

Complex Computing Problem

OPTIMIZING A KLT FEATURE TRACKER USING GPU KERNELS

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Experimental Setup

3 workloads:

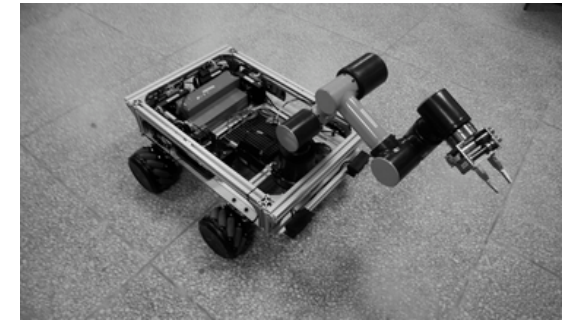
- **Small:** 640x360 px
- **Medium:** 1024x576 px
- **Large:** 1920x1080 px

30 frames each

Running on:

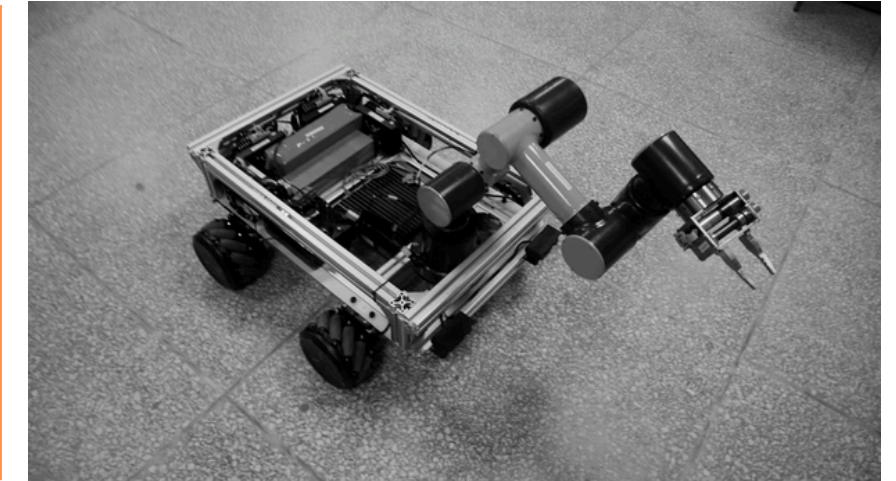
NVIDIA GeForce RTX 3080 (Compute Capability 8.6)

