




























Report Generated by Test Manager

Title: Path Following - Test Report
Author: Gianvincenzo Daddabbo, Gaetano Gallo, Alberto Ruggeri, Martina Tedesco, Alessandro Toschi
Date: 29-Apr-2021 13:50:52

Summary

Name	Outcome	Duration (Seconds)
 Path Following test	59  6 	2350
 Hyundai Azera	12  1 	555
 Puglia		86
 Switzerland		104
 Straight Slow		31
 TiltedStraight Slow		49
 Campania		119
 Straight Fast		4
 TiltedStraight Fast		5
 1000mCurve Slow		97
 100mCurve Slow		14
 1000mCurve Fast		13
 100mCurve Fast		2
 Adriatic Highway A 14		19
 Indianapolis Speedway		11
 BMW 325i	12  1 	435
 Puglia		57
 Switzerland		73
 Straight Slow		26
 TiltedStraight Slow		39
 Campania		84
 Straight Fast		4
 TiltedStraight Fast		4

 1000mCurve_Slow		88
 100mCurve_Slow		13
 1000mCurve_Fast		13
 100mCurve_Fast		2
 Adriatic Highway A 14		21
 Indianapolis Speedway		10
 Ford E150	11  2 	442
 Puglia		58
 Switzerland		73
 Straight_Slow		26
 TiltedStraight_Slow		41
 Campania		87
 Straight_Fast		3
 TiltedStraight_Fast		5
 1000mCurve_Slow		90
 100mCurve_Slow		13
 1000mCurve_Fast		12
 100mCurve_Fast		3
 Adriatic Highway A 14		20
 Indianapolis Speedway		11
 Suzuki Samurai	12  1 	444
 Puglia		57
 Switzerland		76
 Straight_Slow		25
 TiltedStraight_Slow		41

 Campania		85
 Straight_Fast		3
 TiltedStraight_Fast		5
 1000mCurve_Slow		90
 100mCurve_Slow		15
 1000mCurve_Fast		13
 100mCurve_Fast		2
 Adriatic Highway A 14		21
 Indianapolis Speedway		11
 Volkswagen Beetle	12  1 	474
 Puglia		62
 Switzerland		82
 Straight_Slow		27
 TiltedStraight_Slow		44
 Campania		93
 Straight_Fast		3
 TiltedStraight_Fast		4
 1000mCurve_Slow		98
 100mCurve_Slow		13
 1000mCurve_Fast		13
 100mCurve_Fast		2
 Adriatic Highway A 14		21
 Indianapolis Speedway		12

Path_Following_test

Test Result Information

Result Type: Test File Result
Parent: None
Start Time: 29-Apr-2021 12:39:20
End Time: 29-Apr-2021 13:18:30
Outcome: Total: 65, Passed: 59, Failed: 6
Description:

These tests are aimed to evaluate the performance of a path follower in different scenarios

Test Suite Information

Name: Path_Following_test

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Hyundai Azera

Test Result Information

Result Type: Test Suite Result
Parent: [Path_Following_test](#)
Start Time: 29-Apr-2021 12:39:20
End Time: 29-Apr-2021 12:48:35
Outcome: Total: 13, Passed: 12, Failed: 1

Test Suite Information

Name: Hyundai Azera

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Puglia

Test Result Information

Result Type: Test Case Result
Parent: [Hyundai Azera](#)
Start Time: 29-Apr-2021 12:39:20
End Time: 29-Apr-2021 12:40:46
Outcome: Passed
Description:

This scenario is taken from an Highway and it is a road that is straight for the most with some smooth corners.

In this test we try to follow the path with a speed of 40 km/h.

Test Case Information

Name: Puglia
Type: Simulation Test

Verify Result

Name	
✓	Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓	Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓	Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 651.65546907329576
Checksum: 202620085 696037187 1566738105 3145763362

Switzerland

Test Result Information

Result Type: Test Case Result
Parent: [Hyundai Azera](#)
Start Time: 29-Apr-2021 12:40:46
End Time: 29-Apr-2021 12:42:30
Outcome: **Failed**
Cause of Failure: **Failed criteria: Verification**
Description:




This is the slowest scenario considered, with lots of corners one after another.

We try to follow this scenario with 15 km/h speed.

Test Case Information

Name: Switzerland
Type: Simulation Test

Verify Result

Name
 Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
 Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
 Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 759.09368017233703
Checksum: 2813384938 3166038877 3099671345 3384845185

Straight_Slow

Test Result Information

Result Type: Test Case Result
Parent: [Hyundai Azera](#)
Start Time: 29-Apr-2021 12:42:31
End Time: 29-Apr-2021 12:43:02
Outcome: **Passed**
Description:

Sample scenario consisting in a straight line.

Speed 10 km/h.

