



UNIVERSITÀ DEGLI STUDI DI VERONA

# Spectral shape analysis for 3D matching

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# Instructor



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# Outline

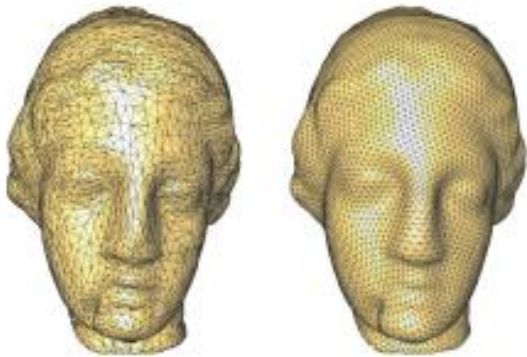
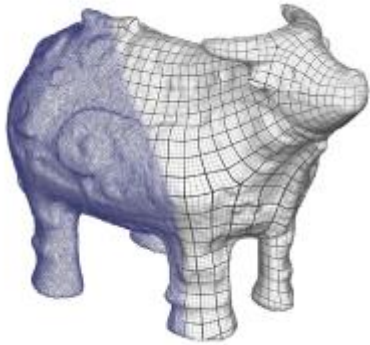
- » Introduction,
- » 3D Matching,
- » 3D Shape,
- » Spectral Shape Analysis,
- » Schedule





# Introduction

Digital representations of 3D objects and scene are ubiquitous

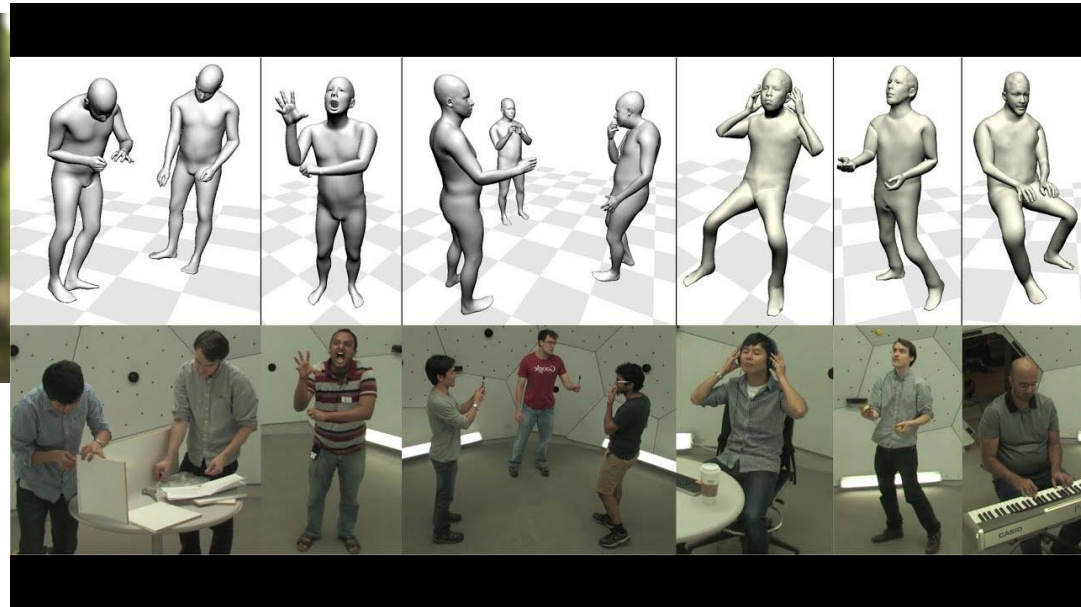


<https://giphy.com/>



# Introduction

## Virtual objects from real world

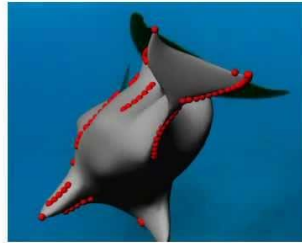
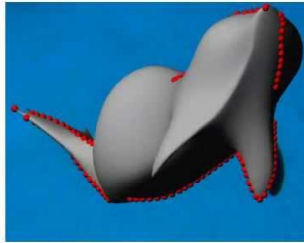
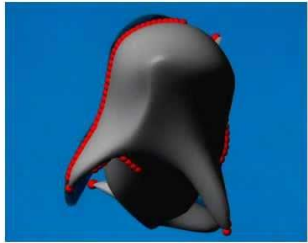
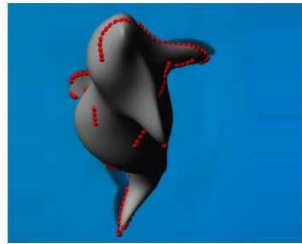
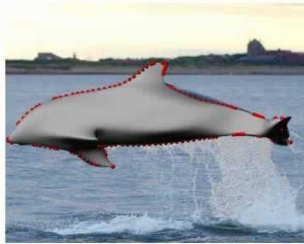




