

GPS 室内外判别

GPS indoor / outdoor classification

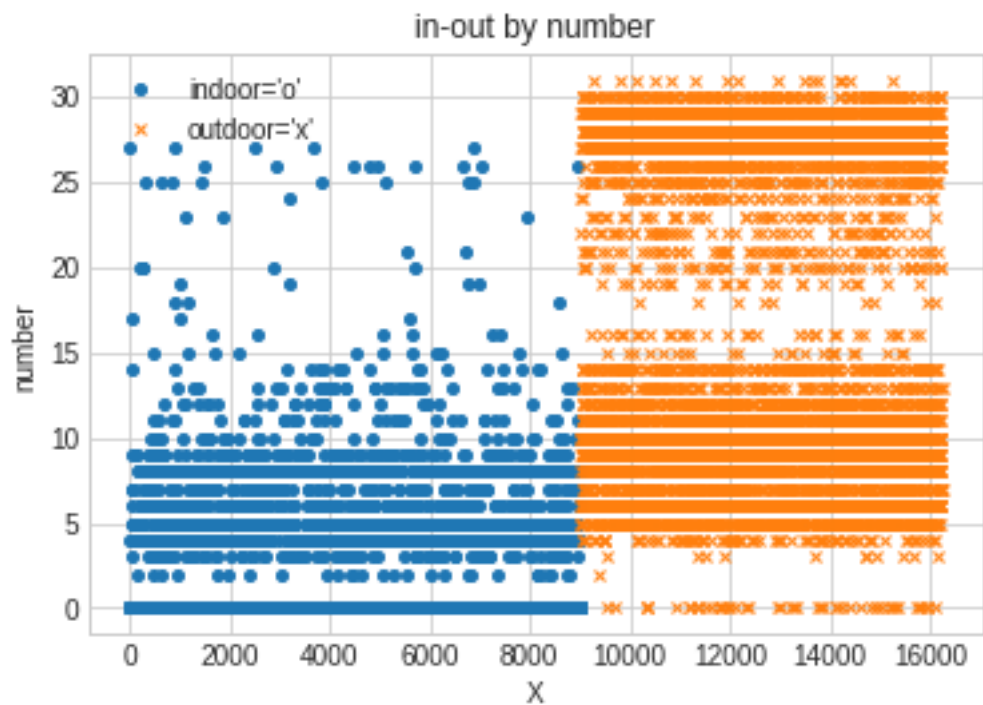
- ▶ 特征分析 feature analysis
- ▶ 模型调试 model trials
- ▶ Notice: for this project, training data & testing data collected by different people. So there is a need to compare the features between them before deciding which model will be suitable.

特征分析 - 采集的数据对比

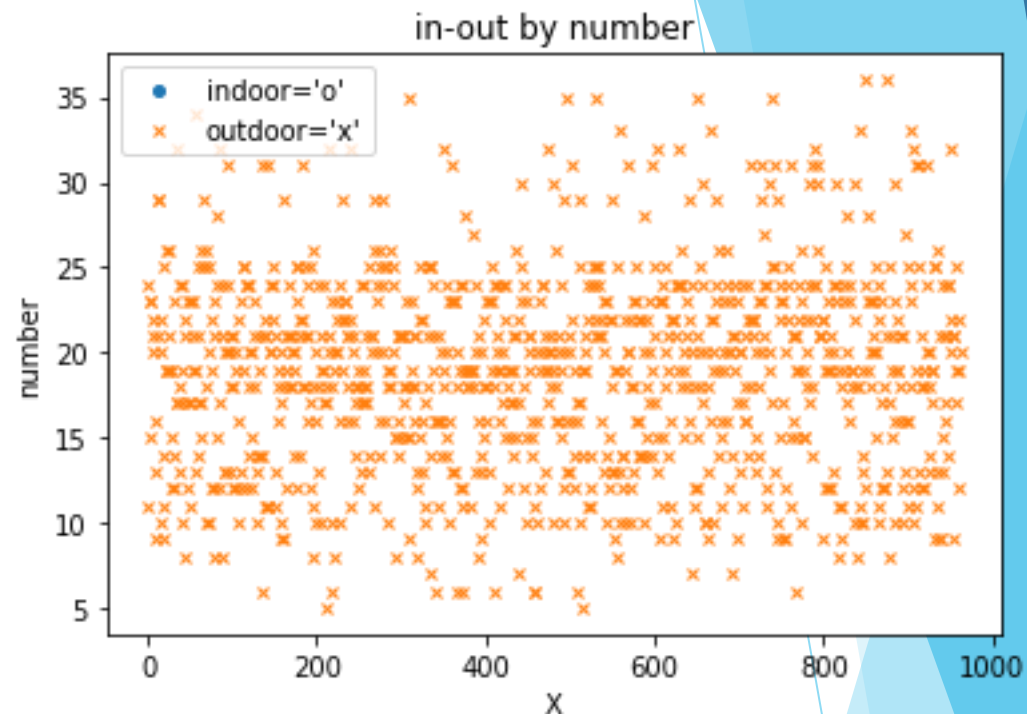
feature analysis, comparisons between training data & testing data

- ▶ 12 个 特征的值域, 分布对比 compare the features between training data & testing data
- ▶ 地铁室外跑 组 the testing data when subway-train running outdoors
- ▶ 地铁站内 组 the testing data when in the subway stations (indoors)
- ▶ 其他 组 other main scenes such as streets, communities, stores, buildings, etc.

地铁室外跑 the testing data when subway-
train running outdoors



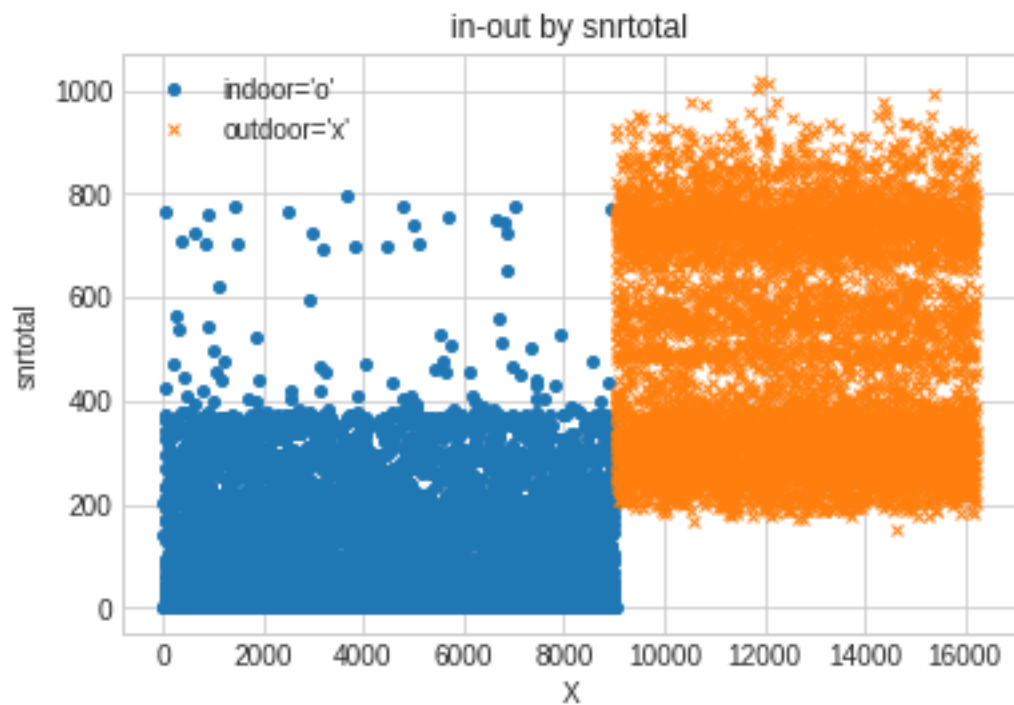
Training data



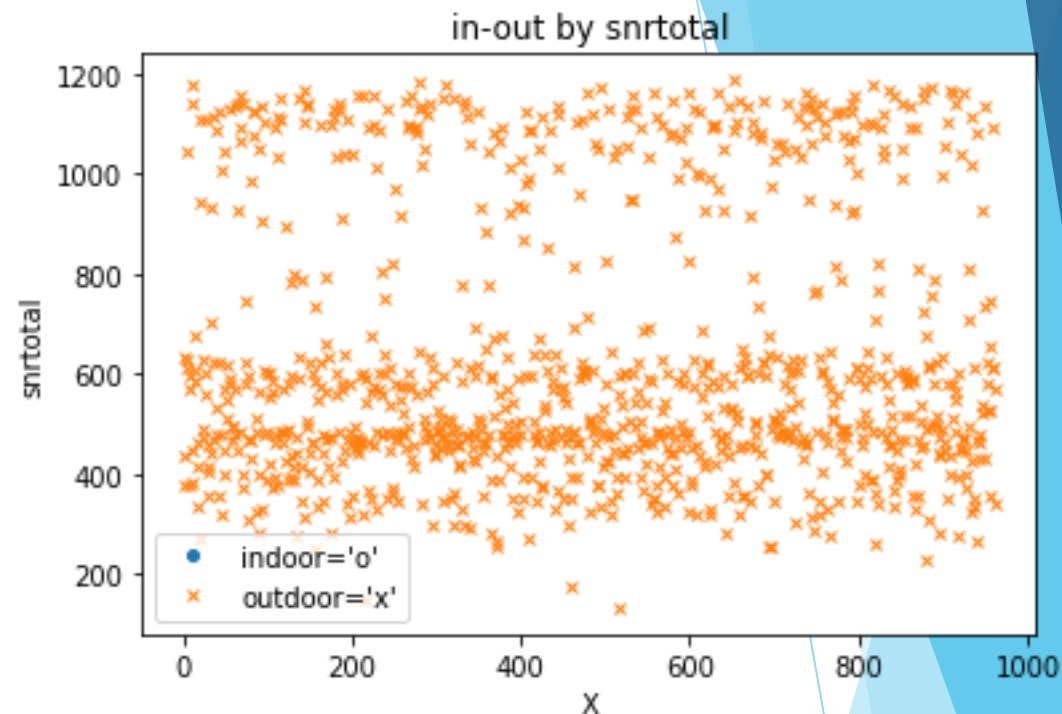
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特征 1 / feature 1

number: 手机将卫星用于定位的数量



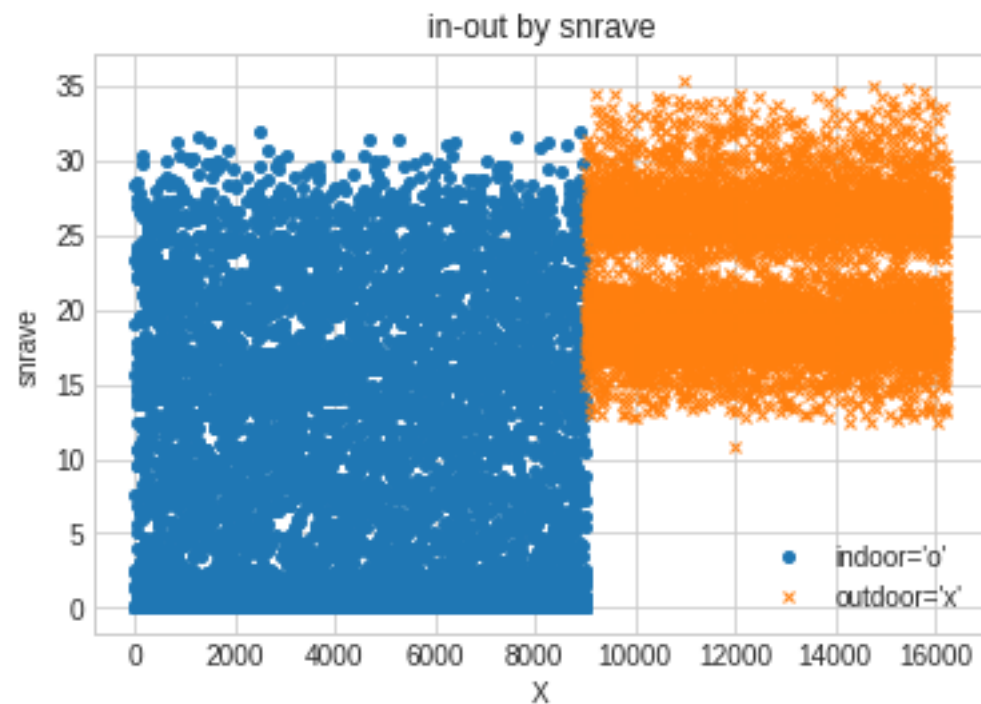
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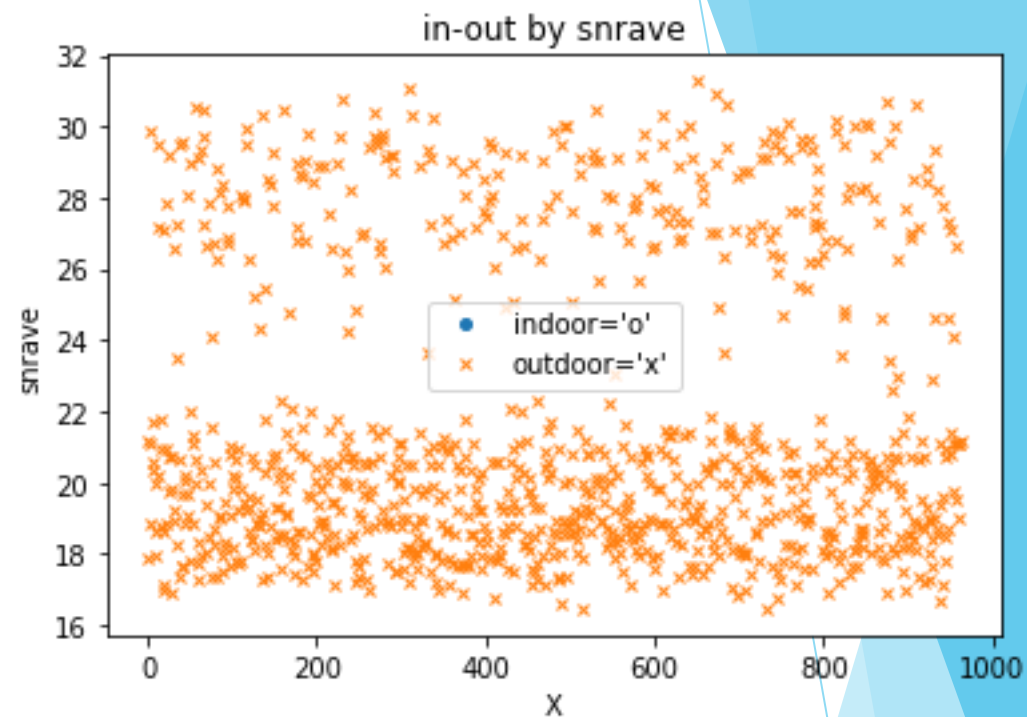
Testing data

特征 2 / feature 2

snrtotal : 所有能检测到卫星的信噪比总和



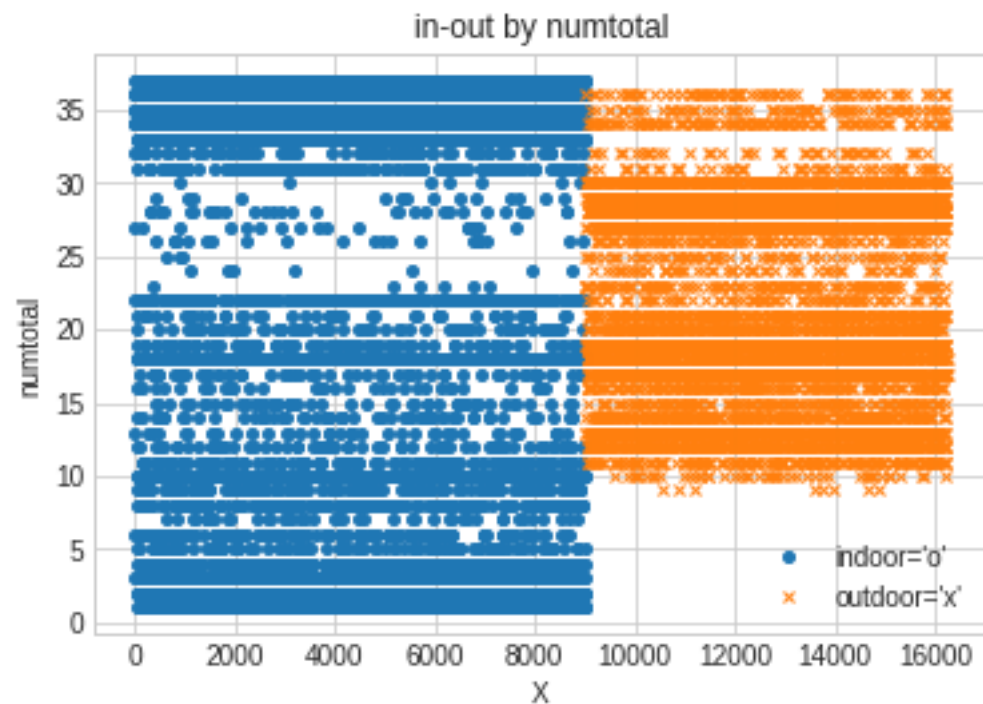
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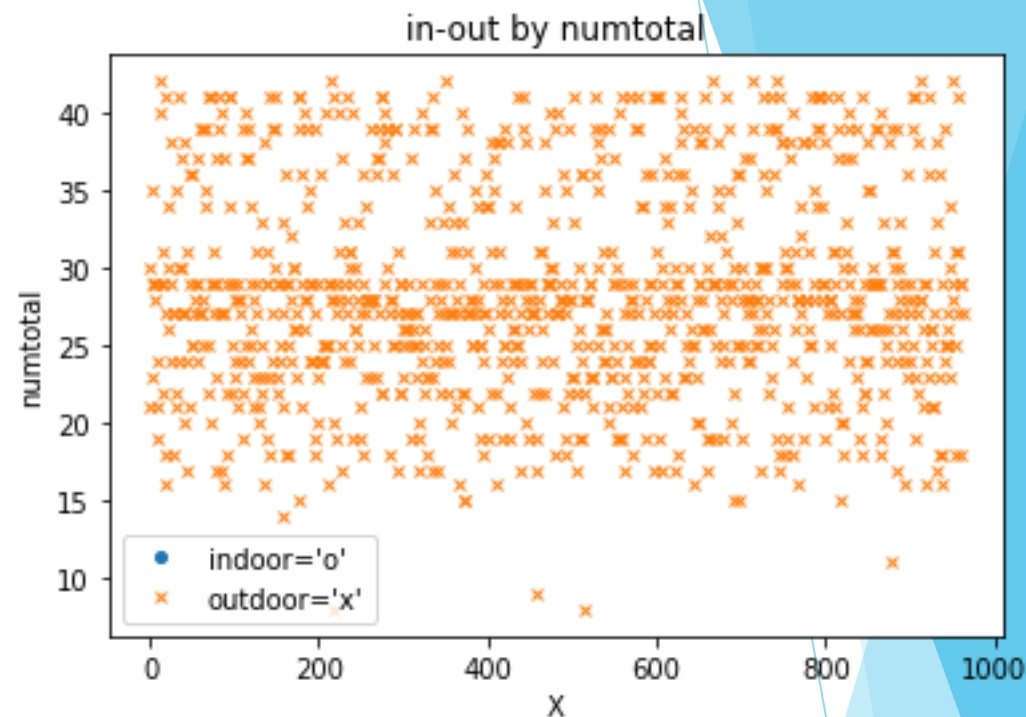
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特征 3 / feature 3

snrave : 所有能检测到卫星的信噪比的平均值



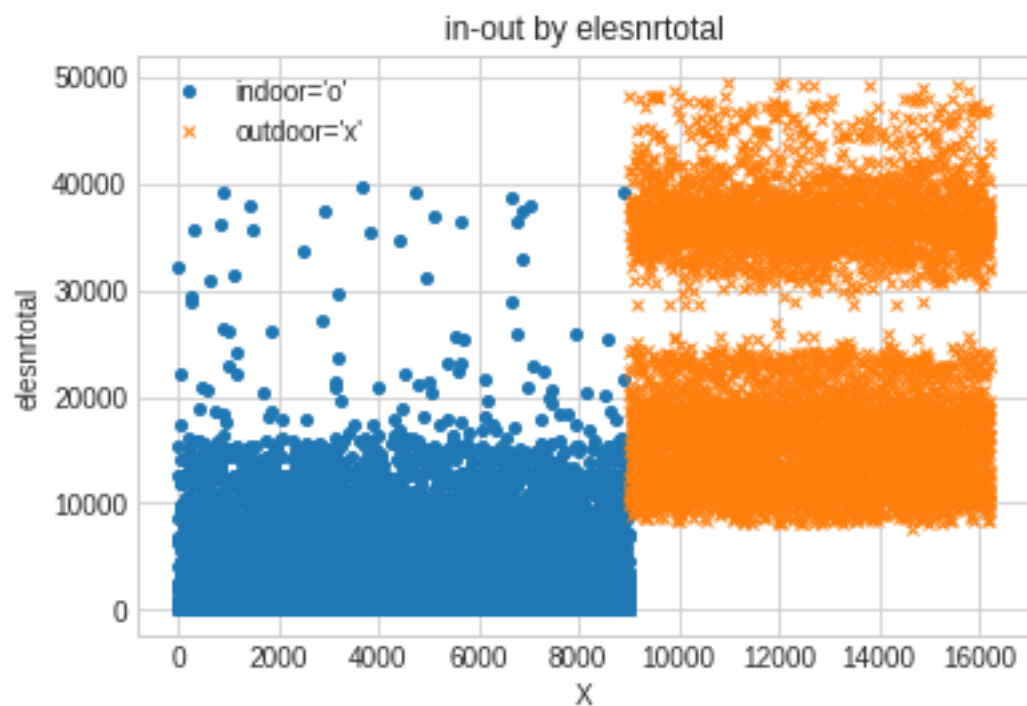
Training data



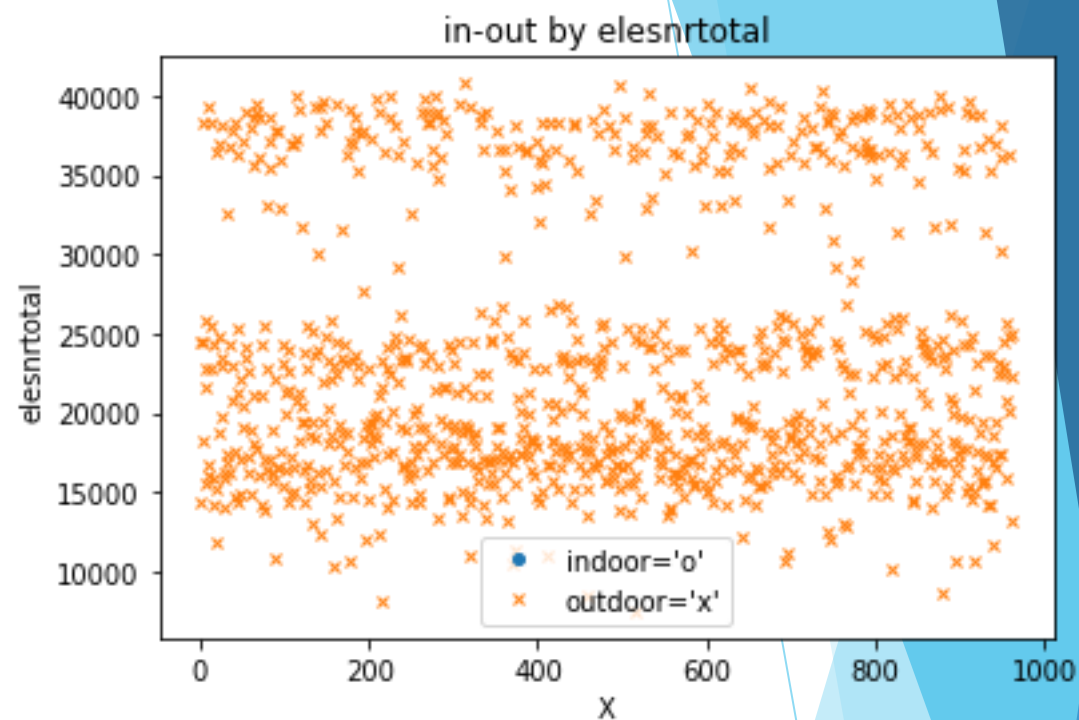
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numtotal : 当前手机所能检测的所有卫星数量 (包括信号强度低的卫星)



