# Statistical testing of the covariance matrix rank in multidimensional neuronal models

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Seminar du departement DATA,

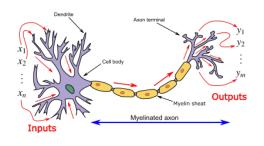
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Part I: Motivation

#### Motivation







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## Example 1: Hodgkin-Huxley model

Conductance-based model of action potential in neurons:

$$\begin{cases} I &= C_m \frac{\mathrm{d} V_m}{\mathrm{d} t} + \bar{g}_K n^4 (V_m - V_K) + \bar{g}_{Na} m^3 h(V_m - V_{Na}) + \bar{g}_l(V_m - V_l) \\ \frac{\mathrm{d} n}{\mathrm{d} t} &= \alpha_n(V_m)(1-n) - \beta_n(V_m) n \\ \frac{\mathrm{d} m}{\mathrm{d} t} &= \alpha_m(V_m)(1-m) - \beta_m(V_m) m \\ \frac{\mathrm{d} h}{\mathrm{d} t} &= \alpha_h(V_m)(1-h) - \beta_h(V_m) h \end{cases}$$

- ► *I* membrane potential
- ▶ *n*, *m*, *h* − quantities between 0 and 1 that are associated with potassium channel activation, sodium channel activation, and sodium channel inactivation.

**References:** Hodgkin and Huxley (1952) - 1963 Nobel Prize in Physiology or Medicine,

Modifications: Fitzhugh (1961), Morris and Lecar (1981)





#### Example 2: Jansen and Rit Neural Mass model

Convolution-based model of a **neuronal population with excitatory and enhibitory subpopulations**:

$$\begin{cases} dQ(t) = \nabla_P H(Q, P) dt, \\ dP(t) = (-\nabla H(Q, P) - 2\Gamma P + G(t, Q)) dt + \Sigma(t) dW_t, \end{cases}$$

- $ightharpoonup Q = (X_0, X_1, X_2) \in \mathbb{R}^3, P = (X_3, X_4, X_5) \in \mathbb{R}^3$
- ▶  $\Gamma = \text{diag}[a, a, b] \in \mathbb{R}^{3 \times 3}$  is a damping part,
- $\Sigma(t) = \text{diag}[\sigma_3(t), \sigma_4(t), \sigma_5(t)] \in \mathbb{R}^{3 \times 3}$  is a diffusion part,
- ightharpoonup G(t, Q) is a nonlinear displacement term.
- ▶ Diffusion components are of **different order** (e.q.  $\sigma_3(t), \sigma_5(t) \ll \sigma_4(t)$ )!

References: Jansen and Rit (1995), Ableidinger et al. (2017), Buckwar et al. (2)





#### Example 2: Jansen and Rit Neural Mass model

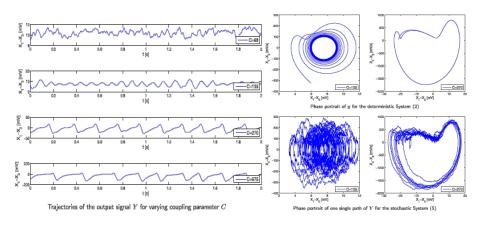


Figure: Source: Ableidinger et al. (2017)





# Example 3: Diffusion approximation of a Hawkes process

**Hawkes process** (point process with memory), describing the action potentials in a population of neurons, can be approximated by a stochastic diffusion:

$$dZ_t = A(Z_t)dt + B(Z_t)dW_t.$$

$$A(z) = \begin{pmatrix} -\nu_1 z^1 + z^2 \\ -\nu_1 z^2 + z^3 \\ \vdots \\ -\nu_1 z^{\eta_1 + 1} + c_1 f_2(z^{\eta_1 + 2}) \\ -\nu_2 z^{\eta_1 + 2} + z^{\eta_1 + 3} \\ \vdots \\ -\nu_n z^{\kappa} + c_n f_1(z^1) \end{pmatrix}, \quad B(z) = \frac{1}{\sqrt{N}} \begin{pmatrix} 0 & 0 \\ \vdots & \vdots \\ 0 & \frac{c_1}{\sqrt{p}_2} \sqrt{f_2(z^{\eta_1 + 2})} \\ 0 & 0 \\ \vdots & \vdots \\ \frac{c_n}{\sqrt{p}_1} \sqrt{f_1(z^1)} & 0 \end{pmatrix},$$

Reference: Ditlevsen and Löcherbach (2017), Chevallier (2017)





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## Example 3: Diffusion approximation of a Hawkes process