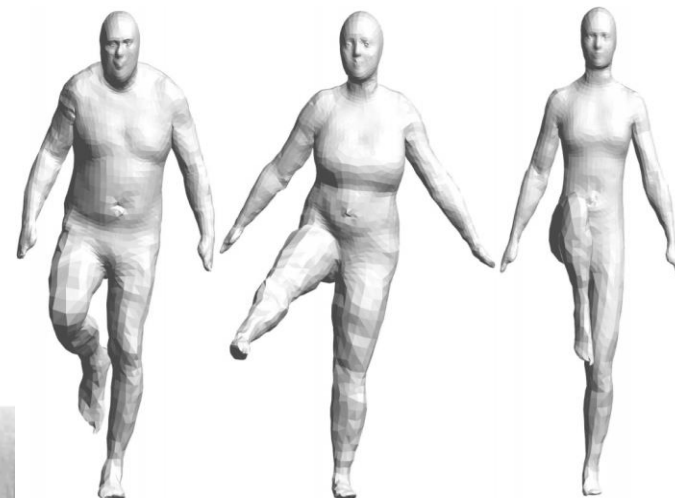
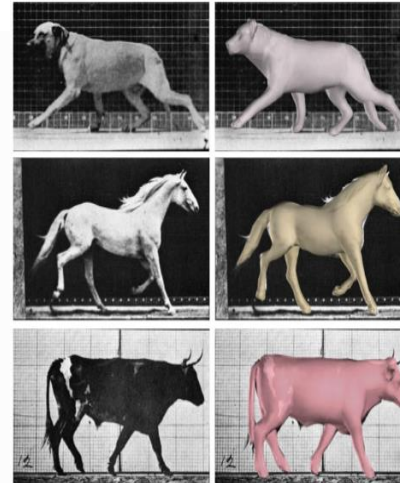


# Introduction

## Non-rigid world



Morphable model parameters: I



What shape are dolphin?, Cashman et. al., '12  
3D Menagerie: Modeling the 3D Shape and Pose of Animals, Zu et. al, '17  
Total Capture: A 3D Deformation Model for Tracking Faces, Joo et. al, '18  
Expressive Body Capture: 3D Hands, Face, and Body, Pavlakos et. al, '19  
Multi-chart Generative Surface Modeling, Ben-Hamu et. al, '19  
Learning an Infant Body Model from RGB-D Data, Hesse et .al, '18



# Introduction

Where digital representation are important



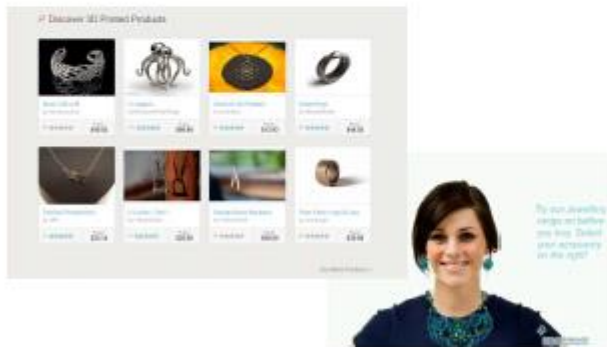
Medical



Engineering



Games



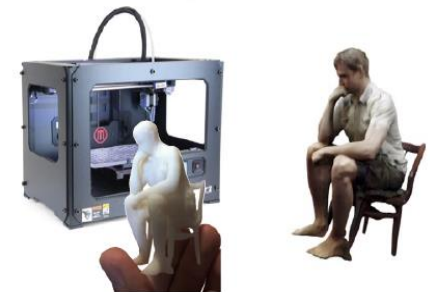
E-Commerce



Culture



Simulation



3D printing



# Introduction

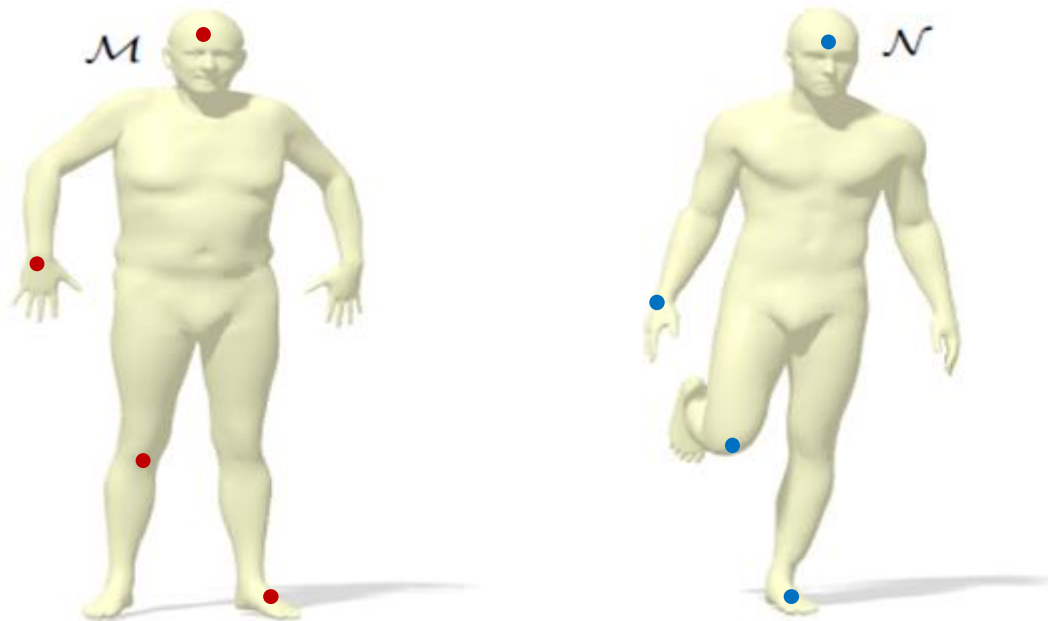
In all these contexts there is a fundamental issue to solve:

