

May 2025



Real-Time Object Detection Using MATLAB and IP Camera

Digital Signal Processing (ME)

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DSP

01 Project Introduction



Objective & Key Technologies:

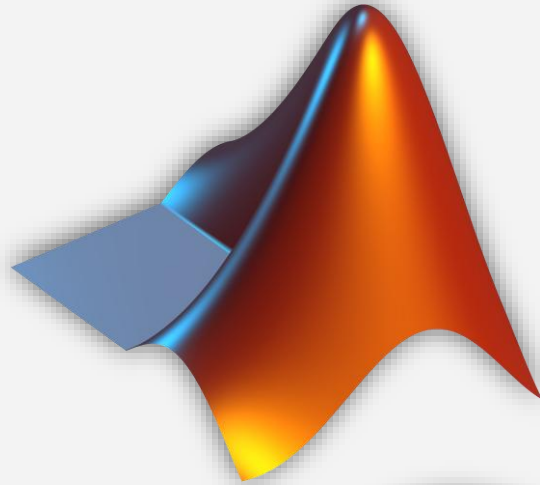


Objective:

To detect and highlight objects in
real-time video streams using
MATLAB and an IP camera.

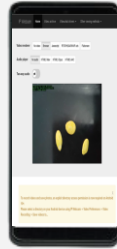
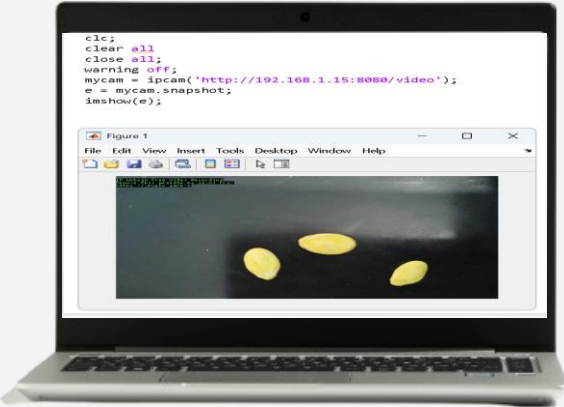
Key Technologies:

- MATLAB
- Image Segmenter
- IP Camera Integration





System Overview



- Components:
 - IP Camera (network camera streaming video)
 - MATLAB (for processing and visualization)
- Workflow:
 - Capture video from IP camera
 - Process each frame
 - Detect objects
 - Display results in real-time



Capturing Video from IP Camera



MATLAB Code:

```
mycam =  
ipcam('http://192.168.1.101:8  
080/video');
```

Explanation:

Connects MATLAB to the IP camera using its network address.

Continuously captures frames for processing.



Image Preprocessing

Convert to Grayscale

Reduces computational complexity.

```
ms = rgb2gray(e);
```

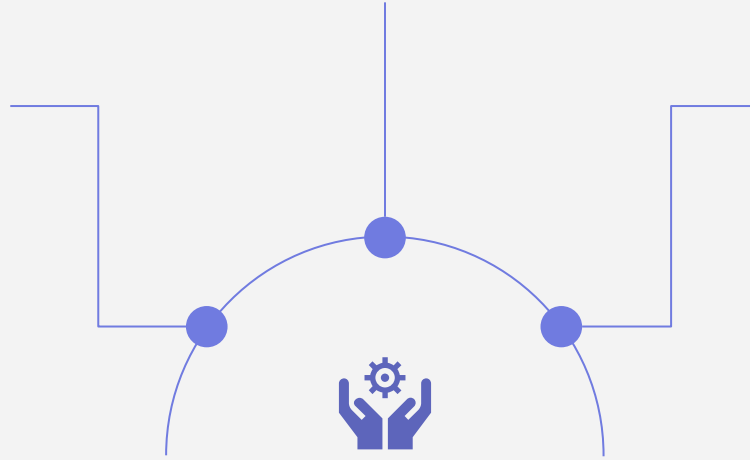
imshow(e);

