- Directly minimizing $\mathcal{D}_{JS}(p(z) || q(z))$ is intractable
- \Rightarrow Attach adversarial network on top of z
 - Encoder of autoencoder is also generator of adversarial network

$$G(z) = q(z | x)$$

- Discriminator D distinguishes $p(z)$ (positive samples) from $q(z)$ (negative samples)

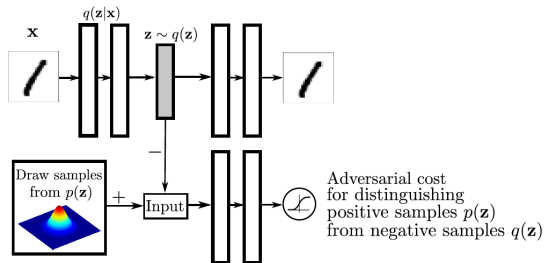


Figure 1: Architecture of an adversarial autoencoder. The top row is a standard autoencoder that reconstructs an image \mathbf{x} from a latent code \mathbf{z} . The bottom row diagrams a second network trained to discriminatively predict whether a sample arises from the hidden code of the autoencoder or from a sampled distribution specified by the user.

Trained by alternately minimizing reconstruction error and training adversarial network

- 1 *Reconstruction phase.* Encoder q and decoder p are trained to minimize reconstruction error:

$$\min_{q,p} \mathbb{E}_{q(z|x)}[-\log p(x|z)] \quad (1)$$

- 2 *Regularization phase.* Adversarial network is trained on GAN objective:

$$\min_q \max_D \mathbb{E}_{p(z)}[\log D(z)] + \mathbb{E}_{q(z|x)}[\log(1 - D(z))]$$

Choice of Encoder q

- Deterministic: q is deterministic function of x
 - may not produce smooth mapping; empirical distribution of data is fixed by training set
- Gaussian posterior: q is Gaussian distribution whose parameters are predicted by encoder network

$$z \sim \mathcal{N}(\mu(x), \sigma(x))$$

- Universal approximator posterior

- Gaussian posterior + universal approximator posterior give network additional sources of stochasticity that could help it in the adversarial regularization stage by smoothing out $q(z)$.
- In practice, authors obtain similar test likelihoods for all 3 choices.

Published as a conference paper at ICLR 2018

WASSERSTEIN AUTO-ENCODERS

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A Quick Review of VAEs

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$$D_{KL}(P_X, P_G) = \underbrace{-\mathbb{E}_{P_X}[\log P_G(X)]}_{\text{negative log-likelihood}} + \underbrace{\mathbb{E}_{P_X}[\log P_X(X)]}_{\text{entropy of data}}$$

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- The NLL cannot be optimized directly, so VAEs use an **upper bound**.

$$NLL \leq \underbrace{\inf_{Q(Z|X) \in \mathcal{Q}}}_{\text{min over all encoders}} -\mathbb{E}_{P_X} \left[\underbrace{\mathbb{E}_{Q(Z|X)}[\log P_G(X|Z)]}_{\text{reconstruction loss}} - \underbrace{D_{KL}(Q(Z|X), P_Z)}_{\text{regularization loss}} \right]$$

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- Take-Away: VAEs **minimize an upper bound on KL divergence** between the data and the model.

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- Alternative way to measure distance between probability distributions
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- Defined with respect to a cost function $c : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}_+$ as

$$W_c(P_X, P_Y) = \inf_{\Gamma \in \mathcal{P}(X \sim P_X, Y \sim P_Y)} \mathbb{E}_{(X, Y) \sim \Gamma} [c(X, Y)]$$

where $\Gamma(x, y)$ is the "transport plan".



Using Wasserstein instead of KL

- The objective is

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- Γ must be some joint distribution of X, Y because
 - $\int_x \Gamma(x, y) dx = P_X(x) \Rightarrow$ Total earth leaving x = total earth at x
 - $\int_y \Gamma(x, y) dy = P_Y(y) \Rightarrow$ Total earth entering y = total earth at y

- Consider a latent space \mathcal{Z} with prior P_Z . We want to find a model (i.e. decoder) $G : \mathcal{Z} \rightarrow \mathcal{X}$ that minimizes the **Wasserstein distance**

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- [Bousquet et al. (2017)]** This is equivalent to minimizing

$$W_c(P_X, P_G) = \underbrace{\inf_{Q : Q_Z = P_Z}}_{\text{min over encoders with marginal } P_Z} \mathbb{E}_{P_X} \underbrace{\mathbb{E}_{Q(Z|X)} [c(X, G(Z))]}_{\text{reconstruction cost}}$$

where $Q_Z = \int Q(Z|X)P_X(X)dX$.

Wasserstein Auto-Encoder

- The **WAE objective** relaxes the constraint $Q_Z = P_Z$ by adding a penalty. It minimizes

$$D_{WAE}(P_X, P_G) = \inf_{Q(Z|X) \in \mathcal{Q}} \mathbb{E}_{P_X} \mathbb{E}_{Q(Z|X)}[c(X, G(Z))] + \lambda \cdot \mathcal{D}_Z(Q_Z, P_Z)$$

where \mathcal{D} is some divergence and λ is some regularization parameter.

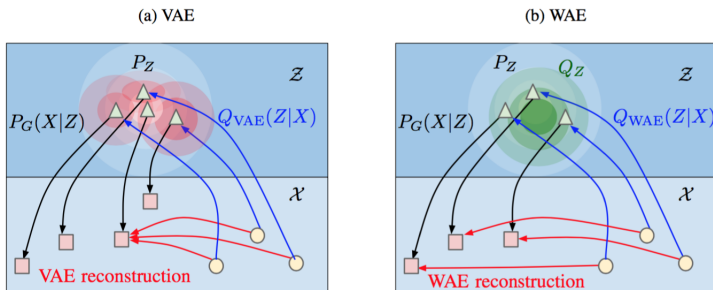
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- Claims to fix **blurriness issue** of VAEs



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WAE-GAN	WAE-MMD
$\mathcal{D}_Z = D_{JS}$	$\mathcal{D}_Z = MMD_k$
Introduce adversarial discriminator in \mathcal{Z}	Use unbiased U-statistic estimator

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 - Theoretical justification of AAE as minimizing 2-Wasserstein distance

- Test VAE, WAE-GAN, WAE-MMD on MNIST and CelebA
- Record Frechet Inception Distance (FID) to assess quality of images

Algorithm	FID
VAE	82
WAE-MMD	55
WAE-GAN	42

Table 1: FID scores for samples on CelebA (smaller is better).

ADVERSARIALLY REGULARIZED AUTOENCODERS

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WASSERSTEIN AUTO-ENCODERS: LATENT DIMENSIONALITY AND RANDOM ENCODERS

Paul Rubenstein*, Bernhard Schölkopf, Ilya Tolstikhin

Empirical Inference

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LEARNING DISENTANGLED REPRESENTATIONS WITH WASSERSTEIN AUTO-ENCODERS

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- Formal English vs. Informal English

Informal: *I'd say it is punk though.*

Formal: *However, I do believe it to be punk.*

Informal: *Gotta see both sides of the story.*

Formal: *You have to consider both sides of the story.*