## 3D Shape matching





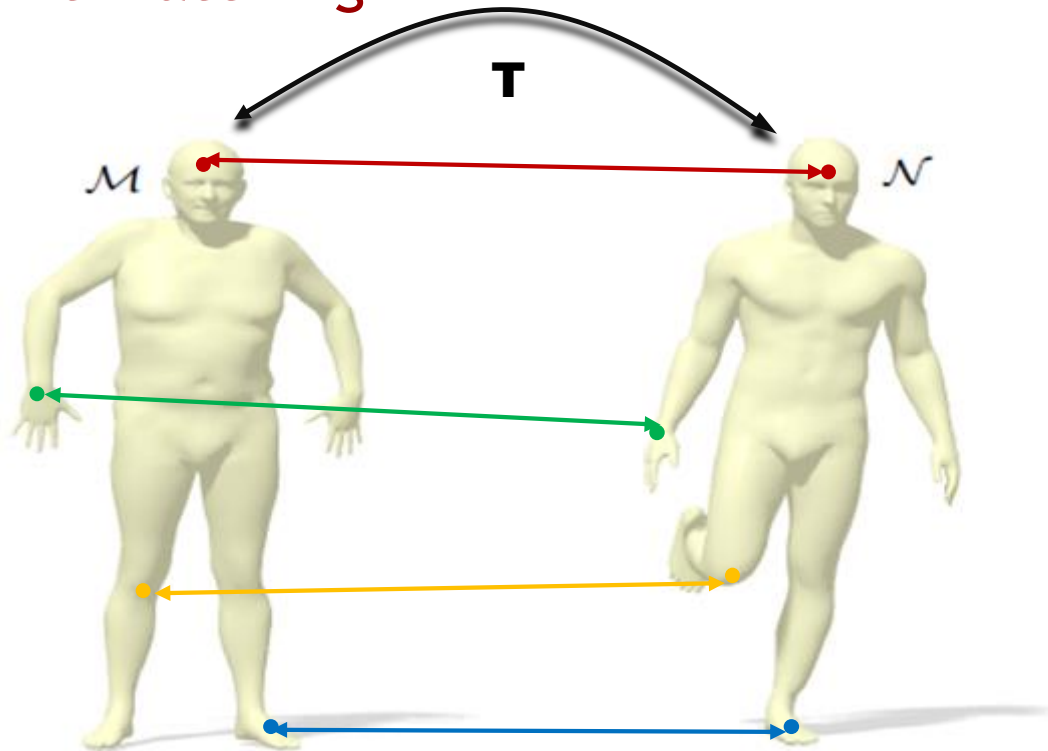
# 3D Shape matching





# 3D Shape matching

## Point to point matching





# 3D Shape matching

## Open problems:

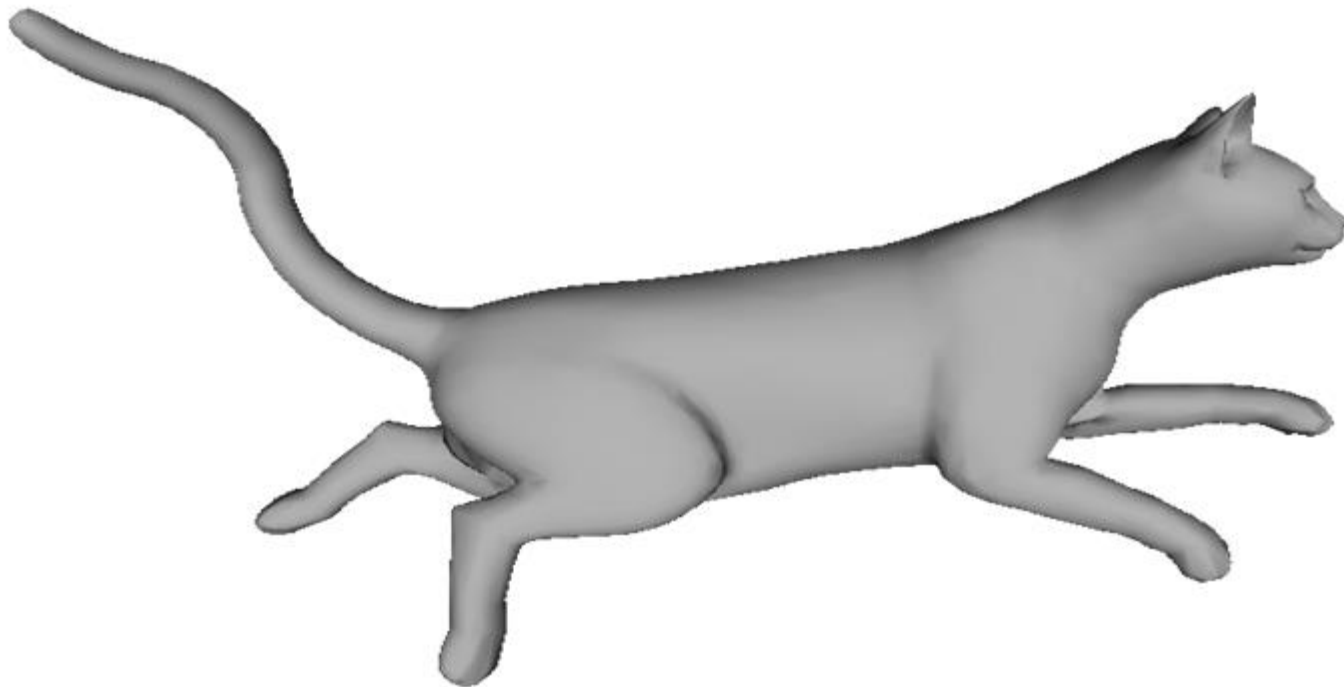
- » Reliability and accuracy of matching,
- » Robustness to heterogeneous data representation,
- » Matching between non rigid objects,
- » Computational complexity,
- » Robustness to noise and missing parts,