Test Case Information

Name: Straight_Slow
Type: Simulation Test

Verify Result

Name	
✓	Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓	Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓	Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 360
Checksum: 1885704342 1639022262 1968123643 3686124085

TiltedStraight_Slow

Test Result Information

Result Type: Test Case Result
Parent: [Hyundai Azera](#)
Start Time: 29-Apr-2021 12:43:02
End Time: 29-Apr-2021 12:43:51
Outcome: **Passed**
Description:

Sample scenario consisting in a straight line with a direction of 45 degrees in the X-Y plane.

Speed 10 km/h.

Test Case Information

Name: TiltedStraight_Slow
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 509.11688245431424
Checksum: 2284227124 546201088 1198533080 2624571421

Campania

Test Result Information

Result Type: Test Case Result
Parent: [Hyundai Azera](#)
Start Time: 29-Apr-2021 12:43:51
End Time: 29-Apr-2021 12:45:50
Outcome: **Passed**
Description:

This scenario is made up by a sequence of smooth corners.

We try to follow this path with 30 km/h speed.

Test Case Information

Name: Campania
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 843.22474949384798
Checksum: 2515822173 245894926 3757805933 999516670

Straight_Fast

Test Result Information

Result Type: Test Case Result
Parent: [Hyundai Azera](#)
Start Time: 29-Apr-2021 12:45:50
End Time: 29-Apr-2021 12:45:54
Outcome: **Passed**
Description:

Sample scenario consisiting in a straight line.

Speed: 100 km/h.

Test Case Information

Name: Straight_Fast
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 36
Checksum: 3695475672 3866628070 3423434440 3754794952

TiltedStraight_Fast

Test Result Information

Result Type: Test Case Result
Parent: [Hyundai Azera](#)
Start Time: 29-Apr-2021 12:45:54
End Time: 29-Apr-2021 12:45:59
Outcome: **Passed**
Description:

Sample scenario consisting in a straight line tilted by 135 degrees in the X-Y plane.

Speed: 100 km/h.

Test Case Information

Name: TiltedStraight_Fast
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 50.911688245431421
Checksum: 3021946026 1579631363 1462477640 3610898823

1000mCurve_Slow

Test Result Information

Result Type: Test Case Result
Parent: [Hyundai Azera](#)
Start Time: 29-Apr-2021 12:45:59
End Time: 29-Apr-2021 12:47:36
Outcome: **Passed**
Description:

Sample scenario consisting in a constant curve with radius 1000m.

Speed set to 20 km/h.

Test Case Information

Name: 1000mCurve_Slow
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 848.240000000088108
Checksum: 3004570499 2739380835 3100569206 3150539238

100mCurve_Slow

Test Result Information

Result Type: Test Case Result
Parent: [Hyundai Azera](#)
Start Time: 29-Apr-2021 12:47:36
End Time: 29-Apr-2021 12:47:50
Outcome: **Passed**
Description:

Sample scenario consisting in a constant curve with radius 100m.

Speed: 10 km/h.

Test Case Information

Name: 100mCurve_Slow
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 169.64999999997565
Checksum: 658694597 4226064997 1514237116 1328707384

1000mCurve_Fast

Test Result Information

Result Type: Test Case Result
Parent: [Hyundai Azera](#)
Start Time: 29-Apr-2021 12:47:50
End Time: 29-Apr-2021 12:48:03
Outcome: **Passed**
Description:

Sample scenario consisting in a constant curve with 1000m radius.

Speed: 100 km/h.

Test Case Information

Name: 1000mCurve_Fast
Type: Simulation Test

Verify Result

Name	
✓	Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓	Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓	Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 169.650000000000313
Checksum: 1784879213 492416093 3665038557 1990414366

100mCurve_Fast

Test Result Information

Result Type: Test Case Result
Parent: [Hyundai Azera](#)
Start Time: 29-Apr-2021 12:48:03
End Time: 29-Apr-2021 12:48:05
Outcome: **Passed**
Description:

Sample scenario consisting of a constant curve with radius 100m.

Speed: 100 km/h.

Test Case Information

Name: 100mCurve_Fast
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 16.969999999999757
Checksum: 185083763 2040008444 1282780612 2456380744

Adriatic Highway A 14

Test Result Information

Result Type: Test Case Result
Parent: [Hyundai Azera](#)
Start Time: 29-Apr-2021 12:48:05
End Time: 29-Apr-2021 12:48:24
Outcome: **Passed**
Description:

This scenario is taken from the A14 Highway which is a straight road for the most of it, with some high-speed corners.

We simulate this scenario at 100 km/h.

Test Case Information

Name: Adriatic Highway A 14
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 275.08204274327625
Checksum: 2317052902 4180118644 981246727 2737245983

Indianapolis Speedway

Test Result Information

Result Type: Test Case Result
Parent: [Hyundai Azera](#)
Start Time: 29-Apr-2021 12:48:24
End Time: 29-Apr-2021 12:48:35
Outcome: **Passed**
Description:

This scenario is taken from the Indianapolis Speedway. We simulate it at 100 km/h.