360



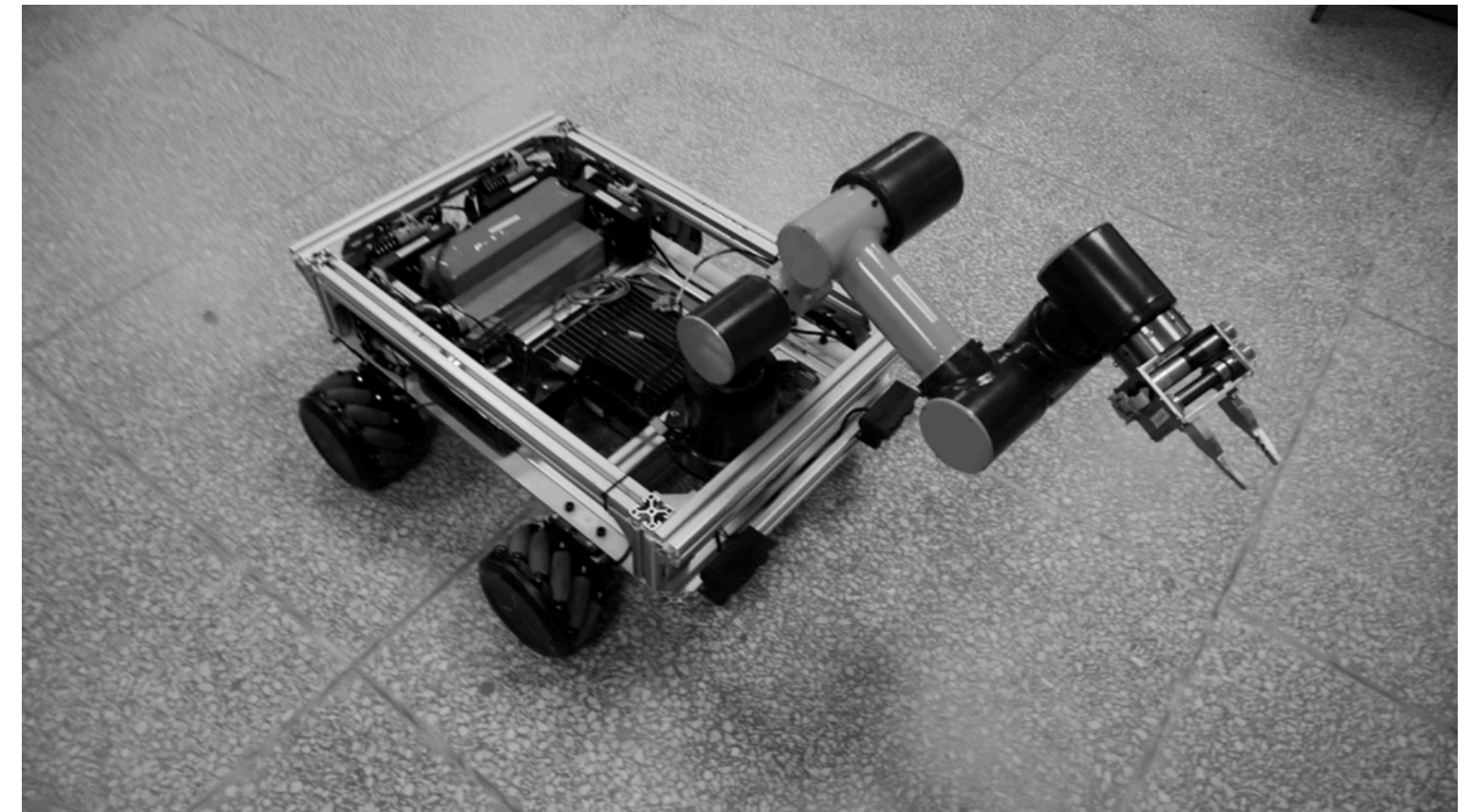
640

576



1024

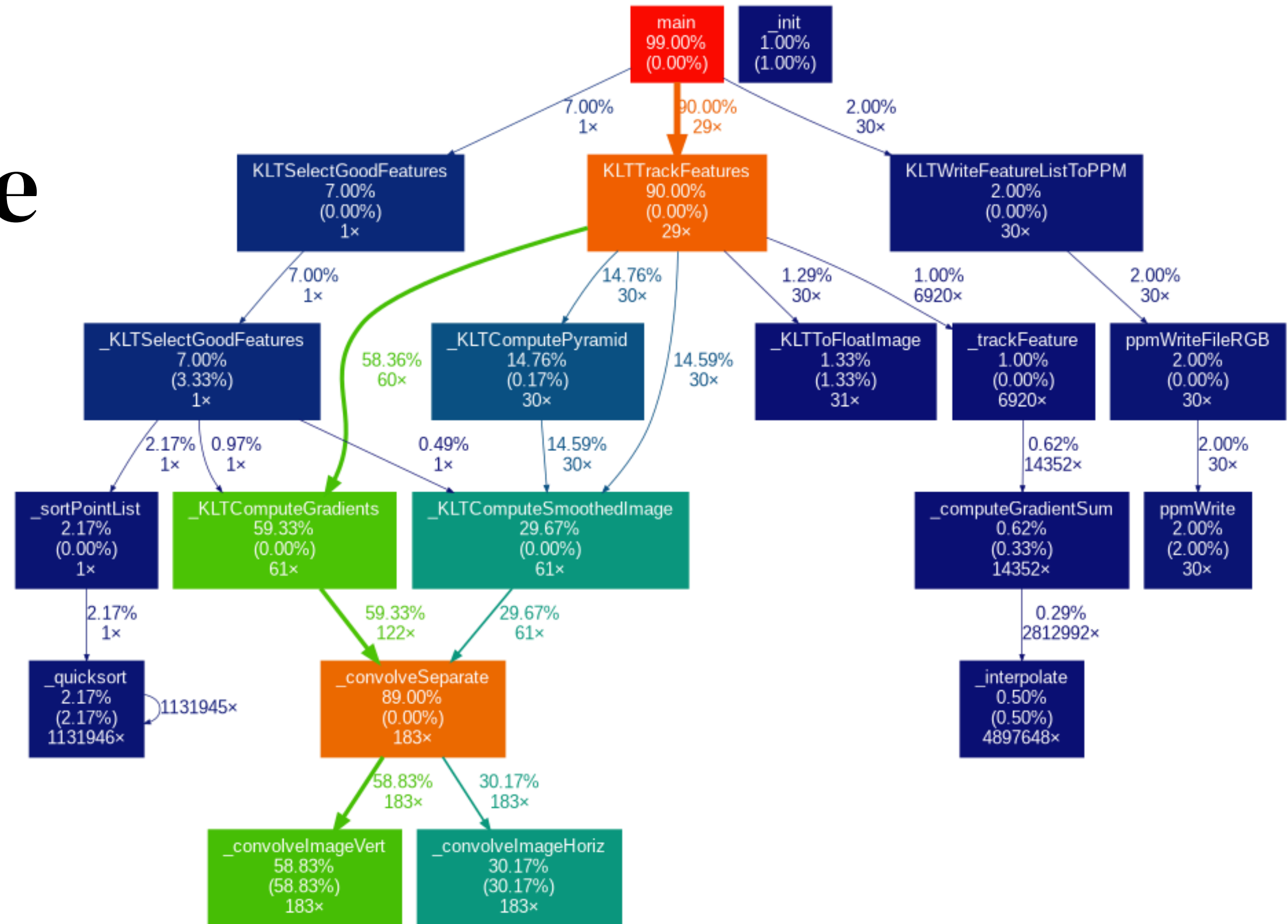
1080



1920

Motivation

V1: CPU baseline



gprof2dot results on V1

Our bottlenecks...

