

# Marius Memmel

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## EDUCATION

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<b>University of Washington (UW)</b> <i>PhD Student in Computer Science &amp; Engineering, GPA: 3.81/4.00, in progress</i> <b>Advisors:</b> Prof. Dieter Fox, Prof. Abhishek Gupta	Seattle, US <i>Sept. 2022 – Present</i>
<b>Technical University of Darmstadt (TU Darmstadt)</b> <i>Master of Science, Grade 1.1 (scale 1-6, 1 best), GPA: 3.94/4.00, Top 6.93%</i> <b>Major:</b> Computer Science, <i>Minor:</i> Entrepreneurship & Innovation	Darmstadt, DE <i>Oct. 2019 – Sept. 2022</i>
<b>Swiss Federal Institute of Technology Lausanne (EPFL)</b> <i>Swiss-European Mobility Programme / Exchange Program, Master Thesis</i>	Lausanne, CH <i>Sept. 2021 – May 2022</i>
<b>Appalachian State University</b> <i>Exchange Program, GPA: 4.0/4.0</i>	Boone, US <i>Aug. 2018 – Dec. 2018</i>
<b>Baden-Württemberg Cooperative State University (DHBW)</b> <i>Bachelor of Science, Final Grade 1.4 (scale 1-6, 1 best), GPA: 3.97/4.00, Rank 1</i> <b>Major:</b> Business Information Systems, <i>Concentration:</i> Software Engineering	Mannheim, DE <i>Aug. 2016 – Sept. 2019</i>

## PUBLICATIONS

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- [12] **Mammel M.\***, Zhang J.\*, Kim K., Fox D., Thomason J., Ramos F., Gupta A.†, Li A.† "PEEK: Guiding and Minimal Image Representations for Zero-Shot Generalization of Robot Manipulation Policies", *pre-print*, 2025 [paper]
- [11] Yan G., Zhu J.\*, Deng Y.\*, Yang S., Qiu R., Cheng X., **Mammel M.**, Kirshna R.†, Goyal A.†, Wang X.†, Fox D.† "ManiFlow: A General Robot Manipulation Policy via Consistency Flow Training", *Conference on Robot Learning (CoRL)*, 2025 [paper]
- [10] Park C.\*, Fisher Jillian\*, **Mammel M.**, Khullar D., Yun S., Gupta A., Choi Y. "Making VLMs More Robot-Friendly: Self-Critical Distillation of Low-Level Procedural Reasoning", *Empirical Methods in Natural Language Processing (EMNLP)*, 2025 [paper]
- [9] **Mammel M.\***, Berg K.\*, Chen B., Gupta A.†, Francis J.† "STRAP: Robot Sub-Trajectory Retrieval for Augmented Policy Learning", *Conference on Learning Representations (ICLR)*, 2025 [paper]
- [8] Li Yi.\*, Deng Y.\*, Zhang J.\*, Jang J., **Mammel M.**, Garrett C., Ramos R., Fox D., Li A., Gupta A., Goyal A. "HAMSTER: Hierarchical Action Models for Open-World Robot Manipulation", *Conference on Learning Representations (ICLR)*, 2025 [paper]
- [7] Xia H., Su E., **Mammel M.**, Jain A., Yu R., Mbiziwo-Tiapo N., Farhadi A., Gupta A., Wang S., Ma W. "DRAWER: Digital Reconstruction and Articulation With Environment Realism", *Computer Vision and Pattern Recognition Conference (CVPR)*, 2025 [paper]
- [6] Chen Z., Walsman A., **Mammel M.**, Mo K., Fang A., Fox D.†, Gupta A.† "URDFormer: A Pipeline for Constructing Articulated Simulation Environments from Real-World Images", *Robotics: Science and Systems (RSS)*, 2024 [paper]
- [5] Khazatsky K., Pertsch K., Nair S., ..., **Mammel M.**, ..., Kollar T., Levine S., Finn C. "DROID: A Large-Scale In-The-Wild Robot Manipulation Dataset", *Robotics: Science and Systems (RSS)*, 2024 [paper]
- [4] **Mammel M.**, Wagenmaker A., Zhu C., Fox D., and Gupta A. "ASID: Active Exploration for System Identification and Reconstruction in Robotic Manipulation", *International Conference on Learning Representations (ICLR)* (**oral, top 1.2%**), 2024 [paper]
- [3] **Mammel M.**, Bachmann R., and Zamir A., "Modality-invariant Visual Odometry for Embodied Vision", *Conference on Computer Vision and Pattern Recognition (CVPR)*, 2023 [paper]

[2] Stammer W., **Memmel M.**, Schramowski P., and Kersting K., "Interactive Disentanglement: Learning Concepts by Interacting with their Prototype Representations", *Conference on Computer Vision and Pattern Recognition (CVPR)*, 2022 [paper]

[1] **Memmel M.**, Liu P., Tateo D., and Peters J., "Dimensionality Reduction and Prioritized Exploration for Policy Search", *Artificial Intelligence and Statistics (AISTATS)*, 2022 [paper]

\* equal contribution, † equal advising

## THESES

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**Master Thesis:** "Multi-modal Vision Transformers For Data-Efficient Visual Odometry In Embodied Indoor Navigation", Supervisor: Prof. Amir Zamir and Prof. Stefan Roth, TU Darmstadt, 2022 [thesis]

**Bachelor Thesis:** "Conception and Development of a Machine Learning Model for the Analysis of the Energy Consumption of a Plasterboard Dryer", Supervisors: Prof. Julian Reichwald and Halgurt Bapierre, DHBW, 2019 [thesis]

## WORK & RESEARCH EXPERIENCE

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<b>Graduate Research Assistant</b> <i>Paul G. Allen School of Computer Science &amp; Engineering</i>	Seattle, US Sept. 2022 – Present
<b>Research Intern</b> <i>NVIDIA</i>	Seattle, US Dec. 2024 – Present
<b>Robot Learning Research Intern</b> <i>Bosch USA</i>	Pittsburgh, US June 2024 – Sept. 2024
<b>Student Research Assistant</b> <i>Artificial Intelligence and Machine Learning Lab, TU Darmstadt</i>	Darmstadt, DE Nov. 2020 – Aug. 2021
<b>Student Research Assistant</b> <i>Medical &amp; Environmental Computing Lab, TU Darmstadt</i>	Darmstadt, DE Oct. 2020 – March 2021
<b>Machine Learning Engineer (part-time)</b> <i>Sopra Steria Group SA</i>	Frankfurt, DE Jan. 2020 – Dec. 2020
<b>Software Engineer (part-time)</b> <i>Knauf IT</i>	Würzburg, DE Aug. 2016 – Sept. 2019

## AWARDS & SCHOLARSHIPS

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<b>European Informatics Student Award</b> <i>Award for the brightest European students to facilitate understanding among the nations</i>	2022
<b>Deutschlandstipendium</b> <i>Merit-based scholarship given to less than 1% of all students in Germany</i>	2019 – 2020
<b>Best Graduate</b> <i>Award for the best graduate of Business Information Systems (Software Engineering) at DHBW</i>	2019
<b>Baden-Württemberg-Stipendium</b> <i>Scholarship given to 1500 high-achieving students/year to promote exchange</i>	2018