

# **EGC 301P Operating Systems Lab**

# **List of Operating Systems Lab Exercises**

### I File Management

- 1. **Creating Different File Types:** Utilize both shell commands and system calls to create the following types of files:
  - a. soft link (using the symlink system call)
  - b. hard link (using the link system call)
  - c. FIFO (using either the mkfifo Library Function or the mknod system call)
- 2. **Background Process Exploration:** Develop a simple program to execute indefinitely in the background. Traverse the /proc directory and extract relevant process information from the corresponding proc directories.
- 3. **File Creation and Descriptor Printing:** Write a program that creates a file and prints its file descriptor value using the creat() system call.
- 4. **Opening Existing File:** Write a program to open an existing file in read-write mode. Experiment with the O\_EXCL flag.
- 5. **Continuous File Creation:** Create a program that generates five new files in an infinite loop. Execute the program in the background and inspect the file descriptor table at /proc/pid/fd.
- 6. **Input and Output Using System Calls:** Craft a program to take input from STDIN and display it on STDOUT using only read/write system calls.
- 7. **File Copying:** Develop a program to copy the contents of file1 into file2, emulating the behavior of the **\$cp file1 file2** command.



- 8. **Read-Only File Reading:** Write a program to open a file in read-only mode, read line by line, and display each line as it is read. Close the file upon reaching the end of the file.
- 9. **File Information Extraction:** Create a program to print various details about a given file, including:
  - a. Inode
  - b. Number of hard links
  - c. UID
  - d. GID
  - e. Size
  - f. Block size
  - g. Number of blocks
  - h. Time of last access
  - i. Time of last modification
  - j. Time of last change
- 10. **File Write and Seek:** Implement a program to open a file in read-write mode, write 10 bytes, move the file pointer by 10 bytes using Iseek, and then write another 10 bytes.
  - a. Check the return value of Iseek.
  - b. Open the file with od command and examine the empty spaces between the data.
- 11. **File Descriptor Duplication and Appending:** Write a program to open a file, duplicate the file descriptor, append the file with both descriptors, and verify whether the file is updated correctly.
  - a. Use **dup**
  - b. Use **dup2**
  - c. Use fcntl



- 12. **Determining Opening Mode of a File:** Create a program to find out the opening mode of a file using the **fcntl** system call.
- 13. **Waiting for STDIN Using Select:** Develop a program to wait for input from STDIN for 10 seconds using **select**. Include proper print statements to verify data availability within the specified time.
- 14. **File Type Identification:** Write a program that takes input from the command line and identifies the type of file. Ensure the program can recognize various file types.
- 15. **Displaying User Environmental Variables:** Create a program to display the environmental variables of the user, utilizing the **environ** variable.
- 16. **Mandatory Locking Implementation:** Write a program to perform mandatory locking with the following implementations:
  - a. Implement a write lock.
  - b. Implement a read lock.
- 17. **Online Ticket Reservation Simulation:** Develop a program to simulate online ticket reservation with the implementation of a write lock. Write one program to open a file, store a ticket number, and exit. Write a separate program to open the file, implement a write lock, read the ticket number, increment the number, print the new ticket number, and then close the file.
- 18. **Record Locking Implementation:** Write a program to perform record locking with the following implementations:
  - a. Implement a write lock.
  - b. Implement a read lock.

Create three records in a file. Whenever you access a particular record, first lock it, then modify/access it to avoid race conditions.



## **II Process Management**

- 19. **Process States:** Develop a program to initiate a process in distinct states:
  - a. running
  - b. sleeping
  - c. stopped

Confirm the current state of the process using the relevant commands.

- 20. **Printing Parent and Child Process IDs:** Write a program that calls fork and prints both the parent and child process IDs.
- 21. **File Writing by Parent and Child Processes:** Develop a program that opens a file, calls fork, and allows both the child and parent processes to write to the file. Examine the output of the file.
- 22. **Creating a Zombie State:** Write a program to create a zombie state in the running program.
- 23. **Creating an Orphan Process:** Develop a program to create an orphan process.
- 24. **Creating and Waiting for Child Processes:** Write a program to create three child processes. The parent process should wait for a specific child process using the waitpid system call.
- 25. Executing an Executable Program:
  - a. Execute a program using the exec system call.
  - b. Pass input to an executable program (e.g., execute an executable as **\$./a.out name**).
- 26. **Executing Is -RI Using Various exec System Calls:** Write a program to execute **Is - RI** using the following system calls:
  - a. execl
  - b. execlp



- c. execle
- d. execv
- e. execvp
- 27. **Getting Maximum and Minimum Real-Time Priority:** Develop a program to retrieve the maximum and minimum real-time priority.
- 28. **Determining and Modifying Program Priority:** Find out the priority of your running program and modify it using the nice command.
- 29. **Getting and Modifying Scheduling Policy:** Write a program to obtain the scheduling policy and modify it (e.g., SCHED\_FIFO, SCHED\_RR).
- 30. **Running a Script at a Specific Time with a Daemon Process:** Create a program to execute a task at a specific time using a Daemon process.