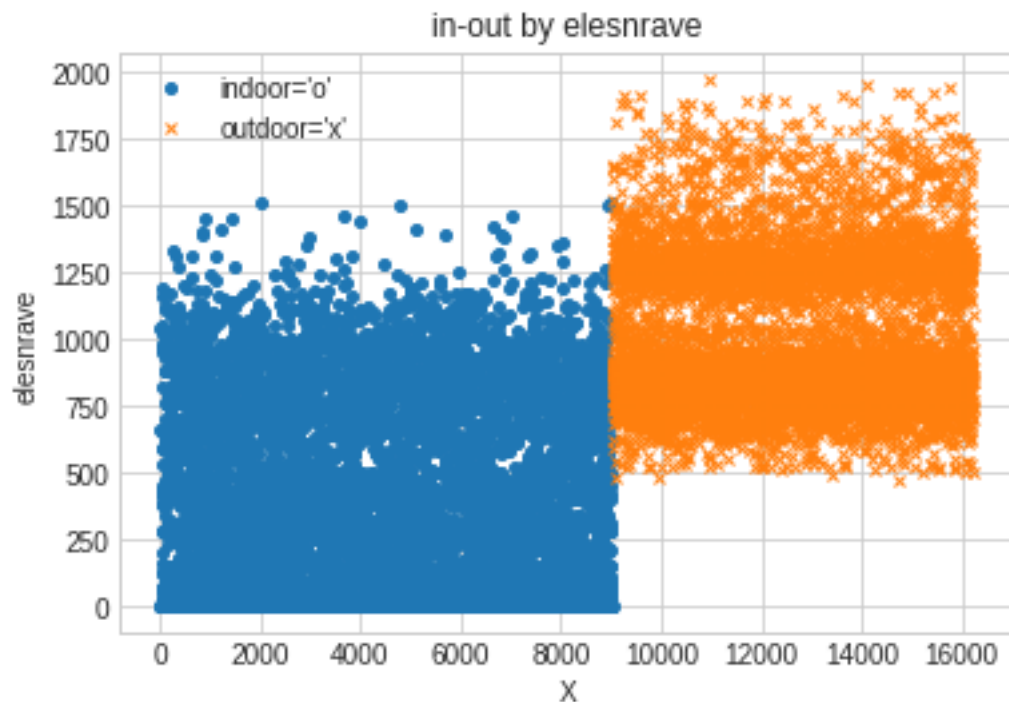
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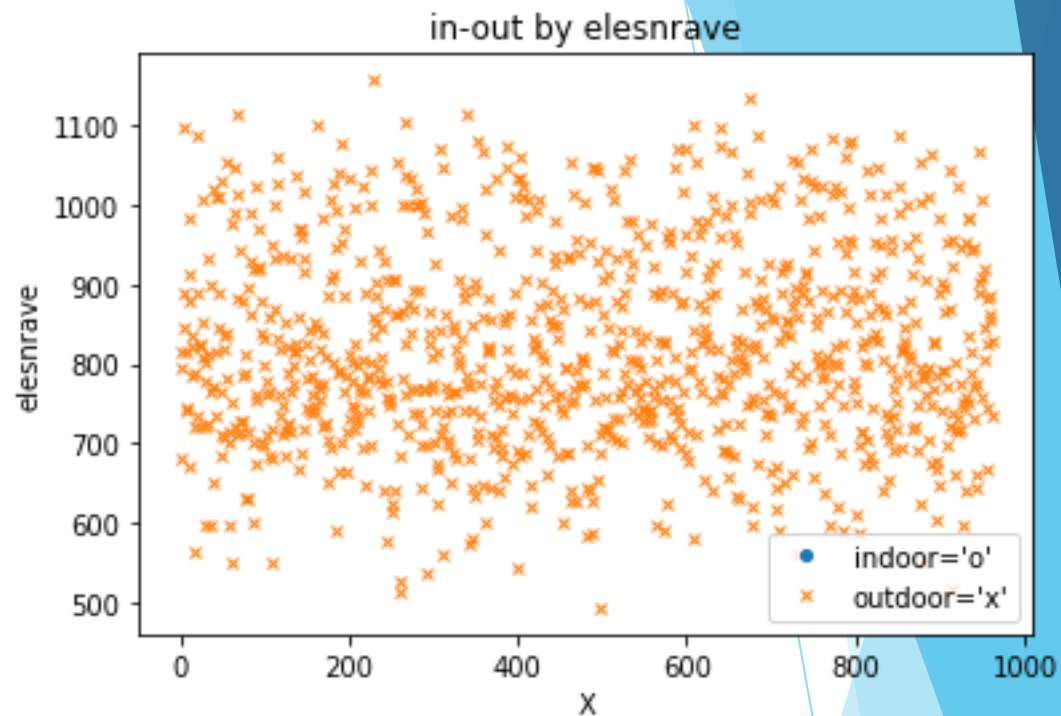
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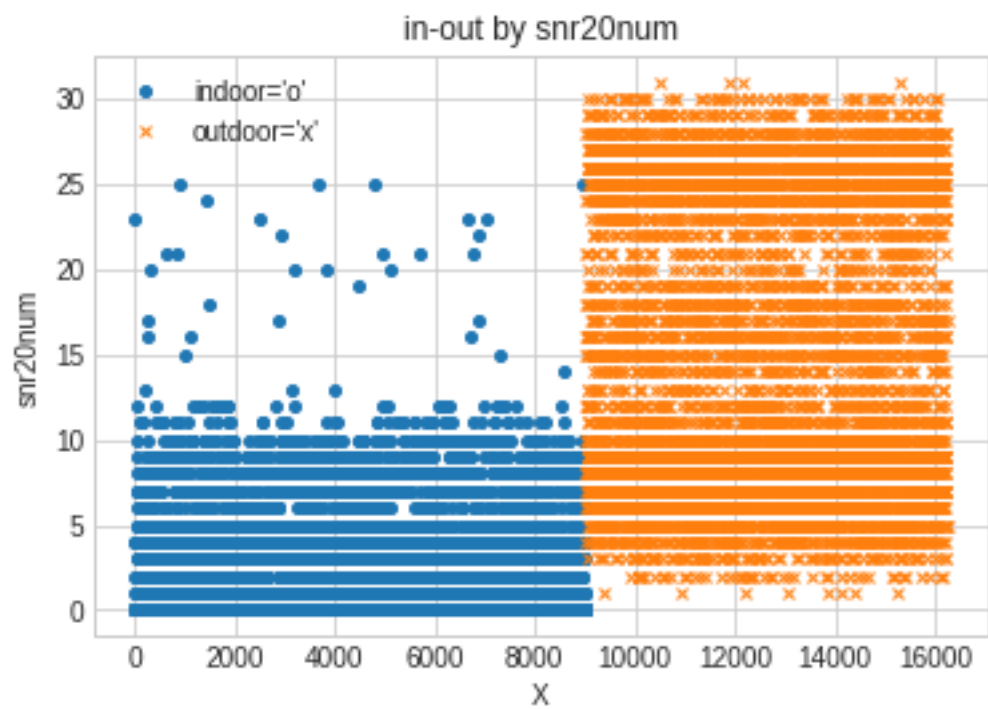
Training data



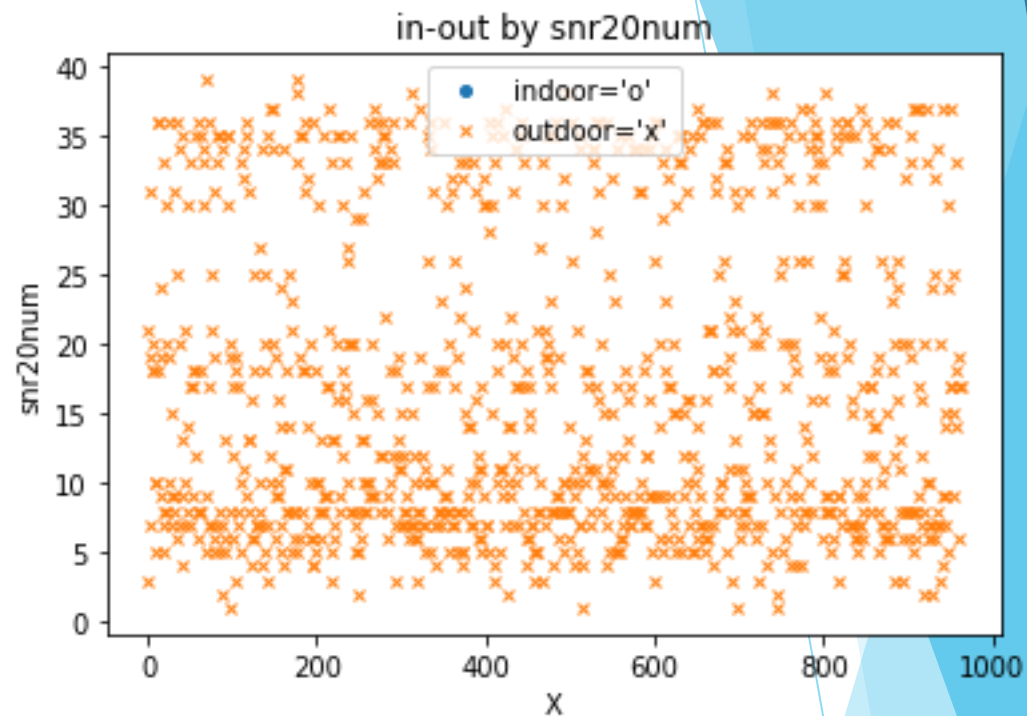
Testing data

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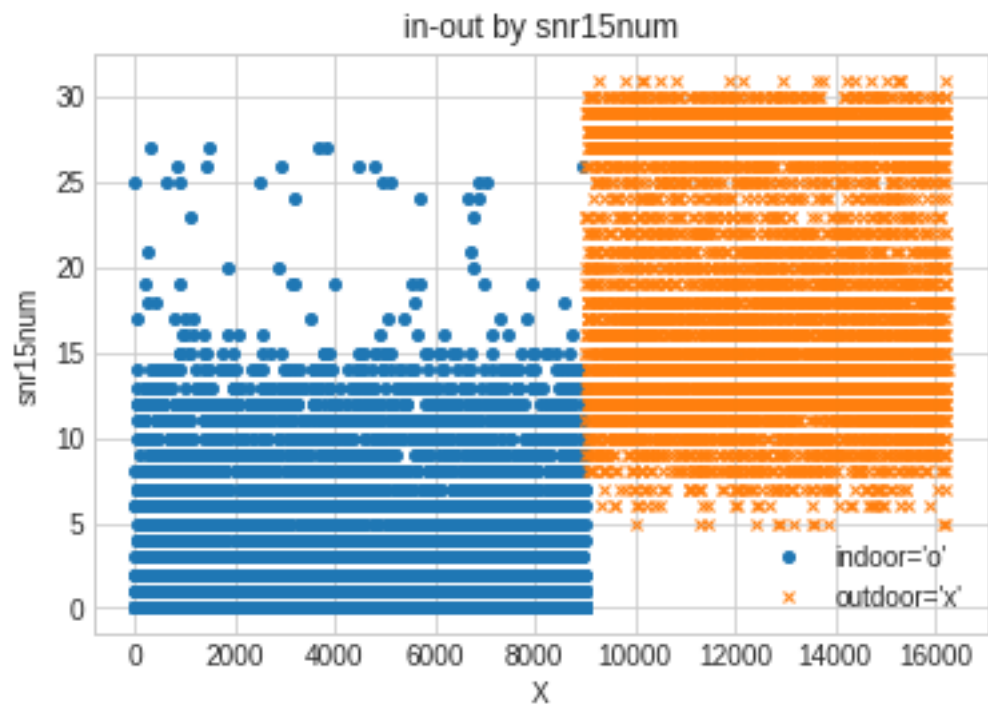
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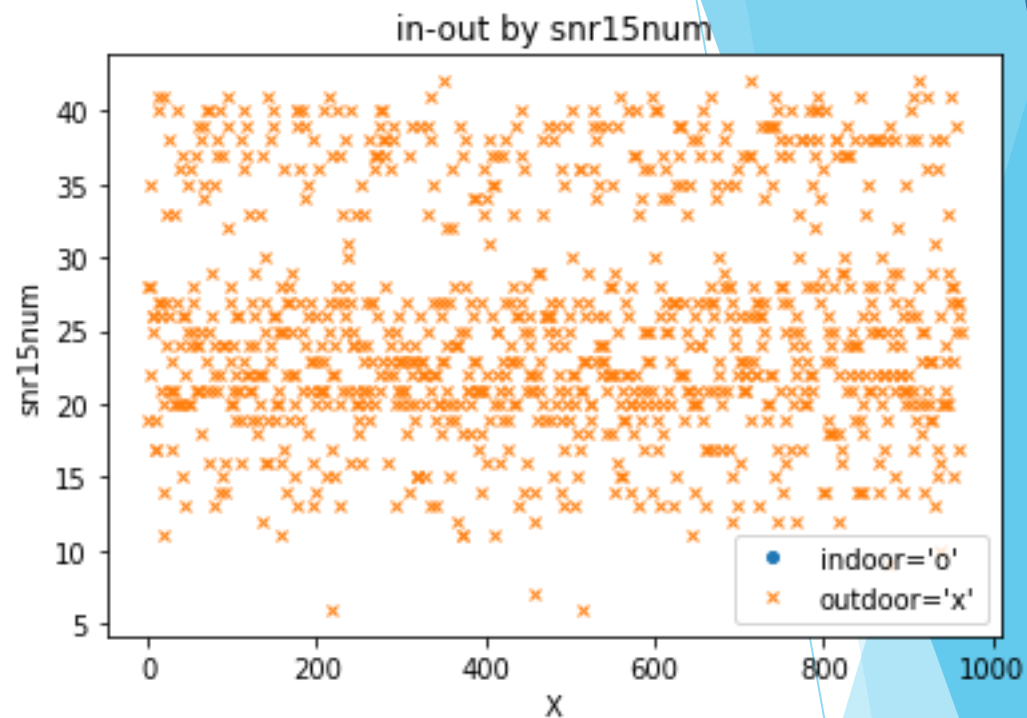
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特征 7 / feature 7

