

# Report Generated by Test Manager

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**Title:** Test\_baseline\_01  
**Author:** Alessandro Barro, Nicolas Bruscoli, Viviana Ceccarelli, Manuel Cintura, Leonardo Chiacchiararelli, Lucia Mariani  
**Date:** 16-Apr-2021 22:14:39

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## Test Environment

Platform: PCWIN64  
MATLAB: (R2019b)

## Summary

Name	Outcome	Duration (Seconds)
<a href="#">Results: 2021-Apr-16 22:13:02</a>	✓	3.4
 <a href="#">SoC_handle_FSM_BaselineTest</a>	✓	3.4

## Results: 2021-Apr-16 22:13:02

Result Type: Result Set  
Parent: None  
Start Time: 16-Apr-2021 22:13:02  
End Time: 16-Apr-2021 22:13:06  
Outcome: Total: 1, **Passed: 1**

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## SoC\_handle\_FSM\_BaselineTest

### Test Result Information

Result Type: Test Case Result  
Parent: [Results: 2021-Apr-16 22:13:02](#)  
Start Time: 16-Apr-2021 22:13:02  
End Time: 16-Apr-2021 22:13:06  
Outcome: **Passed**

### Test Case Information

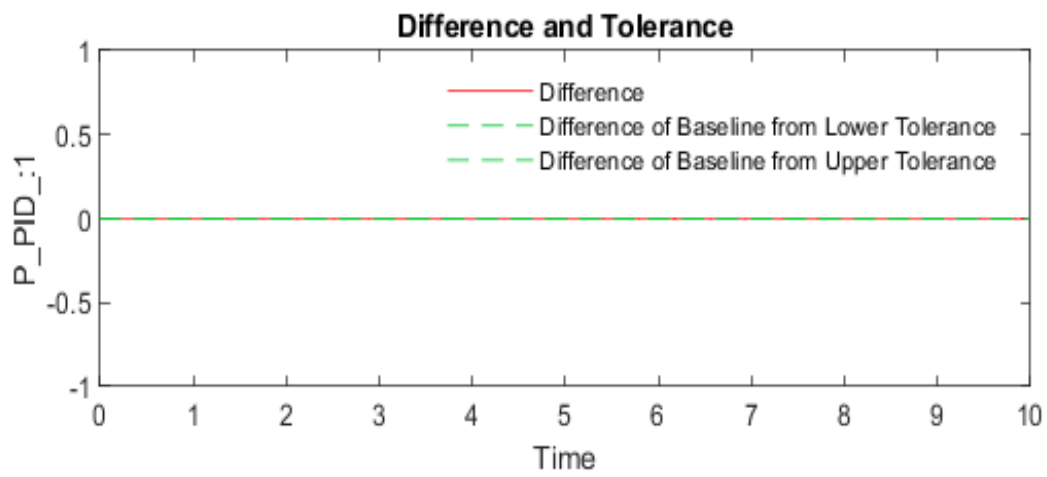
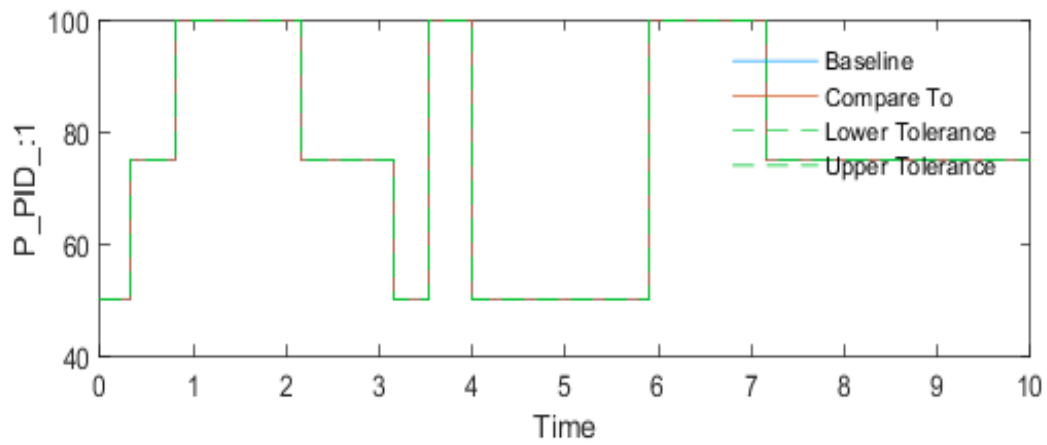
Name: SoC\_handle\_FSM\_BaselineTest  
Type: Baseline Test  
Baseline Name: Baseline\_FSM\_Testing\_rev6\_captured.mat  
Baseline File: D:\Dati\Università\MAGISTRALE\SecondYear\Compliance Design\Project\Git\adaptive-cruise-control\Test\FSM\_unit\_test\Baseline\_FSM\_Testing\_rev6\_captured.mat