# What is a shape?

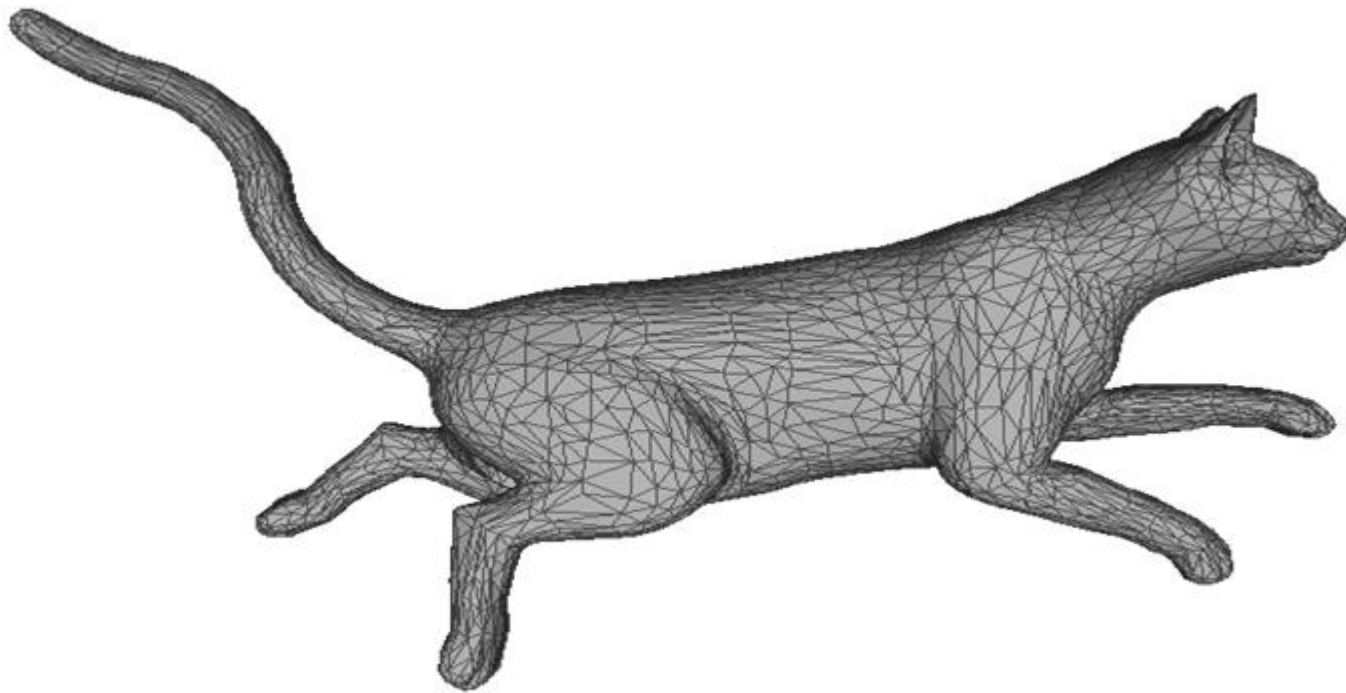
» **Continuous:** a surface embedded in 3D





# What is a shape?

- ▣ **Continuous:** a surface embedded in 3D
- ▣ **Discrete:** a graph embedded in 3D (triangle mesh).