snr20num : 手机检测到信噪比大于等于 20 的卫星 数量



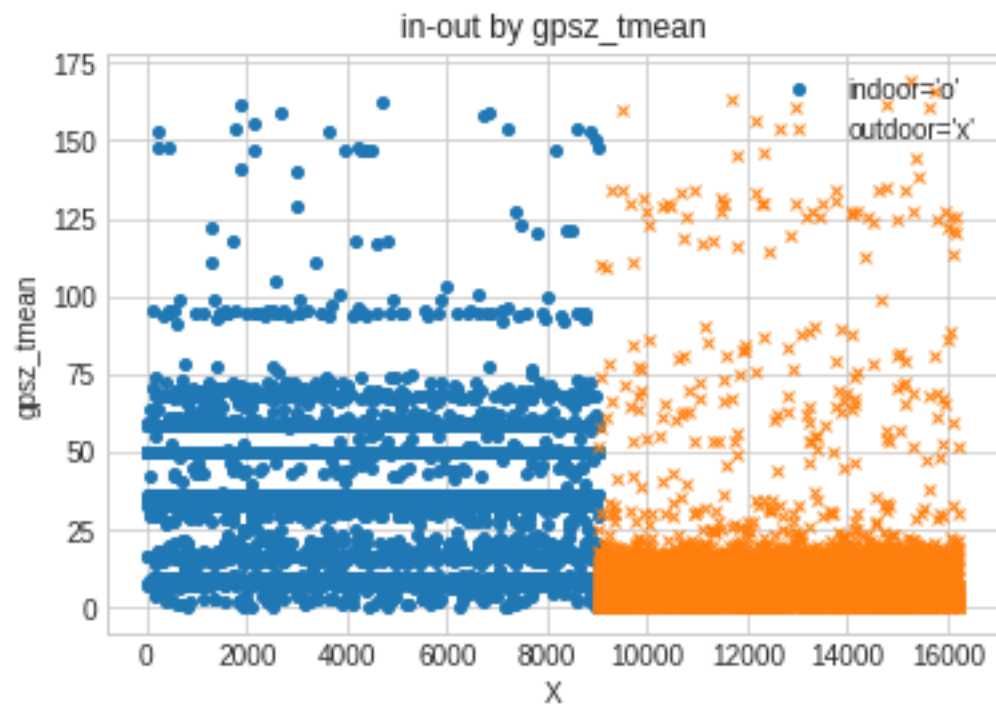
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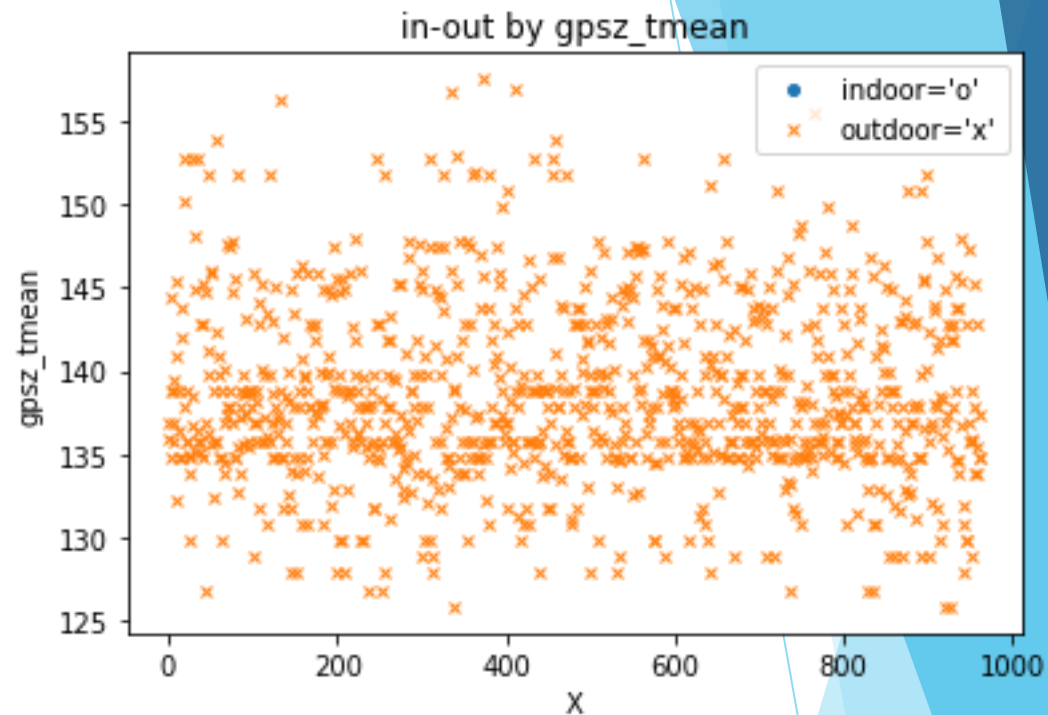
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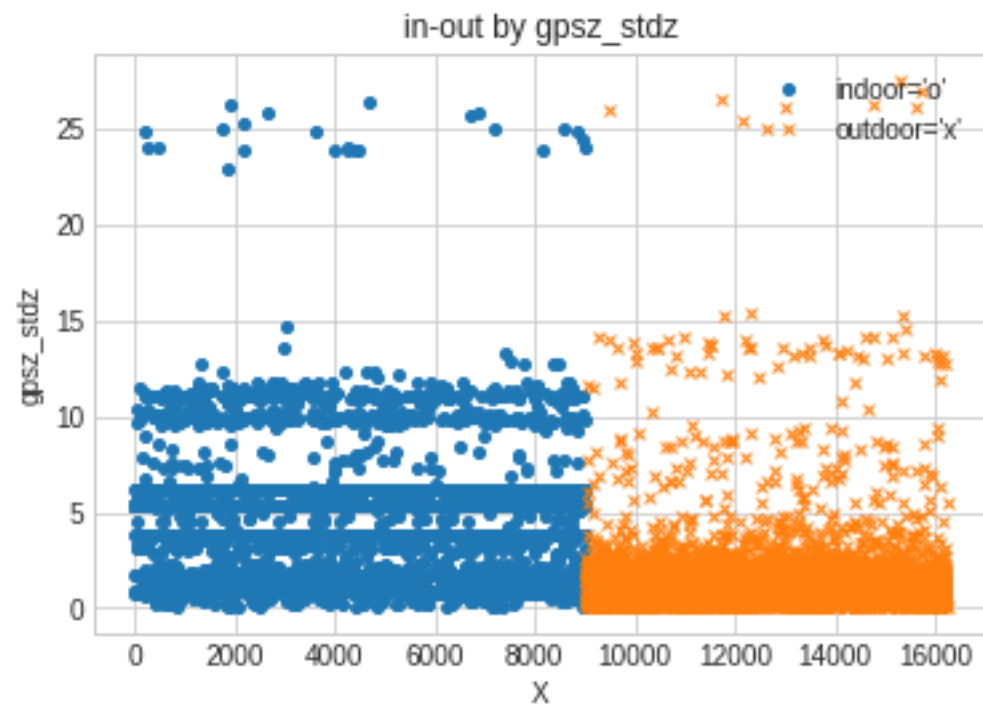
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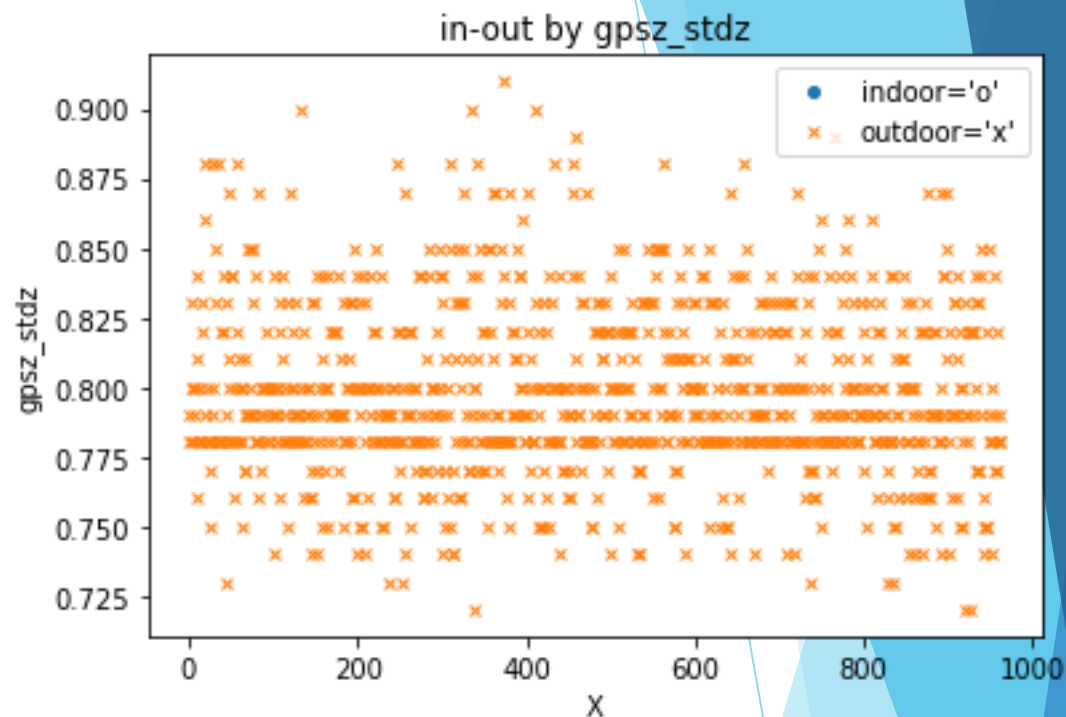
Testing data

特征 9 / feature 9

gpsz_tmean : 当前位置的 GPS 海拔高度与手机测试 海拔高度差的绝对值



Training data

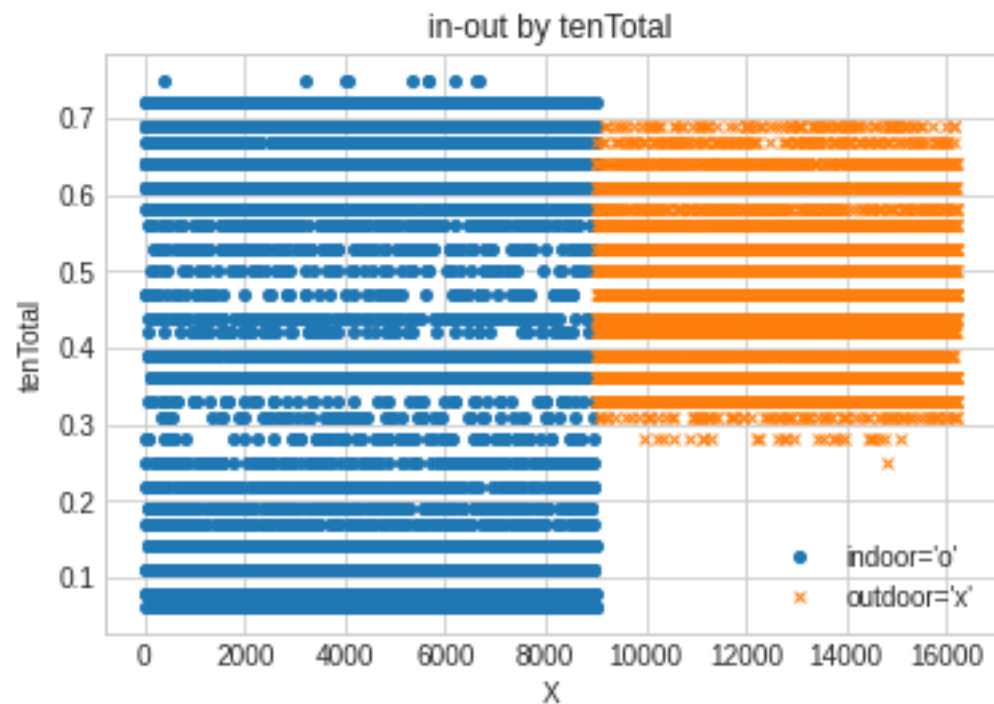


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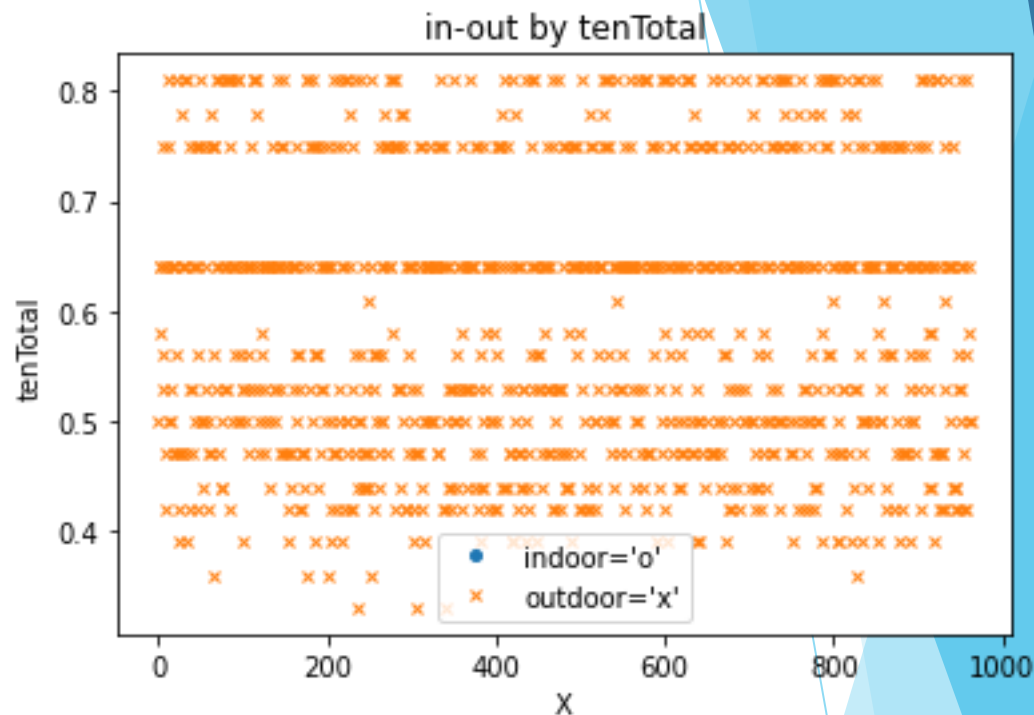
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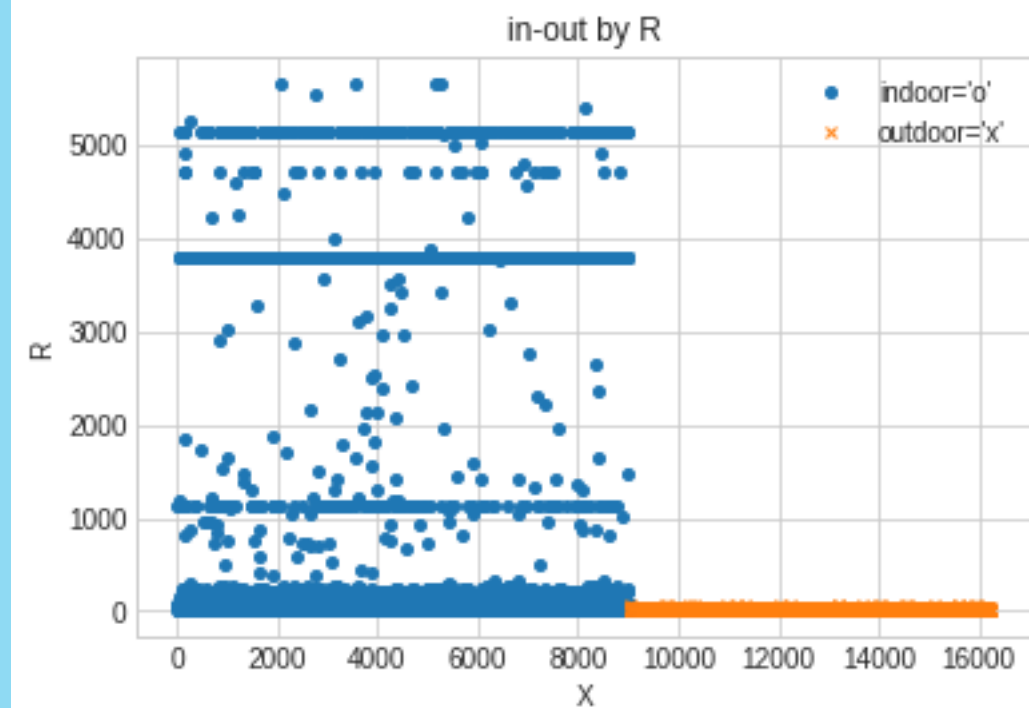
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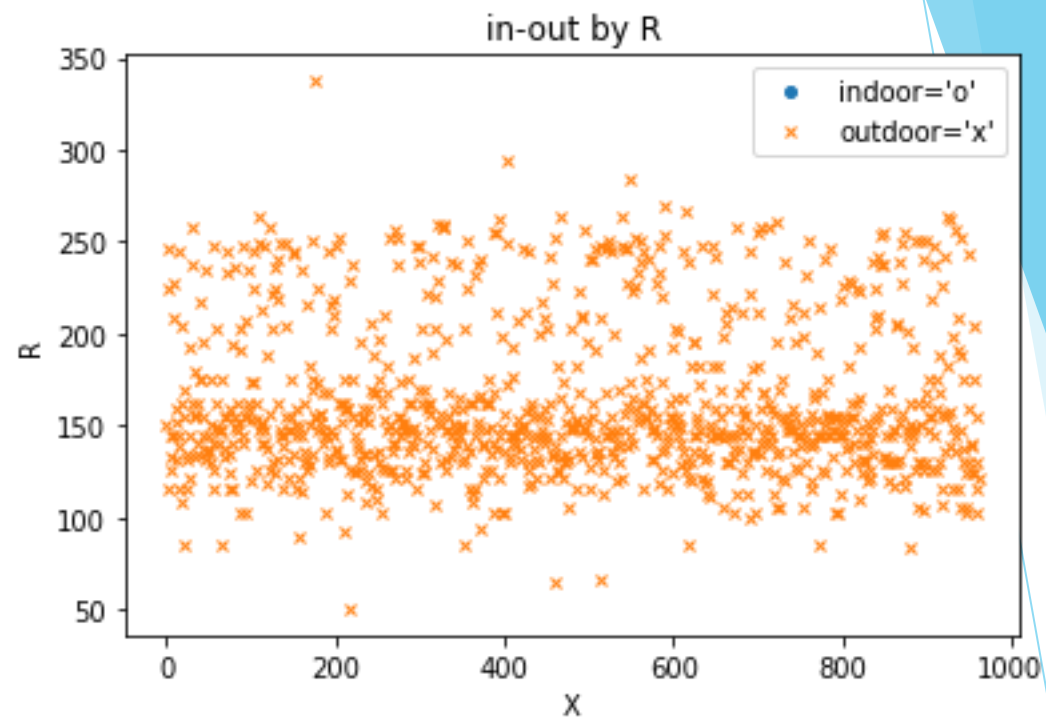
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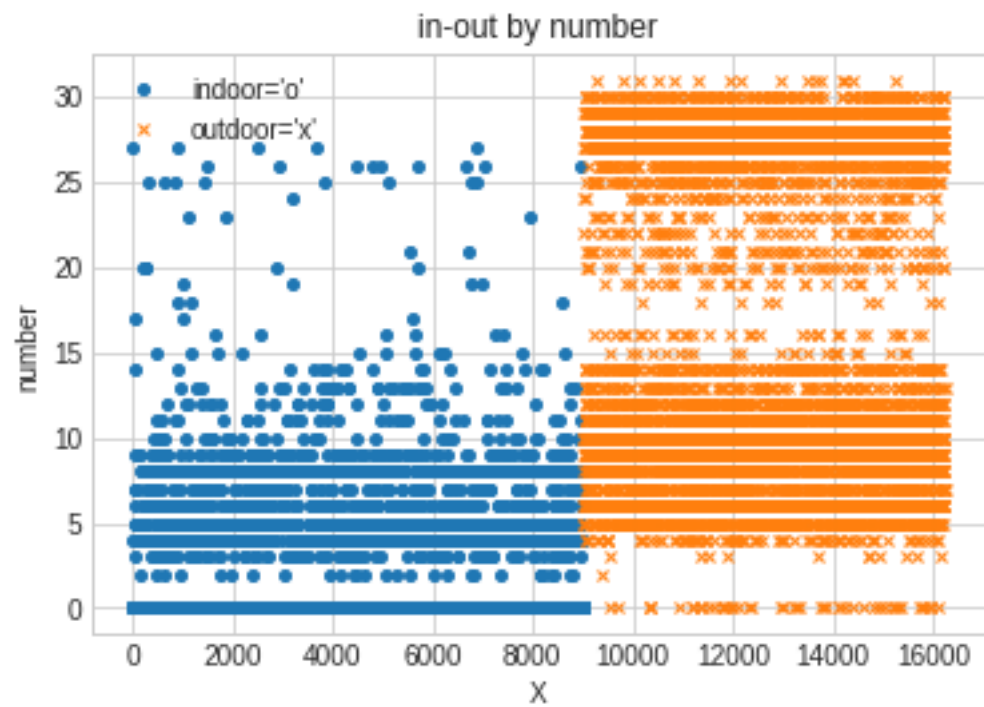
Training data