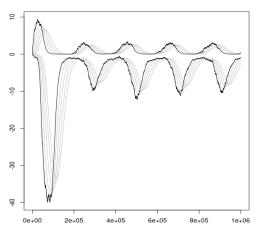


Figure: Diffusion approximation of Hawkes process describing inhibitory and excitatory neuron population (20 neurons in each population)





## Where to put noise?

#### Main challenges:

- Highly non-linear systems
- Computational cost
- Measurements inaccuracy
- Diffusion coefficients of different orders

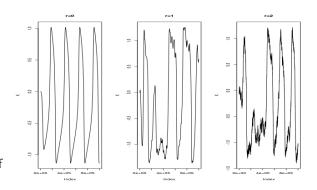


Figure: Membrane potential simulated wiht a FitzHugh-Nagumo model: deterministic, noisy channels, elliptic system

**References:** see Tuckwell (2005) for general overview of stochastic neuronal models





Part II: Problem statement and preliminaries

#### Formalization

#### Given:

Discrete observations  $X_i$  of the d-dimensional process

$$dX_t = A_t dt + B_t dW_t, \ t \in [0, T], \tag{1}$$

 $A_t \in \mathbb{R}^d, B_t \in \mathbb{R}^{d \times q}.$ 

#### Goal:

Propose a test

$$H_0: rank(\Sigma) = r_0$$

$$H_1: rank(\Sigma) \neq r_0,$$

where  $\Sigma = B_t B_t^T$ . If  $B_t$  is not constant, we search  $\sup_t \operatorname{rank}(\Sigma)$  instead.





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## Other applications

- ► Financial mathematics:
  - Volatility rank in multi-assets portfolio
- ► Sensitivity analysis:
  - Number of influential inputs
- ► Number of components in noisy data
  - Estimate rank (or biggest eigenvalues) of *D*, given only observations

$$D+E$$
,

where *E* — unknown matrix of noise.

**References:** Konstantinides and Yao (1988), Zarowski (1998), Kritchman and Nadler (2008), Iooss and Lemaître (2015)

Applications: signal processing, chemometrics, genomics.





## What do we want to study?

Given a *d*-dimensional process i = 1, ..., N, we study the matrices of increments:

$$\bar{s}_{i} := \begin{pmatrix} \frac{X_{id+1}^{(1)} - X_{id}^{(1)}}{\sqrt{\Delta}} & \frac{X_{id+2}^{(1)} - X_{id+1}^{(1)}}{\sqrt{\Delta}} & \cdots & \frac{X_{id+d}^{(1)} - X_{id+d-1}^{(1)}}{\sqrt{\Delta}} \\ \frac{X_{id+1}^{(2)} - X_{id}^{(2)}}{\sqrt{\Delta}} & \frac{X_{id+2}^{(2)} - X_{id+1}^{(2)}}{\sqrt{\Delta}} & \cdots & \frac{X_{id+2d}^{(2)} - X_{id+d-1}^{(2)}}{\sqrt{\Delta}} \\ \cdots & \cdots & \cdots & \cdots \\ \frac{X_{id+1}^{(d)} - X_{id}^{(d)}}{\sqrt{\Delta}} & \frac{X_{id+2}^{(d)} - X_{id+1}^{(d)}}{\sqrt{\Delta}} & \cdots & \frac{X_{id+d}^{(d)} - X_{id+d-1}^{(d)}}{\sqrt{\Delta}} \end{pmatrix}$$

$$(2)$$





#### What is the determinant?

For a 3-dimensional system the determinant

$$\det\begin{pmatrix} e_{11} & e_{12} & e_{13} \\ e_{21} & e_{22} & e_{23} \\ e_{31} & e_{32} & e_{33} \end{pmatrix} = \\ e_{11} \det\begin{pmatrix} e_{22} & e_{23} \\ e_{32} & e_{33} \end{pmatrix} - e_{12} \det\begin{pmatrix} e_{21} & e_{23} \\ e_{31} & e_{33} \end{pmatrix} + e_{13} \det\begin{pmatrix} e_{21} & e_{22} \\ e_{31} & e_{32} \end{pmatrix} = \\ e_{11}e_{22}e_{33} - e_{11}e_{32}e_{23} - e_{12}e_{21}e_{33} + e_{12}e_{31}e_{23} + e_{13}e_{21}e_{32} - e_{13}e_{31}e_{22} \end{pmatrix}$$





# Straightforward approach: Jacod et al. (2008)

Main idea: check if the determinant of the submatrix of a given rank is "small enough"