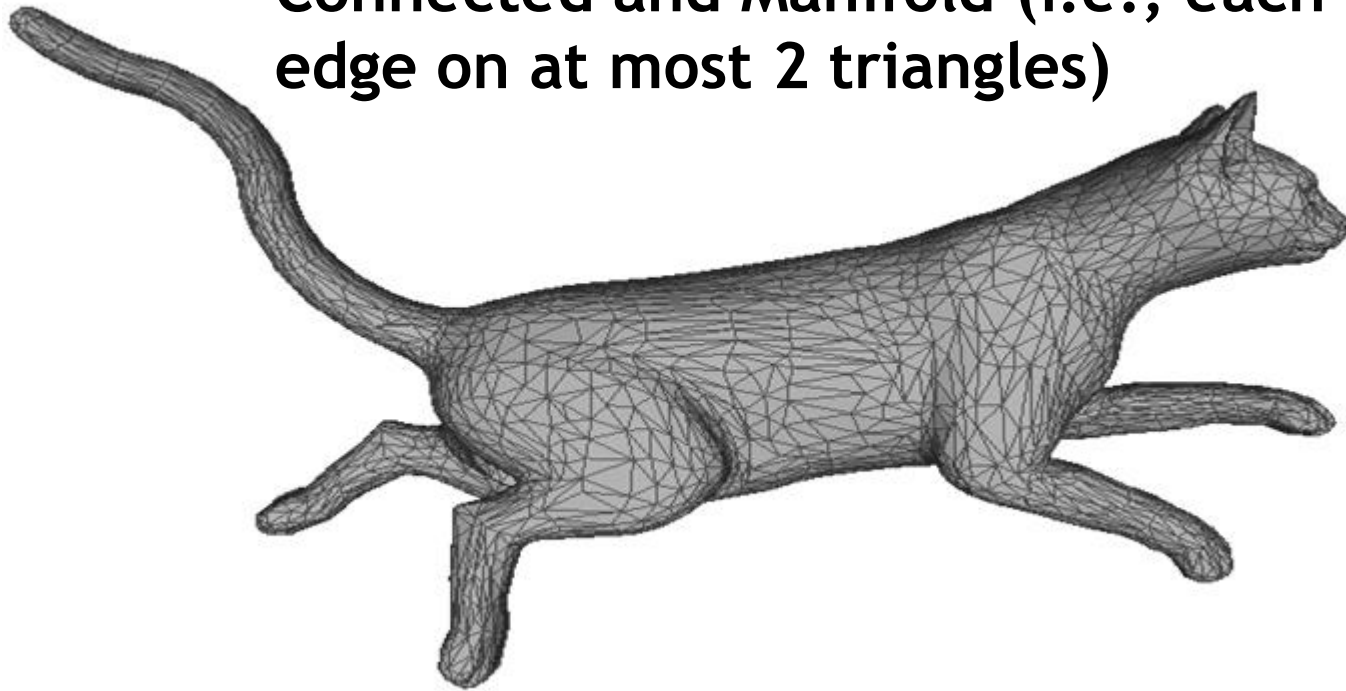




# What is a shape?

- ▣ **Continuous:** a surface embedded in 3D
- ▣ **Discrete:** a graph embedded in 3D (triangle mesh).

**Connected and Manifold (i.e., each edge on at most 2 triangles)**



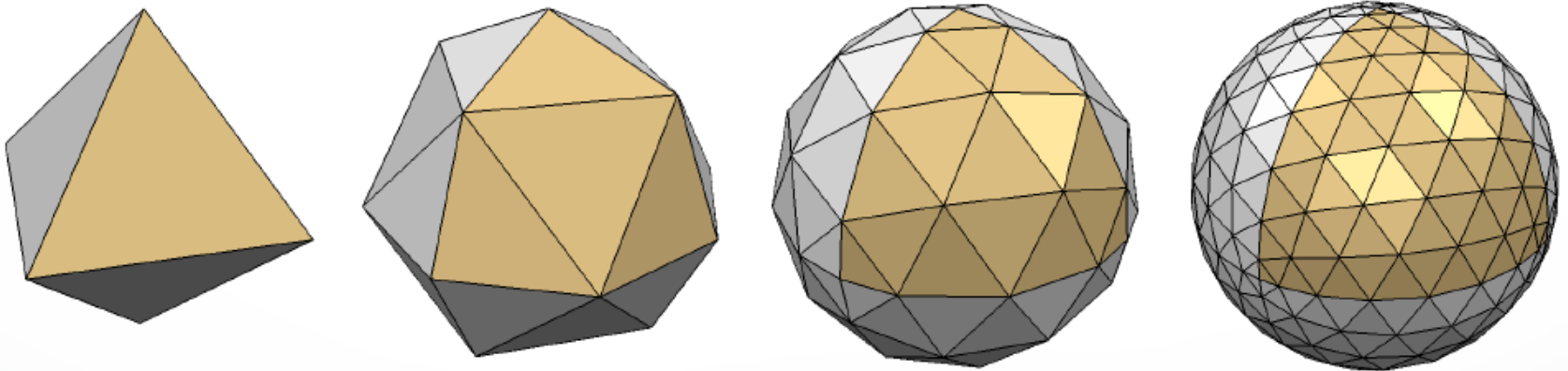




# What is a shape?

- ▣ Polygonal meshes are the most used representation for 3D shapes:

“Piecewise linear approximation --> error is  $O(h^2)$ ”



Error inversely proportional to #faces



# What is a shape?

- ▣ Polygonal meshes are the most used representation for 3D shapes:

“Arbitrary topology surfaces”



