# Notes – Linear Algebra

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# **Prerequisites**

We declare several notations below for convenience and clarity.

Notations 1 (Basic notations).

- $\mathbb{F}$  denotes a number field (often  $\mathbb{R}$  or  $\mathbb{C}$ ).
- U, V, W denotes vector spaces (usually over scalar field  $\mathbb{F}$ ).
- $V^S$  denotes the set of functions from a nonempty set S to V.

# **Vector Spaces**

**Definition 2.** The complexification of V, denoted by  $V_{\mathbb{C}}$ , equals  $V \times V$  with normal addition and real scalar multiplication for product space. But we write an element (u, v) of  $V_{\mathbb{C}}$  as u + iv. Complex scalar multiplication is defined by

$$(a+bi)(u+iv) = (au - bv) + i(av + bu)$$

for all  $a, b \in \mathbb{R}$  and all  $u, v \in V$ .

**Lemma 3** (Linear dependence lemma). *Suppose*  $v_1, \ldots, v_m$  *is a linearly dependent set in* V. *Then there exists*  $k \in \{1, 2, \ldots, m\}$  *such that* 

$$v_k \in \operatorname{span}\{v_1,\ldots,v_m\}$$
.

Further more, removing the kth term from the list does not change the span.2

**Theorem 4.** Any two bases of a finite-dimensional vector space have the same length.<sup>3</sup>

*Proof.* Suppose V is finite-dimensional. Let  $B_1$  and  $B_2$  be two bases of V. Considering  $B_1$  as an independent set and  $B_2$  as a spanning set leads to  $\#B_1 \leq \#B_2$ . Interchanging the roles of  $B_1$  and  $B_2$  and we have  $\#B_2 \leq \#B_1$ . Thus  $\#B_1 = \#B_2$ .  $\square$ 

# <sup>1</sup> Think of V as a subset of $V_{\mathbb{C}}$ by identifying $u \in V$ with u+i0. The construction of $V_{\mathbb{C}}$ from V can then be thought of as generalizing the construction of $\mathbb{C}^n$ from

- <sup>2</sup> The lemma lays the foundation for a series of basic results for vector spaces.
- <sup>3</sup> This proposition ensures that *dimension* is well-defined.

#### **Linear Maps**

#### Kernal and Image of Linear Maps

**Exercise 5.** Suppose U and V are finite-dimensional and  $S \in \mathcal{L}(V, W)$  and  $T \in \mathcal{L}(U, V)$ . Prove that

$$\dim \ker ST \leq \dim \ker S + \dim \ker T$$
.

*Proof.* Restrict to  $Z = \ker ST$ . By the fundamental theorem of linear maps,

$$\begin{split} \dim Z &= \dim T(Z) + \dim \ker T|_Z \\ &\leq \dim T(Z) + \dim \ker T \\ &= \dim ST(Z) + \dim \ker S|_{T(Z)} + \dim \ker T \\ &\leq \dim \ker S + \dim \ker T. \end{split}$$

**Corollary 6** (Sylvester's rank inequality). Suppose  $A \in \mathbb{F}^{m,n}$  and  $B \in \mathbb{F}^{n,p}$  are two matrices. Then<sup>4</sup>

$$\operatorname{rank} A + \operatorname{rank} B - n \leq \operatorname{rank}(AB)$$
.

#### **Products and Quotients of Vector Spaces**

**Lemma 7.** Suppose  $V_1, \ldots, V_m$  are subspaces of  $V^{.5}$  Define a linear map  $\Gamma: V_1 \times \cdots \times V_m \to V_1 + \cdots + V_m$  by

$$\Gamma(v_1,\ldots,v_m)=v_1+\cdots+v_m.$$

*Then*  $V_1 + \cdots + V_m$  *is a direct sum if and only if*  $\Gamma$  *is injective.* 

**Theorem 8.** Suppose V is finite-dimensional and  $V_1, \ldots, V_m$  are subspaces of V. Then  $V_1 + \cdots + V_m$  is a direct sum if and only  $\dim(V_1 + \cdots + V_m) = \dim V_1 + \cdots + \dim V_m$ .

*Proof.* Recall Lemma 7. Because  $\Gamma$  is surjective, by the fundamental theorem of linear maps,  $V_1 + \cdots + V_m$  is a direct sum if and only if  $\dim(V_1 + \cdots + V_m) = \dim(V_1 \times \cdots \times V_m) = \dim V_1 + \cdots + \dim V_m$ .

**Notation 9.** Suppose  $T \in \mathcal{L}(V, W)$ . Define  $\tilde{T}: V + \ker V \to V$  by

$$\tilde{T}(v + \ker T) = Tv.$$

**Exercise 10.** Suppose  $V_1, \ldots, V_m$  are vector spaces. Prove that  $\mathcal{L}(V_1 \times \cdots \times V_m, W)$  and  $\mathcal{L}(V_1, W) \times \cdots \times \mathcal{L}(V_m, W)$  are isomorphic vector spaces.

*Proof.* We construct an isomorphism *T* between the two vector spaces.