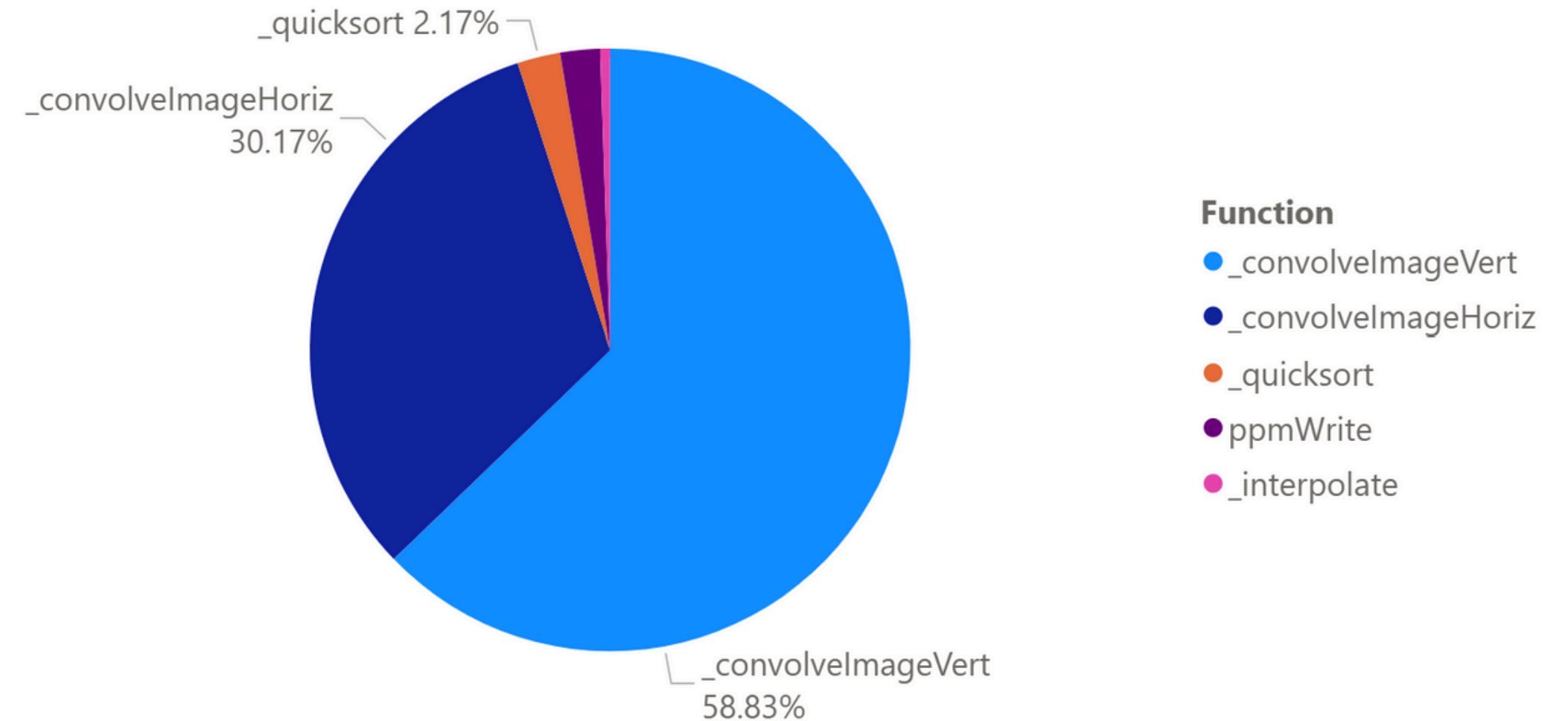
We ran our program several times over different datasets to find our main bottlenecks:

- `_convolveImageHoriz`
- `_convolveImageVert`
- `_interpolate` *

* `_interpolate` is included because it gets called many times

Identified **Convolutions** and **Feature Tracking** as main opportunities for parallel computation

% Time Spent in each Function



V2: Naive GPU Port

Introduction of kernels:

- convolveHorizKernel
- convolveVertKernel
- trackFeatureKernel

Bottlenecks:

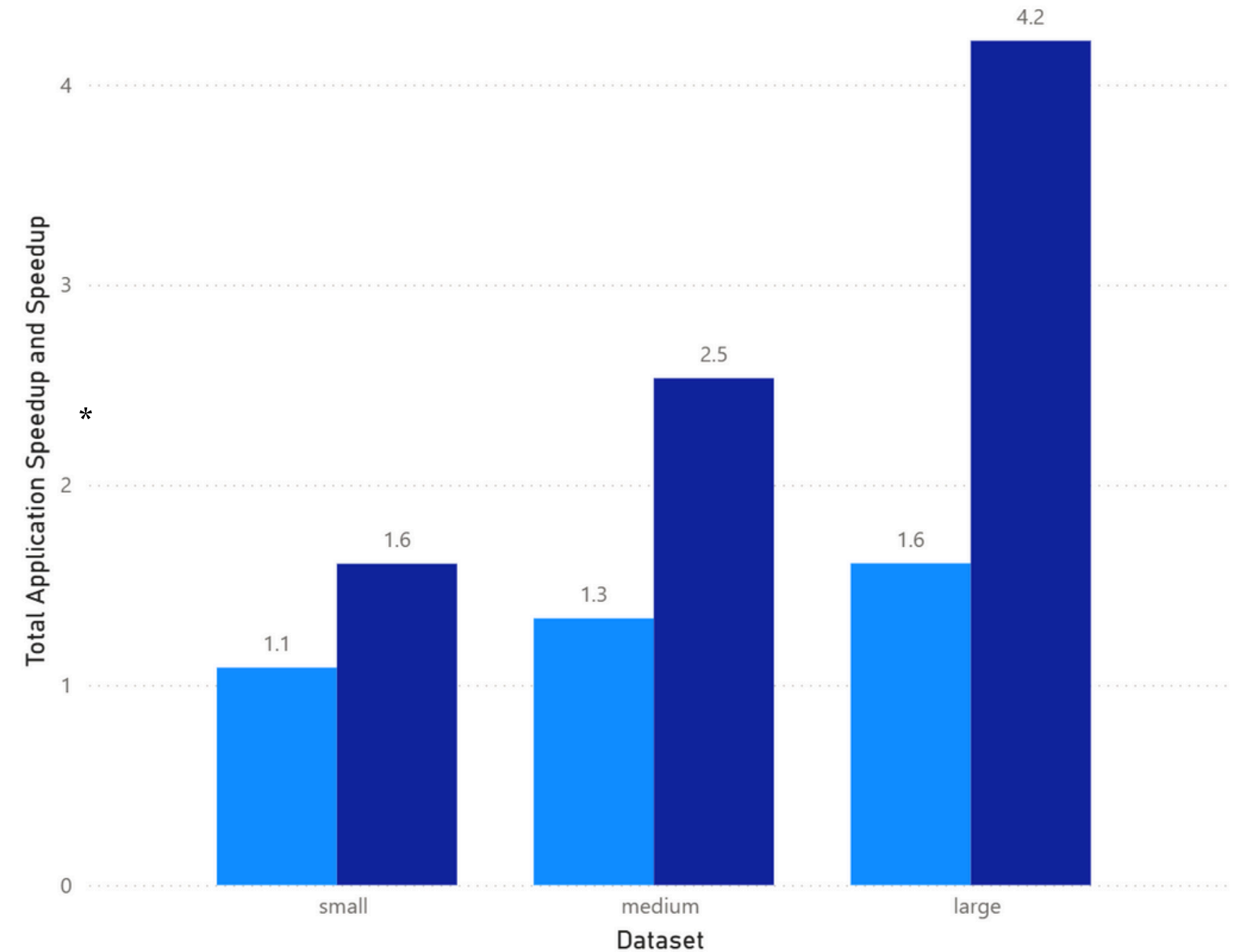
- Memory transfers (H2D, D2H) took upto **51.2%** of tracking time (large dataset)

Small Gains:

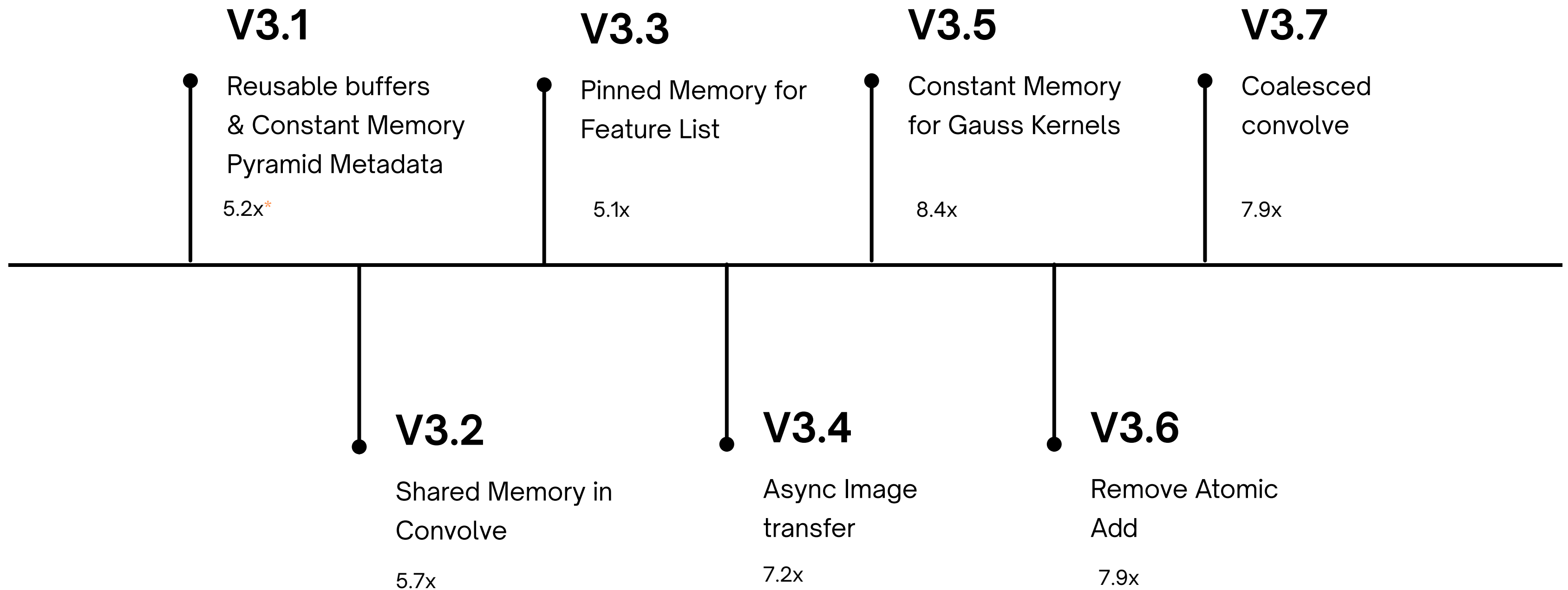
- **1.6x** speedup for total application time
- **4.2x** speedup if only tracking time is considered