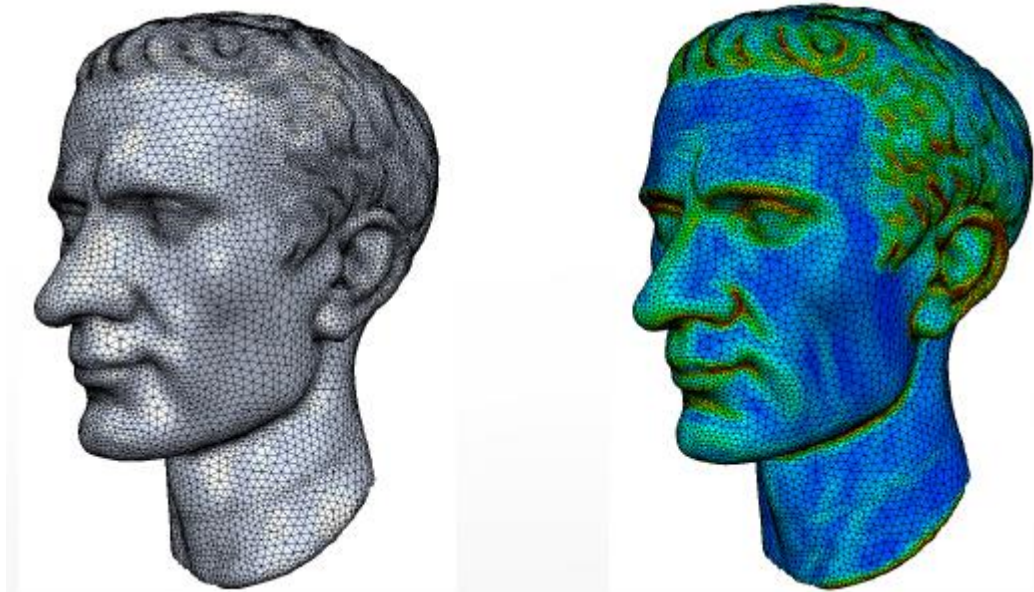
Allow subdivision for smoothness



# What is a shape?

- ▣ Polygonal meshes are the most used representation for 3D shapes:

“Adaptive sampling”



Can add resolution only where necessary

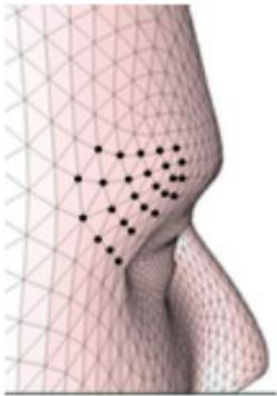




# What is a shape?

» Two main components:

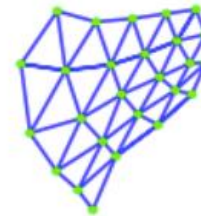
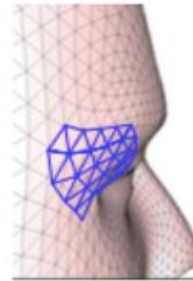
Geometry



vertex  
coordinates

**geometric structure**

"Connectivity": the underlying triangulation



incidence relations  
between triangles,  
vertices and edges

**combinatorial structure**

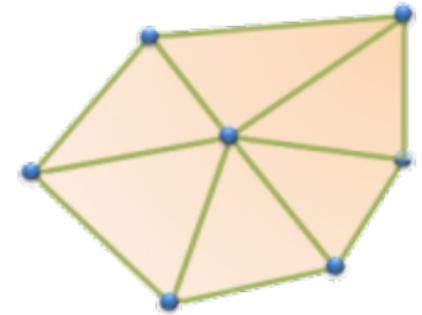


# What is a shape?

## Two main components:

- Geometry: vertex positions

$$\mathcal{P} = \{p_1, p_2, \dots, p_n\}, \quad p_i \in \mathbb{R}^3$$



- Connectivity:

- Vertices:  $\mathcal{V} = \{v_1, v_2, \dots, v_n\}$

- Edges:  $\mathcal{E} = \{e_1, e_2, \dots, e_m\}, \quad e_i \in \mathcal{V} \times \mathcal{V}$

- Faces:  $\mathcal{F} = \{f_1, f_2, \dots, f_k\}, \quad f_i \in \mathcal{V} \times \mathcal{V} \times \mathcal{V}$

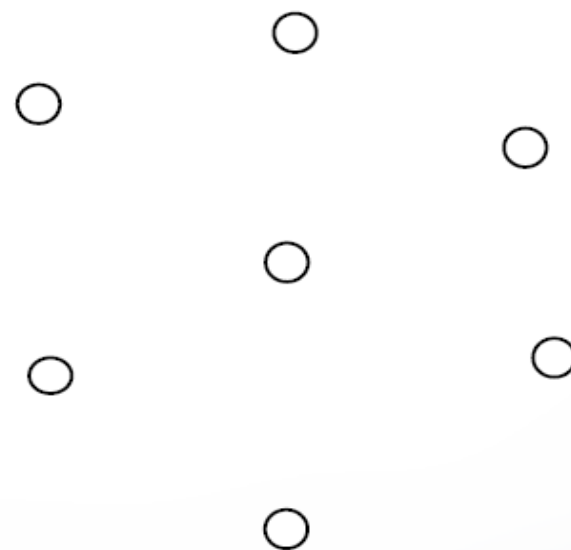


# What is a shape?



$$\mathcal{M} = (\{\mathbf{v}_i\}, \{e_j\}, \{f_k\})$$

geometry  $\mathbf{v}_i \in \mathbb{R}^3$







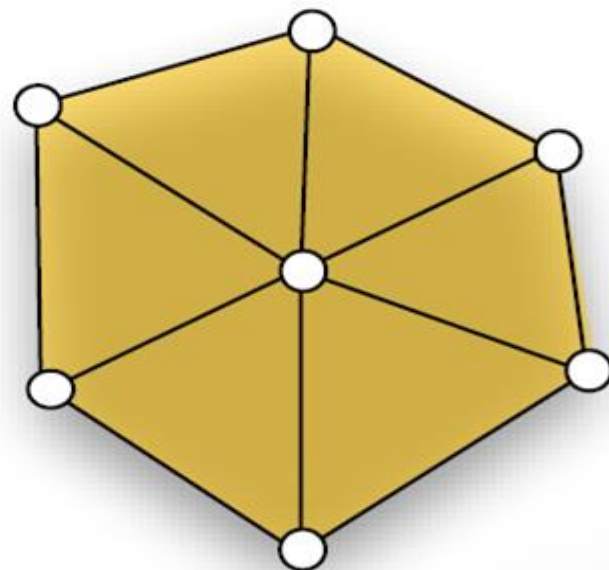
# What is a shape?