- ► Compute matrices of increments (2) (squares of it)
- $\blacktriangleright$  Define a converging sequence  $\{\rho_{\it N}\}$  of "thresholds", s.t.:

$$\rho_N \to 0, \ \rho_N \sqrt{N} \to \infty$$

▶ Define by  $A_r$  class of all subsets of  $\{1, \ldots d\}$  with r elements. Define  $\det_K \Sigma$  the determinant of  $r \times r$  submatrix of  $\Sigma^{kl}$ ,  $k, l \in K$ . Finally, define:

$$\det(r; \Sigma) = \sum_{K \in A} \det_{K} \Sigma \tag{3}$$

 $ightharpoons \widehat{R}_{T,\Delta} = \inf \left\{ r \in \{0,\dots,d-1\} : \frac{1}{\Delta(r+1)!} \sum_{i=1}^{N-r+1} \det(r+1;\bar{s}_i) < \rho_N T \right\}$ 

#### Remark

*Note that*  $det(1; \Sigma) = Tr(\Sigma)$ , and  $det(d; \Sigma) = det(\Sigma)$ .

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# Improved procedure: Jacod et al. (2008)

**Main idea:** check if the *difference* between the determinant of the submatrix of a given rank and the alternative rank is "big enough"

- ► Compute matrices of increments (2)
- ► Compute the statistics (3) and the "estimators" along with their variances:

$$\bar{R}_{T,\Delta}(r) = \frac{1}{\Delta^{r-1}r!} \frac{\sum_{i=1}^{N-r+1} \det(r, \bar{s}_i)}{\left(\sum_{i=1}^{N-r+1} \det(1; \bar{s}_i)\right)^r}$$

- ► Intuitively, if  $r < r_0$ ,  $\bar{R}_{T,\Delta}(r_0) \approx 0$
- ▶ We have *sort of* test for verifying  $H_1 : r < r_0$ .





# Improved procedure: Jacod et al. (2008)

#### **Limitations** of the method:

- ► Complicated to compute when *d* is big
- One-sided test: two-sided test would be more convenient
- Performance for systems with non-linear drift and/or higly-degenerate diffusion matrix





#### When does it fail?

#### Example: Brownian motion

#### Consider the system:

$$\begin{cases} X_t^1 = \int_0^t \sigma^1 dW_t \\ X_t^2 = \int_0^t \sigma^2 dW_t \end{cases}$$

$$s_i = \begin{pmatrix} \sigma^1(W_{2i+1} - W_{2i}) & \sigma^1(W_{2i+2} - W_{2i+1}) \\ \sigma^2(W_{2i+1} - W_{2i}) & \sigma^2(W_{2i+2} - W_{2i+1}) \end{pmatrix}$$





# Part III: Random perturbation

approach

# Going further: Jacod and Podolskij (2013)

**Assume:** computing det *E* is difficult. **But** computing det(E + D) is easy.

Then:

$$\frac{\det\left(E+2hD\right)}{\det\left(E+hD\right)}\approx 2^{d-r}$$

Because:

$$\det (E + hD) = \det E + h\gamma_{d-1}(E, D) + \cdots + h^d \det D,$$

where  $\gamma_r, r=1,\ldots,d$  stands for a sum of determinants of all possible matrices, whose r columns are equal to r columns of a matrix E (with the same indexes), and the remaining d-r to the corresponding columns of a matrix D.