### Baseline Comparison

Name	Abs Tol	Rel Tol	Lead Tol	Lag Tol	Max Diff	Data Type 1	Units 1	Sample Time 1	Data Type 2	Units 2	Sample Time 2	Interp	Sync	Link to Plot
✓ SoC:1	0	0	0	0	0	double		0.001	double		0.001	zoh	union	<a href="#">Link</a>
✓ P_PID_:1	0	0	0	0	0	double		0.001	double		0.001	zoh	union	<a href="#">Link</a>
✓ I_PID_:1	0	0	0	0	0	double		0.001	double		0.001	zoh	union	<a href="#">Link</a>
✓ D_PID_:1	0	0	0	0	0	double		0.001	double		0.001	zoh	union	<a href="#">Link</a>
✓ OutOfRange	0	0	0	0	0	double		0.001	double		0.001	zoh	union	<a href="#">Link</a>

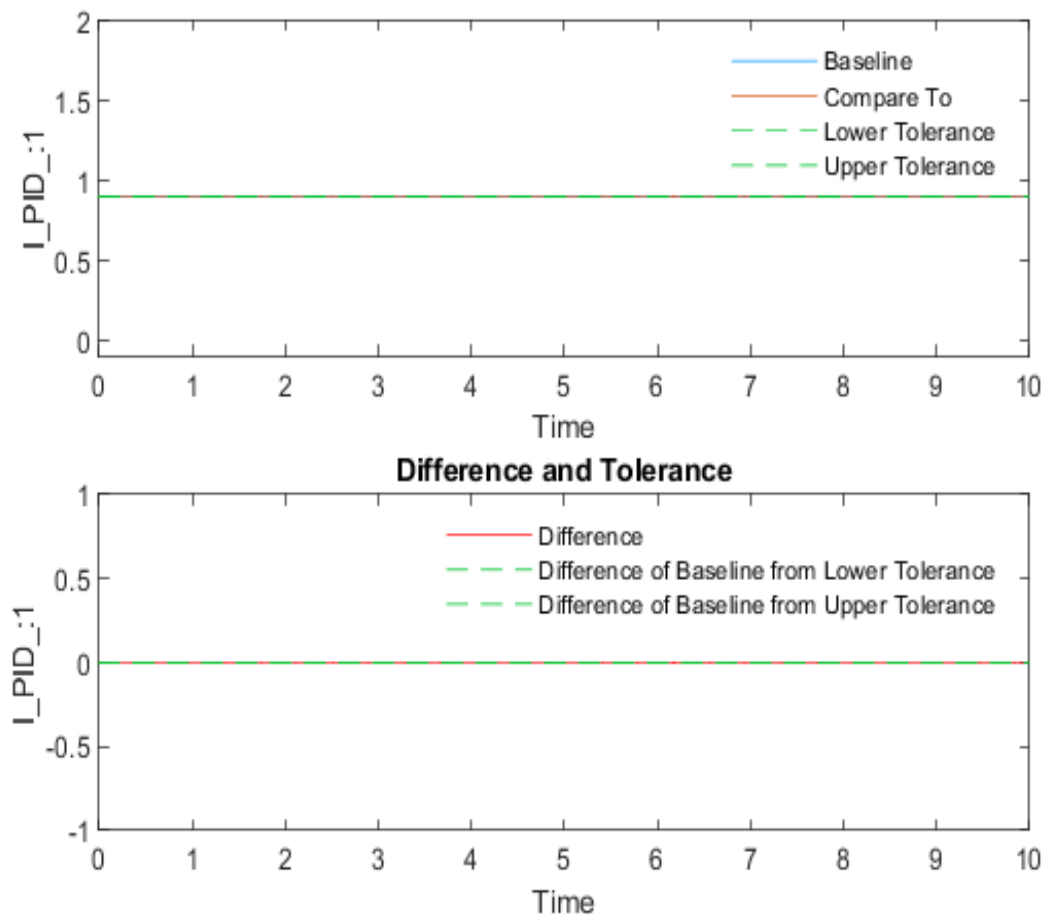
Name	Abs Tol	Rel Tol	Lead Tol	Lag Tol	Max Diff	Data Type 1	Units 1	Sample Time 1	Data Type 2	Units 2	Sample Time 2	Interp	Sync
✓ SoC:1	0	0	0	0	0	double		0.001	double		0.001	zoh	union