For every  $\Gamma \in \mathcal{L}(V_1 \times \cdots \times V_m, W)$ , define  $\varphi_i : V_i \to W$  for each  $i \in \{1, \dots, m\}$  by

$$\varphi_i(v_i) = \Gamma(\mathbf{0}, \ldots, v_i, \ldots, \mathbf{0})$$

with  $v_i$  in the  $i^{th}$  slot and 0 in all other slots. It can be verified that  $\varphi_i \in \mathcal{L}(V_i, W)$ .

Let  $T(\Gamma) = (\varphi_1, \dots, \varphi_m)$ . It can be verified that T is a linear map. We prove T is an isomorphism by constructing its inverse linear map S.

For every 
$$(\varphi_1, \ldots, \varphi_m) \in \mathcal{L}(V_1, W) \times \cdots \times \mathcal{L}(V_m, W)$$
, let

$$S(\varphi_1,\ldots,\varphi_m)(v_1,\ldots,v_m)=\varphi_1(v_1)+\cdots+\varphi_m(v_m).$$

It can be shown that S is a linear map, and that  $S \circ T = I$  and  $T \circ S = I$ , where I is the identity operator on the proper vector space. That proves T is indeed an isomorphism between the two vector spaces, as desired.

**Proposition 11.** A nonempty subset A of V is a translate of some subspace of V if and only if  $\lambda v + (1 - \lambda) w \in A$  for all  $v, w \in A$  and all  $\lambda \in \mathbb{F}$ .

**Exercise 12.** Suppose  $A_1 = v + U_1$  and  $A_2 = w + U_2$  for some  $v, w \in V$  and some subspaces  $U_1, U_2$  of V. Prove that  $A_1 \cap A_2$  is either the empty set or a translate of some subspace of V.<sup>6</sup>

<sup>&</sup>lt;sup>4</sup> There is a slicker proof for this inequality using block matrices. But the proof here using linear maps is more informative.

<sup>&</sup>lt;sup>5</sup> Note that V does not have to be finite-dimensional. Recall that  $V_1 + \cdots + V_m$  is a direct sum if and only if the only way to write  $\mathbf{0}$  as a sum of  $v_1 + \cdots + v_m$ , where each  $v_k \in V_k$ , is by taking each  $v_k$  equal to  $\mathbf{0}$ .

<sup>&</sup>lt;sup>6</sup> Recall Proposition 11.

**Proposition 13.** Suppose U is a subspace of V and  $v_1 + U, ..., v_m + U$  is a basis of V/U and  $u_1, ..., u_n$  is a basis of U. Then  $v_1, ..., v_m, u_1, ..., u_n$  is a basis of V. In other words,  $V = \text{span}\{v_1, ..., v_m\} \oplus U$ .

**Exercise 14.** Suppose U is a subspace of V such that V/U is finite-dimensional.

- (a) Prove that if W is a finite-dimensional subspace of V and V = U + W, then  $\dim W \ge \dim V/U$ .
- (b) Prove that there exists a finite-dimensional subspace W of V such that  $V = U \oplus W$  and dim  $W = \dim V/U$ .

*Proof.* Let  $\overline{w}_1 + U, \ldots, \overline{w}_m + U$  be a basis of V/U. Then by Proposition 13, we have  $V = \text{span}\{\overline{w}_1, \ldots, \overline{w}_m\} \oplus U$ . Let  $W_0 = \text{span}\{\overline{w}_1, \ldots, \overline{w}_m\}$ , then  $V = U \oplus W_0$ , as desired.

Now we prove that for each subspace W of V such that V = U + W, we have  $\dim W \ge m = \dim V/U$ .

For each  $\overline{w}_i \in V$  above, by definition we have  $\overline{w}_i = u_i + w_i$  for some  $u_i \in U$  and  $w_i \in W$ . It can be shown from the linear independence of  $\overline{w}_1 + U, \ldots, \overline{w}_m + U$  that  $\overline{w}_1 - u_1, \ldots, \overline{w}_m - u_m$  are independent vectors in W. Hence dim  $W \ge m$ .

## **Duality**

**Theorem 15.** Suppose V and W are finite-dimensional and  $T \in \mathcal{L}(V, W)$ . Then

T is surjective  $\iff$  T' is injective and T is injective  $\iff$  T' is surjective.<sup>8</sup>

**Proposition 16.** Suppose V is finite-dimensional and U is a subspace of V. Then

$$oldsymbol{U} = \left\{ oldsymbol{v} \in oldsymbol{V} : arphi(oldsymbol{v}) = oldsymbol{0} \ ext{for every} \ arphi \in oldsymbol{U}^0 
ight\}.$$

**Exercise 17.** Suppose V is finite-dimensional and U and W are subspaces of V.

- (a) Prove that  $W^0 \subseteq U^0$  if and only if  $U \subseteq W$ .
- (b) Prove that  $W^0 = U^0$  if and only if  $U = W^{10}$

**Exercise 18.** Suppose V is finite-dimensional and U and W are subspaces of V.

- (a) Prove that  $(U + W)^0 = U^0 \cap W^0$ .
- (b) Prove that  $({\bf U} \cap {\bf W})^0 = {\bf U}^0 + {\bf W}^0$ .