Test Case Information

Name: Indianapolis Speedway
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 146.51791178475014
Checksum: 3889651783 1731957089 2002337100 853584640

BMW 325i

Test Result Information

Result Type: Test Suite Result
Parent: [Path_Following_test](#)
Start Time: 29-Apr-2021 12:48:35
End Time: 29-Apr-2021 12:55:50
Outcome: Total: 13, Passed: 12, Failed: 1

Test Suite Information

Name: BMW 325i

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Puglia

Test Result Information

Result Type: Test Case Result
Parent: [BMW 325i](#)
Start Time: 29-Apr-2021 12:48:35
End Time: 29-Apr-2021 12:49:32

Outcome: **Passed**

Description:

This scenario is taken from an Highway and it is a road that is straight for the most with some smooth corners.

In this test we try to follow the path with a speed of 40 km/h.

Test Case Information

Name: Puglia
Type: Simulation Test

Verify Result

Name	
✓	Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓	Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓	Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 651.65546907329576
Checksum: 202620085 696037187 1566738105 3145763362

Switzerland

Test Result Information

Result Type: Test Case Result
Parent: [BMW 325i](#)
Start Time: 29-Apr-2021 12:49:32
End Time: 29-Apr-2021 12:50:45
Outcome: **Failed**
Cause of Failure: **Failed criteria: Verification**

Description:




This is the slowest scenario considered, with lots of corners one after another.

We try to follow this scenario with 15 km/h speed.

Test Case Information

Name: Switzerland
Type: Simulation Test

Verify Result

Name	
	Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
	Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
	Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 759.09368017233703
Checksum: 2813384938 3166038877 3099671345 3384845185

Straight_Slow

Test Result Information

Result Type: Test Case Result
Parent: [BMW 325i](#)
Start Time: 29-Apr-2021 12:50:45
End Time: 29-Apr-2021 12:51:11
Outcome: **Passed**
Description:

Sample scenario consisting in a straight line.

Speed 10 km/h.

Test Case Information

Name: Straight_Slow
Type: Simulation Test

Verify Result

Name	
✓	Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓	Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓	Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 360
Checksum: 1885704342 1639022262 1968123643 3686124085

TiltedStraight_Slow

Test Result Information

Result Type: Test Case Result
Parent: [BMW 325i](#)
Start Time: 29-Apr-2021 12:51:11
End Time: 29-Apr-2021 12:51:50
Outcome: **Passed**
Description:

Sample scenario consisting in a straight line with a direction of 45 degrees in the X-Y plane.

Speed 10 km/h.

Test Case Information

Name: TiltedStraight_Slow
Type: Simulation Test

Verify Result

Name	
✓	Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓	Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓	Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 509.11688245431424
Checksum: 2284227124 546201088 1198533080 2624571421

Campania

Test Result Information

Result Type: Test Case Result
Parent: [BMW 325i](#)
Start Time: 29-Apr-2021 12:51:51
End Time: 29-Apr-2021 12:53:15
Outcome: **Passed**
Description:

This scenario is made up by a sequence of smooth corners.

We try to follow this path with 30 km/h speed.

Test Case Information

Name: Campania
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 843.22474949384798
Checksum: 2515822173 245894926 3757805933 999516670

Straight_Fast

Test Result Information

Result Type: Test Case Result
Parent: [BMW 325i](#)
Start Time: 29-Apr-2021 12:53:15
End Time: 29-Apr-2021 12:53:19
Outcome: **Passed**
Description:

Sample scenario consisiting in a straight line.

Speed: 100 km/h.

Test Case Information

Name: Straight_Fast
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 36
Checksum: 3695475672 3866628070 3423434440 3754794952

TiltedStraight_Fast

Test Result Information

Result Type: Test Case Result
Parent: [BMW 325i](#)
Start Time: 29-Apr-2021 12:53:19
End Time: 29-Apr-2021 12:53:23
Outcome: **Passed**
Description:

Sample scenario consisting in a straight line tilted by 135 degrees in the X-Y plane.

Speed: 100 km/h.

Test Case Information

Name: TiltedStraight_Fast
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 50.911688245431421
Checksum: 3021946026 1579631363 1462477640 3610898823

1000mCurve_Slow

Test Result Information

Result Type: Test Case Result
Parent: [BMW 325i](#)
Start Time: 29-Apr-2021 12:53:23
End Time: 29-Apr-2021 12:54:51
Outcome: **Passed**
Description:

Sample scenario consisting in a constant curve with radius 1000m.

Speed set to 20 km/h.

Test Case Information

Name: 1000mCurve_Slow
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 848.240000000088108
Checksum: 3004570499 2739380835 3100569206 3150539238

100mCurve_Slow

Test Result Information

Result Type: Test Case Result
Parent: [BMW 325i](#)
Start Time: 29-Apr-2021 12:54:51
End Time: 29-Apr-2021 12:55:04
Outcome: **Passed**
Description:

Sample scenario consisting in a constant curve with radius 100m.

