

CH-231-A

**Algorithms and Data Structures**

ADS

**Lecture 27**

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## Direct Access Table

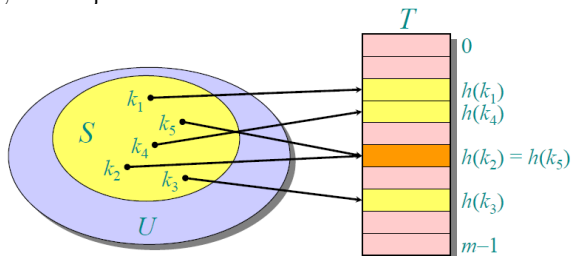
- ▶ The idea of a direct access table is that objects are directly accessed via their key.
- ▶ Assuming that keys are out of  $U = \{0, 1, \dots, m - 1\}$ .
- ▶ Moreover, assume that keys are distinct.
- ▶ Then, we can set up an array  $T[0..m - 1]$  with

$$T[k] = \begin{cases} x & \text{if } x \in K \text{ and } \text{key}[x] = k \\ \text{NIL} & \text{otherwise.} \end{cases}$$

- ▶ **Time complexity:** With this set-up, we can have the dynamic-set operations (Search, Insert, Delete, ...) in  $\Theta(1)$ .
- ▶ Problem:  $m$  is often large. For example, for 64-bit numbers we have 18,446,744,073,709,551,616 different keys.

# Hash Function

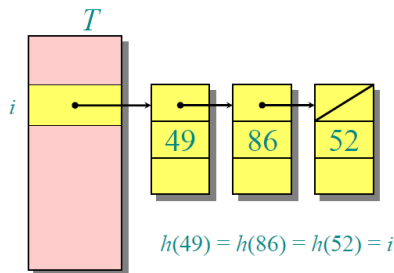
- ▶ Use a function  $h$  that maps  $U$  to a smaller set  $\{0, 1, \dots, m-1\}$ .



- ▶ Such a function is called a **hash function**.
- ▶ The table  $T$  is called a **hash table**.
- ▶ If two keys are mapped to the same location, we have a **collision**.

## Resolving Collisions

- Collisions can be resolved by storing the colliding mappings in a (singly-)linked list.



- **Worst case:** All keys are mapped to the same location. Then, access time is  $\Theta(n)$ .

## Average Case Analysis (1)

- ▶ Assumption (**simple uniform hashing**): Each key is equally likely to be hashed to any slot of the table, independent of where other keys are hashed.
- ▶ Let  $n$  be the number of keys.
- ▶ Let  $m$  be the number of slots.
- ▶ The load factor  $\alpha = n/m$  represents the average number of keys per slot.

## Average Case Analysis (2)

### Theorem:

In a hash table in which collisions are resolved by chaining, an unsuccessful search takes average-case time  $\Theta(1 + \alpha)$  under the assumption of simple uniform hashing.

### Proof:

- ▶ Any key  $k$  not already stored in the table is equally likely to hash to any of the  $m$  slots.
- ▶ The expected time to search unsuccessfully for a key  $k$  is the expected time to search to the end of list  $T[h(k)]$ .
- ▶ Expected length of the list is  $E[n_{h(k)}] = \alpha$ .
- ▶ Time for computing  $h(k) = O(1) \Rightarrow$  overall time  $\Theta(1 + \alpha)$ .

## Average Case Analysis (3)

- ▶ Runtime for unsuccessful search:  
The expected time for an unsuccessful search is  $\Theta(1 + \alpha)$  including applying the hash function and accessing the slot and searching the list.
- ▶ What does this mean?
  - ▶  $m \sim n$ , i.e., if  $n = O(m) \Rightarrow \alpha = n/m = O(m)/m = O(1)$
  - ▶ Thus, search time is  $O(1)$
- ▶ A successful search has the same asymptotic bound.

## Choosing a Hash Function (1)

- ▶ What makes a good hash function?
  - ▶ The goal for creating a hash function is to distribute the keys as uniformly as possible to the slots.
- ▶ Division method
  - ▶ Define hashing function  $h(k) = k \bmod m$ .
  - ▶ **Deficiency**: Do not pick an  $m$  that has a small divisor  $d$ , as a prevalence of keys with the same modulo  $d$  can negatively effect uniformity.
  - ▶ **Example**: if  $m$  is a power of 2, the hash function only depends on a few bits: If  $k = 1011000111011010$  and  $m = 2^6$ , then  $h(k) = 011010$ .