Shows original image
from ipwebcam

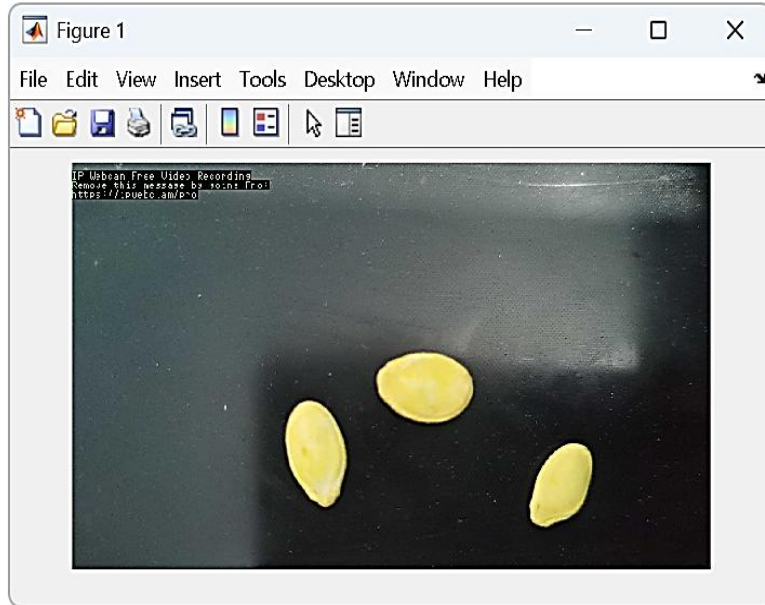
Segmentation

Separates objects from
the background.

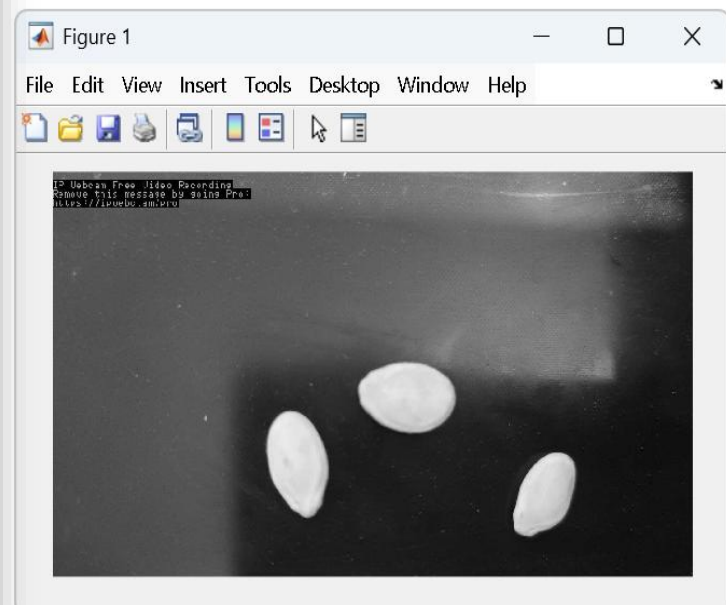
```
segmentImage(ms);
```

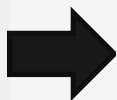


```
clc;
clear all
close all;
warning off;
mycam = ipcam('http://192.168.1.15:8080/video');
e = mycam.snapshot;
imshow(e);
```