Speed: 10 km/h.

Test Case Information

Name: 100mCurve_Slow
Type: Simulation Test

Verify Result

Name	
✓	Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓	Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓	Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 169.64999999997565
Checksum: 658694597 4226064997 1514237116 1328707384

1000mCurve_Fast

Test Result Information

Result Type: Test Case Result
Parent: [BMW 325i](#)
Start Time: 29-Apr-2021 12:55:04
End Time: 29-Apr-2021 12:55:17
Outcome: **Passed**
Description:

Sample scenario consisting in a constant curve with 1000m radius.

Speed: 100 km/h.

Test Case Information

Name: 1000mCurve_Fast
Type: Simulation Test

Verify Result

Name	
✓	Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓	Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓	Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 169.650000000000313
Checksum: 1784879213 492416093 3665038557 1990414366

100mCurve_Fast

Test Result Information

Result Type: Test Case Result
Parent: [BMW 325i](#)
Start Time: 29-Apr-2021 12:55:17
End Time: 29-Apr-2021 12:55:19
Outcome: **Passed**
Description:

Sample scenario consisting of a constant curve with radius 100m.

Speed: 100 km/h.

Test Case Information

Name: 100mCurve_Fast
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 16.969999999999757
Checksum: 185083763 2040008444 1282780612 2456380744

Adriatic Highway A 14

Test Result Information

Result Type: Test Case Result
Parent: [BMW 325i](#)
Start Time: 29-Apr-2021 12:55:19
End Time: 29-Apr-2021 12:55:40
Outcome: **Passed**
Description:

This scenario is taken from the A14 Highway which is a straight road for the most of it, with some high-speed corners.

We simulate this scenario at 100 km/h.

Test Case Information

Name: Adriatic Highway A 14
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 275.08204274327625
Checksum: 2317052902 4180118644 981246727 2737245983

Indianapolis Speedway

Test Result Information

Result Type: Test Case Result
Parent: [BMW 325i](#)
Start Time: 29-Apr-2021 12:55:40
End Time: 29-Apr-2021 12:55:50
Outcome: **Passed**
Description:

This scenario is taken from the Indianapolis Speedway. We simulate it at 100 km/h.

Test Case Information

Name: Indianapolis Speedway
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 146.51791178475014
Checksum: 3889651783 1731957089 2002337100 853584640

Ford E150

Test Result Information

Result Type: Test Suite Result
Parent: [Path_Following_test](#)
Start Time: 29-Apr-2021 12:55:50
End Time: 29-Apr-2021 13:03:12
Outcome: Total: 13, Passed: 11, Failed: 2

Test Suite Information

Name: Ford E150

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Puglia

Test Result Information

Result Type: Test Case Result
Parent: [Ford E150](#)
Start Time: 29-Apr-2021 12:55:50
End Time: 29-Apr-2021 12:56:48

Outcome: **Passed**

Description:

This scenario is taken from an Highway and it is a road that is straight for the most with some smooth corners.

In this test we try to follow the path with a speed of 40 km/h.

Test Case Information

Name: Puglia
Type: Simulation Test

Verify Result

Name	
✓	Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓	Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓	Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 651.65546907329576
Checksum: 202620085 696037187 1566738105 3145763362

Switzerland

Test Result Information

Result Type: Test Case Result
Parent: [Ford E150](#)
Start Time: 29-Apr-2021 12:56:48
End Time: 29-Apr-2021 12:58:01
Outcome: **Failed**
Cause of Failure: **Failed criteria: Verification**

Description:




This is the slowest scenario considered, with lots of corners one after another.

We try to follow this scenario with 15 km/h speed.

Test Case Information

Name: Switzerland
Type: Simulation Test

Verify Result

Name	
	Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
	Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
	Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 759.09368017233703
Checksum: 2813384938 3166038877 3099671345 3384845185

Straight_Slow

Test Result Information

Result Type: Test Case Result
Parent: [Ford E150](#)
Start Time: 29-Apr-2021 12:58:01
End Time: 29-Apr-2021 12:58:27
Outcome: **Passed**
Description:

Sample scenario consisting in a straight line.

Speed 10 km/h.

Test Case Information

Name: Straight_Slow
Type: Simulation Test

Verify Result

Name	
✓	Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓	Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓	Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 360
Checksum: 1885704342 1639022262 1968123643 3686124085

TiltedStraight_Slow

Test Result Information

Result Type: Test Case Result
Parent: [Ford E150](#)
Start Time: 29-Apr-2021 12:58:27
End Time: 29-Apr-2021 12:59:08
Outcome: **Passed**
Description:

Sample scenario consisting in a straight line with a direction of 45 degrees in the X-Y plane.

Speed 10 km/h.