$$\mathcal{M} = (\{\mathbf{v}_i\}, \{e_j\}, \{f_k\})$$

geometry  $\mathbf{v}_i \in \mathbb{R}^3$

topology  $e_i, f_i \subset \mathbb{R}^3$





# Why spectral shape analysis?

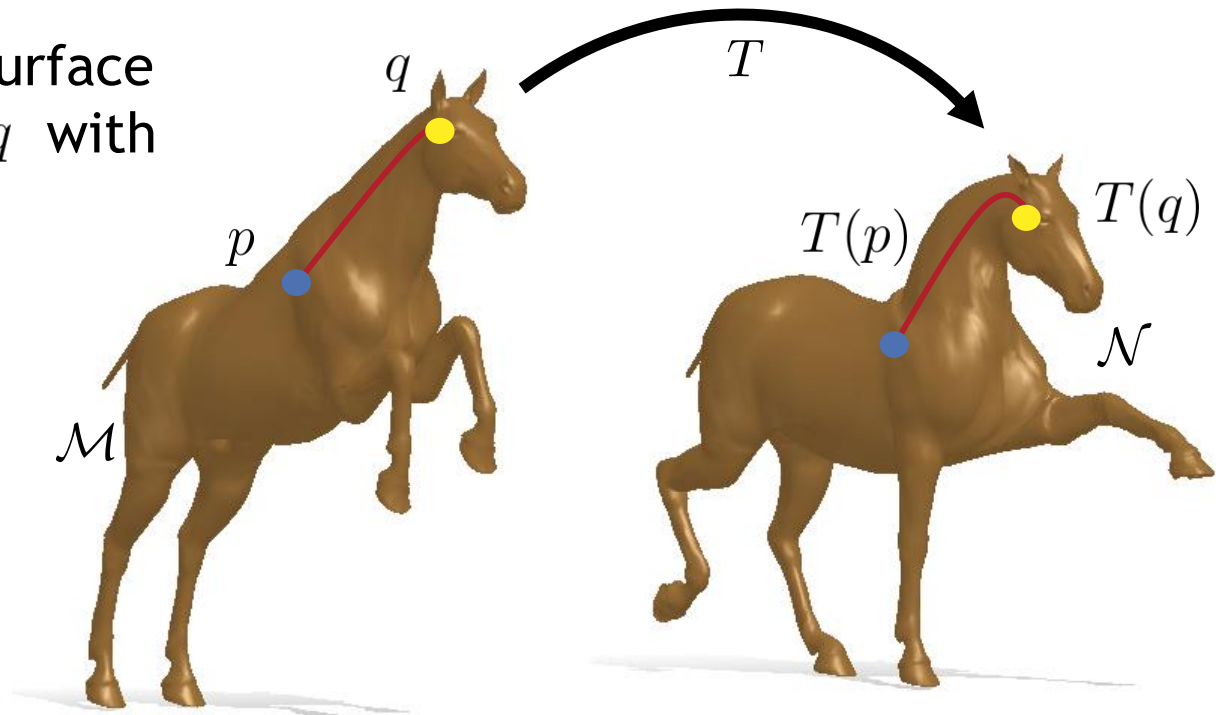
- » Representation independent,
- » Intrinsic, hence deformation-invariant,
- » Computationally efficient,
- » Can be interpreted in terms of classical signal processing.



# Why spectral shape analysis?

## » The geodesics

The path on the surface connecting  $p$  to  $q$  with minimum length



$$T \text{ is an isometry} \iff d_{\mathcal{M}}(p, q) = d_{\mathcal{N}}(T(p), T(q)) \quad \forall p, q \in \mathcal{M}$$



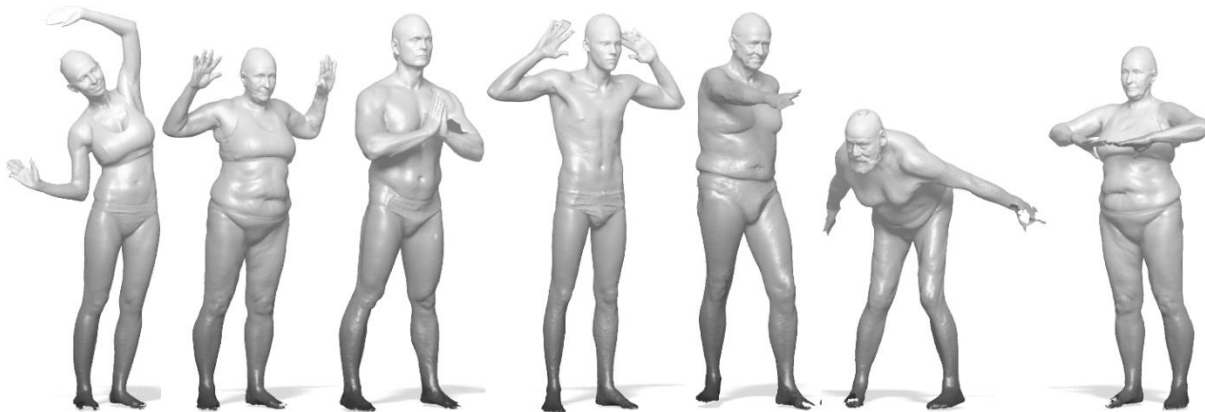


# Why spectral shape analysis?

- ⇒ Spectral shape analysis deals with intrinsic information which is invariant to **isometric variation**



**We can deal with non-rigid shapes**





# Why spectral shape analysis?

## ➤ Rough intuition

What can you learn about its shape from vibration frequencies and oscillation patterns?