#### Determinant expansion: deterministic 3d-example

$$\det(E+hD) = \\ \det\begin{pmatrix} e_{11} + hd_{11} & e_{12} + hd_{12} & e_{13} + hd_{13} \\ e_{21} + hd_{21} & e_{22} + hd_{22} & e_{23} + hd_{23} \\ e_{31} + hd_{31} & e_{32} + hd_{32} & e_{33} + hd_{33} \end{pmatrix} = \det\begin{pmatrix} e_{11} & e_{12} & e_{13} \\ e_{21} & e_{22} & e_{23} \\ e_{31} & e_{32} & e_{33} \end{pmatrix} + \\ h \det\begin{pmatrix} e_{11} & e_{12} & d_{13} \\ e_{21} & e_{22} & d_{23} \\ e_{31} & e_{32} & d_{33} \end{pmatrix} + h \det\begin{pmatrix} e_{11} & d_{12} & e_{13} \\ e_{21} & d_{22} & e_{23} \\ e_{31} & d_{32} & e_{33} \end{pmatrix} + h \det\begin{pmatrix} d_{11} & e_{12} & e_{13} \\ d_{21} & e_{22} & e_{23} \\ d_{31} & e_{32} & e_{33} \end{pmatrix} + \\ h^2 \det\begin{pmatrix} e_{11} & d_{12} & d_{13} \\ e_{21} & d_{22} & d_{23} \\ e_{31} & d_{32} & d_{33} \end{pmatrix} + h^2 \det\begin{pmatrix} d_{11} & d_{12} & e_{13} \\ d_{21} & d_{22} & e_{23} \\ d_{31} & d_{32} & d_{33} \end{pmatrix} + h^2 \det\begin{pmatrix} d_{11} & d_{12} & d_{13} \\ d_{21} & d_{22} & d_{23} \\ d_{31} & d_{32} & d_{33} \end{pmatrix} + \\ h^3 \det\begin{pmatrix} d_{11} & d_{12} & d_{13} \\ d_{21} & d_{22} & d_{23} \\ d_{31} & d_{32} & d_{33} \end{pmatrix} + \\ h^3 \det\begin{pmatrix} d_{11} & d_{12} & d_{13} \\ d_{21} & d_{22} & d_{23} \\ d_{31} & d_{32} & d_{33} \end{pmatrix} + h^3 \det\begin{pmatrix} d_{11} & d_{12} & d_{13} \\ d_{21} & d_{22} & d_{23} \\ d_{31} & d_{32} & d_{33} \end{pmatrix} + h^3 \det\begin{pmatrix} d_{11} & d_{12} & d_{13} \\ d_{21} & d_{22} & d_{23} \\ d_{31} & d_{32} & d_{33} \end{pmatrix} + h^3 \det\begin{pmatrix} d_{11} & d_{12} & d_{13} \\ d_{21} & d_{22} & d_{23} \\ d_{31} & d_{32} & d_{33} \end{pmatrix} + h^3 \det\begin{pmatrix} d_{11} & d_{12} & d_{13} \\ d_{21} & d_{22} & d_{23} \\ d_{31} & d_{32} & d_{33} \end{pmatrix} + h^3 \det\begin{pmatrix} d_{11} & d_{12} & d_{13} \\ d_{21} & d_{22} & d_{23} \\ d_{31} & d_{32} & d_{33} \end{pmatrix} + h^3 \det\begin{pmatrix} d_{11} & d_{12} & d_{13} \\ d_{21} & d_{22} & d_{23} \\ d_{31} & d_{32} & d_{33} \end{pmatrix} + h^3 \det\begin{pmatrix} d_{11} & d_{12} & d_{13} \\ d_{21} & d_{22} & d_{23} \\ d_{31} & d_{32} & d_{33} \end{pmatrix} + h^3 \det\begin{pmatrix} d_{11} & d_{12} & d_{13} \\ d_{21} & d_{22} & d_{23} \\ d_{31} & d_{32} & d_{33} \end{pmatrix} + h^3 \det\begin{pmatrix} d_{11} & d_{12} & d_{13} \\ d_{21} & d_{22} & d_{23} \\ d_{31} & d_{32} & d_{33} \end{pmatrix} + h^3 \det\begin{pmatrix} d_{11} & d_{12} & d_{13} \\ d_{21} & d_{22} & d_{23} \\ d_{21} & d_{22}$$





#### Random perturbation approach

Given a *d*-dimensional diffusion process *X*, consider 2 new processes:

$$\tilde{X}_t^{(k)} = X_t + \sqrt{k\Delta} \tilde{\Sigma} \tilde{W}_t,$$

where  $\tilde{\Sigma}$  is a non-random matrix of full rank.

**Idea:** "Measure the influence" of the perturbation by considering the statistics with different step size (here:  $\Delta$  and  $2\Delta$ ).





## Toy example: 1-d process with constant drift and diffusion

Take the process:

$$dX_t = adt + \sigma dW_t$$

Add the random perturbation:

$$\begin{split} \tilde{X}_t^{(1)} &= adt + \sigma dW_t + \sqrt{\Delta} \tilde{\sigma} \, \tilde{W}_t, \\ \tilde{X}_t^{(2)} &= adt + \sigma dW_t + \sqrt{2\Delta} \tilde{\sigma} \, \tilde{W}_t \end{split}$$

Using the first-order approximation, compute:

$$\mathbb{E}\left[\left(\frac{\tilde{X}_{i+1}^{(k)} - \tilde{X}_{i}^{(k)}}{\sqrt{k\Delta}}\right)^{2}\right] = \sigma^{2} + k\Delta a + k\Delta \tilde{\sigma} =: s_{i}^{k}$$

Notice that

$$\frac{s_i^2}{s_i^1} = \begin{cases} 1 + O(\Delta) & \text{if } \sigma \neq 0\\ 2 & \text{if } \sigma = 0 \end{cases}$$