Test Case Information

Name: TiltedStraight_Slow
Type: Simulation Test

Verify Result

Name	
✓	Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓	Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓	Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 509.11688245431424
Checksum: 2284227124 546201088 1198533080 2624571421

Campania

Test Result Information

Result Type: Test Case Result
Parent: [Ford E150](#)
Start Time: 29-Apr-2021 12:59:08
End Time: 29-Apr-2021 13:00:35
Outcome: **Failed**
Cause of Failure: **Failed criteria: Verification**
Description:




This scenario is made up by a sequence of smooth corners.

We try to follow this path with 30 km/h speed.

Test Case Information

Name: Campania
Type: Simulation Test

Verify Result

Name	
	Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
	Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
	Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 843.22474949384798
Checksum: 2515822173 245894926 3757805933 999516670

Straight_Fast

Test Result Information

Result Type: Test Case Result
Parent: [Ford E150](#)
Start Time: 29-Apr-2021 13:00:35
End Time: 29-Apr-2021 13:00:38
Outcome: **Passed**
Description:

Sample scenario consisiting in a straight line.

Speed: 100 km/h.

Test Case Information

Name: Straight_Fast
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 36
Checksum: 3695475672 3866628070 3423434440 3754794952

TiltedStraight_Fast

Test Result Information

Result Type: Test Case Result
Parent: [Ford E150](#)
Start Time: 29-Apr-2021 13:00:38
End Time: 29-Apr-2021 13:00:43
Outcome: **Passed**
Description:

Sample scenario consisting in a straight line tilted by 135 degrees in the X-Y plane.

Speed: 100 km/h.

Test Case Information

Name: TiltedStraight_Fast
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 50.911688245431421
Checksum: 3021946026 1579631363 1462477640 3610898823

1000mCurve_Slow

Test Result Information

Result Type: Test Case Result
Parent: [Ford E150](#)
Start Time: 29-Apr-2021 13:00:43
End Time: 29-Apr-2021 13:02:13
Outcome: **Passed**
Description:

Sample scenario consisting in a constant curve with radius 1000m.

Speed set to 20 km/h.

Test Case Information

Name: 1000mCurve_Slow
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 848.240000000088108
Checksum: 3004570499 2739380835 3100569206 3150539238

100mCurve_Slow

Test Result Information

Result Type: Test Case Result
Parent: [Ford E150](#)
Start Time: 29-Apr-2021 13:02:13
End Time: 29-Apr-2021 13:02:26
Outcome: **Passed**
Description:

Sample scenario consisting in a constant curve with radius 100m.

Speed: 10 km/h.

Test Case Information

Name: 100mCurve_Slow
Type: Simulation Test

Verify Result

Name	
✓	Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓	Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓	Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 169.64999999997565
Checksum: 658694597 4226064997 1514237116 1328707384

1000mCurve_Fast

Test Result Information

Result Type: Test Case Result
Parent: [Ford E150](#)
Start Time: 29-Apr-2021 13:02:26
End Time: 29-Apr-2021 13:02:38
Outcome: **Passed**
Description:

Sample scenario consisting in a constant curve with 1000m radius.

Speed: 100 km/h.

Test Case Information

Name: 1000mCurve_Fast
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 169.650000000000313
Checksum: 1784879213 492416093 3665038557 1990414366

100mCurve_Fast

Test Result Information

Result Type: Test Case Result
Parent: [Ford E150](#)
Start Time: 29-Apr-2021 13:02:38
End Time: 29-Apr-2021 13:02:41
Outcome: **Passed**
Description:

Sample scenario consisting of a constant curve with radius 100m.

Speed: 100 km/h.

Test Case Information

Name: 100mCurve_Fast
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 16.969999999999757
Checksum: 185083763 2040008444 1282780612 2456380744

Adriatic Highway A 14

Test Result Information

Result Type: Test Case Result
Parent: [Ford E150](#)
Start Time: 29-Apr-2021 13:02:41
End Time: 29-Apr-2021 13:03:01
Outcome: **Passed**
Description:

This scenario is taken from the A14 Highway which is a straight road for the most of it, with some high-speed corners.

We simulate this scenario at 100 km/h.

Test Case Information

Name: Adriatic Highway A 14
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 275.08204274327625
Checksum: 2317052902 4180118644 981246727 2737245983

Indianapolis Speedway

Test Result Information

Result Type: Test Case Result
Parent: [Ford E150](#)
Start Time: 29-Apr-2021 13:03:01
End Time: 29-Apr-2021 13:03:12
Outcome: **Passed**
Description:

This scenario is taken from the Indianapolis Speedway. We simulate it at 100 km/h.

Test Case Information

Name: Indianapolis Speedway
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 146.51791178475014
Checksum: 3889651783 1731957089 2002337100 853584640

Suzuki Samurai

Test Result Information

Result Type: Test Suite Result
Parent: [Path_Following_test](#)
Start Time: 29-Apr-2021 13:03:12
End Time: 29-Apr-2021 13:10:36
Outcome: Total: 13, Passed: 12, Failed: 1

Test Suite Information

Name: Suzuki Samurai

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Puglia

Test Result Information

Result Type: Test Case Result
Parent: [Suzuki Samurai](#)
Start Time: 29-Apr-2021 13:03:12
End Time: 29-Apr-2021 13:04:09

Outcome: **Passed**

Description:

This scenario is taken from an Highway and it is a road that is straight for the most with some smooth corners.