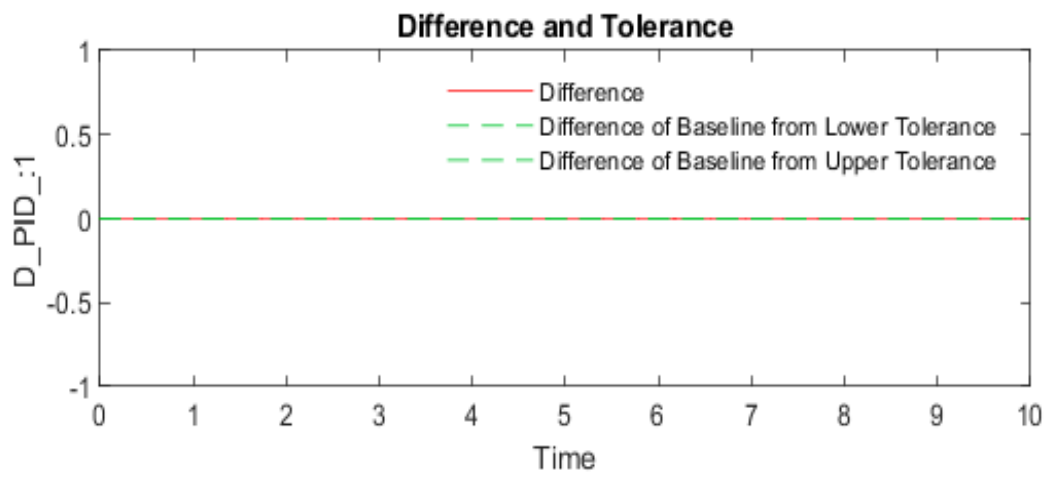
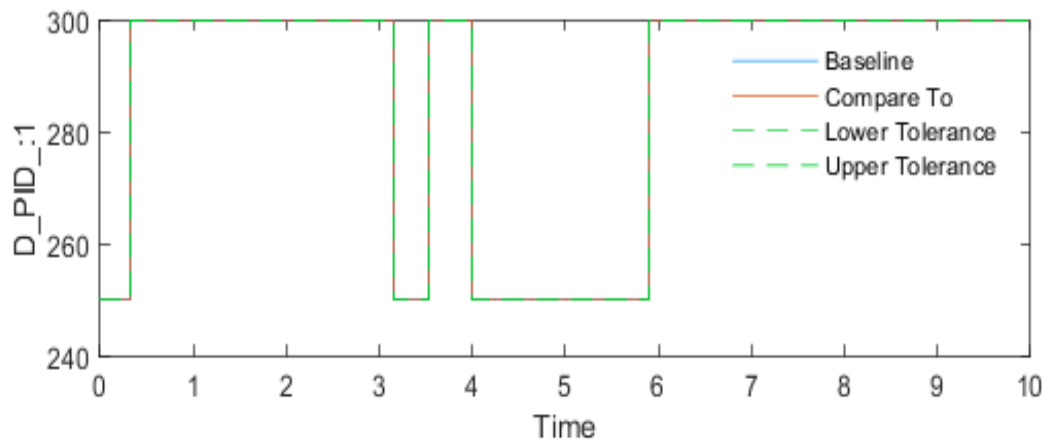
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Name	Abs Tol	Rel Tol	Lead Tol	Lag Tol	Max Diff	Data Type 1	Units 1	Sample Time 1	Data Type 2	Units 2	Sample Time 2	Interp	Sync
✓ I_PID_:1	0	0	0	0	0	double		0.001	double		0.001	zoh	union