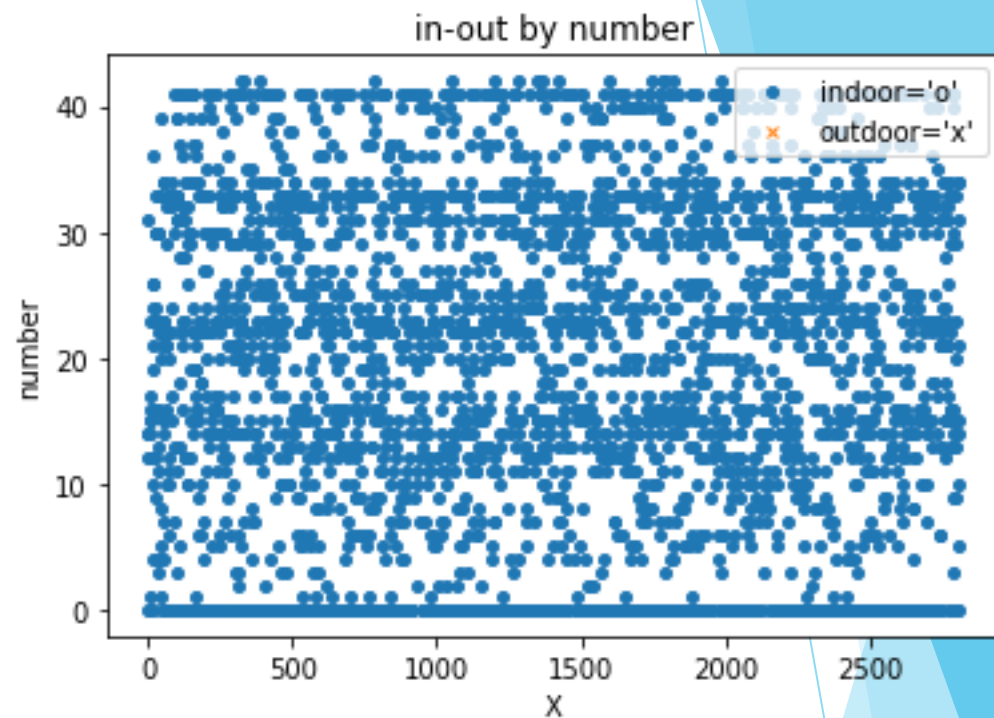
Testing data

特征 12 / feature 12
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地铁站内 the testing data when in the subway
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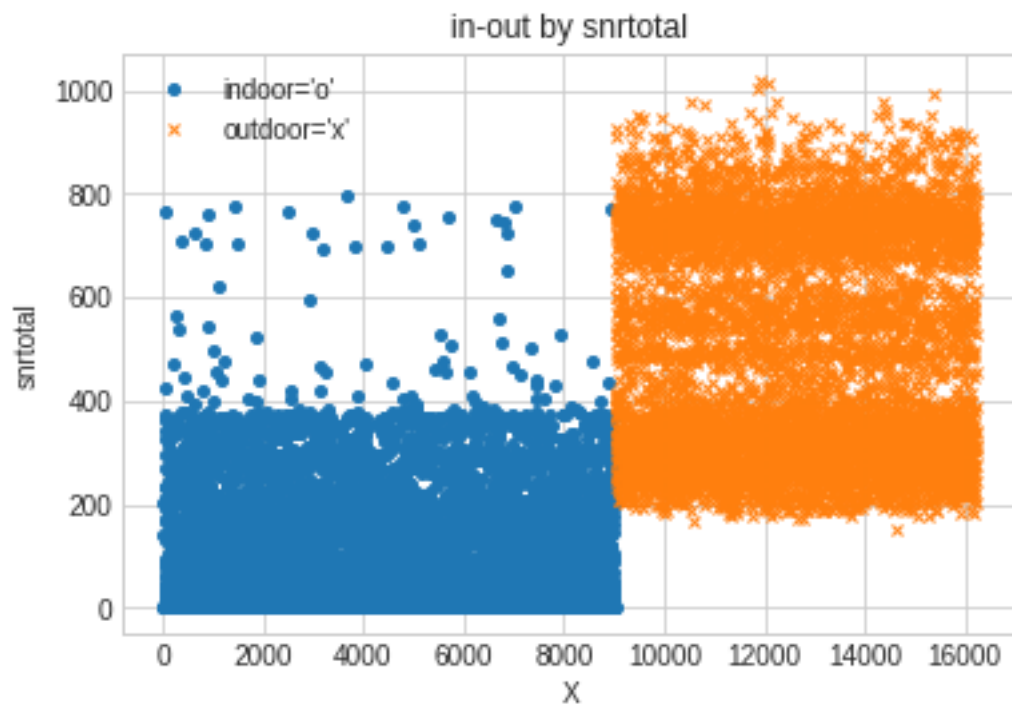
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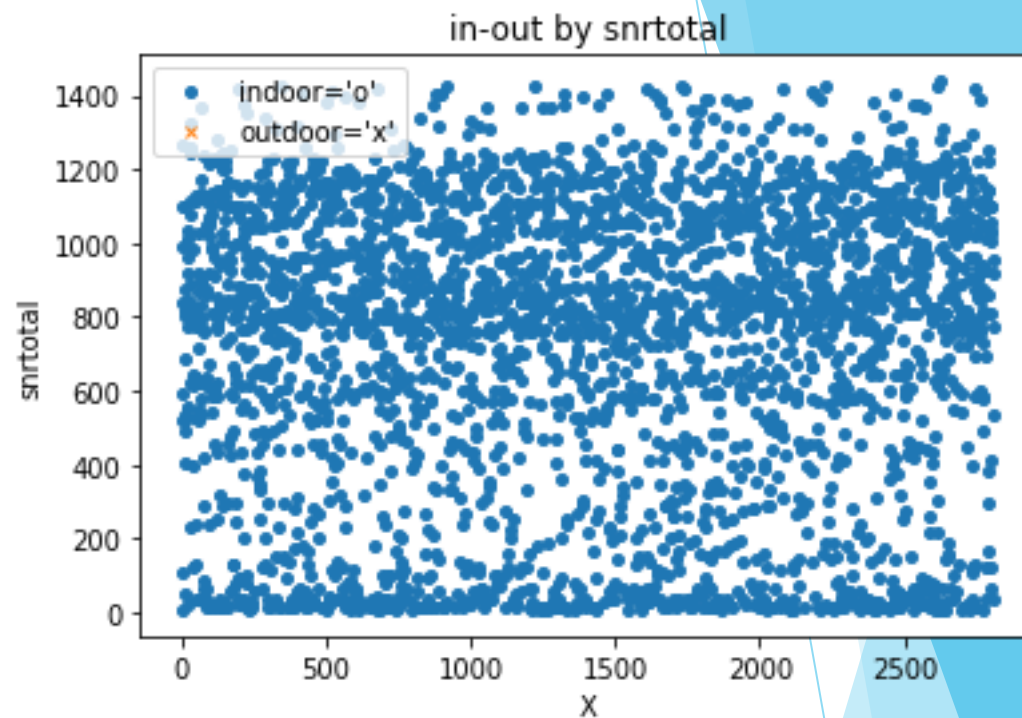
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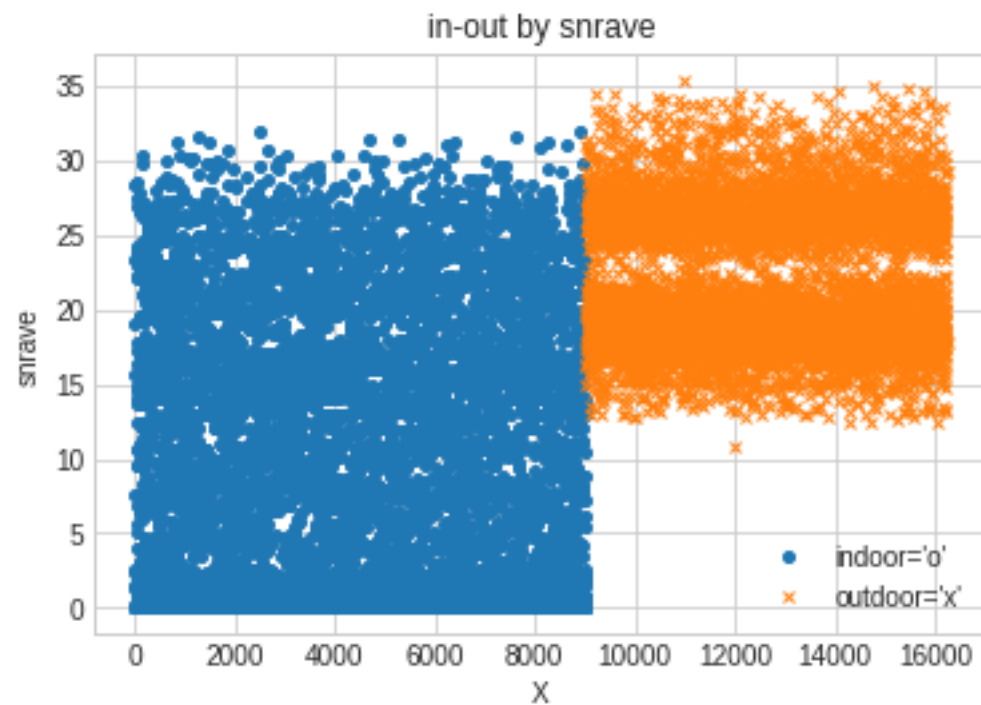
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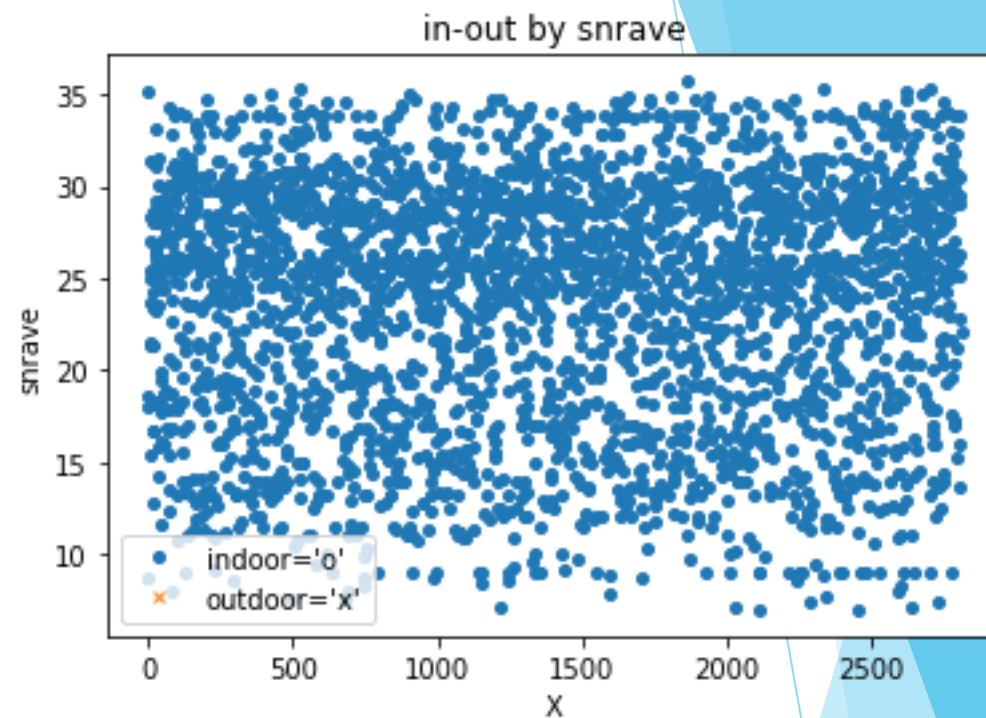
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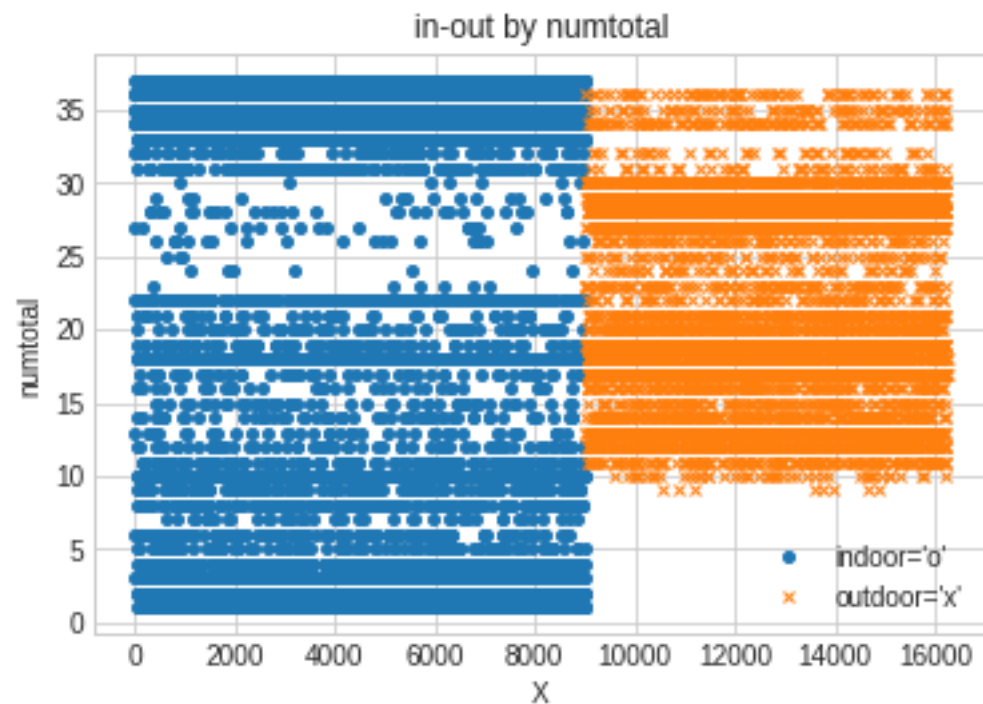
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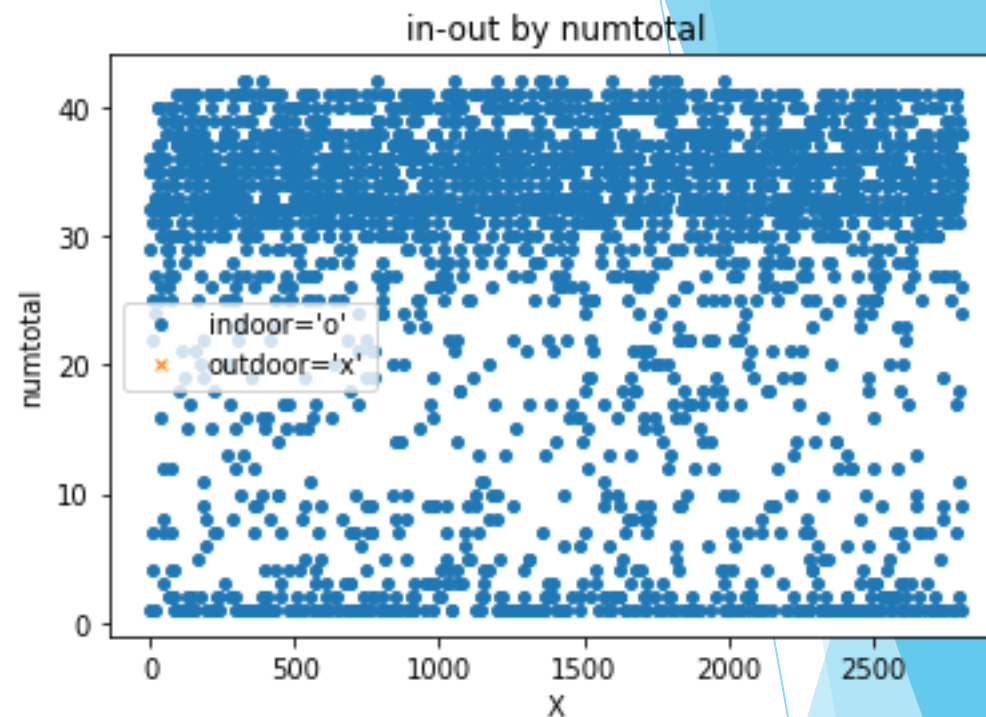
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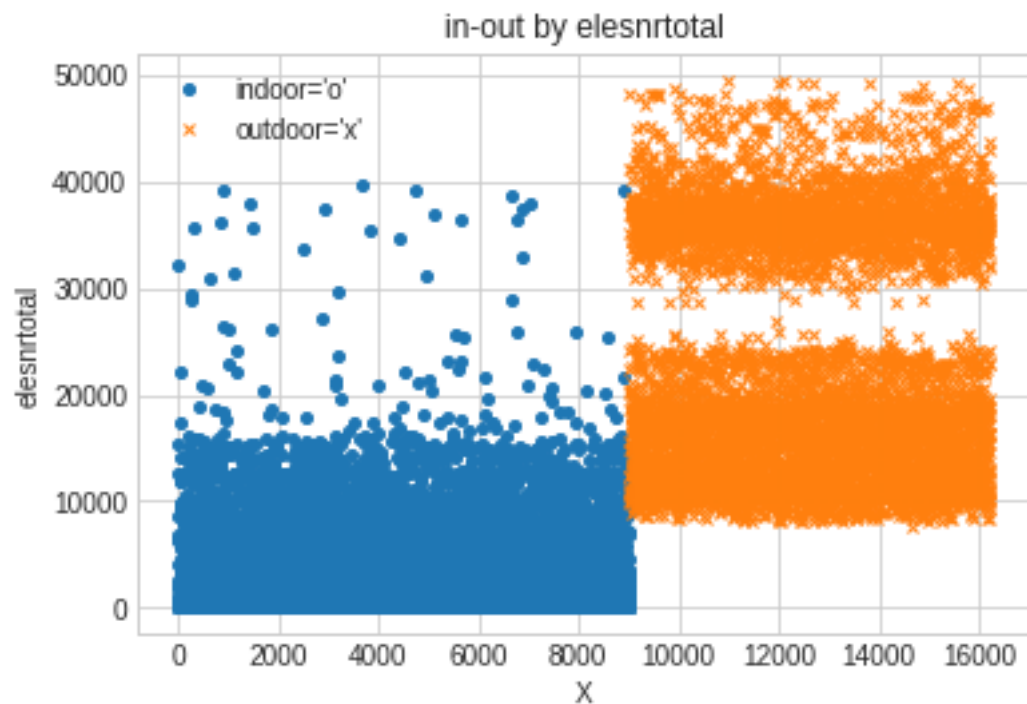
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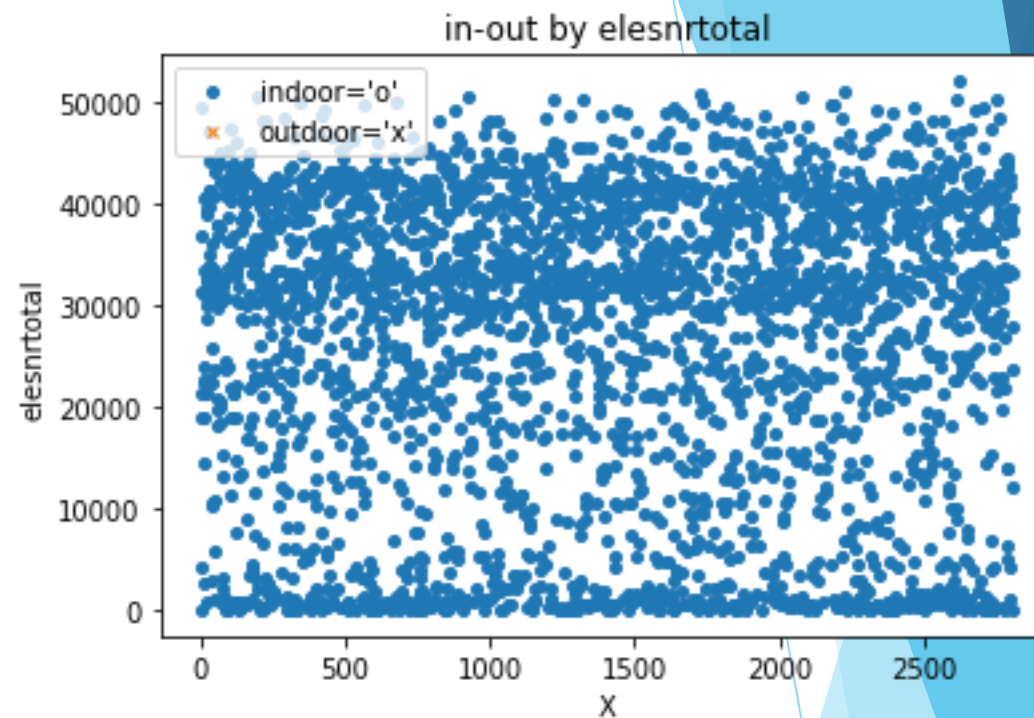