In this test we try to follow the path with a speed of 40 km/h.

Test Case Information

Name: Puglia
Type: Simulation Test

Verify Result

Name	
✓	Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓	Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓	Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 651.65546907329576
Checksum: 202620085 696037187 1566738105 3145763362

Switzerland

Test Result Information

Result Type: Test Case Result
Parent: [Suzuki Samurai](#)
Start Time: 29-Apr-2021 13:04:09
End Time: 29-Apr-2021 13:05:25
Outcome: **Failed**
Cause of Failure: **Failed criteria: Verification**

Description:




This is the slowest scenario considered, with lots of corners one after another.

We try to follow this scenario with 15 km/h speed.

Test Case Information

Name: Switzerland
Type: Simulation Test

Verify Result

Name	
	Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
	Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
	Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 759.09368017233703
Checksum: 2813384938 3166038877 3099671345 3384845185

Straight_Slow

Test Result Information

Result Type: Test Case Result
Parent: [Suzuki Samurai](#)
Start Time: 29-Apr-2021 13:05:25
End Time: 29-Apr-2021 13:05:50
Outcome: **Passed**
Description:

Sample scenario consisting in a straight line.

Speed 10 km/h.

Test Case Information

Name: Straight_Slow
Type: Simulation Test

Verify Result

Name	
✓	Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓	Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓	Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 360
Checksum: 1885704342 1639022262 1968123643 3686124085

TiltedStraight_Slow

Test Result Information

Result Type: Test Case Result
Parent: [Suzuki Samurai](#)
Start Time: 29-Apr-2021 13:05:50
End Time: 29-Apr-2021 13:06:31
Outcome: **Passed**
Description:

Sample scenario consisting in a straight line with a direction of 45 degrees in the X-Y plane.

Speed 10 km/h.

Test Case Information

Name: TiltedStraight_Slow
Type: Simulation Test

Verify Result

Name	
✓	Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓	Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓	Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 509.11688245431424
Checksum: 2284227124 546201088 1198533080 2624571421

Campania

Test Result Information

Result Type: Test Case Result
Parent: [Suzuki Samurai](#)
Start Time: 29-Apr-2021 13:06:31
End Time: 29-Apr-2021 13:07:56
Outcome: **Passed**
Description:

This scenario is made up by a sequence of smooth corners.

We try to follow this path with 30 km/h speed.

Test Case Information

Name: Campania
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 843.22474949384798
Checksum: 2515822173 245894926 3757805933 999516670

Straight_Fast

Test Result Information

Result Type: Test Case Result
Parent: [Suzuki Samurai](#)
Start Time: 29-Apr-2021 13:07:56
End Time: 29-Apr-2021 13:07:59
Outcome: **Passed**
Description:

Sample scenario consisiting in a straight line.

Speed: 100 km/h.

Test Case Information

Name: Straight_Fast
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 36
Checksum: 3695475672 3866628070 3423434440 3754794952

TiltedStraight_Fast

Test Result Information

Result Type: Test Case Result
Parent: [Suzuki Samurai](#)
Start Time: 29-Apr-2021 13:07:59
End Time: 29-Apr-2021 13:08:04
Outcome: **Passed**
Description:

Sample scenario consisting in a straight line tilted by 135 degrees in the X-Y plane.

Speed: 100 km/h.

Test Case Information

Name: TiltedStraight_Fast
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 50.911688245431421
Checksum: 3021946026 1579631363 1462477640 3610898823

1000mCurve_Slow

Test Result Information

Result Type: Test Case Result
Parent: [Suzuki Samurai](#)
Start Time: 29-Apr-2021 13:08:04
End Time: 29-Apr-2021 13:09:34
Outcome: **Passed**
Description:

Sample scenario consisting in a constant curve with radius 1000m.

Speed set to 20 km/h.

Test Case Information

Name: 1000mCurve_Slow
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 848.240000000088108
Checksum: 3004570499 2739380835 3100569206 3150539238

100mCurve_Slow

Test Result Information

Result Type: Test Case Result
Parent: [Suzuki Samurai](#)
Start Time: 29-Apr-2021 13:09:34
End Time: 29-Apr-2021 13:09:49
Outcome: **Passed**
Description:

Sample scenario consisting in a constant curve with radius 100m.

Speed: 10 km/h.

Test Case Information

Name: 100mCurve_Slow
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 169.64999999997565
Checksum: 658694597 4226064997 1514237116 1328707384

1000mCurve_Fast

Test Result Information

Result Type: Test Case Result
Parent: [Suzuki Samurai](#)
Start Time: 29-Apr-2021 13:09:49
End Time: 29-Apr-2021 13:10:02
Outcome: **Passed**
Description:

Sample scenario consisting in a constant curve with 1000m radius.