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Notice that

$$\frac{s_i^2}{s_i^1} = \begin{cases} 1 + O(\Delta) & \text{if } \sigma \neq 0 \\ 2 & \text{if } \sigma = 0 \end{cases} \Rightarrow 1 - \frac{\log \mathbb{E} \frac{s_i}{s_i^1}}{\log 2} = \begin{cases} 1 & \text{if } \sigma \neq 0 \\ 0 & \text{if } \sigma = 0 \end{cases}$$



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#### Random perturbation approach: key statistics

Key statistics of the test for a *d*-dimensional process  $s_i^k$ , i = 1, 2 is defined as follows:

$$S_{T}^{k} = 2d\Delta \sum_{i=0}^{N-1} \det \begin{pmatrix} \tilde{\chi}_{2id+k}^{1,(k)} - \tilde{\chi}_{2id}^{1,(k)} & \tilde{\chi}_{2id+2k}^{1,(k)} - \tilde{\chi}_{2id+k}^{1,(k)} & \cdots & \tilde{\chi}_{2id+2d}^{1,(k)} - \tilde{\chi}_{2id+kd-k}^{1,(k)} \\ \frac{\tilde{\chi}_{2id+k}^{2,(k)} - \tilde{\chi}_{2id}^{2,(k)}}{\sqrt{k\Delta}} & \frac{\tilde{\chi}_{2id+2k}^{2,(k)} - \tilde{\chi}_{2id+k}^{2,(k)}}{\sqrt{k\Delta}} & \cdots & \frac{\tilde{\chi}_{2id+2d}^{1,(k)} - \tilde{\chi}_{2id+kd-k}^{2,(k)}}{\sqrt{k\Delta}} \\ \cdots & \cdots & \cdots & \cdots \\ \frac{\tilde{\chi}_{2id+k}^{d,(k)} - \tilde{\chi}_{2id}^{d,(k)}}{\sqrt{k\Delta}} & \frac{\tilde{\chi}_{2id+2k}^{d,(k)} - \tilde{\chi}_{2id+k}^{d,(k)}}{\sqrt{k\Delta}} & \cdots & \frac{\tilde{\chi}_{2id+2d}^{d,(k)} - \tilde{\chi}_{2id+kd-k}^{d,(k)}}{\sqrt{k\Delta}} \end{pmatrix}^{2d}$$





## Random perturbation approach: estimator

Define:

$$\begin{split} \hat{R}_{T,\Delta} &= d - \frac{\log \frac{S_T^2}{S_T^1}}{\log 2} \\ V(T,\Delta) &:= Var \Big[ \widehat{R}_{T,\Delta} \Big] &= \frac{\left( \frac{E[S_T^1]}{E[S_T^2]} \right)^2 Var[S_T^2] - 2 \frac{E[S_T^1]}{E[S_T^2]} Cov[S_T^1 S_T^2] + Var[S_T^1]}{(E[S_T^1] \log 2)^2} \end{split}$$

Corollary (3.6 in Jacod and Podolskij (2013))

$$\frac{\widehat{R}(T,\Delta) - r_0}{\sqrt{\Delta V(T,\Delta)}} \xrightarrow{\mathcal{L}} \mathcal{N}(0,1)$$





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# Random perturbation approach: testing procedure

#### **Summary:**

$$H_0: rank(\Sigma) = r_0$$
  
 $H_1: rank(\Sigma) \neq r_0$ 

**Decision rule:** reject  $H_0$  with  $(1 - \alpha)\%$  confidence level if

$$q_{\frac{\alpha}{2}} \nleq \frac{\widehat{R}(T,\Delta) - r_0}{\sqrt{\Delta V(T,\Delta)}} \nleq q_{1-\frac{\alpha}{2}}$$





# Random perturbation approach: testing procedure

#### Summary:

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**Decision rule:** reject  $H_0$  with  $(1 - \alpha)\%$  confidence level if

$$q_{\frac{\alpha}{2}} \nleq \frac{\widehat{R}(T,\Delta) - r_0}{\sqrt{\Delta V(T,\Delta)}} \nleq q_{1-\frac{\alpha}{2}}$$

**Problem:** choose  $\tilde{\Sigma}$  wisely!





# Question 1: why do we need perturbations?

#### Example: Brownian motion

Consider the system:

$$\begin{cases} X_t^1 = \int_0^t \sigma^1 dW_t \\ X_t^2 = \int_0^t \sigma^2 dW_t \end{cases}$$

$$s_i^k = \frac{1}{k\Delta} \det \begin{pmatrix} \sigma^1(W_{2i+k} - W_{2i}) & \sigma^1(W_{2i+2k} - W_{2i+k}) \\ \sigma^2(W_{2i+k} - W_{2i}) & \sigma^2(W_{2i+2k} - W_{2i+k}) \end{pmatrix}^2$$

Note that  $\mathbb{E}[s_i^k] = 0$  for k = 1, 2.