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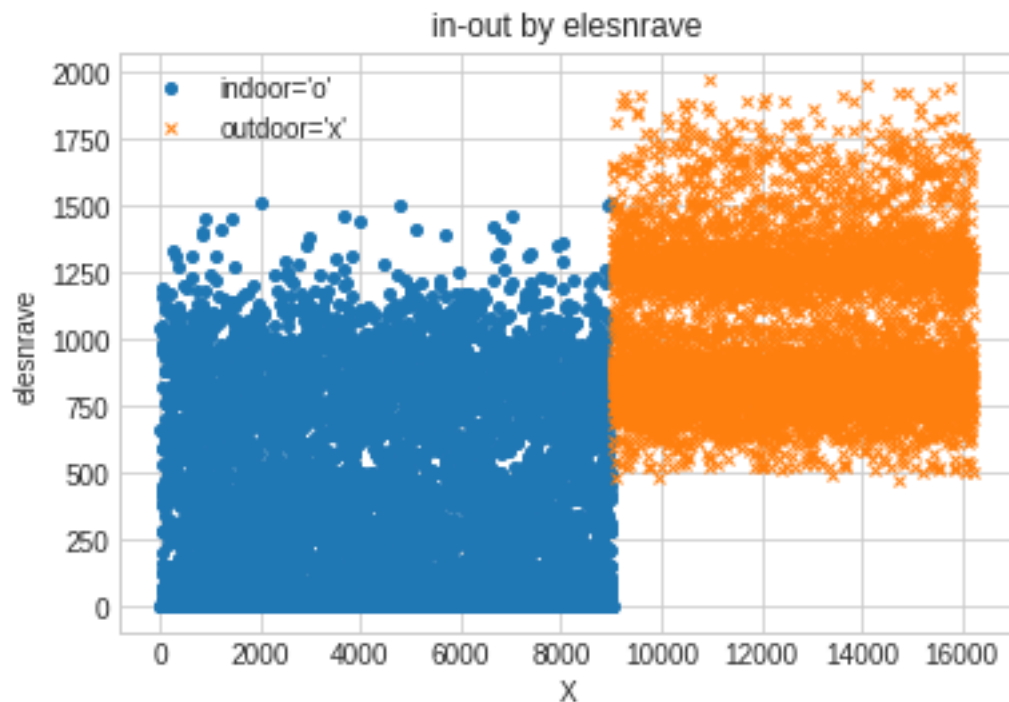
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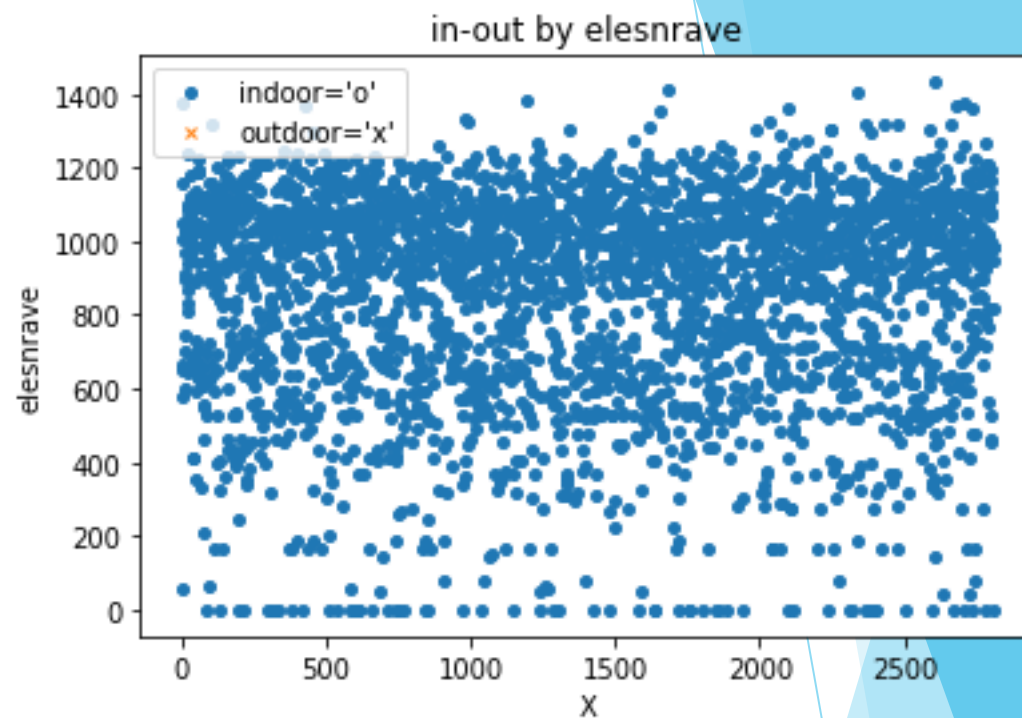
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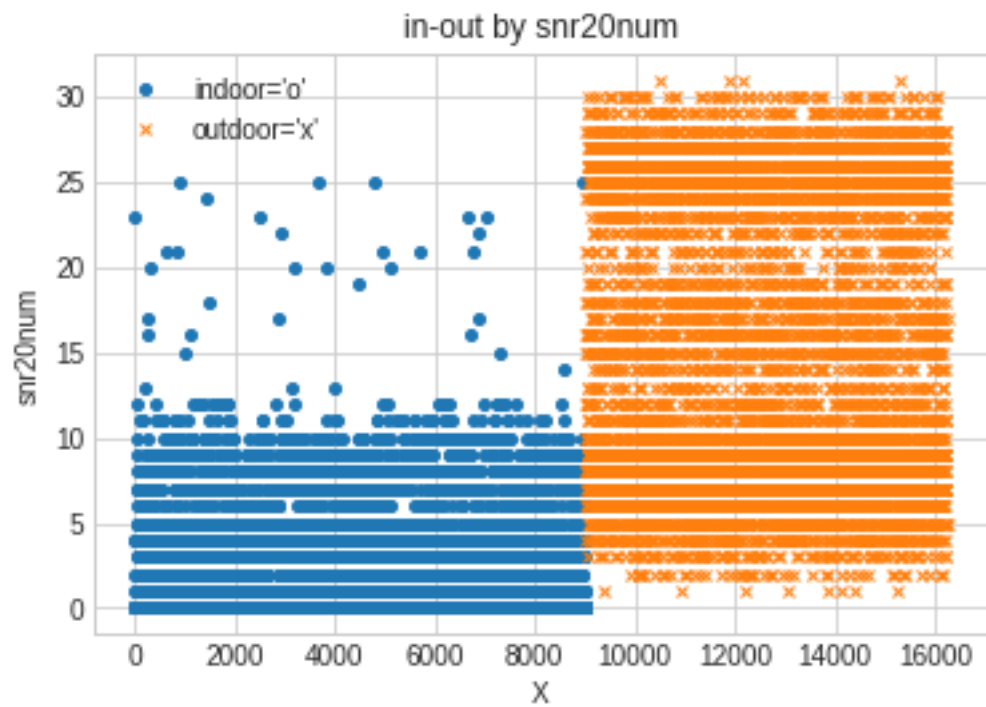
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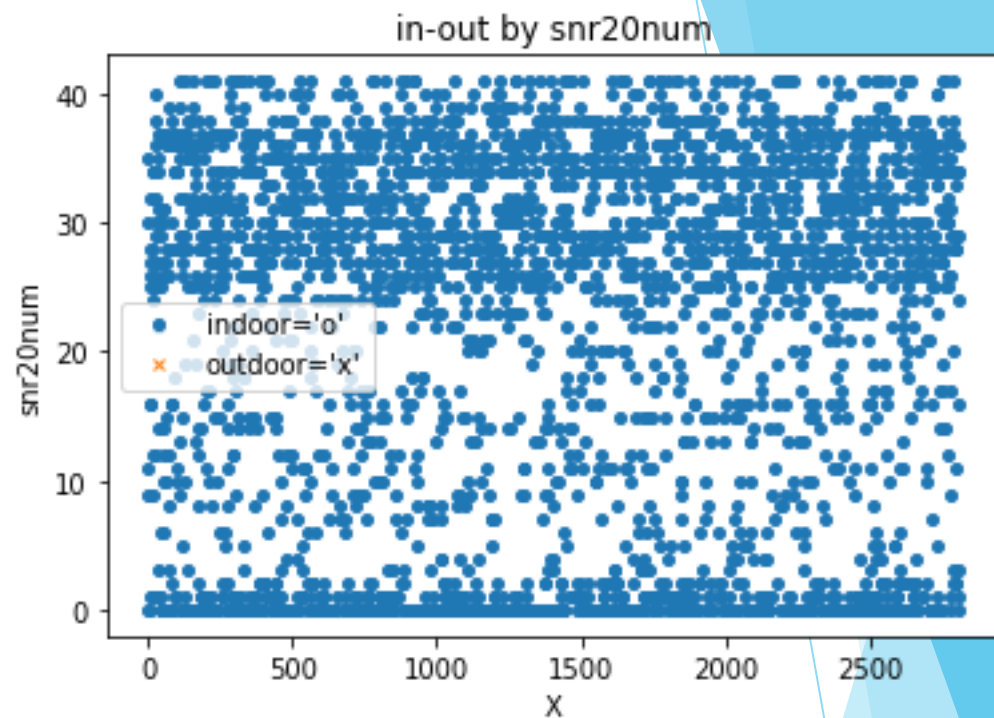
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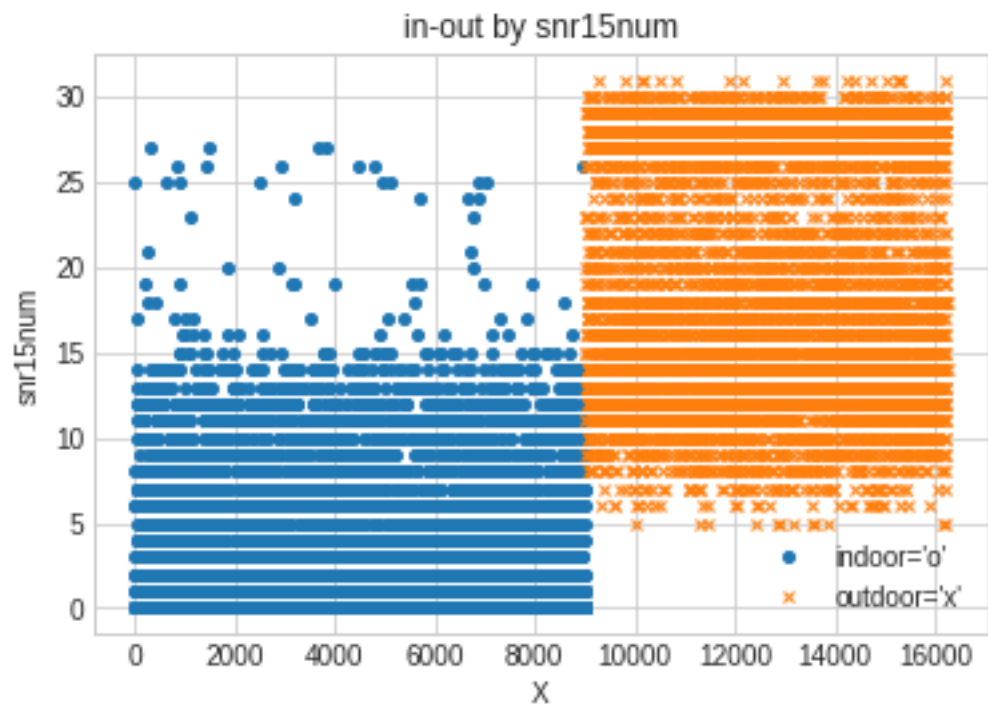
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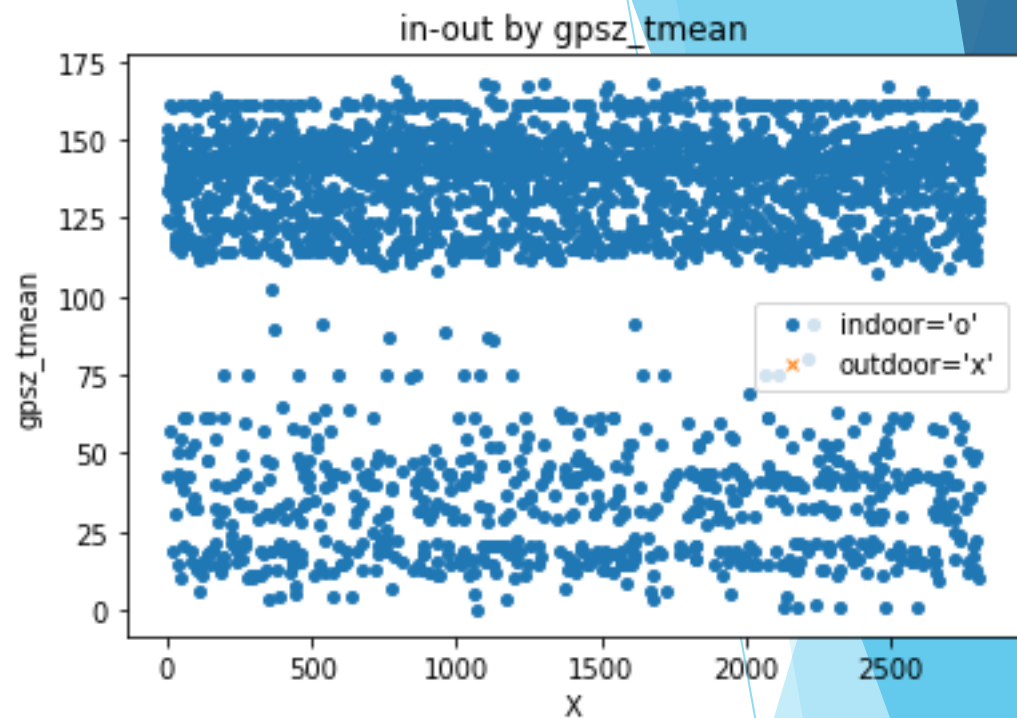
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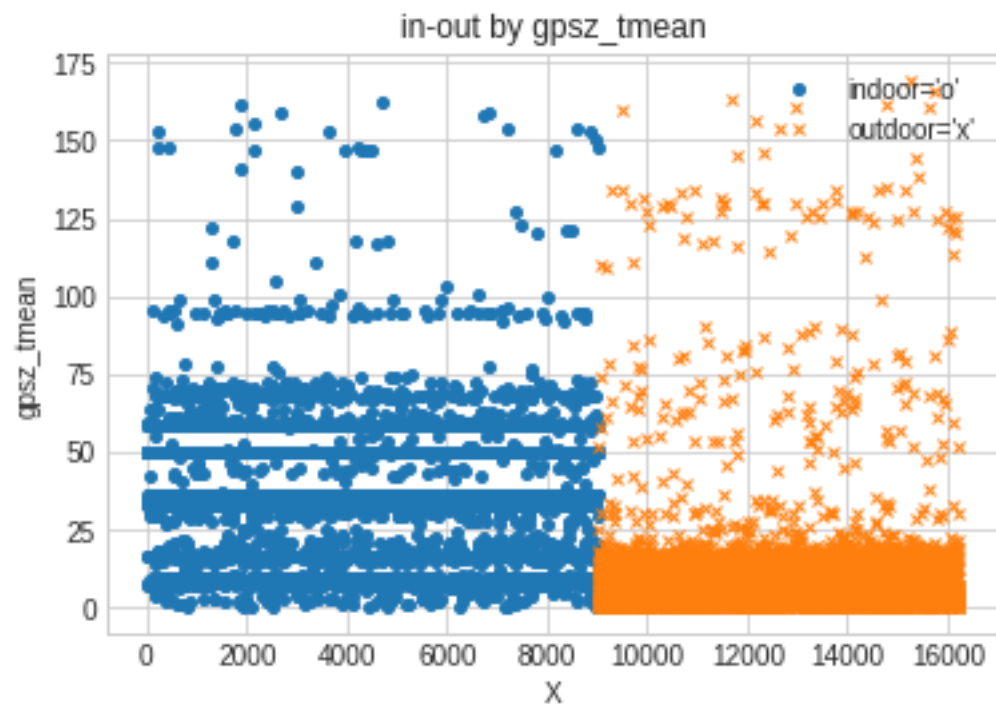
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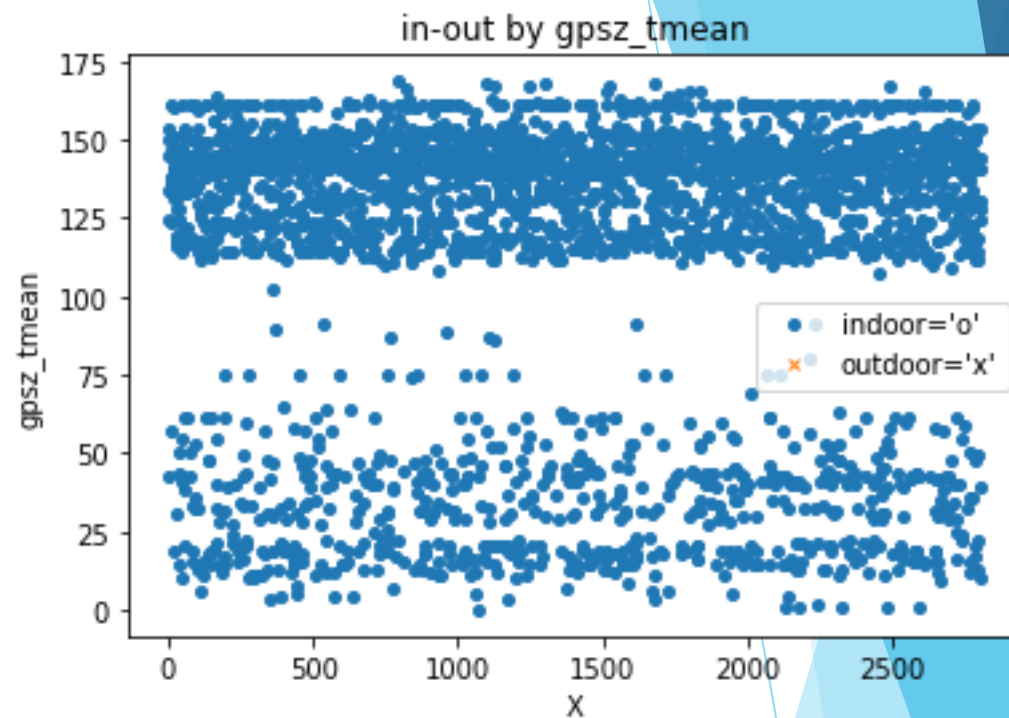
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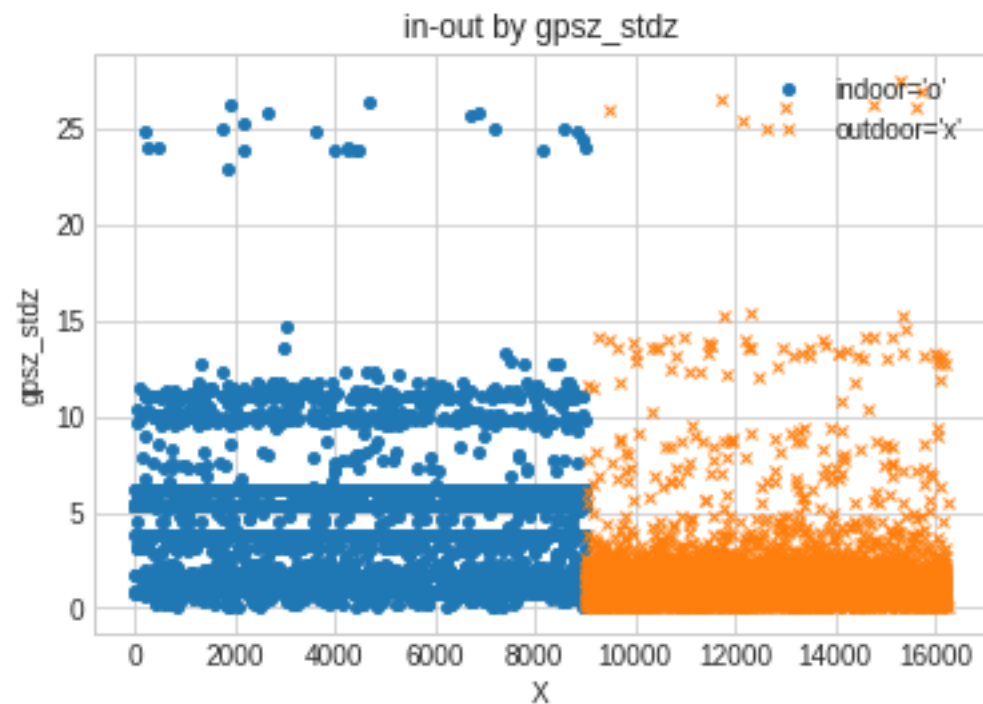
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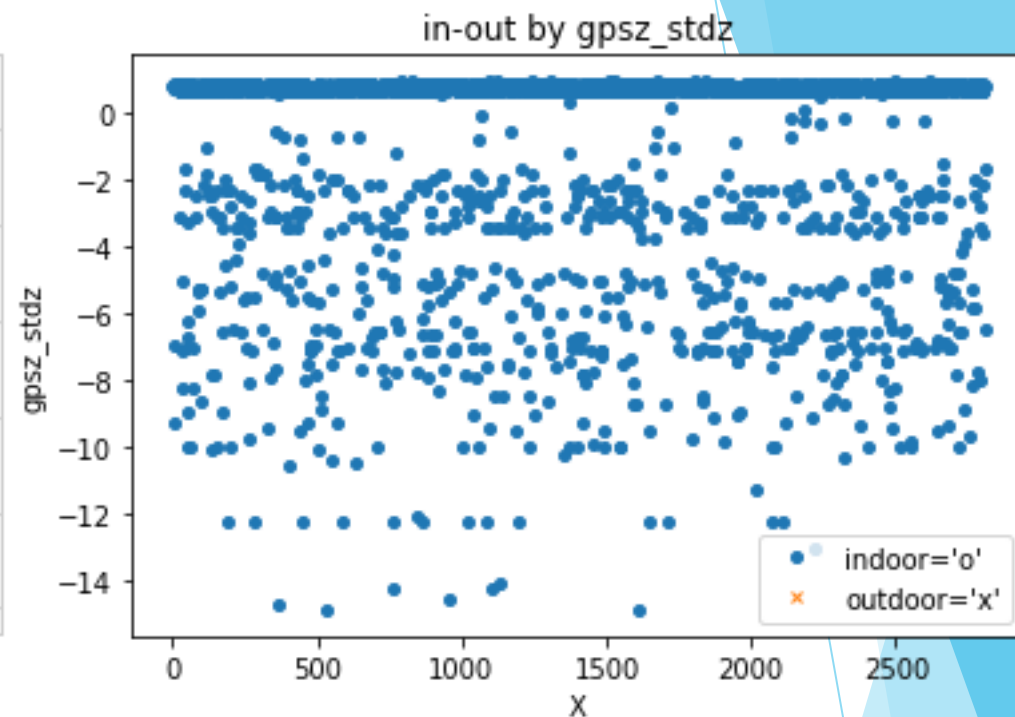
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特征 9 / feature 9

