

CH-231-A

Algorithms and Data Structures

ADS

Lecture 28

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Resolving Collisions by Open Addressing

- ▶ No additional storage is used.
- ▶ Only store one element per slot.
- ▶ Insertion probes the table systematically until an empty slot is found.
- ▶ The hash function depends on the key and the probe number, i.e., $h : U \times \{0, 1, \dots, m - 1\} \rightarrow \{0, 1, \dots, m - 1\}$.
- ▶ The probe sequence $\langle h(k, 0), h(k, 1), \dots, h(k, m - 1) \rangle$ should be a permutation of $\{0, 1, \dots, m - 1\}$.

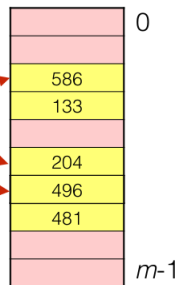
Insert Example

- Insert key $k = 496$:

0. Probe $h(496, 0)$

1. Probe $h(496, 1)$

2. Probe $h(496, 2)$



`HASH-INSERT(T, k)`

```
1   $i = 0$ 
2  repeat
3       $j = h(k, i)$ 
4      if  $T[j] == \text{NIL}$ 
5           $T[j] = k$ 
6          return  $j$ 
7      else  $i = i + 1$ 
8  until  $i == m$ 
9  error "hash table overflow"
```

Search Example

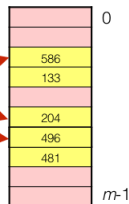
HASH-SEARCH(T, k)

```
1   $i = 0$ 
2  repeat
3       $j = h(k, i)$ 
4      if  $T[j] == k$ 
5          return  $j$ 
6       $i = i + 1$ 
7  until  $T[j] == \text{NIL}$  or  $i == m$ 
8  return NIL
```

0. Probe $h(496, 0)$

1. Probe $h(496, 1)$

2. Probe $h(496, 2)$



- ▶ Search key $k = 496$
 - ▶ Search uses the same probe sequence, terminating successfully if it finds the key and unsuccessfully if it encounters an empty slot (or made it all the way through the list)
 - ▶ Search times no longer depend on load factor α
- ▶ What about delete?
 - ▶ Have a special node type: DELETED
 - ▶ Chaining more commonly used when keys must also be deleted

Probing Strategies (1)

Linear probing:

- ▶ Given an ordinary hash function $h'(k)$, linear probing uses the hash function $h(k, i) = (h'(k) + i) \bmod m$.
- ▶ This is a simple computation.
- ▶ However, it may suffer from **primary clustering**, where long runs of occupied slots build up and tend to get longer.
 - ▶ empty slot preceded by i full slots gets filled next with probability $(i + 1)/m$

Probing Strategies (2)

Quadratic probing:

- ▶ Quadratic probing uses the hash function $h(k, i) = (h'(k) + c_1 \cdot i + c_2 \cdot i^2) \bmod m$.
- ▶ Offset by amount that depends on quadratic manner, works much better than linear probing
- ▶ But, it may still suffer from **secondary clustering**: If two keys have initially the same value, then they also have the same probe sequence
- ▶ In addition c_1 , c_2 , and m need to be constrained to make full use of the hash table

Probing Strategies (3)

Double hashing:

- ▶ Given two ordinary hash functions $h_1(k)$ and $h_2(k)$, double hashing uses the hash function $h(k, i) = (h_1(k) + i \cdot h_2(k)) \bmod m$.
- ▶ The initial probe goes to position $T[h_1(k)]$; successive probe positions are offset by $h_2(k) \rightarrow$ the initial probe position, the offset, or both, may vary
- ▶ This method generates excellent results, if $h_2(k)$ is relatively prime to the hash-table size m ,

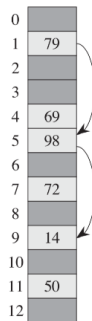
Probing Strategies (4)

Double hashing (continue):

- ▶ e.g., by making m a power of 2 and design $h_2(k)$ to only produce odd numbers.
- ▶ or let m be prime and design h_2 such that it always returns a positive integer less than m , e.g. let m' be slightly less than m :

$$h_1(k) = k \bmod m$$

$$h_2(k) = 1 + (k \bmod m')$$



$$h_1(k) = k \bmod 13$$

$$h_2(k) = 1 + (k \bmod 11)$$

$$\rightarrow k=14; h_1(k)=1, h_2(k)=4$$

$$\rightarrow k=27; h_1(k)=1, h_2(k)=6$$

Analysis of Open Addressing (1)

Theorem:

- ▶ Assume uniform hashing, i.e., each key is likely to have any one of the $m!$ permutations as its probe sequence.
- ▶ Given an open-addressed hash table with load factor $\alpha = n/m < 1$.
- ▶ The expected number of probes in an unsuccessful search is, at most $\frac{1}{1 - \alpha}$.

Analysis of Open Addressing (2)

Proof:

- ▶ At least, one probe is always necessary.
- ▶ With probability n/m , the first probe hits an occupied slot, i.e., a second probe is necessary.
- ▶ With probability $(n-1)/(m-1)$, the second probe hits an occupied slot, i.e., a third probe is necessary.
- ▶ With probability $(n-2)/(m-2)$, the third probe hits an occupied slot, i.e., a fourth probe is necessary.
- ▶ ...

Analysis of Open Addressing (3)

Given that $\frac{n-i}{m-i} < \frac{n}{m} = \alpha$ for $i = 1, 2, \dots, n$.

$$\begin{aligned} & 1 + \frac{n}{m} \left(1 + \frac{n-1}{m-1} \left(1 + \frac{n-2}{m-2} \left(\dots \left(1 + \frac{1}{m-n+1} \right) \dots \right) \right) \right) \\ & \leq 1 + \alpha (1 + \alpha (1 + \alpha (\dots (1 + \alpha) \dots))) \\ & \leq 1 + \alpha + \alpha^2 + \alpha^3 + \dots \\ & = \sum_{i=0}^{\infty} \alpha^i \\ & = \frac{1}{1-\alpha}. \end{aligned}$$

Analysis of Open Addressing (4)

- ▶ The successful search takes less number of probes
[expected number is at most $\frac{1}{\alpha} \ln \frac{1}{1 - \alpha}$].
- ▶ We conclude that if α is constant, then accessing an open-addressed hash table takes constant time.
- ▶ For example, if the table is half full, the expected number of probes is $1/(1 - 0.5) = 2$.
- ▶ Or, if the table is 90% full, the expected number of probes is $1/(1 - 0.9) = 10$.

Summary

- ▶ Dynamic sets with queries and modifying operations.
- ▶ Array: Random access, search in $O(\lg n)$, but modifying operations $O(n)$.
- ▶ Stack: LIFO only. Operations in $O(1)$.
- ▶ Queue: FIFO only. Operations in $O(1)$.
- ▶ Linked list: Modifying operations in $O(1)$, but search $O(n)$.
- ▶ BST: All operations in $O(h)$.
- ▶ Red-black trees: All operations in $O(\lg n)$.
- ▶ Heap: All operations in $O(\lg n)$.
- ▶ Hash tables: Operations in $O(1)$, but additional storage space.