# CS4341: Bec-Man System Design The MetaStable Flip-Flops

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Fall 2019

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### 1 Module Descriptions and Listing

Each used module is documented here with a high-level description and its function. Detailed port listings follow in the next section.

#### 1.1 Game State Engine (game\_state.sv)

The game state is where the "game" proper lives in logic. It is a combination of a sequencing state machine, along with a decision path, that produces the outputs required for the video layer.

The logic is keyed into different states annotated by a *state* enum. This state advanced unconditionally except when initially leaving the "idle" state. The condition for leaving the idle state is a positive edge on the state engine enable. This causes the game to update once per frame, allowing for consistant timing on based on the screen refresh rate.

### 1.2 Video Timing Generator (vtg.sv)

The Video Timing Generator is a critical component of timing and sequencing both the game state and video engine. Its principal role is for creating the necessary signals to output to a VGA display for video output. It also outputs screen coordinates internally to the rest of the design to allow the video systems to have an easy reference to the currently drawn pixels.

The VTG is also used for sequencing the handover between the game state and the video subsystem. The vertical blanking signal is routed to the enable of the game state, and its inverse to the sprite engines. This allows game state to remain constant while the screen is drawing preventing visual artifacts, and provides for timing based on the screen refresh rate. The horizontal blanking signal is also used to properly sequence the sprite engines in addition to the vblank signal.

### 1.3 Sprite Generators (becman\_sprite.sv and map\_sprite.sv)

The sprite generators form the core of the video engine. They are a purely feedforward system, taking information from the VTG and the game state to blit pixels to the screen. Both the Bec-Man and Map sprite engine use a series of ROMs or RAMs to hold the graphics data.

When a sprite engine decides to output a pixel, it emits a valid signal and the color information. This is fed into the video arbiter as a final processing step.

#### 1.4 Map RAM (map\_ram.sv)

This hold the current map state. In our current implementation, the write signal is always held low treating it like a ROM, but it supports writes to enable a dynamic update of the map for future implementation of bonuses or dots.

This was broken out as a seperate module to be easily reused in both the game state engine and the map sprite subsystems.

#### 1.5 Video Arbiter (video\_arbiter.sv)

The video arbiter is the last component before sending the signal to the display. It decides for each pixel which sprite takes priority and has its color drawn to screen. This is done with a fixed priority based on input port.

This is required as the video subsystem contains no framebuffer in memory, requiring it to generate video in realtime without a compositing step. This requires we select the appropriate signal in realtime as well. Since the valid signals are able to be toggled on a pixel by pixel basis, this allows a crude form of transparancy by allowing a lower priority pixel to come through at that time if a higher priority pixel is not being shown. If no sprite engine is attempting to write data at that time, the arbiter outputs black to set a global background color.

### 1.6 TMDS Encoder (tmds\_encoder.sv)

**NOTE:** This module is unused in the final design, but noted here for refrence. It does not appear later in the document as such.

The TMDS encoders function is to translate VGA signals into one that can be output using an FPGA's DDR I/O ports to a HDMI display. This allows the internal design to work with simple signals, and only apply the relatively complex TMDS encoding at a final processing stage.

Since the design was not put onto an FPGA, this module was not used in the final test bench.

## 1.7 Primary Testbench (tb/drawing\_test.sv)

This is the primary testbench file that provides for the top level design. This is fed into Verilator to make a working cycle-accurate of the verilog as if it was on a hardware device like an FPGA or ASIC. It additionally breaks out the signals to enable the VGASim component of the Verilator to read the display information.

# 2 System Listing

## 2.1 Defined Types

We defined multiple new types to assist in development. These are replicated commonly in the next sections.

Table 1: **Defined Types** 

Type Name	Width	Description
s_width_t	${\rm clogb2}({\rm SCREEN\_WIDTH})$	Generated type that fits the visible screen width.
$s_{-}height_{-}t$	clogb2(SCREEN_HEIGHT)	Generated type that fits the visible screen height.
coord_t	$s_width_t + s_height_t$	XY Coordinate Pair.
$ m rgb\_t$	[23:0]	Packed struct representing 8:8:8 RGB color.