# Question 1: why do we need perturbations?

#### Example: Brownian motion

Consider the system:

$$\begin{cases} \tilde{X}_t^{1,(k)} = \int_0^t \sigma^1 dW_t + \sqrt{k\Delta} \tilde{\sigma} d\tilde{W}_t^1 \\ \tilde{X}_t^{2,(k)} = \int_0^t \sigma^2 dW_t + \sqrt{k\Delta} \tilde{\sigma} d\tilde{W}_t^2 \end{cases}$$

$$s_{i}^{k} = \frac{1}{k\Delta} \det \begin{pmatrix} \sigma^{1}(W_{2i+k} - W_{2i}) + \sqrt{k\Delta}\tilde{\sigma}(W_{2i+k}^{1} - W_{2i}^{1}) \\ \sigma^{2}(W_{2i+k} - W_{2i}) + \sqrt{k\Delta}\tilde{\sigma}(\tilde{W}_{2i+k}^{2} - \tilde{W}_{2i}^{2}) \end{pmatrix}$$

$$\frac{\sigma^{1}(W_{2i+2k} - W_{2i+k}) + \sqrt{k\Delta}\tilde{\sigma}(\tilde{W}_{2i+2k}^{1} - \tilde{W}_{2i+k}^{1})}{\sigma^{2}(W_{2i+2k} - W_{2i+k}) + \sqrt{k\Delta}\tilde{\sigma}(\tilde{W}_{2i+2k}^{2} - \tilde{W}_{2i+k}^{2})}^{2}$$

Note that  $\mathbb{E}[s_i^k] = k\Delta(\tilde{\sigma})^2$  for k = 1, 2.



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# Question 2: how to choose $\Sigma$ ?

#### Ongoing work

A. M., Adeline Samson, Patricia Reynaud-Bouret

Assume  $\tilde{\Sigma} = \tilde{\sigma} \mathit{I}$ . The increments of the perturbed process can be decomposed as:

$$\begin{split} \frac{\tilde{X}_{i+k}^{j,(k)} - \tilde{X}_{i}^{j,(k)}}{\sqrt{k\Delta}} &\approx \frac{1}{\sqrt{k\Delta}} \sum_{l=1}^{q} \sigma_{i}^{jl} \left( W_{i+k}^{jl} - W_{i}^{jl} \right) + \\ &\sqrt{k\Delta} \left( a_{i}^{j} + \frac{1}{\sqrt{k\Delta}} \tilde{\sigma} \left( \tilde{W}_{i+k}^{j} - \tilde{W}_{i}^{j} \right) \right) + \\ &\frac{1}{\sqrt{k\Delta}} a_{i}^{\prime j} \sum_{l=1}^{q} \int_{i\Delta}^{(i+k)\Delta} \sigma_{i}^{jl} \left( W_{i+k}^{il} - W_{i}^{jl} \right) dW_{s}^{j} + O(\Delta^{\frac{3}{2}}) \end{split}$$





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Assume  $\tilde{\Sigma} = \tilde{\sigma} I$ . The increments of the perturbed process can be decomposed as:

$$\frac{\tilde{\chi}_{i+k}^{j,(k)} - \tilde{\chi}_{i}^{j,(k)}}{\sqrt{k\Delta}} \approx \frac{1}{\sqrt{k\Delta}} \sum_{l=1}^{q} \sigma_{i}^{jl} \left( W_{i+k}^{jl} - W_{i}^{jl} \right) + \frac{d_{i}^{j} + \tilde{\sigma} \cdot \mathcal{N}(0,1)}{\sqrt{k\Delta}} \left( d_{i}^{j} + \frac{1}{\sqrt{k\Delta}} \tilde{\sigma} \left( \tilde{W}_{i+k}^{j} - \tilde{W}_{i}^{j} \right) \right) + \frac{1}{\sqrt{k\Delta}} d_{i}^{j} \sum_{l=1}^{q} \int_{i\Delta}^{(i+k)\Delta} \sigma_{i}^{jl} \left( W_{i+k}^{jl} - W_{i}^{jl} \right) dW_{s}^{j} + O(\Delta^{\frac{3}{2}})$$
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# Part IV: Numerical experiments