Naive GPU Performance

● Total Application Speedup ● Speedup



V3: Optimising V2...



*on our medium workload

V3: Optimised!

Obtained up to **18.6x** speedup!

Small:

- **2.5x** tracking time
- **1.4x** total application time

Medium:

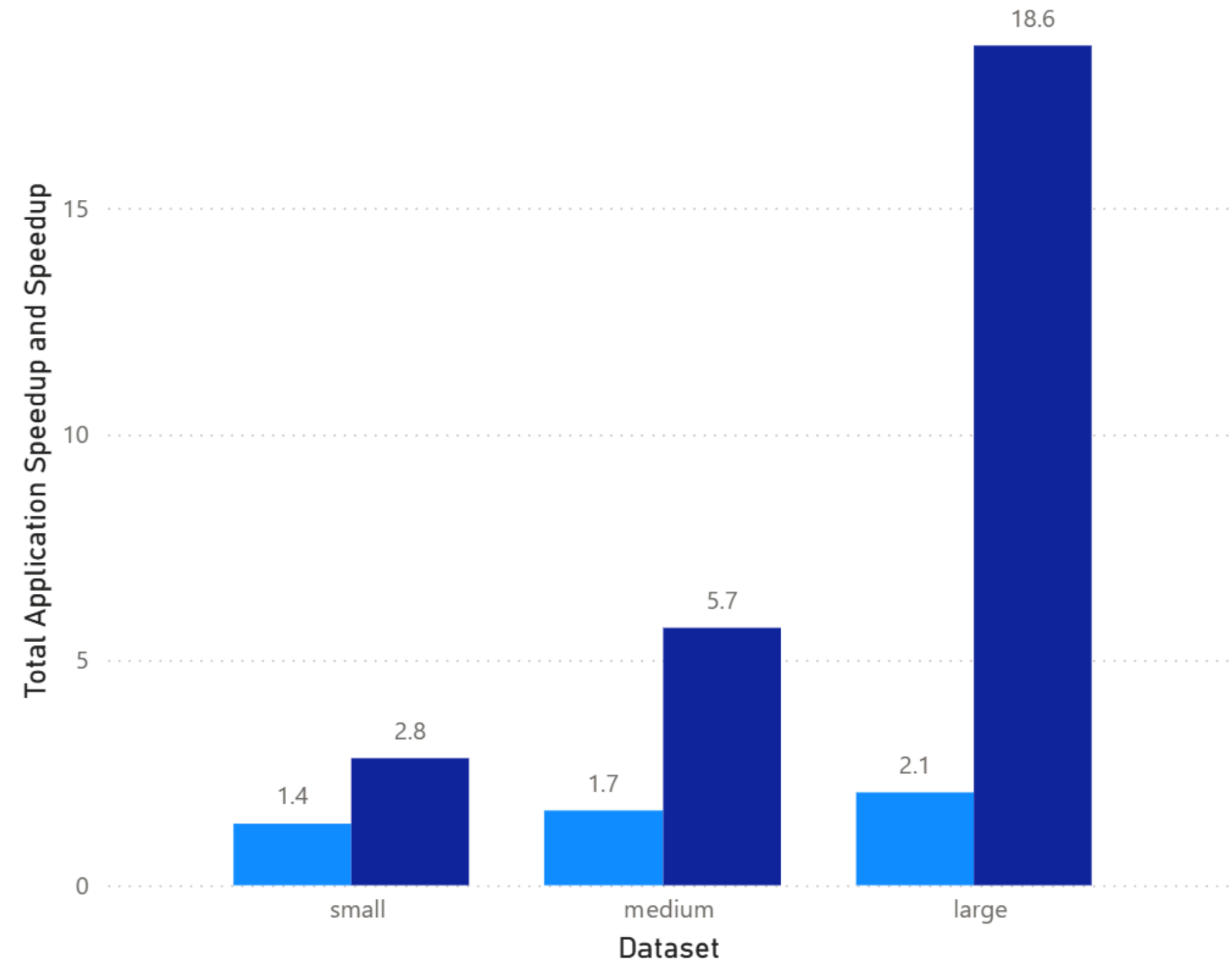
- **5.7x** tracking time
- **1.7x** total application time