## 2.2 Input Listing

Each module has its input(s) name, type, and description listed in a table below. Inputs that are prevelent and share the same semantic meaning are in Table 2.

Table 2: Common Inputs

Name	Type	Description
i_clk	logic	Global system clock tree. All logic is driven off of this or a derived clock from a PLL / MMCM module.
i_rst	logic	Active high reset. Module must reset registers and/or outputs to known base state on activation.
i_en	logic	Active high clock enable. Registers part of the data path should only update when activated. Control registers or edge detect registers may not be disabled on a low if necessary for proper function.

Table 3: Video Timing Generator (vtg)

Name	Type	Description
ACTIVE_WIDTH	parameter	The width of the visible area of the display.
ACTIVE_HEIGHT	parameter	The height of the visible area of the display.
V_FRONT_PORCH	parameter	Vertical front porch of the timing spec in lines.
V_BACK_PORCH	parameter	Vertical back porch of the timing spec in lines.
V_PULSE	parameter	Length of vertical sync pulse in lines.
V_POL	parameter	Defines if the module outputs a active high/low vertical sync pulse.
H_FRONT_PORCH	parameter	Horizontal front porch of the timing spec in pixels.
H_BACK_PORCH	parameter	Horizontal back porch of the timing spec in pixels.
H_PULSE	parameter	Length of horizontal sync pulse in pixels.
H_POL	parameter	Defines if the module outputs a active high/low horizontal sync pulse.

Table 4: Game State Engine (game\_state)

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	Name	Type	Description
Ī	i_joystick	logic [3:0]	Joystick Input, lowest bit represents the left direction. Successive
			bits represent the next cardinal direction in a counter-clockwise
			manner. The zero vector represents no input.

Table 5: Bec-Man Sprite Generator (becman\_sprite)

Name	Type	Description
i_rotate	logic [2:0]	Dictates the rotation of the becman sprite. This value must be held constant while the enable is active.
i_becman	coord_t	The screen top-left referenced screen coordnates of the becman sprite. This value must be held constant while the enable is active.
i_screen	coord_t	The pixel currently being blited to the screen. This is used to determine if the sprite contains an active pixel at the translated coordinates.

Table 6: Map Sprite Generator (map\_sprite)

Name	Type	Description	
i_screen	coord_t	The pixel currently being blited to the screen. This is used to determine if the sprite contains an active map element.	

Table 7: Map RAM (map\_ram)

Name	Type	Description
i_write	logic	Sets if the RAM is in read/write mode.
i_tile_x	logic [5:0]	The X address of the map tile.
i_tile_y	logic [4:0]	The Y address of the map tile.

Table 8: Video Arbiter (video\_arbiter)

Name	Type	Description
i_vsync	logic	Passthrough input for vsync to keep it in sync with the muxed video signal.
i_hsync	logic	Passthrough input for hypnc to keep it in sync with the muxed video signal.
i_req	logic [1:0]	Arbiter request input, MSB takes priority. A zero vector indicates to draw the default color.
i_vport	rgb_t [1:0]	Array of input video ports. These are muxed depedent on the decided input from the arbiter.

## 2.3 Output Listing

Each module has its output(s) name, type, and description listed in a table below.

Table 9: Video Timing Generator (vtg)

Name	Type	Description	
o_hsync	logic	Horizontal sync pulse output.	
o_vsync	logic	Vertical sync pulse output.	
o_hblank	logic	Active high when the display is in the horizontal blanking period.	
o_vblank	logic	Active high when the display is in the vertical blanking period.	
o_blank	logic	$o\_hblank \mid\mid o\_vblank$	
o_screen	$coord_t$	The current XY pixel being sent to the display, in relation to the	
		sync pulses.	

Table 10: Game State Engine (game\_state)

Name	Type	Description
o_becman	$\operatorname{coord}_{-\!t}$	Where the Bec-Man sprite should be drawn on the display, as derived from the internal state.
o_becman_dir	logic [2:0]	The direction of the Bec-Man sprite should be rotated to, as derived from the internal state.

Table 11: Bec-Man Sprite Generator (becman\_sprite)

Name	Type	Description		
o_valid	logic	Active high when the video system should blit pixels from this sprite.		
o_color	$rgb_t$	The color to display when o_valid is high.		