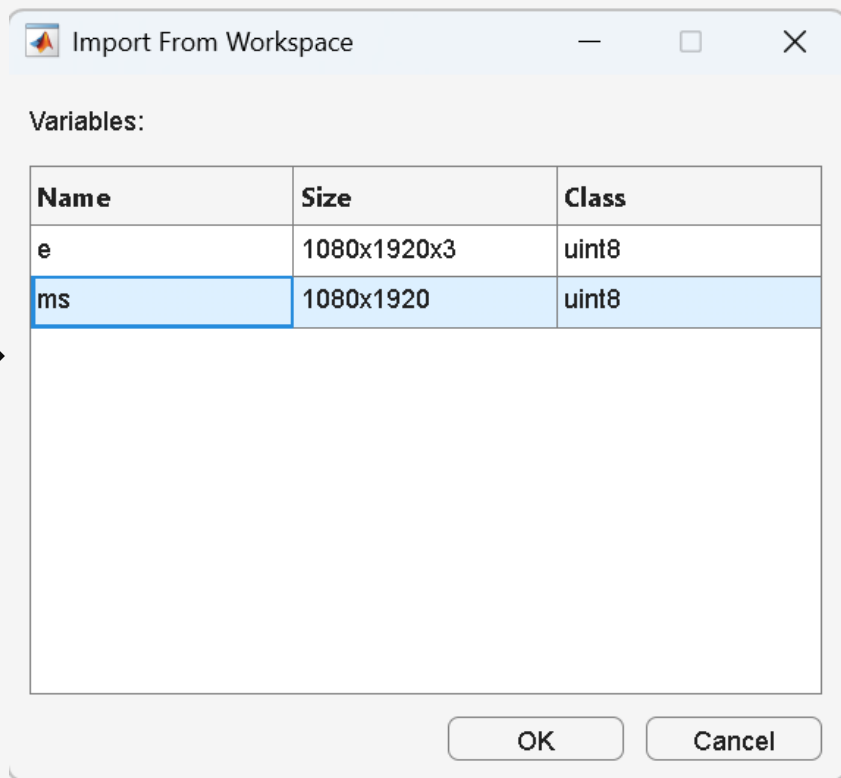


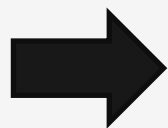
```
clc;
clear all
close all;
warning off;
mycam = ipcam('http://192.168.1.15:8080/video');
e = mycam.snapshot;
imshow(e);
ms = rgb2gray(e);
imshow(ms);
```



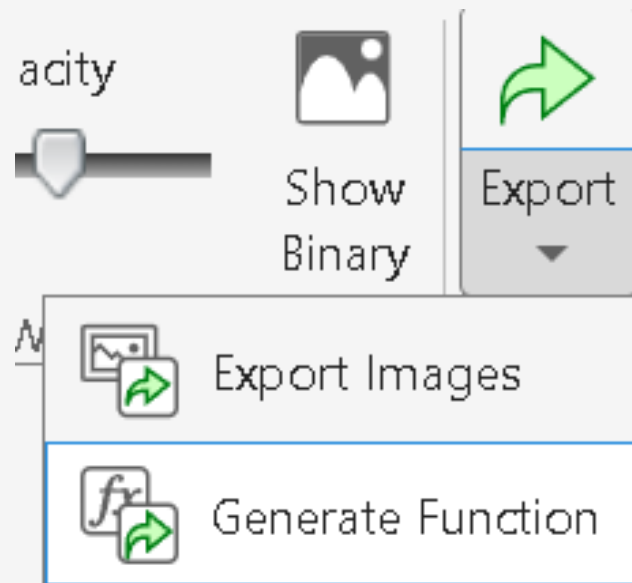
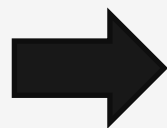