Large

- **18.6x** tracking time
- **2.1x** total application time

Optimised GPU Performance

● Total Application Speedup ● Speedup



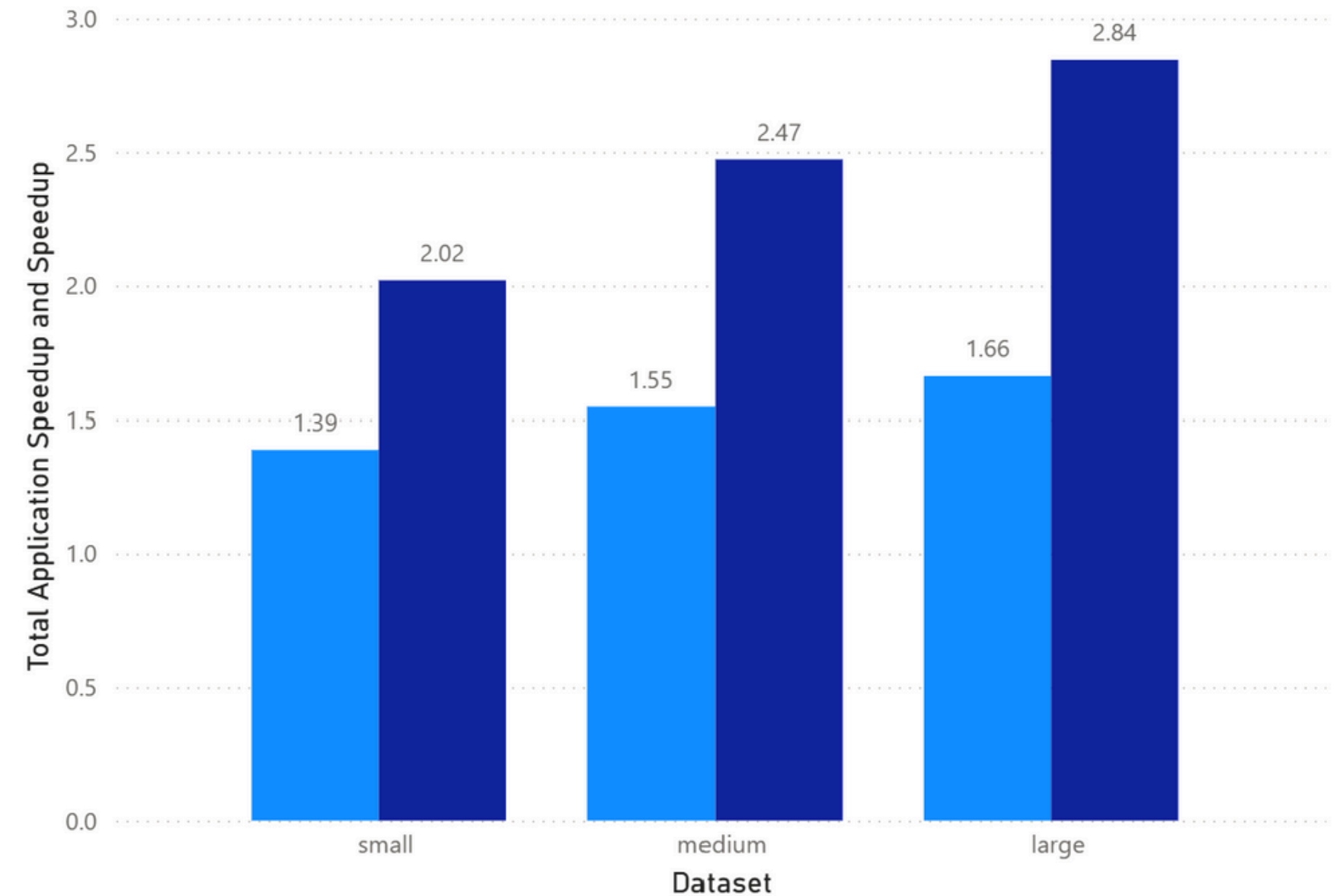
V4: OpenACC

Parallalesing our main bottlenecks:
Horizontal and Vertical Convolution
using pragma ACC kernels

Quick, but Small Gains: 2.84x
on large dataset
(1.66x application speedup)