gpsz_tmean : 当前位置的 GPS 海拔高度与手机测试 海拔高度差的绝对值



Training data

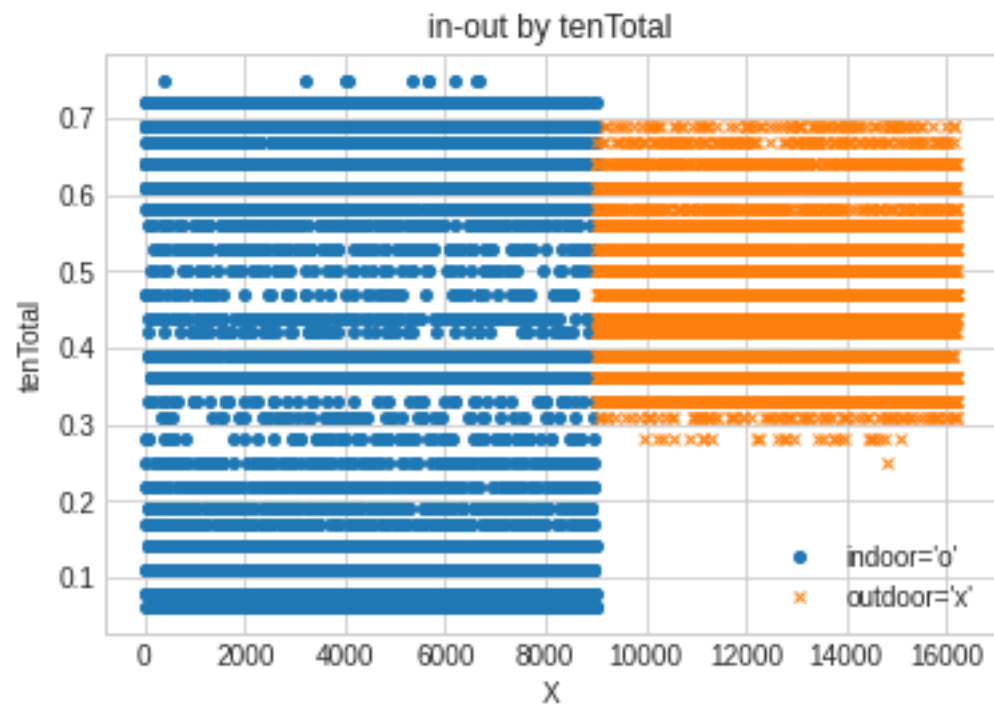


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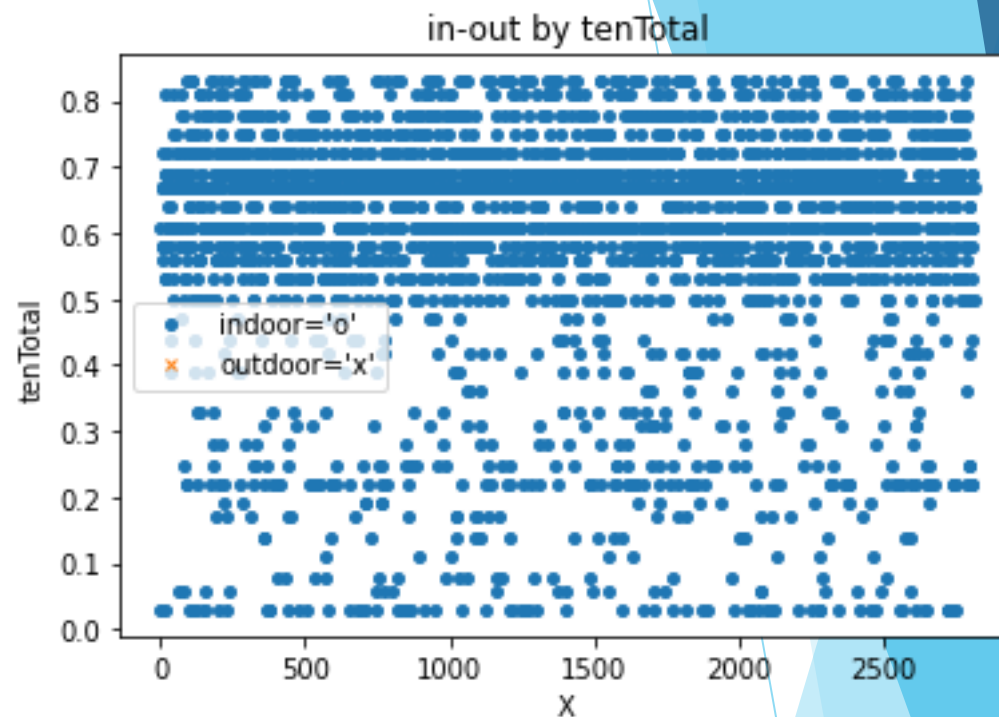
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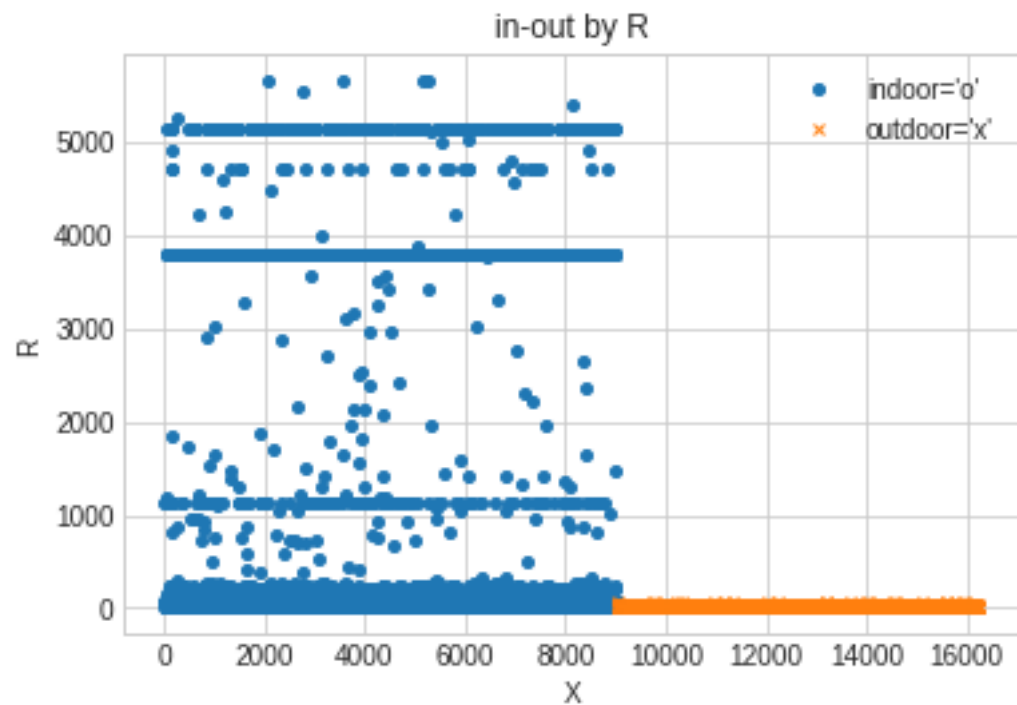
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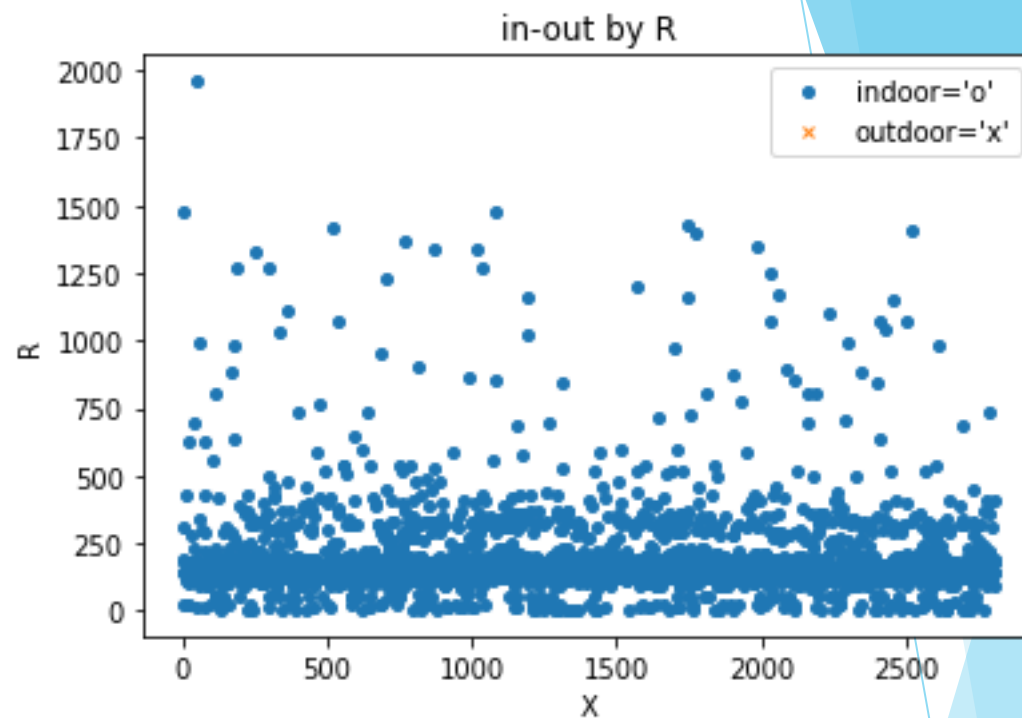
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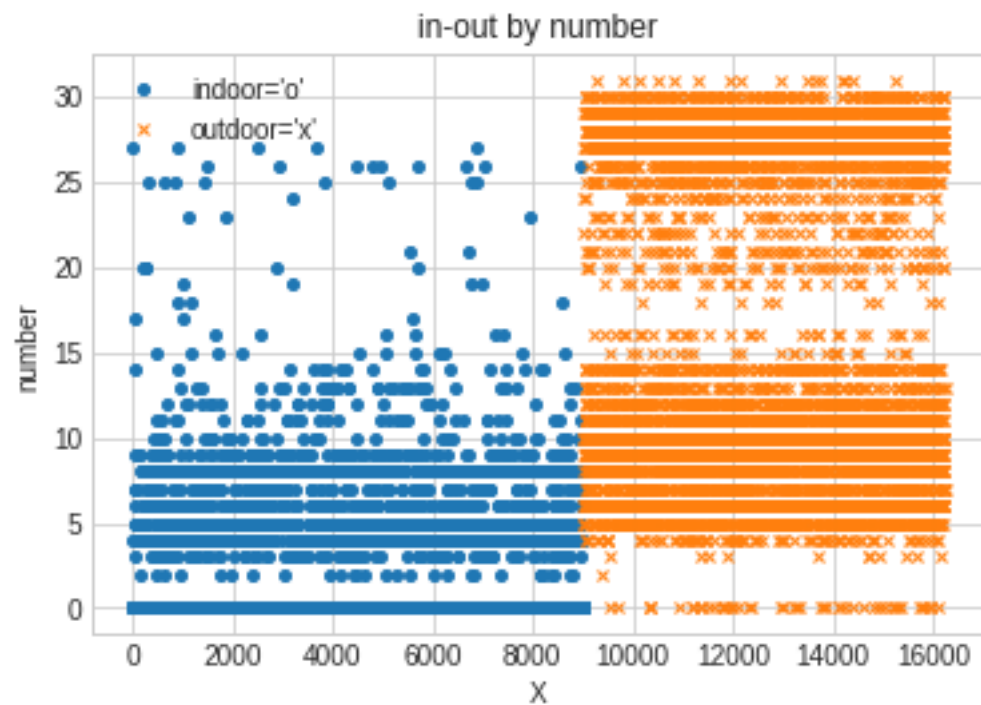