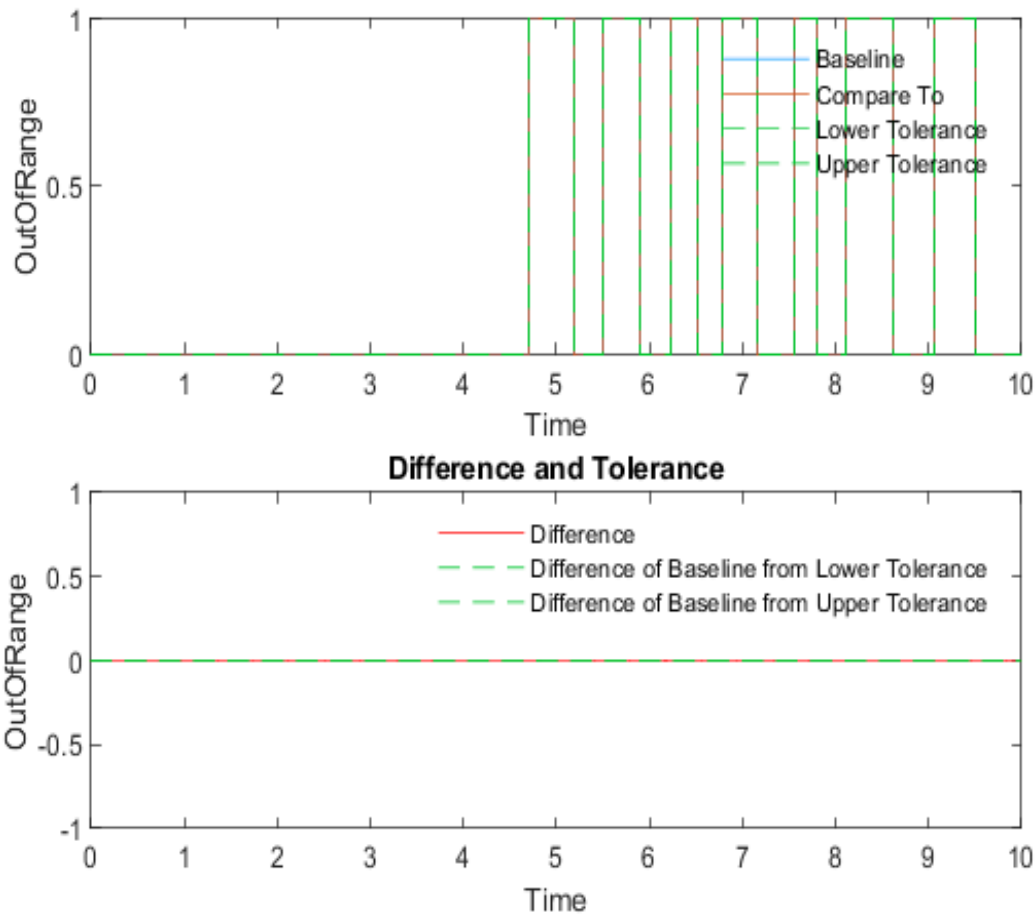
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Name	Abs Tol	Rel Tol	Lead Tol	Lag Tol	Max Diff	Data Type 1	Units 1	Sample Time 1	Data Type 2	Units 2	Sample Time 2	Interp	Sync
✓ D_PID_:1	0	0	0	0	0	double		0.001	double		0.001	zoh	union



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Name	Abs Tol	Rel Tol	Lead Tol	Lag Tol	Max Diff	Data Type 1	Units 1	Sample Time 1	Data Type 2	Units 2	Sample Time 2	Interp	Sync
✓ OutOfRange	0	0	0	0	0	double		0.001	double		0.001	zoh	union



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## Baseline\_FSM\_Testing\_rev6\_captured.mat

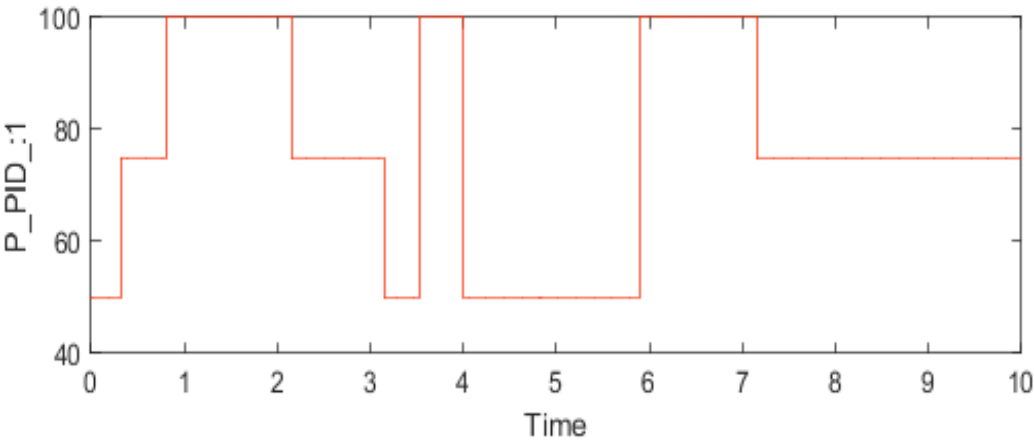
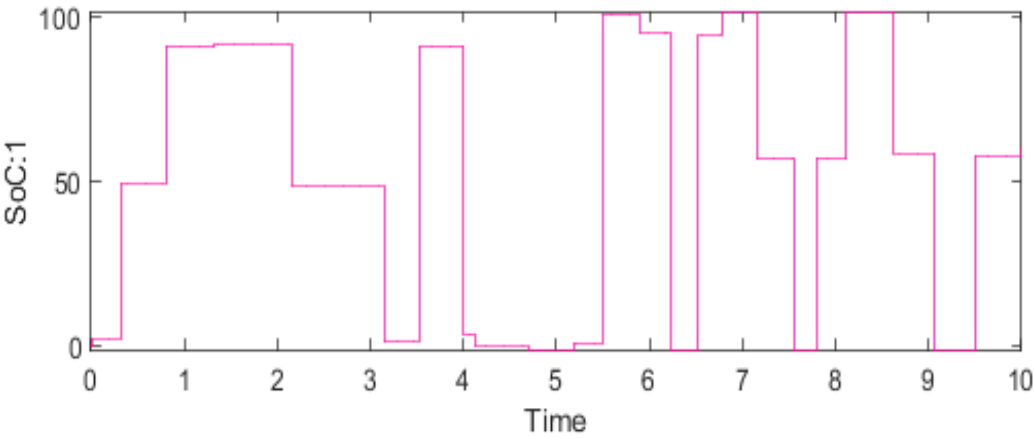
### Baseline Information