**Lemma 19.** Suppose V is finite-dimensional.  $v_1, \ldots, v_n$  is a basis of V. Then  $\varphi_1, \ldots, \varphi_n \in V'$  is the dual basis of  $v_1, \ldots, v_n$  if and only if

$$egin{bmatrix} \mathcal{M}(arphi_1) \ dots \ \mathcal{M}(arphi_n) \end{bmatrix} = I$$

where  $\mathcal{M}(\varphi_i)$  is the  $1 \times n$  matrix of  $\varphi_i$  with respect to basis  $v_1, \dots v_n$  of V for each  $i \in \{1, \dots, n\}$ .

 $^{7}$   $V = \text{span}\{v_1, \dots, v_m\} \oplus U$  still holds without the hypothesis that U is finite-dimensional.

 $<sup>^8</sup>$  This result can be useful because sometimes it is easier to verify that T' is injective (surjective) than to show directly that T is surjective (injective).

<sup>&</sup>lt;sup>9</sup> The proposition can be easily verified from definition. But it can be useful.

<sup>10</sup> Recall Proposition 16.

**Exercise 20.** Suppose V is finite-dimensional and  $\varphi_1, \ldots, \varphi_n$  is a basis of V'. Prove that there exists a basis of V whose dual basis is  $\varphi_1, \ldots, \varphi_n$ .

*Proof.* We start from an arbitrary basis  $u_1, \ldots, u_n$  of V. Let  $\psi_1, \ldots, \psi_n$  be its dual basis. In this proof, we take standard basis  $e_1, \ldots, e_n$  as the basis of  $\mathbb{F}^n$ .

Define  $S, T \in \mathcal{L}(V, \mathbb{F}^n)$  by

$$T(v) = (\varphi_1(v), \ldots, \varphi_n(v)), S(v) = (\psi_1(v), \ldots, \psi_n(v)).$$

Then by Lemma 19,  $\mathcal{M}(S, (u_1, \ldots, u_n)) = I$ .

Let *A* be the change of basis matrix from  $\psi$ 's to  $\varphi$ 's, i.e.,

$$A = \mathcal{M}(I, (\psi_1, \ldots, \psi_n), (\varphi_1, \ldots, \varphi_n)).$$

Then by the definition of change of basis matrix, we have

$$\mathcal{M}(T,(u_1,\ldots,u_n)) = \begin{bmatrix} \mathcal{M}(\varphi_1,(u_1,\ldots,u_n)) \\ \vdots \\ \mathcal{M}(\varphi_n,(u_1,\ldots,u_n)) \end{bmatrix}$$

$$=A^{t}\begin{bmatrix}\mathcal{M}(\psi_{1},(u_{1},\ldots,u_{n}))\\\vdots\\\mathcal{M}(\psi_{n},(u_{1},\ldots,u_{n}))\end{bmatrix}=A^{t}\mathcal{M}(S,(u_{1},\ldots,u_{n}))=A^{t}.$$

Consider basis  $\overline{v}_1, \dots, \overline{v}_n$  of V such that the change of basis matrix from v's to  $\overline{v}$ 's is  $A^t$ . Thus

$$\mathcal{M}(T,(\overline{v}_1,\ldots,\overline{v}_n)) = \mathcal{M}(T,(v_1,\ldots,v_n)) \mathcal{M}(I,(\overline{v}_1,\ldots,\overline{v}_n),(v_1,\ldots,v_n)) = I.$$

Then by Lemma 19, the dual basis of  $\overline{v}_1, \ldots, \overline{v}_n$  is precisely  $\varphi_1, \ldots, \varphi_n$ , as desired.

# **Polynomials**

**Theorem 21** (Division algorithm for polynomials). Suppose that  $p,s \in \mathcal{P}(\mathbb{F})$ , with  $s \neq 0$ . Then there exist unique polynomials  $q, r \in \mathcal{P}(\mathbb{F})$  such that p = sq + r.<sup>11</sup>

*Proof.* Let  $n = \deg p$  and  $m = \deg s$ . The case where n < m is trivial. Thus we now assume that  $n \ge m$ .

The list

$$1, z, \ldots, z^{m-1}, s, zs, \ldots, z^{n-m}s$$

is linearly independent in  $\mathcal{P}_n(\mathbb{F})$ . And it also has length n+1. Hence the list is a basis of  $\mathcal{P}_n(\mathbb{F})$ .

Because  $p \in \mathcal{P}_n(\mathbb{F})$ , there exist unique constants  $a_0, \ldots, a_{m-1}, b_0, \ldots, b_{n-m} \in \mathbb{F}$  such that

$$p = a_0 + a_1 z + \dots + a_{m-1} z^{m-1} + b_0 s + b_1 z s + \dots + b_{n-m} z^{n-m} s$$
  
=  $\left( a_0 + a_1 z + \dots + a_{m-1} z^{m-1} \right) + s \left( b_0 + b_1 z + \dots + b_{n-m} z^{n-m} \right).$ 

<sup>11</sup> The division algorithm for polynomials can be proved without using any linear algebra. This proof makes a nice use of a basis of  $\mathcal{P}_n(\mathbb{F})$ .