# General setting

- 1. Generate 1000 trajectories with  $\Delta=1e-5,\, T=10,$  using 1.5 strong order scheme
- 2. Subsample the data with a bigger  $\Delta$  (see tables for details)
- 3. Compute test statistics  $\hat{R}(T, \Delta)$  and  $V(T, \Delta)$
- 4. Test the "true" and a "wrong" hypothesis
- 5. Report the results





## Example 1: FitzHugh-Nagumo model

The behaviour of the neuron is defined through:

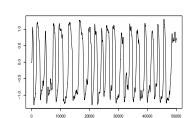
$$\begin{cases} dX_t = \frac{1}{\varepsilon} (X_t - X_t^3 - Y_t - s) dt + \sigma_1 dW_t^1 \\ dY_t = (\gamma X_t - Y_t + \beta) dt + \sigma_2 dW_t^2 \end{cases}$$

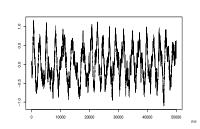
- $ightharpoonup X_t$  membrane potential
- $ightharpoonup Y_t$  recovery variable
- ightharpoonup s magnitude of the stimulus current

#### Parameters used in simulations:

$$\varepsilon = 0.1, \beta = 0.3, \gamma = 1.5, s = 0.01.$$







# Numerical performance: FitzHugh-Nagumo model

$r_0 = 2$	$\tilde{\sigma} = 0$	$\tilde{\sigma} = 0.5$	$\tilde{\sigma} = 1$	$\tilde{\sigma} = 10$
$\Delta = 0.1$	0.653 (0.964)	0.655 (0.966)	0.655 (0.966)	0.056 (0.805)
	47.9%, 80.9%	48%, 20.4%	49.7%, 19.5%	78.6%, 38.1%
$\Delta = 1e - 2$	1.713 (0.293)	1.699 (0.292)	1.656 (0.286)	0.407 (0.254)
	20.7%, 99%	22.4%, 42.8%	26.9%, 67.9%	100%, 65.4%
$\Delta = 1e - 3$	1.962 (0.082)	1.960 (0.082)	1.954 (0.082)	1.410 (0.085)
	8.8%, 100%	9.4%, 100%	10%, 100%	100%, 99.8%
$\Delta = 1e - 4$	1.998 (0.026)	1.995 (0.026)	1.995 (0.026)	1.920 (0.026)
	6.1%, 100%	6.2%, 100%	6.1%, 100%	87.4%, 100%

Table: Results of the 5%-test for FitzHugh-Nagumo: **elliptic case**. First line: mean value of  $\hat{R}(\Delta, T)$  and its standard deviation, second line: percent of rejections of the true  $H_0$  hypothesis and false  $H_0$  ( $r = r_0 - 1$ )





# Numerical performance: FitzHugh-Nagumo model

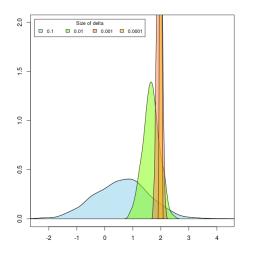
$r_0 = 1$	$\tilde{\sigma} = 0$	$\tilde{\sigma} = 0.5$	$\tilde{\sigma} = 1$	$\tilde{\sigma} = 10$
$\Delta = 0.1$	0.436 (1.044)	0.432 (1.032)	0.452 (1.040)	0.044 (0.807)
	22.8%, 52.3%	23.1%, 55.7%	25.7%, 58.6%	38.1%, 12.7%
$\Delta = 1e - 2$	0.950 (0.478)	0.942 (0.470)	0.913 (0.435)	0.204 (0.266)
	9.6%, 68.2%	11.2%, 92%	10.3%, 98.1%	87%, 14.8%
$\Delta = 1e - 3$	0.994 (0.147)	0.993 (0.145)	0.989 (0.138)	0.711 (0.085)
	4.8%, 100%	4.9%, 100%	5.6%, 100%	93.5%, 100%
$\Delta = 1e - 4$	0.997 (0.047)	0.997 (0.026)	0.997 (0.047)	0.961 (0.027)
	5.2%, 100%	4.7%, 100%	4.8%, 100%	30.9%, 100%

Table: Results of the 5%-test for FitzHugh-Nagumo: **hypoelliptic** case. First line: mean value of  $\hat{R}(\Delta, T)$  and its standard deviation, second line: percent of rejections of the true  $H_0$  hypothesis and false  $H_0$  ( $r = r_0 - 1$ )