Baseline Name: Baseline\_FSM\_Testing\_rev6\_captured.mat  
 Baseline File: D:\Dati\Università\MAGISTRALE\SecondYear\Compliance Design\Project\Git\adaptive-cruise-control\Test\FSM\_unit\_test\Baseline\_FSM\_Testing\_rev6\_captured.mat



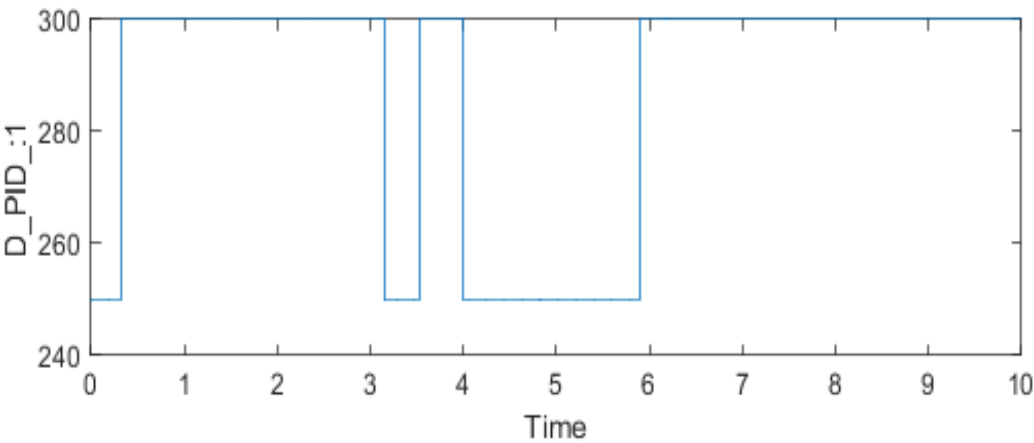
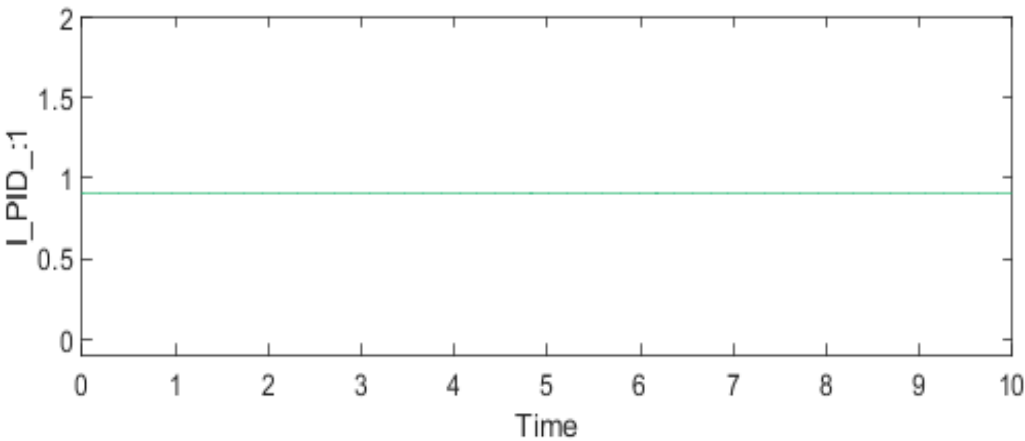
Name	Data Type	Units	Sample Time	Interp	Sync	Link to Plot
SoC:1	double		0.001	zoh	union	<a href="#">Link</a>
P_PID_:1	double		0.001	zoh	union	<a href="#">Link</a>
I_PID_:1	double		0.001	zoh	union	<a href="#">Link</a>
D_PID_:1	double		0.001	zoh	union	<a href="#">Link</a>
OutOfRange	double		0.001	zoh	union	<a href="#">Link</a>