Speed: 100 km/h.

Test Case Information

Name: 1000mCurve_Fast
Type: Simulation Test

Verify Result

Name	
✓	Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓	Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓	Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 169.650000000000313
Checksum: 1784879213 492416093 3665038557 1990414366

100mCurve_Fast

Test Result Information

Result Type: Test Case Result
Parent: [Suzuki Samurai](#)
Start Time: 29-Apr-2021 13:10:02
End Time: 29-Apr-2021 13:10:04
Outcome: **Passed**
Description:

Sample scenario consisting of a constant curve with radius 100m.

Speed: 100 km/h.

Test Case Information

Name: 100mCurve_Fast
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 16.969999999999757
Checksum: 185083763 2040008444 1282780612 2456380744

Adriatic Highway A 14

Test Result Information

Result Type: Test Case Result
Parent: [Suzuki Samurai](#)
Start Time: 29-Apr-2021 13:10:04
End Time: 29-Apr-2021 13:10:25
Outcome: **Passed**
Description:

This scenario is taken from the A14 Highway which is a straight road for the most of it, with some high-speed corners.

We simulate this scenario at 100 km/h.

Test Case Information

Name: Adriatic Highway A 14
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 275.08204274327625
Checksum: 2317052902 4180118644 981246727 2737245983

Indianapolis Speedway

Test Result Information

Result Type: Test Case Result
Parent: [Suzuki Samurai](#)
Start Time: 29-Apr-2021 13:10:25
End Time: 29-Apr-2021 13:10:36
Outcome: **Passed**
Description:

This scenario is taken from the Indianapolis Speedway. We simulate it at 100 km/h.

Test Case Information

Name: Indianapolis Speedway
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 146.51791178475014
Checksum: 3889651783 1731957089 2002337100 853584640

Volkswagen Beetle

Test Result Information

Result Type: Test Suite Result
Parent: [Path_Following_test](#)
Start Time: 29-Apr-2021 13:10:36
End Time: 29-Apr-2021 13:18:30
Outcome: Total: 13, Passed: 12, Failed: 1

Test Suite Information

Name: Volkswagen Beetle

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Puglia

Test Result Information

Result Type: Test Case Result
Parent: [Volkswagen Beetle](#)
Start Time: 29-Apr-2021 13:10:36
End Time: 29-Apr-2021 13:11:38

Outcome: **Passed**

Description:

This scenario is taken from an Highway and it is a road that is straight for the most with some smooth corners.

In this test we try to follow the path with a speed of 40 km/h.

Test Case Information

Name: Puglia
Type: Simulation Test

Verify Result

Name	
✓	Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓	Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓	Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 651.65546907329576
Checksum: 202620085 696037187 1566738105 3145763362

Switzerland

Test Result Information

Result Type: Test Case Result
Parent: [Volkswagen Beetle](#)
Start Time: 29-Apr-2021 13:11:38
End Time: 29-Apr-2021 13:13:00
Outcome: **Failed**
Cause of Failure: **Failed criteria: Verification**

Description:




This is the slowest scenario considered, with lots of corners one after another.

We try to follow this scenario with 15 km/h speed.

Test Case Information

Name: Switzerland
Type: Simulation Test

Verify Result

Name	
	Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
	Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
	Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 759.09368017233703
Checksum: 2813384938 3166038877 3099671345 3384845185

Straight_Slow

Test Result Information

Result Type: Test Case Result
Parent: [Volkswagen Beetle](#)
Start Time: 29-Apr-2021 13:13:00
End Time: 29-Apr-2021 13:13:27
Outcome: **Passed**
Description:

Sample scenario consisting in a straight line.

Speed 10 km/h.

Test Case Information

Name: Straight_Slow
Type: Simulation Test

Verify Result

Name	
✓	Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓	Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓	Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 360
Checksum: 1885704342 1639022262 1968123643 3686124085

TiltedStraight_Slow

Test Result Information

Result Type: Test Case Result
Parent: [Volkswagen Beetle](#)
Start Time: 29-Apr-2021 13:13:27
End Time: 29-Apr-2021 13:14:11
Outcome: **Passed**
Description:

Sample scenario consisting in a straight line with a direction of 45 degrees in the X-Y plane.

Speed 10 km/h.

Test Case Information

Name: TiltedStraight_Slow
Type: Simulation Test

Verify Result

Name	
✓	Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓	Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓	Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 509.11688245431424
Checksum: 2284227124 546201088 1198533080 2624571421

Campania

Test Result Information

Result Type: Test Case Result
Parent: [Volkswagen Beetle](#)
Start Time: 29-Apr-2021 13:14:11
End Time: 29-Apr-2021 13:15:44
Outcome: **Passed**
Description:

This scenario is made up by a sequence of smooth corners.

We try to follow this path with 30 km/h speed.