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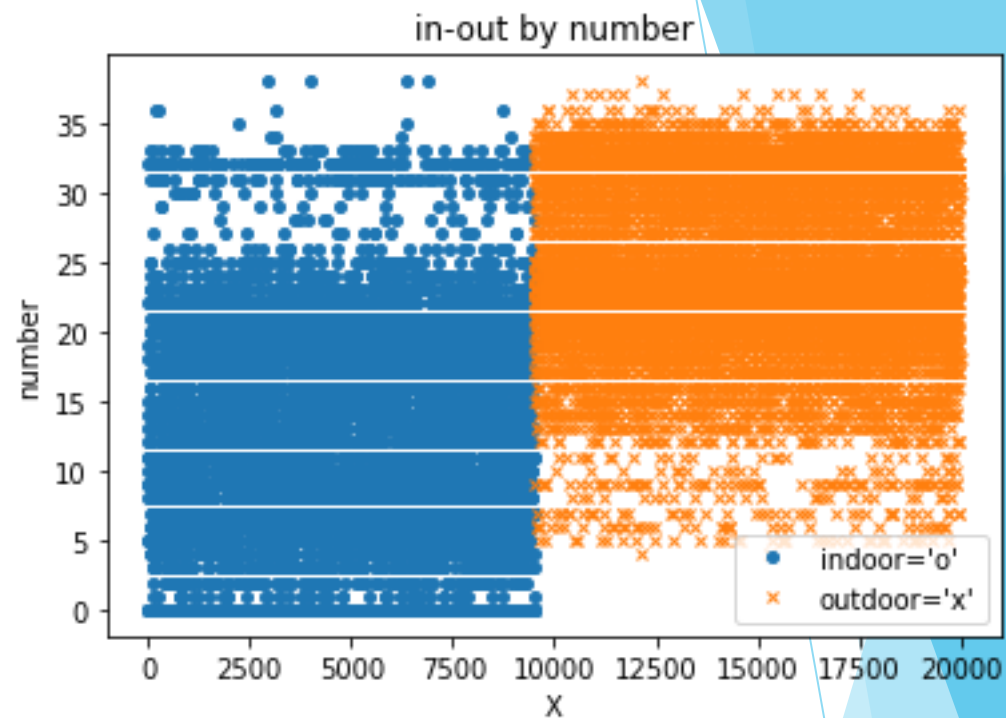
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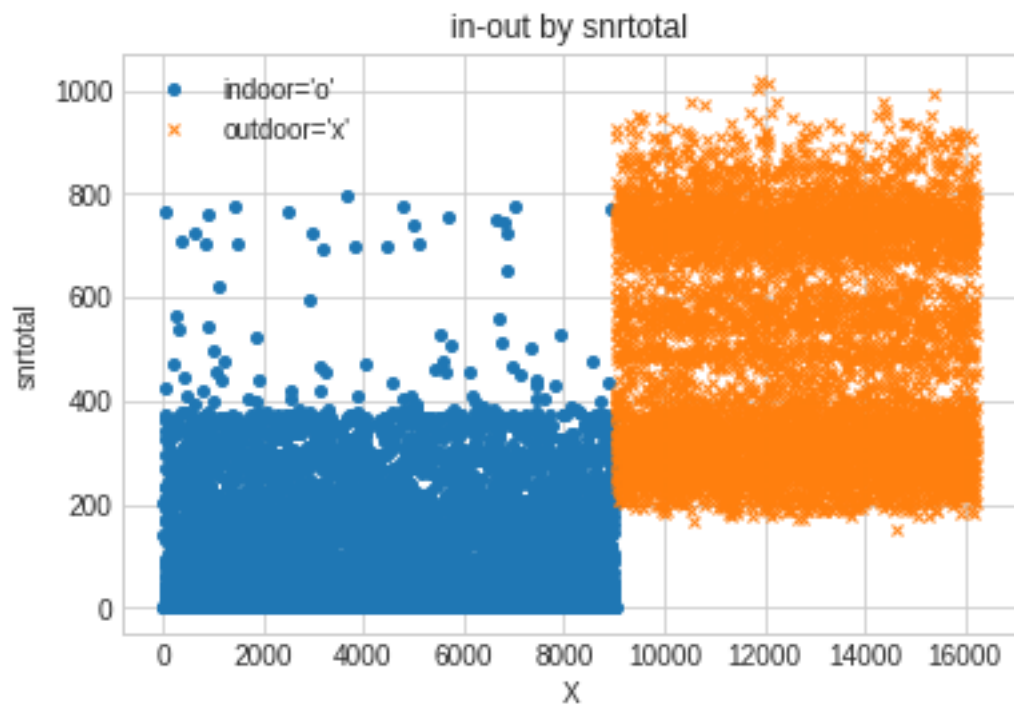
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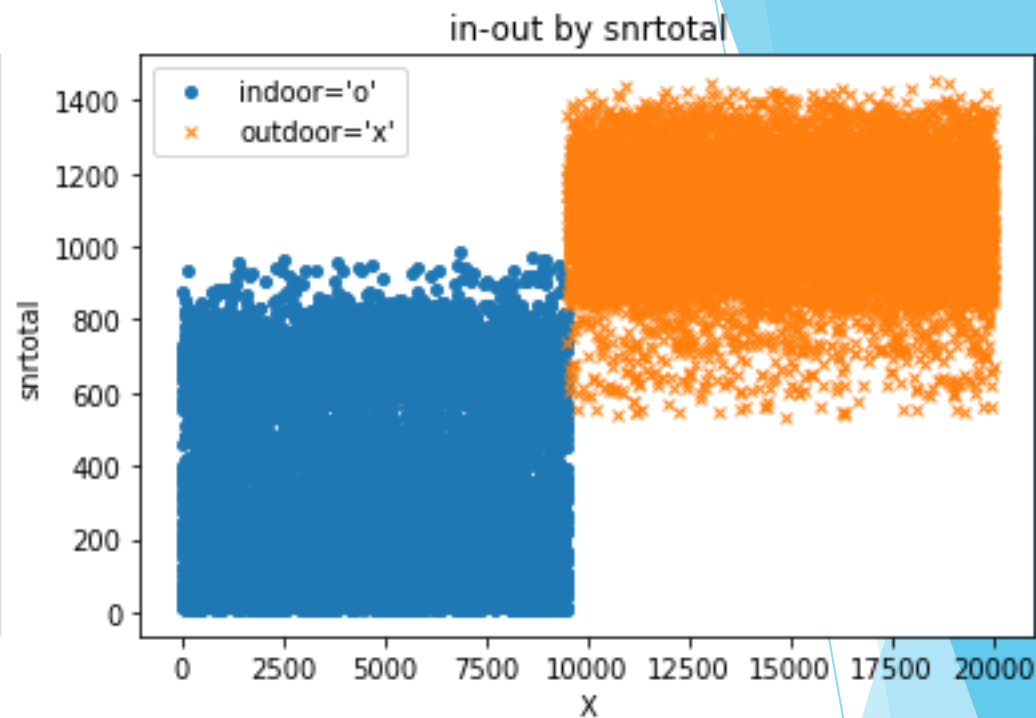
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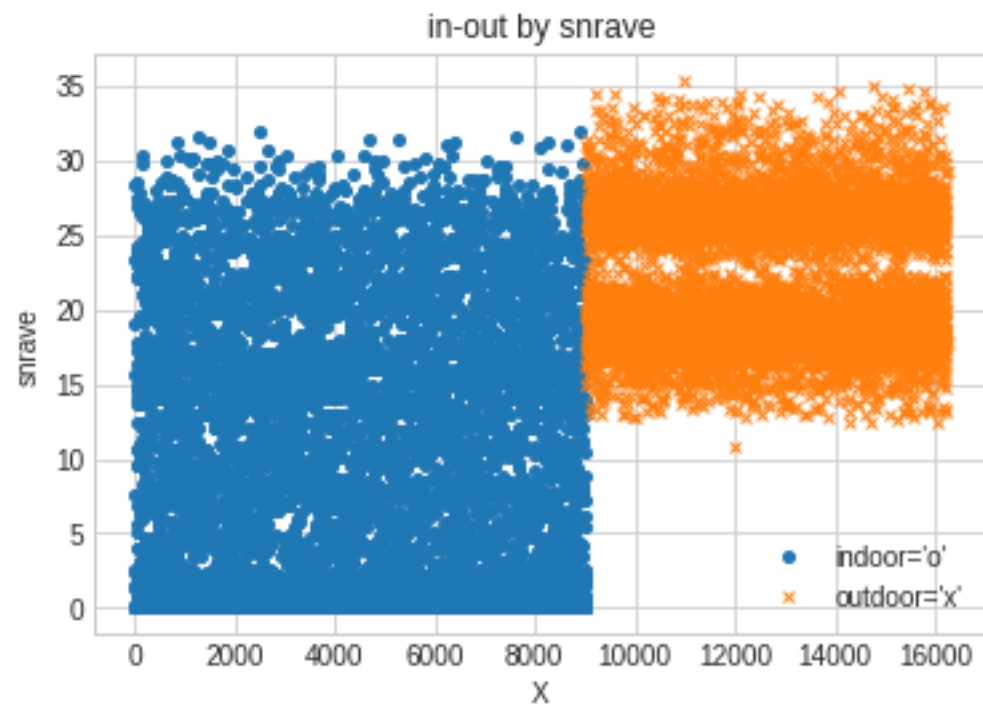
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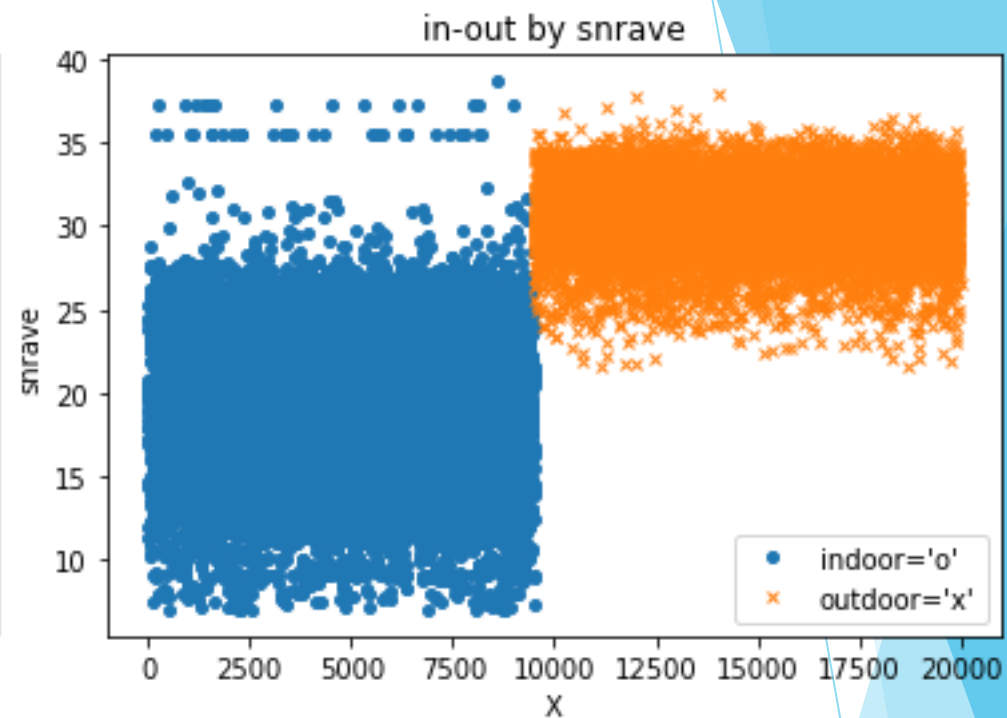
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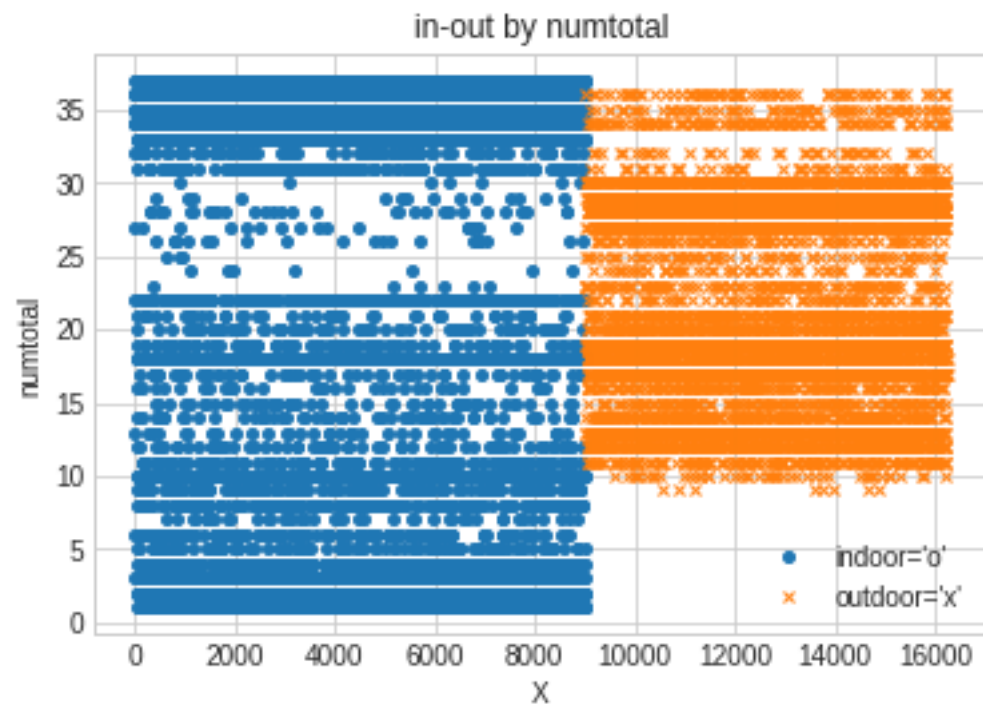
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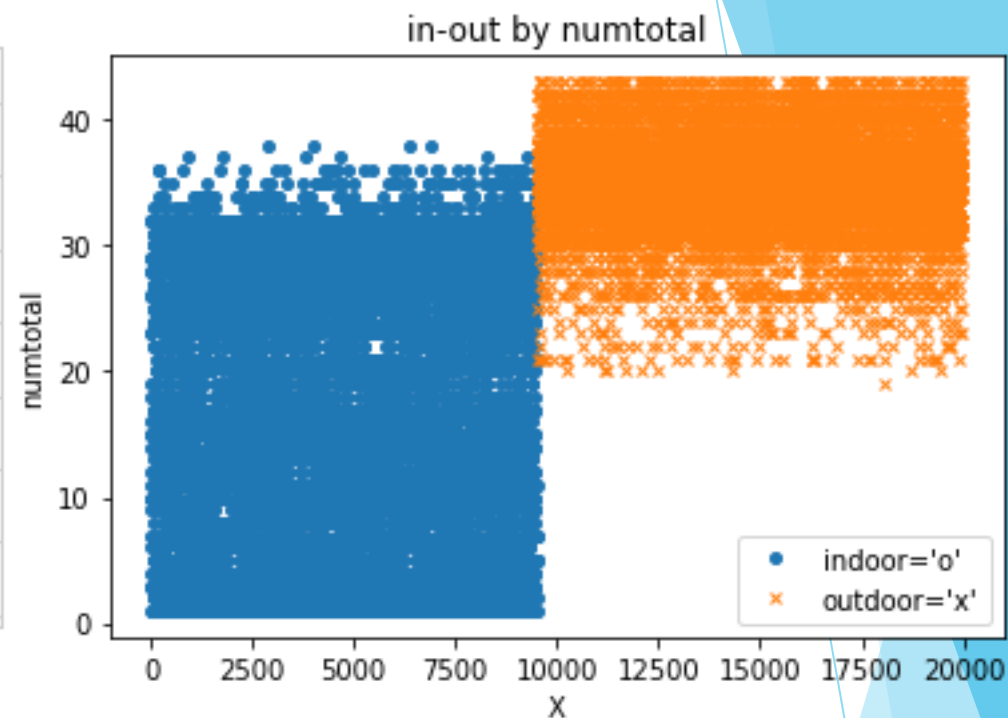
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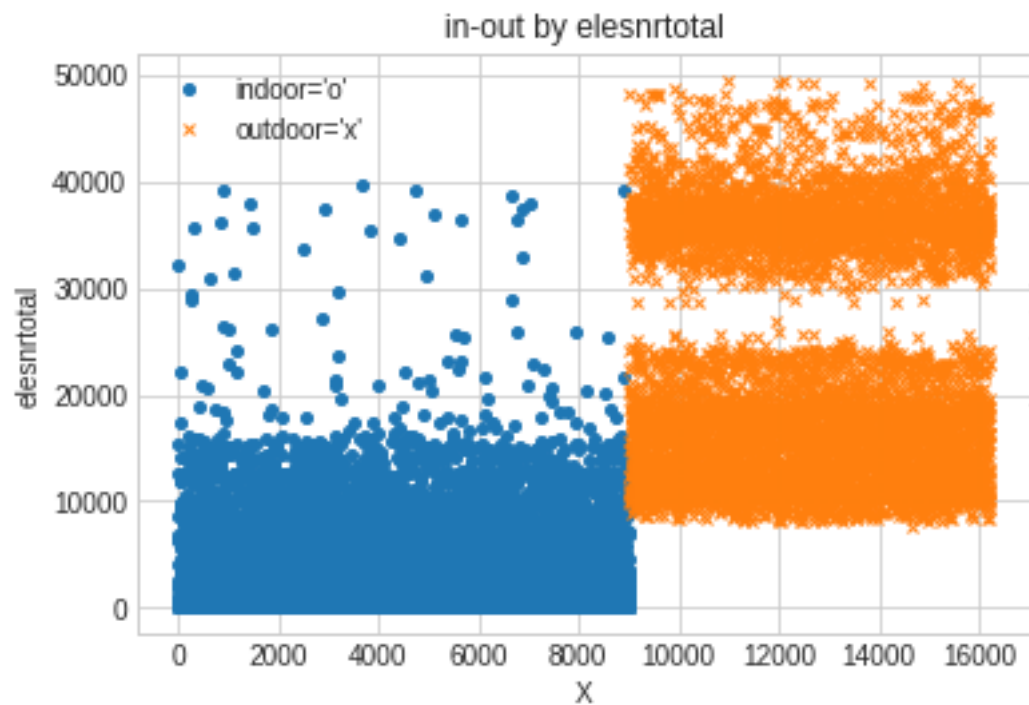
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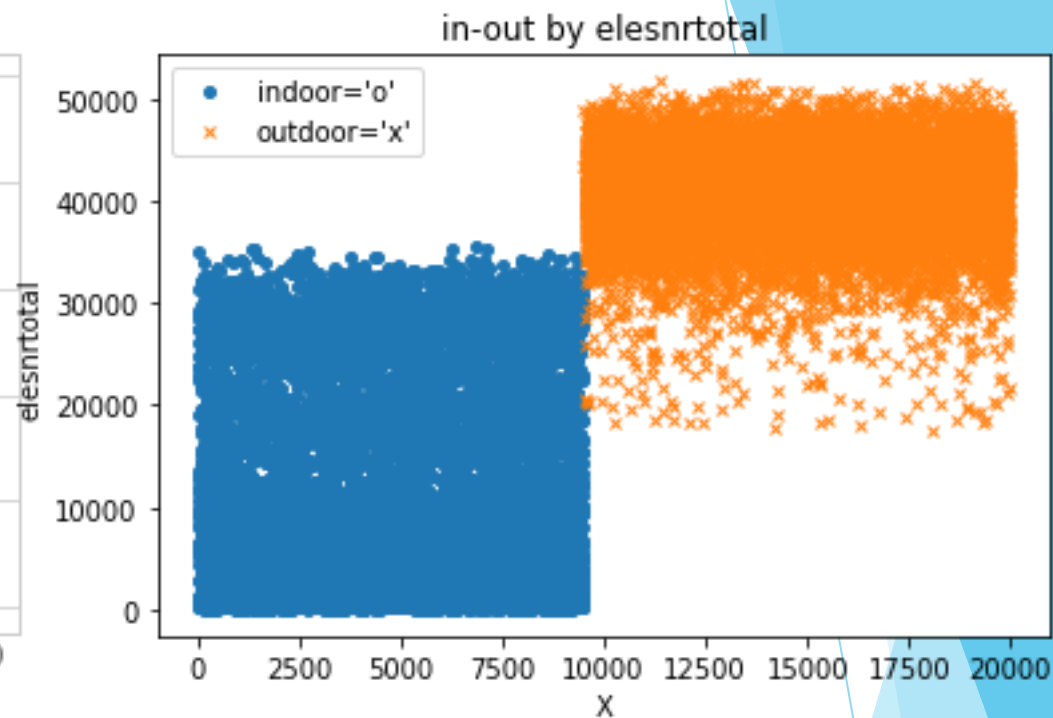
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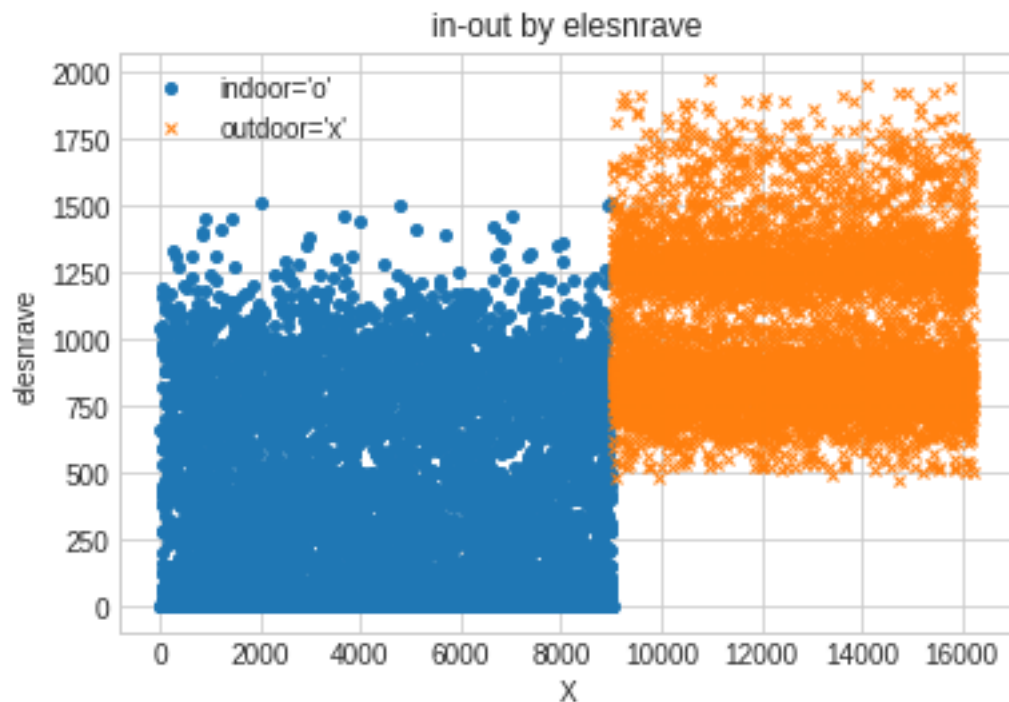
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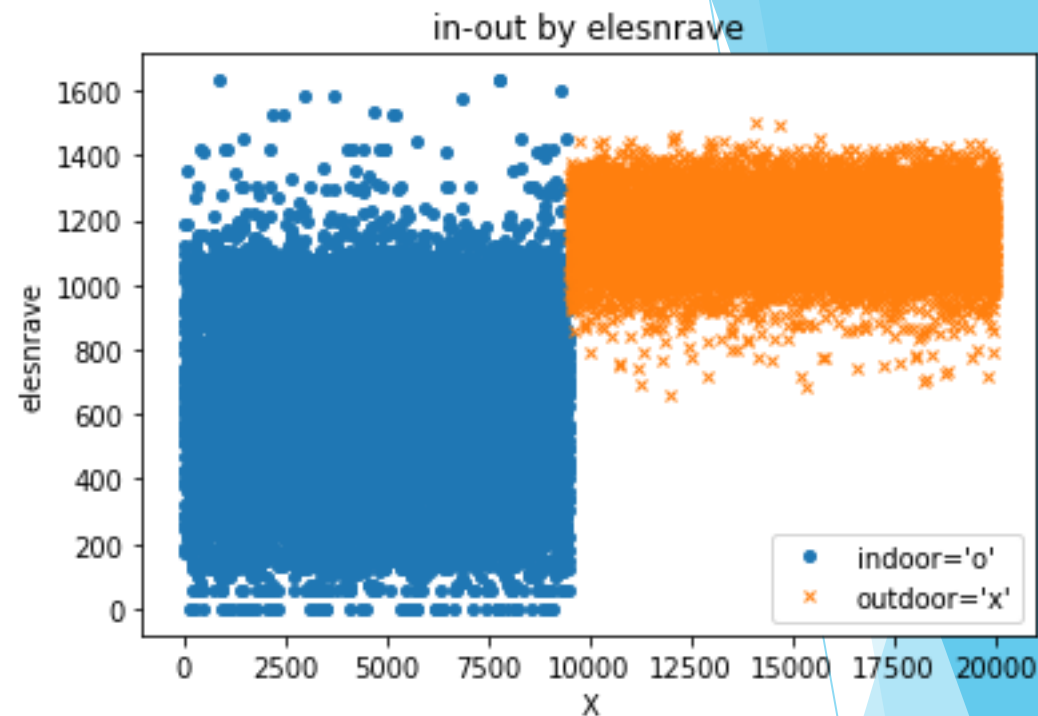
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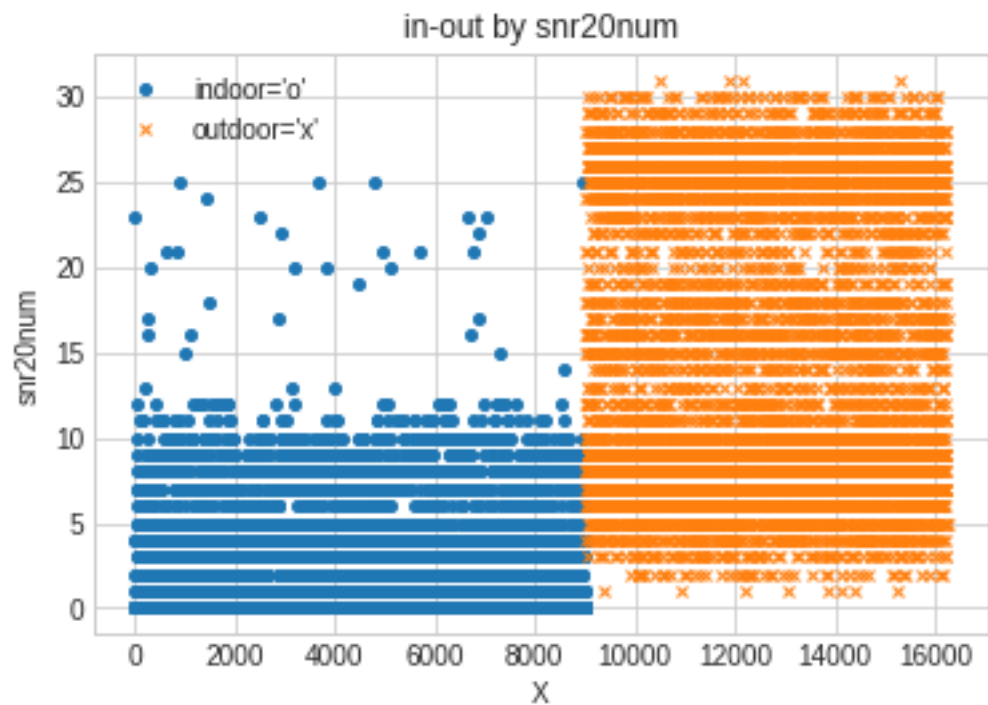
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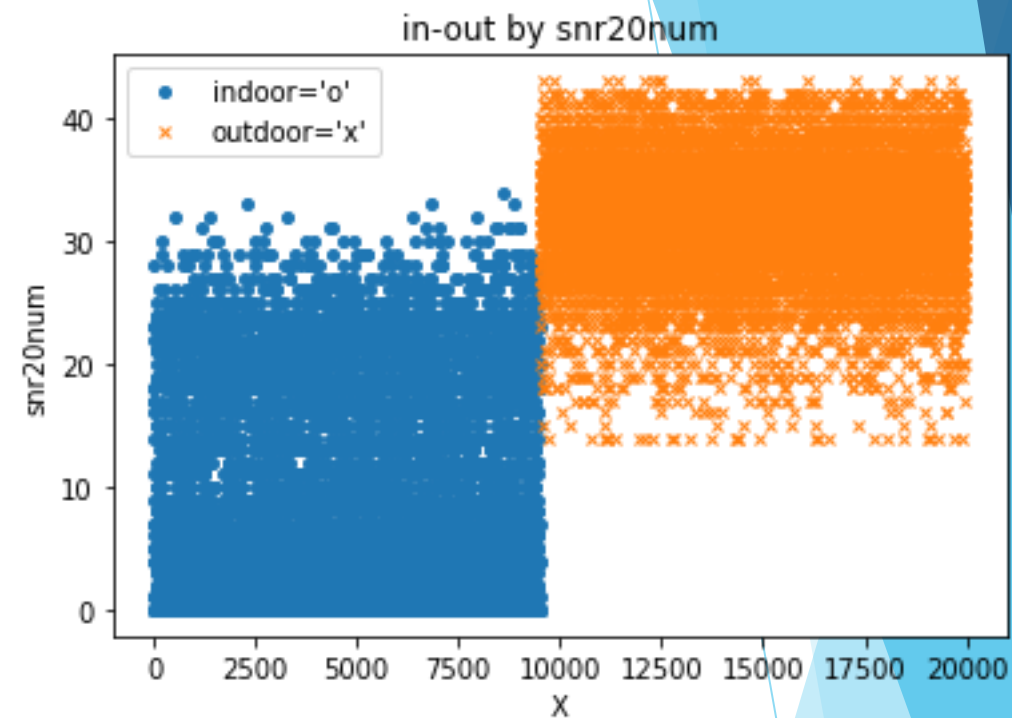
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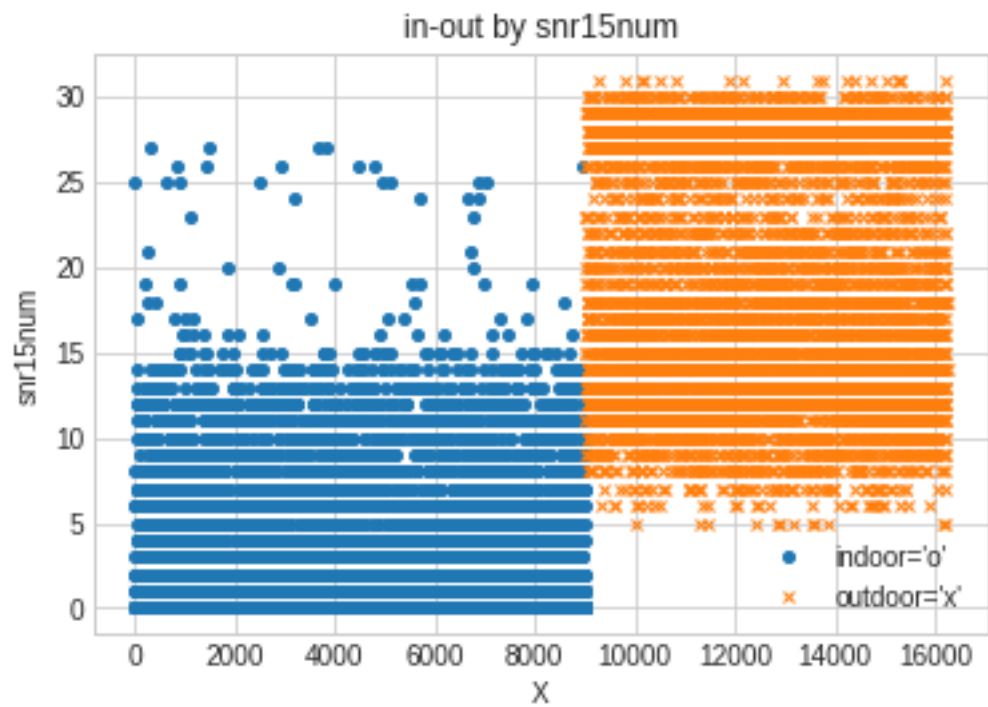
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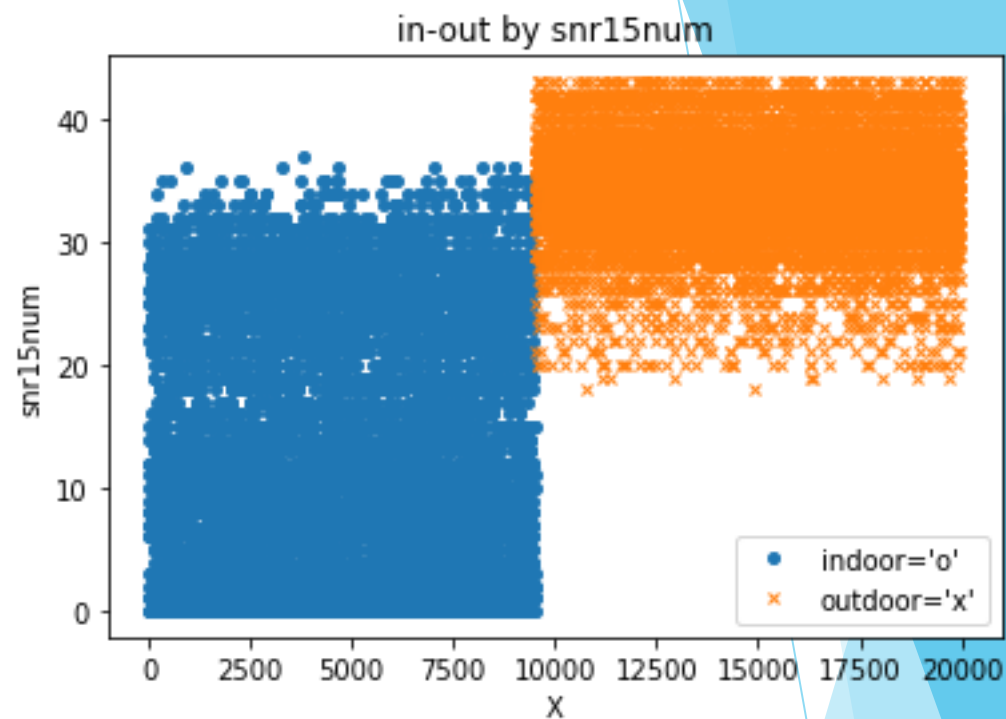
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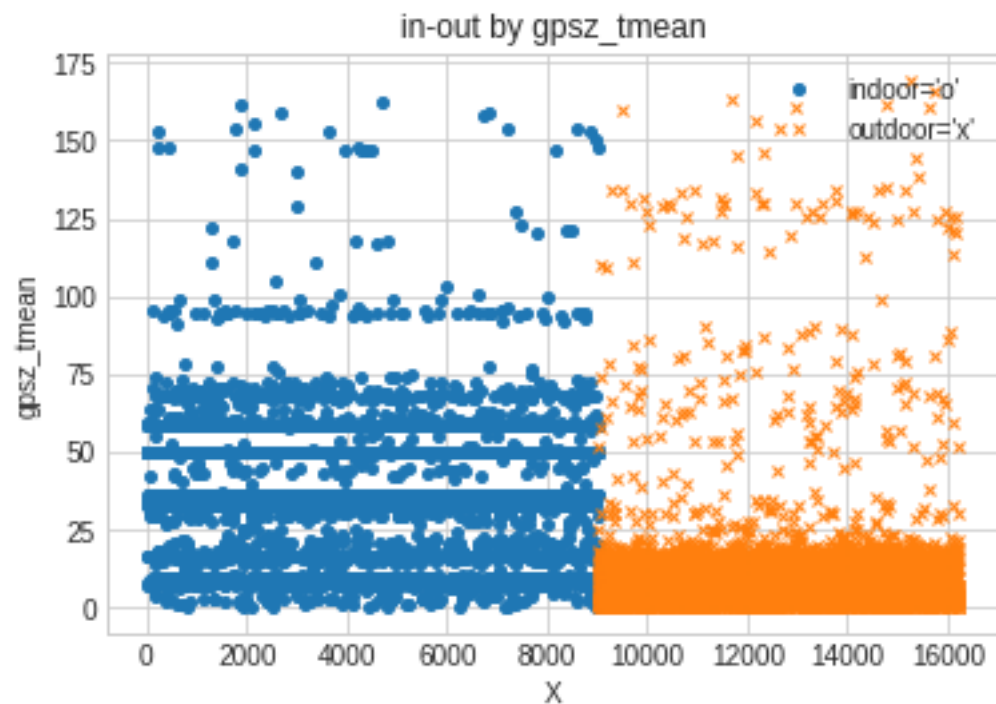
Training data