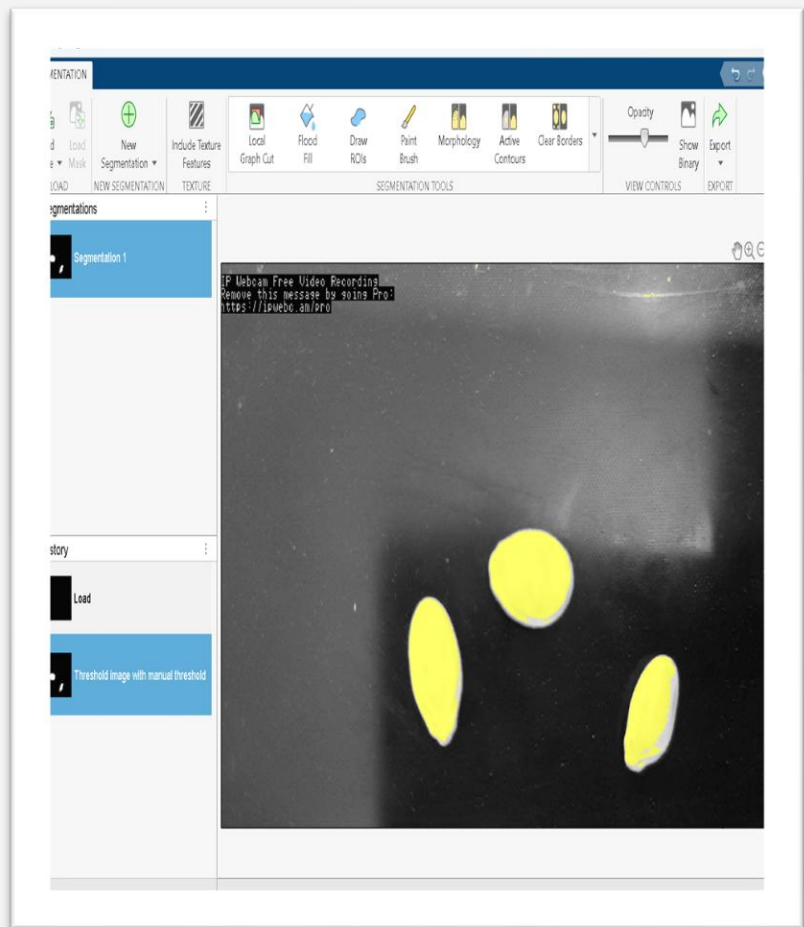
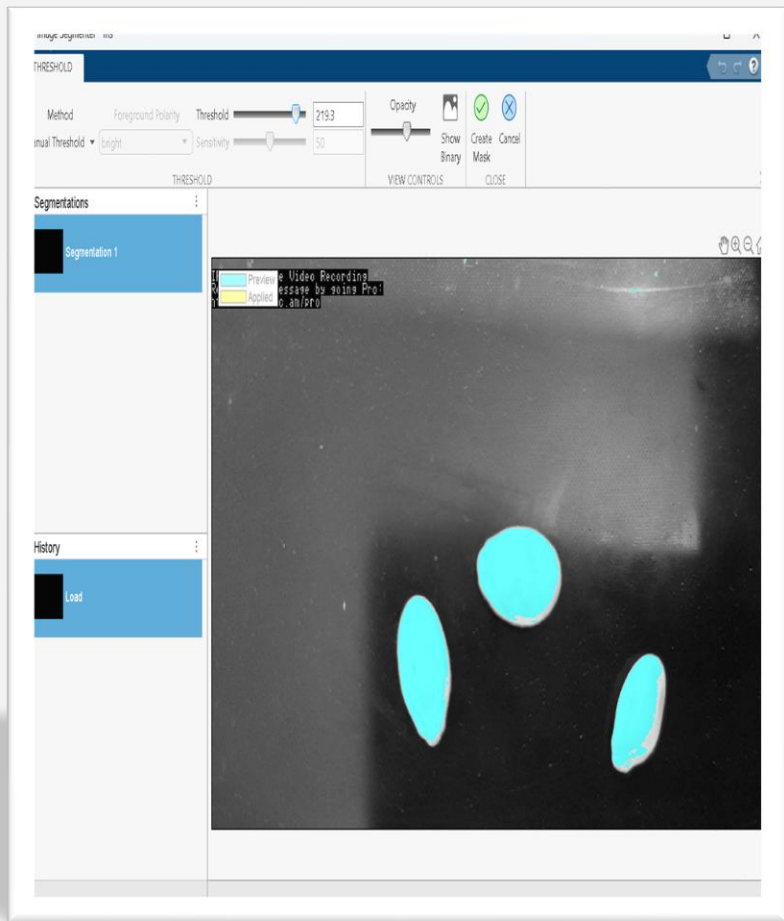
Load
Image ▼





Create
Mask





Object Detection & Noise Removal

Thresholding:

Converts grayscale to binary image for easier object detection.

Noise Removal:

Removes small objects/noise using morphological operations:

Labeling Objects:

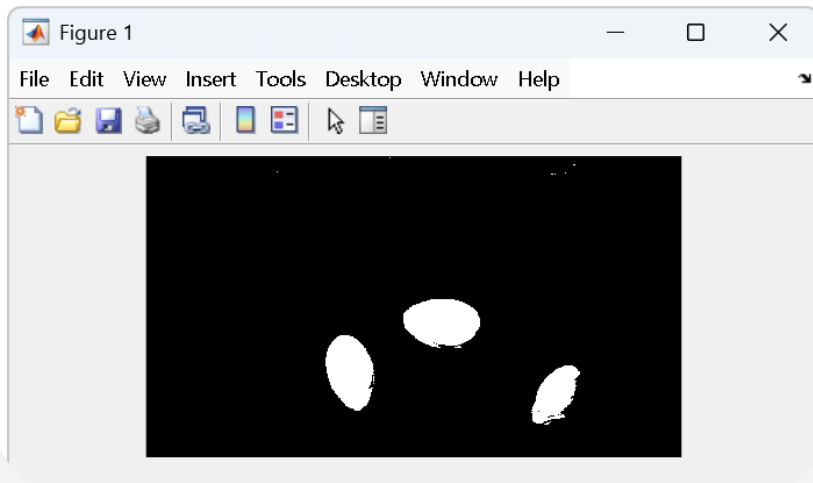
`bwlabel` identifies connected components.



```

clc;
%clear all
close all;
warning off;
% mycam = ipcam('http://192.168.1.15:8080/video');
% e = mycam.snapshot;
% imshow(e);
ms = rgb2gray(e);
[BW,maskedImage] = segmentImage2(ms);
imshow(BW);