You can learn a lot about a shape by **hitting it** (lightly) **with a hammer!**

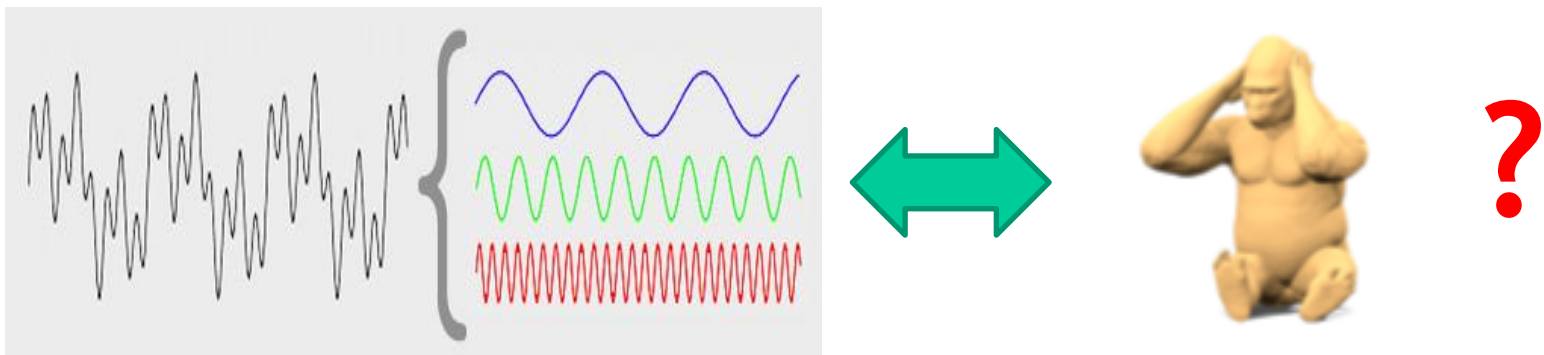
Solomon et al., “Laplace-Beltrami: The Swiss Army Knife of Geometry Processing” - SGP School 2014



# Why spectral shape analysis?

«Spectral shape analysis aims at porting standard signal processing tools to the setting of 3D mesh models»  
[Levy and Zhang09].

- The main motivation is the pursuit of Fourier analysis in the manifold setting (i.e., 3D meshes)

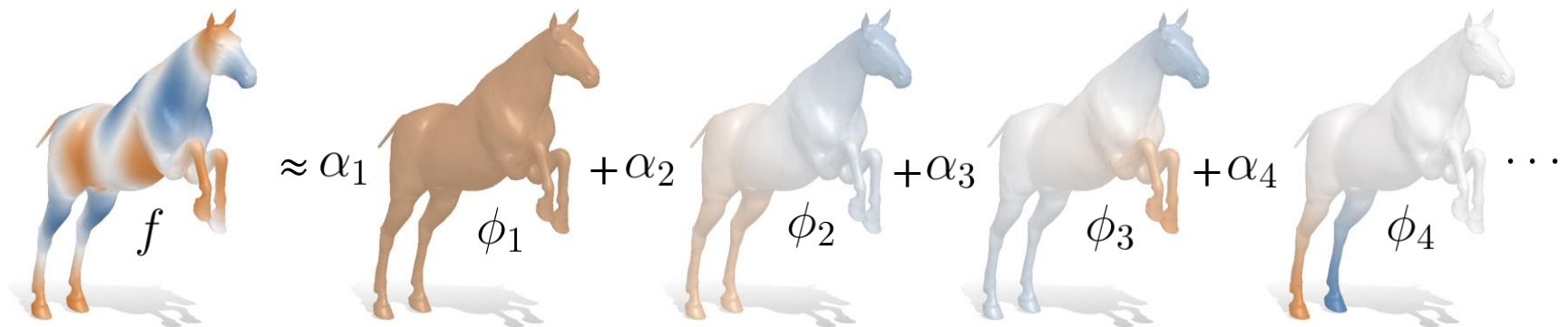






# Why spectral shape analysis?

## Fourier representation on 3D shapes



Laplace-beltrami eigenfunctions towards an algorithm that understands geometry, *Levy, SMI, 2006*



# Why spectral shape analysis?



Image from the Michael Bronstein's SGP school 2012 on Spectral geometry of shape



# Why spectral shape analysis?

**Laplace-Beltrami:** *“The Swiss Army Knife of Geometry Processing”*



Solomon et al., “Laplace-Beltrami: The Swiss Army Knife of Geometry Processing” - SGP School 2014





# Schedule

## ☐ Tuesday 28

10-13

- Introduction (1h)
- Differential geometry (2h)

15-17

- Harmonic analysis (2h)

## ☐ Wednesday 29

10-13

- Spectral analysis on shape (2h)
- Exercise (1h)

15-17

- Descriptors for shape matching (2h)

## ☐ Friday 31

10-13

- Functional map(2h)
- Exercise(1h)

15-18

- Advanced methods(2h)
- Conclusions(1h)

**At the end of the school (last day) we will discuss the assignments for credits.**