Test Case Information

Name: Campania
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 843.22474949384798
Checksum: 2515822173 245894926 3757805933 999516670

Straight_Fast

Test Result Information

Result Type: Test Case Result
Parent: [Volkswagen Beetle](#)
Start Time: 29-Apr-2021 13:15:44
End Time: 29-Apr-2021 13:15:47
Outcome: **Passed**
Description:

Sample scenario consisiting in a straight line.

Speed: 100 km/h.

Test Case Information

Name: Straight_Fast
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 36
Checksum: 3695475672 3866628070 3423434440 3754794952

TiltedStraight_Fast

Test Result Information

Result Type: Test Case Result
Parent: [Volkswagen Beetle](#)
Start Time: 29-Apr-2021 13:15:47
End Time: 29-Apr-2021 13:15:51
Outcome: **Passed**
Description:

Sample scenario consisting in a straight line tilted by 135 degrees in the X-Y plane.

Speed: 100 km/h.

Test Case Information

Name: TiltedStraight_Fast
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 50.911688245431421
Checksum: 3021946026 1579631363 1462477640 3610898823

1000mCurve_Slow

Test Result Information

Result Type: Test Case Result
Parent: [Volkswagen Beetle](#)
Start Time: 29-Apr-2021 13:15:51
End Time: 29-Apr-2021 13:17:29
Outcome: **Passed**
Description:

Sample scenario consisting in a constant curve with radius 1000m.

Speed set to 20 km/h.

Test Case Information

Name: 1000mCurve_Slow
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 848.240000000088108
Checksum: 3004570499 2739380835 3100569206 3150539238

100mCurve_Slow

Test Result Information

Result Type: Test Case Result
Parent: [Volkswagen Beetle](#)
Start Time: 29-Apr-2021 13:17:29
End Time: 29-Apr-2021 13:17:42
Outcome: **Passed**
Description:

Sample scenario consisting in a constant curve with radius 100m.

Speed: 10 km/h.

Test Case Information

Name: 100mCurve_Slow
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 169.64999999997565
Checksum: 658694597 4226064997 1514237116 1328707384

1000mCurve_Fast

Test Result Information

Result Type: Test Case Result
Parent: [Volkswagen Beetle](#)
Start Time: 29-Apr-2021 13:17:42
End Time: 29-Apr-2021 13:17:55
Outcome: **Passed**
Description:

Sample scenario consisting in a constant curve with 1000m radius.

Speed: 100 km/h.

Test Case Information

Name: 1000mCurve_Fast
Type: Simulation Test

Verify Result

Name	
✓	Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓	Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓	Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 169.650000000000313
Checksum: 1784879213 492416093 3665038557 1990414366

100mCurve_Fast

Test Result Information

Result Type: Test Case Result
Parent: [Volkswagen Beetle](#)
Start Time: 29-Apr-2021 13:17:55
End Time: 29-Apr-2021 13:17:57
Outcome: **Passed**
Description:

Sample scenario consisting of a constant curve with radius 100m.

Speed: 100 km/h.

Test Case Information

Name: 100mCurve_Fast
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 16.969999999999757
Checksum: 185083763 2040008444 1282780612 2456380744

Adriatic Highway A 14

Test Result Information

Result Type: Test Case Result
Parent: [Volkswagen Beetle](#)
Start Time: 29-Apr-2021 13:17:57
End Time: 29-Apr-2021 13:18:18
Outcome: **Passed**
Description:

This scenario is taken from the A14 Highway which is a straight road for the most of it, with some high-speed corners.

We simulate this scenario at 100 km/h.

Test Case Information

Name: Adriatic Highway A 14
Type: Simulation Test

Verify Result

Name
✓ Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓ Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓ Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 275.08204274327625
Checksum: 2317052902 4180118644 981246727 2737245983

Indianapolis Speedway

Test Result Information

Result Type: Test Case Result
Parent: [Volkswagen Beetle](#)
Start Time: 29-Apr-2021 13:18:18
End Time: 29-Apr-2021 13:18:30
Outcome: **Passed**
Description:

This scenario is taken from the Indianapolis Speedway. We simulate it at 100 km/h.

Test Case Information

Name: Indianapolis Speedway
Type: Simulation Test

Verify Result

Name	
✓	Lateral Deviation Assessment/GlobalAssessments:verify(duration(lateral_dev > 0.75,sec)<1)
✓	Maximum Lateral Deviation Assessment/Maximum_Lateral_Dev_Assessment:verify(lateral_dev < 1)
✓	Lateral Acceleration Assessment/Global_Assessment:verify(duration(Lateral_acceleration>=2,sec)<=0.5)

Simulation

System Under Test Information

Model: Dynamic_obstacle_avoidance
Harness: Path_Following_Harness
Harness Owner: Dynamic_obstacle_avoidance/Subsystem
Simulation Mode: normal
Configuration Set: Configuration1
Start Time: 0
Stop Time: 146.51791178475014
Checksum: 3889651783 1731957089 2002337100 853584640