```

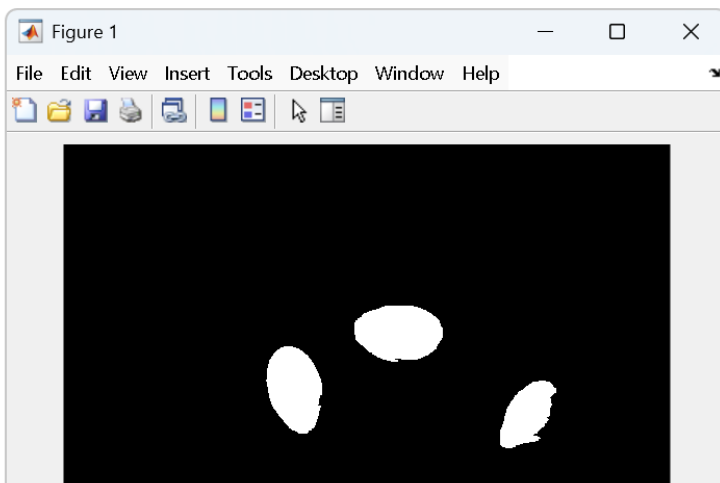


```

clc;
%clear all
close all;
warning off;
% mycam = ipcam('http://192.168.1.15:8080/video');
% e = mycam.snapshot;
% imshow(e);
ms = rgb2gray(e);
[BW,maskedImage] = segmentImage2(ms);

filta=imfill(imdilate(bwareaopen(BW,300),ones(5,5)),'hole');
figure;
imshow(filta);

```



● Drawing Bounding ● Boxes

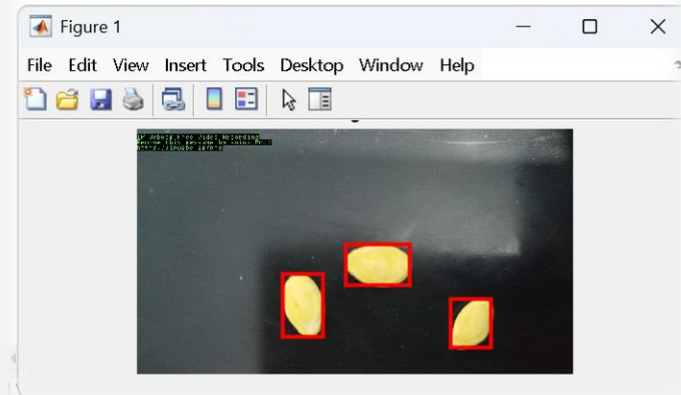
● Bounding Box Extraction:

- regionprops of desu
rof sexob gnidnuob teg
tcejbo detceted hcae

● Visualization:

Draws red rectangles
around detected objects
in each frame.

```
clc;  
%clear all  
close all;  
warning off;  
% mycam = ipcam('http://192.168.1.15:8080/video');  
% e = mycam.snapshot;  
% imshow(e);  
ms = rgb2gray(e);  
[BW,maskedImage] = segmentImage2(ms);  
filt=imfill(imdilate(bwareaopen(BW,300),ones(5,5)),'hole');  
[a b]=bwlabel(filt,8);  
measurements=regionprops(a,'BoundingBox');  
imshow(e);  
hold on;  
for k=1:length(measurements)  
    thisBB=measurements(k).BoundingBox;  
    rectangle('Position',[thisBB(1),thisBB(2),thisBB(3),thisBB(4)],  
        'EdgeColor','r','LineWidth',2);  
end  
title(b);  
hold off;  
end
```





Real-Time Display

- The process runs in a loop for real-time detection and display.
- User Interface:
- Shows original video with detected objects highlighted.



Applications



- Security and surveillance**
- Industrial automation**
- Smart home monitoring**
- Research and education**





Conclusion

Summary:

- Demonstrated real-time object detection using MATLAB and an IP camera.
- Showed key steps: capturing, preprocessing, detection, and visualization.

Future Improvements:

- Enhanced object classification
- Integration with machine learning models