Name	Data Type	Units	Sample Time	Interp	Sync
SoC:1	double		0.001	zoh	union
P_PID_:1	double		0.001	zoh	union



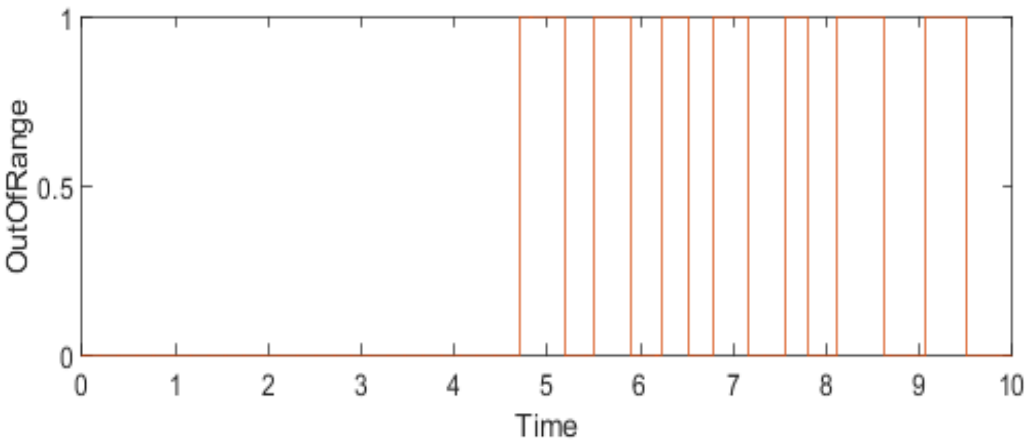
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Name	Data Type	Units	Sample Time	Interp	Sync
I_PID_:1	double		0.001	zoh	union
D_PID_:1	double		0.001	zoh	union



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Name	Data Type	Units	Sample Time	Interp	Sync
OutOfRange	double		0.001	zoh	union



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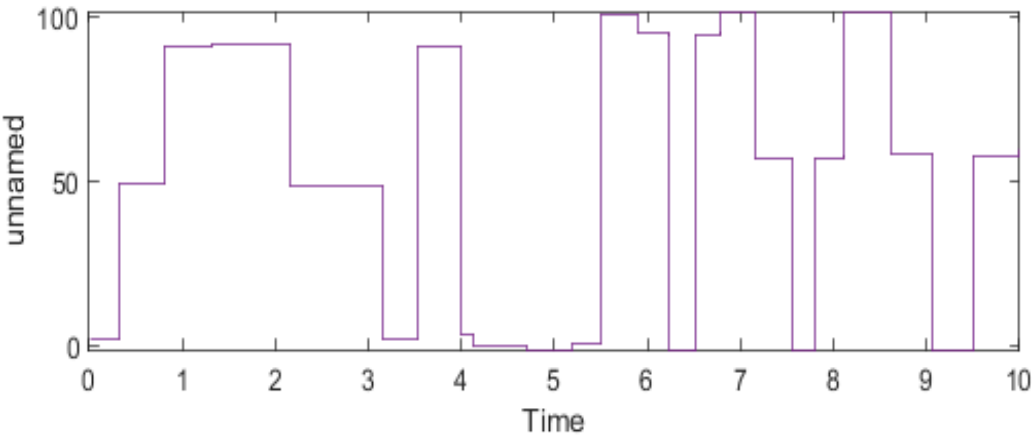
**Input Data**

**Input Information**

External Input Name: Test\_chart\_rev2.mat  
 External Input File: D:\Dati\Università\MAGISTRALE\SecondYear\Compliance Design\Project\Git\adaptive-cruise-control\Test\FSM\_unit\_test\Test\_chart\_rev2.mat

Name	Data Type	Units	Sample Time	Interp	Sync	Link to Plot
unnamed	double			zoh	union	<a href="#">Link</a>