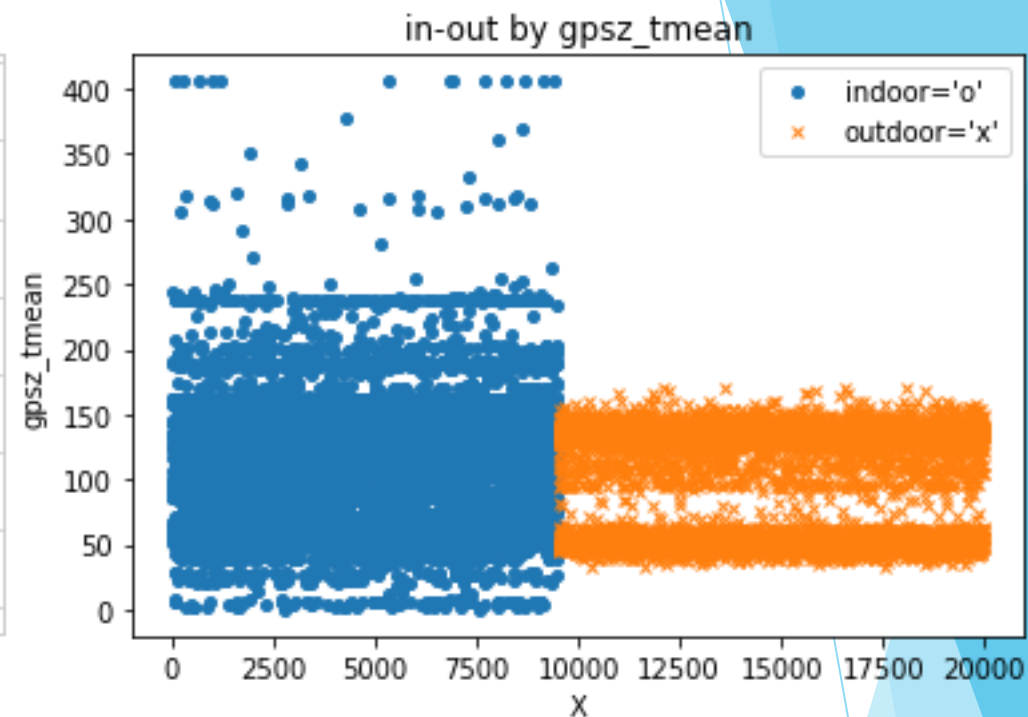
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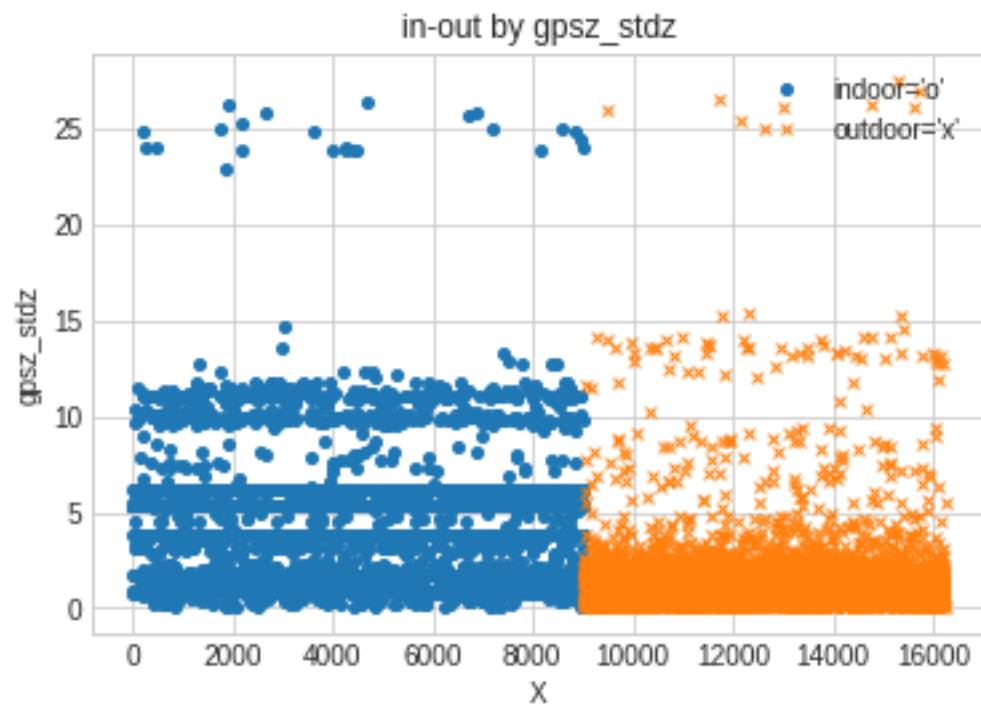
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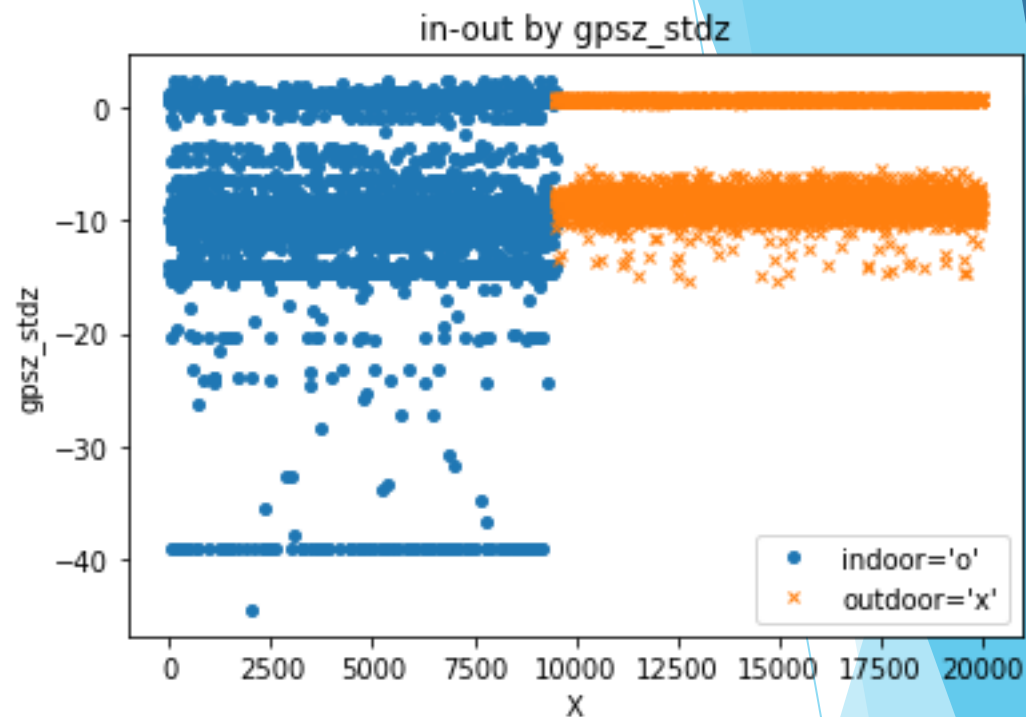
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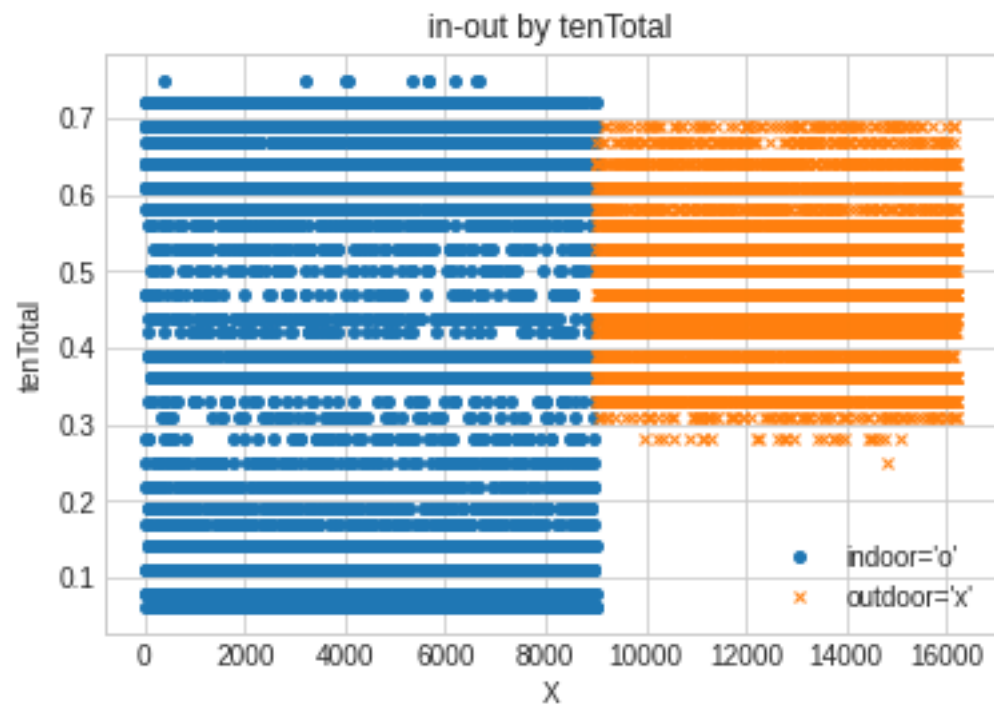


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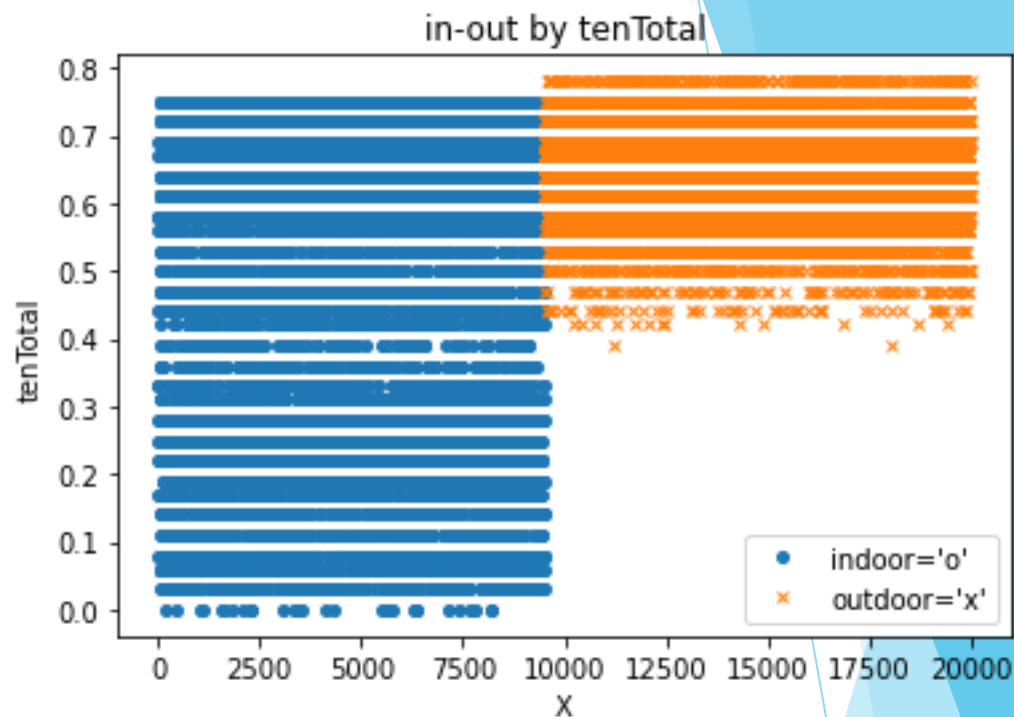
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特征 10 / feature 10

gpsz_stdz : 当前位置的 GPS 海拔高度与手机测试 海拔高度差的绝对值是否小于标准差 (0 or 1)



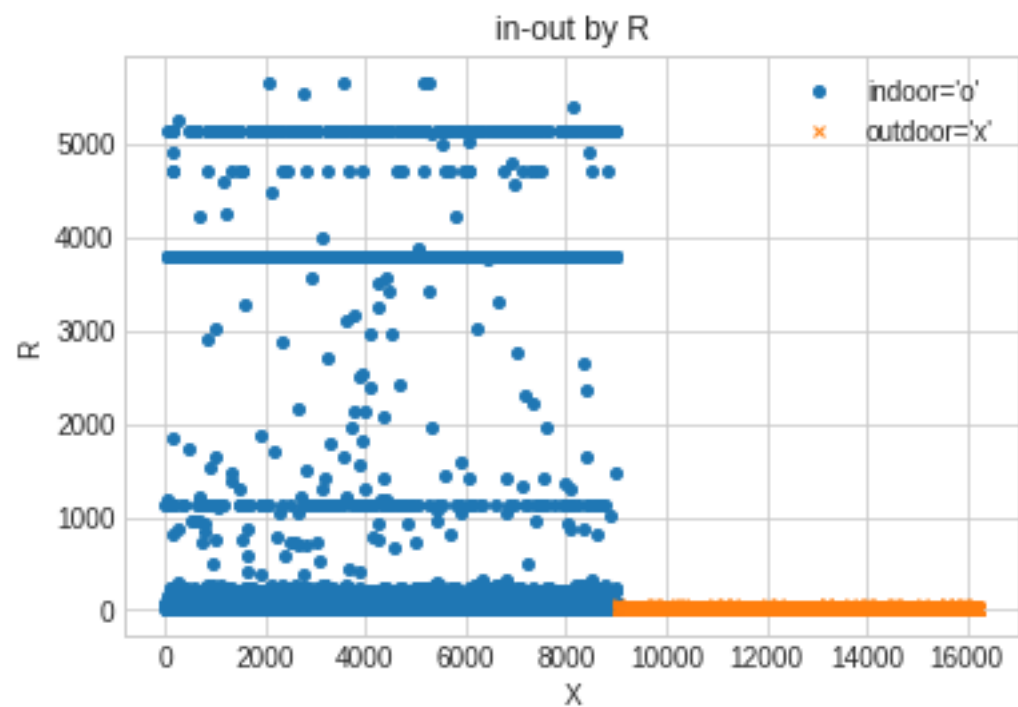
Training data



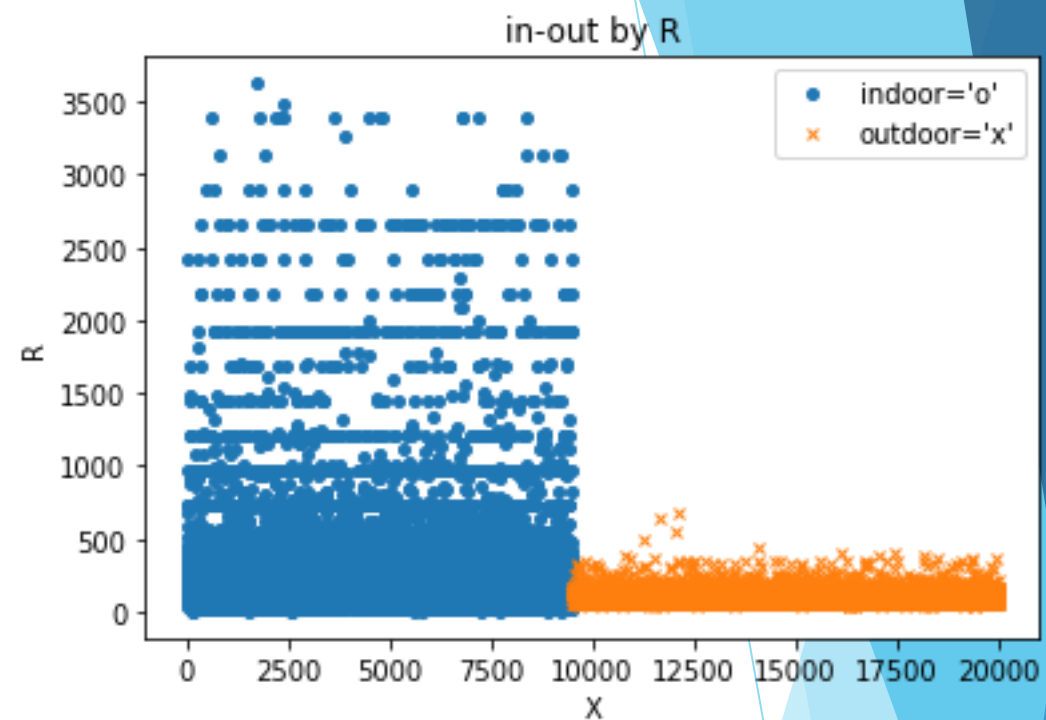
Testing data

特征 11 / feature 11

tenTotal : 将 360° 分为 36 份(10°), 包含卫星的份数总和与 36 之比



Training data



Testing data

特征 12 / feature 12
R :GPS 预测误差半径

模型 调试 try different models

- ▶ 特征个数减少 reduce training features from 12 to 11, 8.
- ▶ 参数调整 parameters adjustments.

采集的训练数据集 zhuyining

采集的测试数据集 guihan

去掉 gpsz_stdz, 用 11 个特征, 4个子模型, 深度6

地铁室外跑

	(963, 13)				
	(963, 11)	(963,)			
	0.993959938366718	0.4818276220145379			
	precision	recall	f1-score	support	
indoor	0.00	0.00	0.00	0	
outdoor	1.00	0.48	0.65	963	
accuracy			0.48	963	
macro avg	0.50	0.24	0.33	963	
weighted avg	1.00	0.48	0.65	963	

地铁站内

	(2809, 13)				
	(2809, 11)	(2809,)			
	0.993959938366718	0.33855464578141686			
	precision	recall	f1-score	support	
indoor	1.00	0.34	0.51	2809	
outdoor	0.00	0.00	0.00	0	
accuracy			0.34	2809	
macro avg	0.50	0.17	0.25	2809	
weighted avg	1.00	0.34	0.51	2809	

其他
(删掉 地铁室外跑& 地铁站内)

	(19990, 13)				
	(19990, 11)	(19990,)			
	0.993959938366718	0.9173586793396699			
	precision	recall	f1-score	support	
indoor	0.98	0.85	0.91	9502	
outdoor	0.88	0.98	0.93	10488	
accuracy			0.92	19990	
macro avg	0.93	0.91	0.92	19990	
weighted avg	0.92	0.92	0.92	19990	

采集的训练数据集 zhuyining

采集的测试数据集 guihan

去掉 gpsz_stdz, 用 11 个特征, 4个子模型, 深度6

用 12 个特征, 4个子模型, 深度10

	precision	recall	f1-score	support
indoor	0.00	0.00	0.00	0
outdoor	1.00	0.48	0.65	963
accuracy			0.48	963
macro avg	0.50	0.24	0.33	963
weighted avg	1.00	0.48	0.65	963

地铁室外跑

	precision	recall	f1-score	support
indoor	1.00	0.34	0.51	2809
outdoor	0.00	0.00	0.00	0
accuracy			0.34	2809
macro avg	0.50	0.17	0.25	2809
weighted avg	1.00	0.34	0.51	2809

地铁站内

	precision	recall	f1-score	support
indoor	0.98	0.85	0.91	9502
outdoor	0.88	0.98	0.93	10488
accuracy			0.92	19990
macro avg	0.93	0.91	0.92	19990
weighted avg	0.92	0.92	0.92	19990

其他

	precision	recall	f1-score	support
indoor	0.00	0.00	0.00	0
outdoor	1.00	0.26	0.41	963
accuracy			0.26	963
macro avg	0.50	0.13	0.21	963
weighted avg	1.00	0.26	0.41	963

	precision	recall	f1-score	support
indoor	1.00	0.38	0.55	2809
outdoor	0.00	0.00	0.00	0
accuracy			0.38	2809
macro avg	0.50	0.19	0.28	2809
weighted avg	1.00	0.38	0.55	2809

	precision	recall	f1-score	support
indoor	0.97	0.91	0.94	9502
outdoor	0.92	0.98	0.95	10488
accuracy			0.95	19990
macro avg	0.95	0.94	0.94	19990
weighted avg	0.95	0.95	0.94	19990

Reference

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The background features abstract, overlapping geometric shapes in various shades of blue, ranging from light sky blue to deep navy blue. These shapes are primarily located on the right side of the frame, creating a modern, layered effect. The rest of the background is a solid, very light blue-grey.

Thank you!