# **III System V IPC Mechanisms**

- 31. **Pipe Creation and Communication:** Write a simple program to create a pipe, write to the pipe, read from the pipe, and display the content on the monitor.
- 32. **Data Transmission from Parent to Child:** Develop a simple program to send data from the parent process to the child process.
- 33. **Two-Way Communication:** Write a program to send and receive data between the parent and child processes using two-way communication.
- 34. **Executing Is -I | wc:** Write a program to execute **Is -I | wc** using:
  - a. dup
  - b. dup2
  - c. fcntl



- 35. **Counting Directories with dup2:** Write a program to find the total number of directories in the present working directory using **Is -I | grep ^d | wc**. Implement the solution using only **dup2**.
- 36. **FIFO File Creation:** Create a FIFO file using:
  - a. **mknod** command
  - b. **mkfifo** command
  - c. Use **strace** command to determine which command (**mknod** or **mkfifo**) is more efficient.
  - d. **mknod** system call
  - e. **mkfifo** library function
- 37. **FIFO Communication (One-Way):** Write two programs to enable communication through FIFO using one-way communication.
- 38. **FIFO Communication (Two-Way):** Write two programs to establish communication through FIFO using two-way communication.
- 39. **Waiting for Data in FIFO:** Write a program to wait for data to be written into a FIFO within 10 seconds, utilizing the **select** system call with the FIFO.
- 40. **Process File Limit and Pipe Size:** Write a program to print the maximum number of files that can be opened within a process and the size of a pipe (circular buffer).
- 41. **Message Queue Creation:** Write a program to create a message queue, and print the key and message queue ID.
- 42. **Message Queue Information:** Write a program to print information about a message queue using **msqid\_ds** and **ipc\_perm** structures:
  - a. Access permission
  - b. UID, GID
  - c. Time of last message sent and received
  - d. Time of last change in the message queue



- e. Size of the queue
- f. Number of messages in the queue
- g. Maximum number of bytes allowed
- h. PID of the **msgsnd** and **msgrcv**
- 43. **Sending Messages to Message Queue:** Write a program to send messages to the message queue. Check using **\$ipcs -q**.
- 44. **Receiving Messages from Message Queue:** Write a program to receive messages from the message queue:
  - a. With 0 as a flag
  - b. With **IPC\_NOWAIT** as a flag
- 45. **Changing Message Queue Permissions:** Write a program to change the existing message queue permissions using the **msqid\_ds** structure.
- 46. **Removing Message Queue:** Write a program to remove the message queue.
- 47. **Shared Memory Operations:** Write a program to create shared memory and perform the following operations:
  - a. Write some data to the shared memory
  - b. Attach with **O\_RDONLY** and check whether you are able to overwrite
  - c. Detach the shared memory
  - d. Remove the shared memory
- 48. **Semaphore Creation and Initialization:** Write a program to create a semaphore and initialize its value:
  - a. Create a binary semaphore
  - b. Create a counting semaphore
- 49. **Semaphore Implementation:** Write a program to implement a semaphore to protect any critical section:
  - a. Rewrite the ticket number creation program using a semaphore



- b. Protect shared memory from concurrent write access
- c. Protect multiple pseudo resources (maybe two) using a counting semaphore
- d. Remove the created semaphore
- 50. **Deadlock:** Develop a program that intentionally induces a deadlock scenario using semaphores.
- 51. **Inter-Machine Communication using Socket:** Write a program to communicate between two machines using sockets.
- 52. **Concurrent Server Creation:** Write a program to create a concurrent server:
  - a. Use **fork**
  - b. Use pthread\_create

### IV Timers, Resource Limits, Multithreading and Signals

- 53. **Interval Timer Programming:** Write separate programs for each time domain to set an interval timer for 10 seconds and 10 microseconds.
  - a. Use ITIMER\_REAL
  - b. Use ITIMER\_VIRTUAL
  - c. Use ITIMER\_PROF
- 54. **System Resource Limits:** Write a program to print system resource limits using the getrlimit system call.
- 55. **Setting System Resource Limit:** Write a program to set a system resource limit using the setrlimit system call.
- 56. **Execution Time Measurement:** Write a program to measure the time taken to execute 100 **getppid()** system calls using a time stamp counter.
- 57. **System Limitation Exploration:** Write a program to print system limitations for:
  - a. Maximum length of arguments in the exec family of functions.
  - b. Maximum number of simultaneous processes per user ID.



- c. Number of clock ticks (jiffies) per second.
- d. Maximum number of open files.
- e. Size of a page.
- f. Total number of pages in physical memory.
- g. Number of currently available pages in physical memory.
- 58. **Multithreading Exploration:** Write a simple program to create three threads and print the IDs of the created threads.
- 59. **Signal Handling:** Write separate programs using the signal system call to catch the following signals:
  - a. SIGSEGV
  - b. SIGINT
  - c. SIGFPE
  - d. SIGALRM (using the alarm system call)
  - e. SIGALRM (using the setitimer system call)
  - f. SIGVTALRM (using the setitimer system call)
  - q. SIGPROF (using the setitimer system call)
- 60. **Ignoring and Resetting Signals:** Write a program to ignore a SIGINT signal and then reset it to the default action using the signal system call.
- 61. **Signal Handling with sigaction:** Write separate programs using the sigaction system call to catch the following signals:
  - a. SIGSEGV
  - b. SIGINT
  - c. SIGFPE
- 62. **Signal Handling with sigaction:** Write a program to ignore a SIGINT signal and then reset it to the default action using the sigaction system call.



- 63. **Creating an Orphan Process:** Write a program to create an orphan process. Utilize the kill system call to send a SIGKILL signal from the child process to the parent process.
- 64. **Signal SIGSTOP Handling:** Create two programs: the first program awaits the SIGSTOP signal, while the second program sends the signal using the kill system call. Determine whether the first program successfully catches the signal or not.

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