Name	Data Type	Units	Sample Time	Interp	Sync
unnamed	double			zoh	union



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**Simulation**

**System Under Test Information**

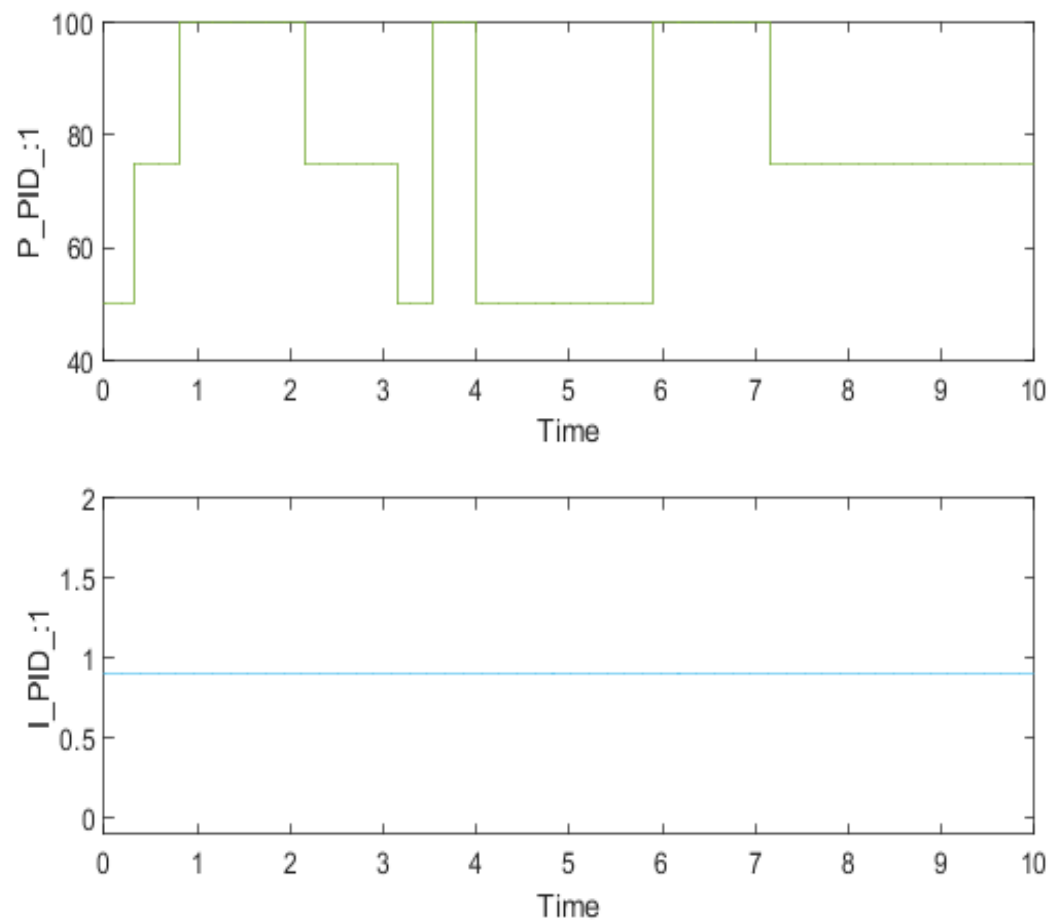
Model: Bozza\_longitudinal\_rev2\_19b  
Harness: Bozza\_longitudinal\_rev2\_19b\_Harness6

Harness Owner: Bozza\_longitudinal\_rev2\_19b/controller/Chart  
 Simulation Mode: normal  
 Override SIL or PIL Mod 0  
 e:  
 Configuration Set: Configuration1  
 External Input Name: Test\_chart\_rev2.mat  
 External Input File: D:\Dati\Università\MAGISTRALE\SecondYear\Compliance Design\Project\Git\adaptive-cruise-control\Test\FSM\_unit\_test\Test\_chart\_rev2.mat  
 Start Time: 0  
 Stop Time: 10  
 Checksum: 4229402656 2431366803 1744661757 603632271  
 Simulink Version: 10.0  
 Model Version: 1.24  
 Model Author: Leo  
 Date: Fri Apr 16 22:11:58 2021  
 User ID: Leo  
 Model Path: D:\Dati\Università\MAGISTRALE\SecondYear\Compliance Design\Project\Git\adaptive-cruise-control\Model\Bozza\_longitudinal\_rev2\_19b.slx  
 Machine Name: PC-LEO  
 Solver Name: FixedStepDiscrete  
 Solver Type: Fixed-Step  
 Fixed Step Size: 0.001  
 Simulation Start Time: 2021-04-16 22:13:02  
 Simulation Stop Time: 2021-04-16 22:13:04  
 Platform: PCWIN64