OpenACC Performance

● Total Application Speedup ● Speedup

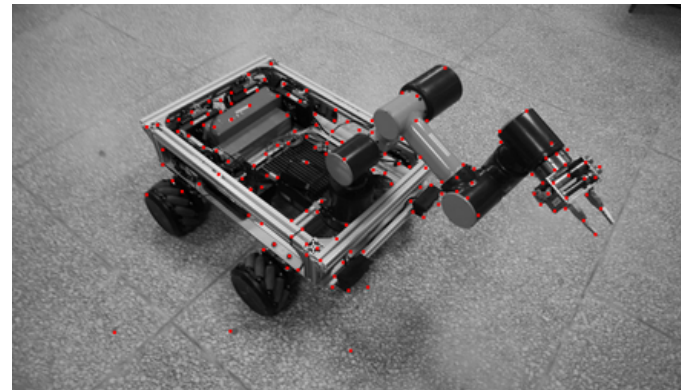


Correctness

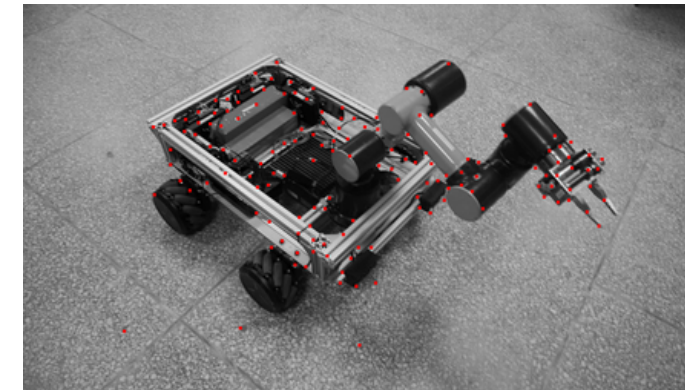
CPU tracks:

- small : 150 features
- medium : 145 features
- large: 113 features

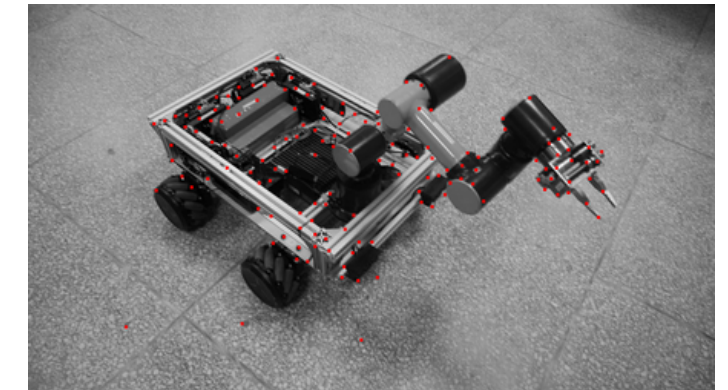
While V2 shows slight divergence, V3 and V4 track features correctly when compared with CPU