# Numerical performance: FitzHugh-Nagumo model







# Example 2: diffusion aproximation of Hawkes process

Approximating SDE describing the spiking activity in a network of neurons, consisting of 2 subpopulations:

$$dZ_t = A(Z_t)dt + B(Z_t)dW_t.$$

- ▶ 2 populations: **inhibitory** and **excitatory** (2 rough variables)
- ightharpoonup 2 or 4 memory variables in each populations (respectively, 4 or 10-dimensional system)
- ▶ 100 neurons in each population





# Numerical performance: Diffusion approximation of Hawkes process

$r_0 = 2$	$\tilde{\sigma} = 0$	$\tilde{\sigma} = 0.1$	$\tilde{\sigma} = 0.5$	$\tilde{\sigma} = 1$
$\Delta = 0.1$	( <u>*</u> <u>*</u>	-1.177 (2.398)	0.338 (2.678)	0.308 (2.195)
		70.1%, 59.3%	62%, 58.4%	56.1%, 42.6%
$\Delta = 1e - 2$	( <u>*</u> *	1.543 (1.157)	1.043 (0.979)	0.850 (0.831)
$\Delta = 1e - 2$		21.6%, 20.8%	34.3%, 14.5%	48.1%, 13.2%
$\Delta = 1e - 3$	<u>(x x)</u>	2.032 (0.386)	1.782 (0.369)	1.179 (0.291)
$\Delta = 1e - 3$		4.1%, 73.3%	14.2%, 57.9%	79.9%, 8.5%
$\Delta = 1e - 4$	( <u>*</u> *)	2.059 (0.137)	1.903 (0.143)	1.805 (0.132)
$\Delta = 1e - 4$		4.2%, 100%	9.6%, 100%	31.8%, 99.9%

Table: Results of the 5%-test for diffusion approximation model (d=4). First line: mean value of  $\hat{R}(\Delta,T)$  and its standard deviation, second line: percent of rejections of the true  $H_0$  hypothesis and false  $H_0$  ( $r=r_0-1$ )





# Numerical performance: Diffusion approximation of Hawkes process

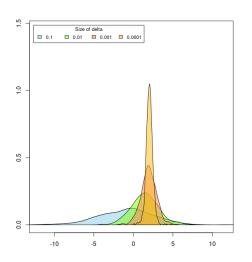
$r_0 = 2$	$\tilde{\sigma} = 0$	$\tilde{\sigma} = 0.1$	$\tilde{\sigma} = 0.5$	$\tilde{\sigma} = 1$
$\Delta = 0.1$	( <u>x</u> <u>x</u> )	-1.023 (3.856)	-0.101 (3.249)	0.300 (3.199)
		75.9%, 72.1%	60.1%, 57%	57.9%, 53.4%
$\Delta = 1e - 2$	( <u>*</u> <u>*</u>	1.211 (1.784)	1.161 (1.471)	1.069 (1.450)
$\Delta = 1e - 2$		33.2%, 27.9%	30.6%, 23.3%	33.6%, 23.6%
$\Delta = 1e - 3$	( <u>*</u> <u>*</u> )	1.822 (0.889)	1.739 (0.772)	1.347 (0.655)
$\Delta = 1e - 3$		15.2%, 34.3%	13.3%, 29.9%	31.5%, 15.6%
$\Delta = 1e - 4$	( <u>*</u> <u>*</u> )	2.004 (0.359)	1.975 (0.348)	1.94 (0.336)
$\Delta = 1e - 4$		6.9%, 84.8%	5.8%, 84.6%	7.9%, 87.9%

Table: Results of the 5%-test for diffusion approximation model (d=10). First line: mean value of  $\hat{R}(\Delta,T)$  and its standard deviation, second line: percent of rejections of the true  $H_0$  hypothesis and false  $H_0$  ( $r=r_0-1$ )





# Numerical performance: Diffusion approximation of Hawkes process







#### General comments

- For **deterministic systems**: in general,  $\tilde{\sigma}$  has no influence on accuracy, BUT setting  $\tilde{\sigma} = 0$  breaks the test.
- ▶ For **elliptic systems**: perturbations diminish the accuracy, setting  $\tilde{\sigma} = 0$  seems to be the optimal choice.
- ▶ For **hypoelliptic systems**: highly-degenerate systems are sensitive to  $\tilde{\sigma}$ . If  $\tilde{\sigma}$  is too big, we will not learn that the system is hypoelliptic, if it's too small, the algorithm will break!

#### **Possible solutions:**

- ▶ Bound the  $\tilde{\sigma}$  to the empirical variance. It is observable, but we need to go back to thresholds.
- ▶ Work with a sequence of  $\tilde{\sigma}_N$ , bounded to the variance?





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