### Simulation Output

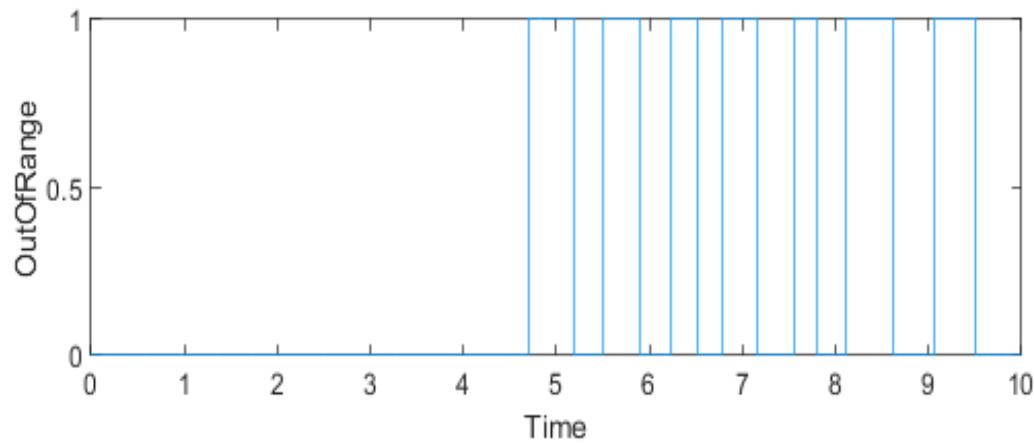
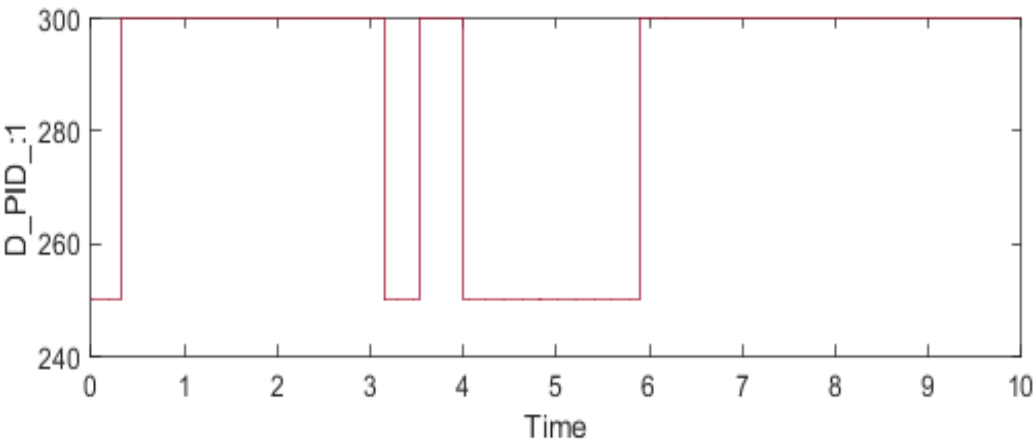
Name	Data Type	Units	Sample Time	Interp	Sync	Link to Plot
P_PID:1	double		0.001	zoh	union	<a href="#">Link</a>
I_PID:1	double		0.001	zoh	union	<a href="#">Link</a>
D_PID:1	double		0.001	zoh	union	<a href="#">Link</a>
OutOfRange	double		0.001	zoh	union	<a href="#">Link</a>
SoC:1	double		0.001	zoh	union	<a href="#">Link</a>

Name	Data Type	Units	Sample Time	Interp	Sync
P_PID_:1	double		0.001	zoh	union
I_PID_:1	double		0.001	zoh	union



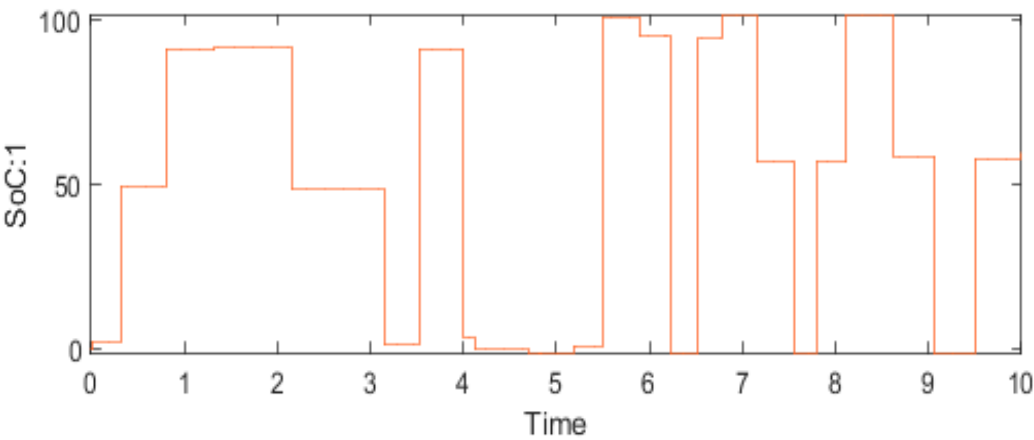
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Name	Data Type	Units	Sample Time	Interp	Sync
D_PID_:1	double		0.001	zoh	union
OutOfRange	double		0.001	zoh	union



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Name	Data Type	Units	Sample Time	Interp	Sync
SoC:1	double		0.001	zoh	union



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