## Choosing a Hash Function (2)

- ▶ **Division method** (continue)
  - ▶ **Common choice:** Pick  $m$  to be a prime not too close to a power of 2 or 10 and not otherwise prominently used in computing environments.
  - ▶ **Example:**  $n = 2000$ ; we are ok with average 3 elements in our collision chain  $\Rightarrow m = 701$  (a prime number close to  $2000/3$ ),  $h(k) = k \bmod 701$ .

## Choosing a Hash Function (3)

### ► Multiplication method

- On advantage of the multiplication method is that the value of  $m$  is not critical
- Knuth suggests that  $A \approx (\sqrt{5} - 1)/2$  works well
- Assume all keys are integers,  $m = 2^r$ , and the computer uses  $w$ -bit words.
- Define hash function  $h(k) = (A \cdot k \bmod 2^w) \gg (w - r)$ , where " $\gg$ " is the right bit-shift operator and  $A$  is an odd integer with  $2^{w-1} < A < 2^w$ .
- **Example:**  $m = 2^3 = 8$  and  $w = 7$ .

$$\begin{array}{r}
 \phantom{\times} \phantom{0000000} 1011001 = A \\
 \times \phantom{0000000} 1101011 = k \\
 \hline
 10010100 \underbrace{110011}_{h(k)}
 \end{array}$$

## Resolving Collisions by Open Addressing

- ▶ No additional storage is used.
- ▶ Only store one element per slot.
- ▶ Insertion probes the table systematically until an empty slot is found.
- ▶ The hash function depends on the key and the probe number, i.e.,  $h : U \times \{0, 1, \dots, m - 1\} \rightarrow \{0, 1, \dots, m - 1\}$ .
- ▶ The probe sequence  $\langle h(k, 0), h(k, 1), \dots, h(k, m - 1) \rangle$  should be a permutation of  $\{0, 1, \dots, m - 1\}$ .

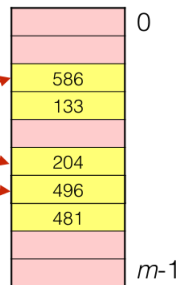
# Insert Example

- Insert key  $k = 496$ :

**0.** Probe  $h(496, 0)$

**1.** Probe  $h(496, 1)$

**2.** Probe  $h(496, 2)$



HASH-INSERT( $T, k$ )

```

1   $i = 0$ 
2  repeat
3       $j = h(k, i)$ 
4      if  $T[j] == \text{NIL}$ 
5           $T[j] = k$ 
6          return  $j$ 
7      else  $i = i + 1$ 
8  until  $i == m$ 
9  error "hash table overflow"
```

## Search Example

`HASH-SEARCH( $T, k$ )`

```

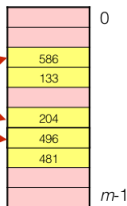
1   $i = 0$ 
2  repeat
3       $j = h(k, i)$ 
4      if  $T[j] == k$ 
5          return  $j$ 
6       $i = i + 1$ 
7  until  $T[j] == \text{NIL}$  or  $i == m$ 
8  return NIL

```

0. Probe  $h(496, 0)$

1. Probe  $h(496, 1)$

2. Probe  $h(496, 2)$



- ▶ Search key  $k = 496$ 
  - ▶ Search uses the same probe sequence, terminating successfully if it finds the key and unsuccessfully if it encounters an empty slot (or made it all the way through the list)
  - ▶ Search times no longer depend on load factor  $\alpha$
- ▶ What about delete?
  - ▶ Have a special node type: DELETED
  - ▶ Chaining more commonly used when keys must also be deleted

## Probing Strategies (1)

### Linear probing:

- ▶ Given an ordinary hash function  $h'(k)$ , linear probing uses the hash function  $h(k, i) = (h'(k) + i) \bmod m$ .
- ▶ This is a simple computation.
- ▶ However, it may suffer from **primary clustering**, where long runs of occupied slots build up and tend to get longer.
  - ▶ empty slot preceded by  $i$  full slots gets filled next with probability  $(i + 1)/m$

## Probing Strategies (2)

### Quadratic probing:

- ▶ Quadratic probing uses the hash function
$$h(k, i) = (h'(k) + c_1 \cdot i + c_2 \cdot i^2) \bmod m.$$
- ▶ Offset by amount that depends on quadratic manner, works much better than linear probing
- ▶ But, it may still suffer from **secondary clustering**: If two keys have initially the same value, then they also have the same probe sequence
- ▶ In addition  $c_1$ ,  $c_2$ , and  $m$  need to be constrained to make full use of the hash table