Table 12: Map Sprite Generator (map\_sprite)

Name	Type	Description
o_valid	logic	Active high when the video system should blit pixels from this sprite.
o_color	$rgb_{-t}$	The color to display when $o\_valid$ is high.

Table 13: Map RAM (map\_ram)

Name	Type	Description	
o_tile_value	logic	Active high when a tile is present at the input coordinates.	

Table 14: Video Arbiter (video\_arbiter)

Name	Type	Description
o_vport	rgb_t	The selected video signal based on the input request and priority level.
o_hsync	logic	Passthrough of the input hypnc signal for timing purposes.
o_vsync	logic	Passthrough of the input vsync signal for timing purposes.

## 3 Diagrams

The various circuit and state diagrams are included here, on seperate pages.

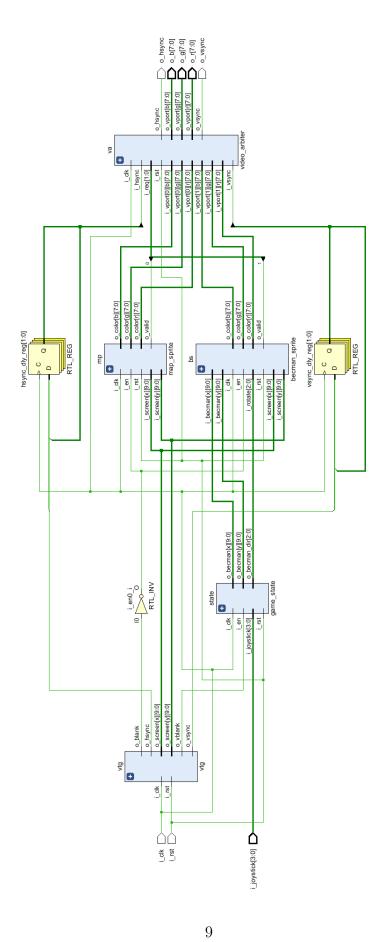


Figure 1: Top Level Block Diagram of the Bec-Man System.

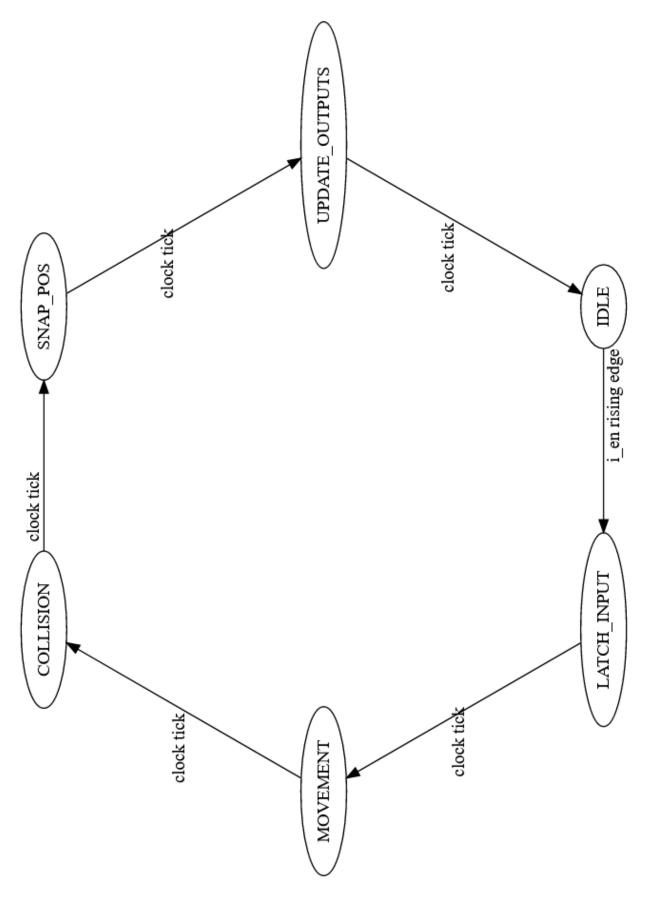


Figure 2: Sequencer State Machine.