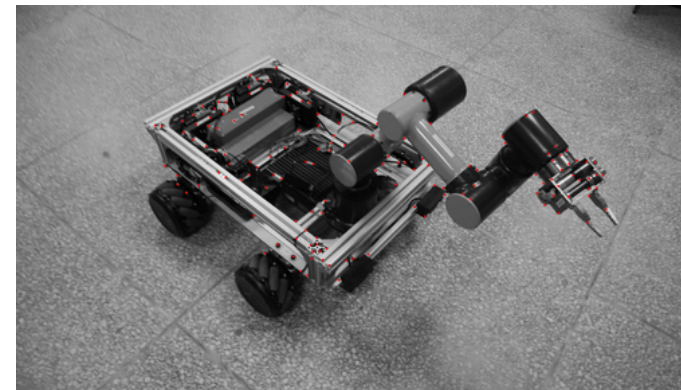
frame 0



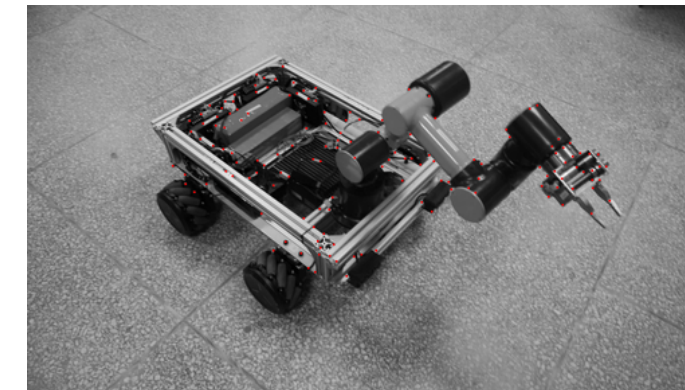
frame 14



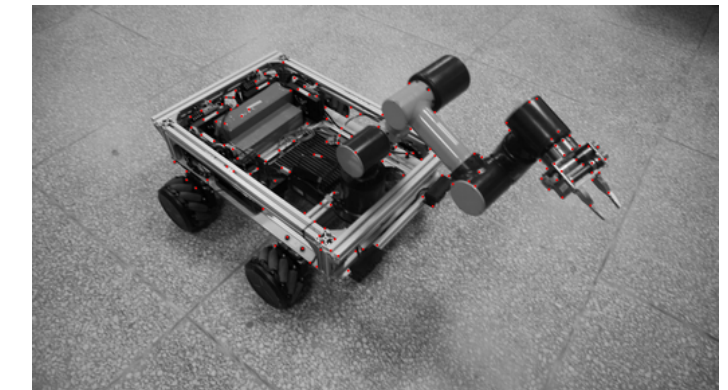
frame 29



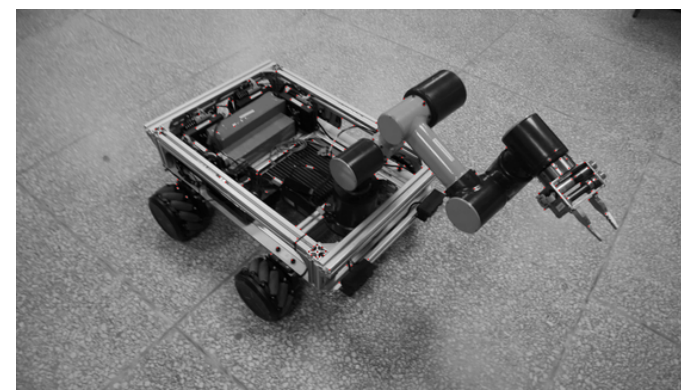
frame 0



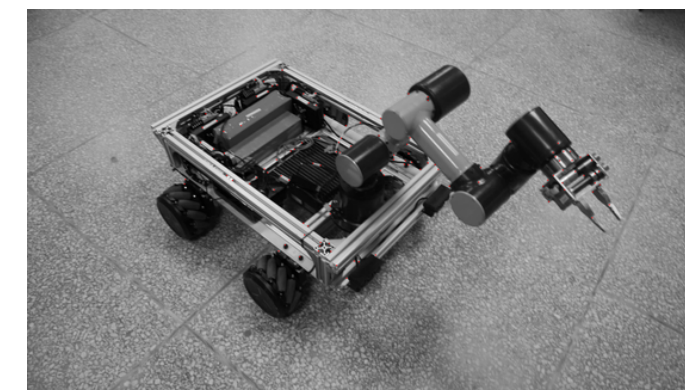
frame 14



frame 29



frame 0



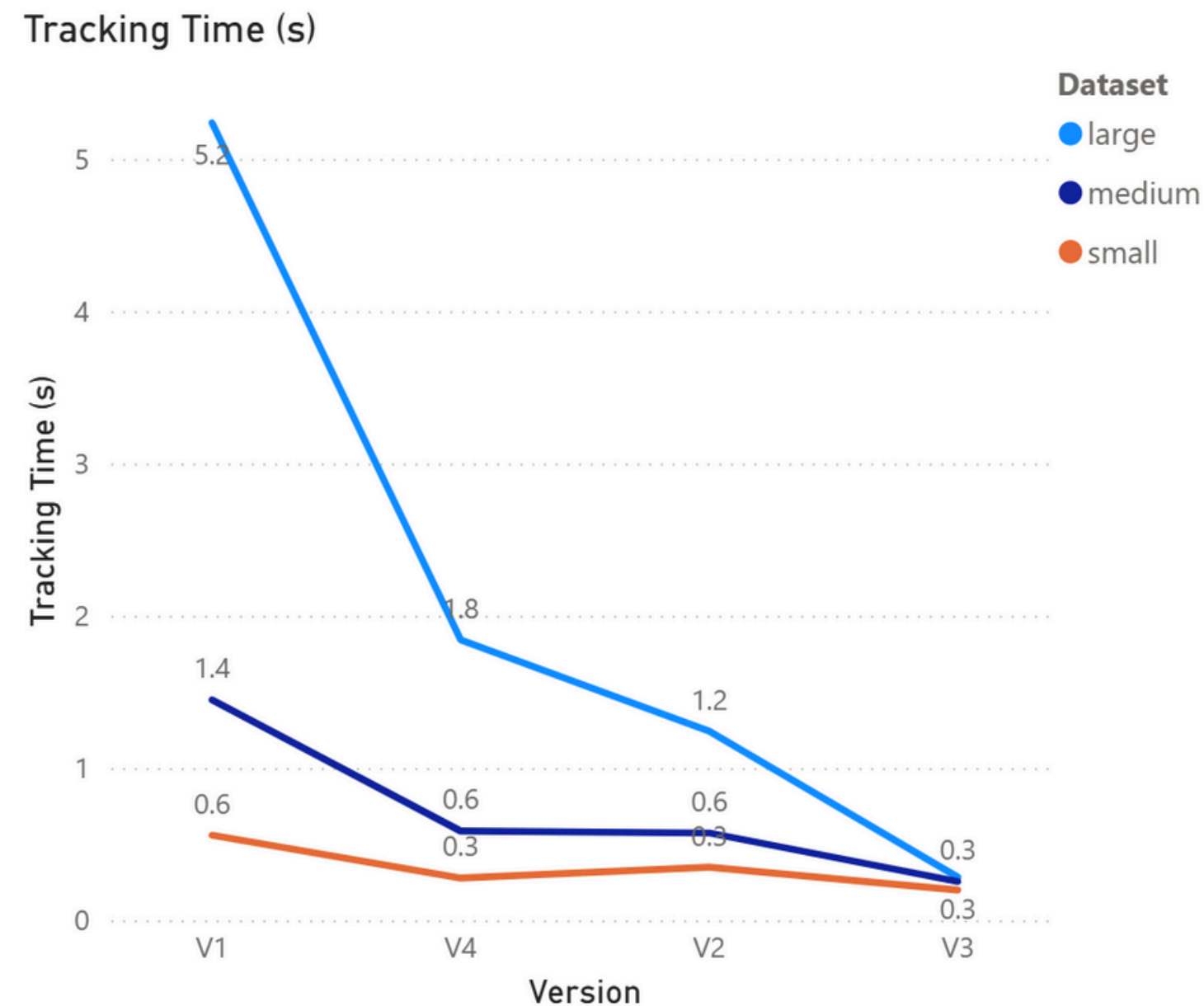
frame 14



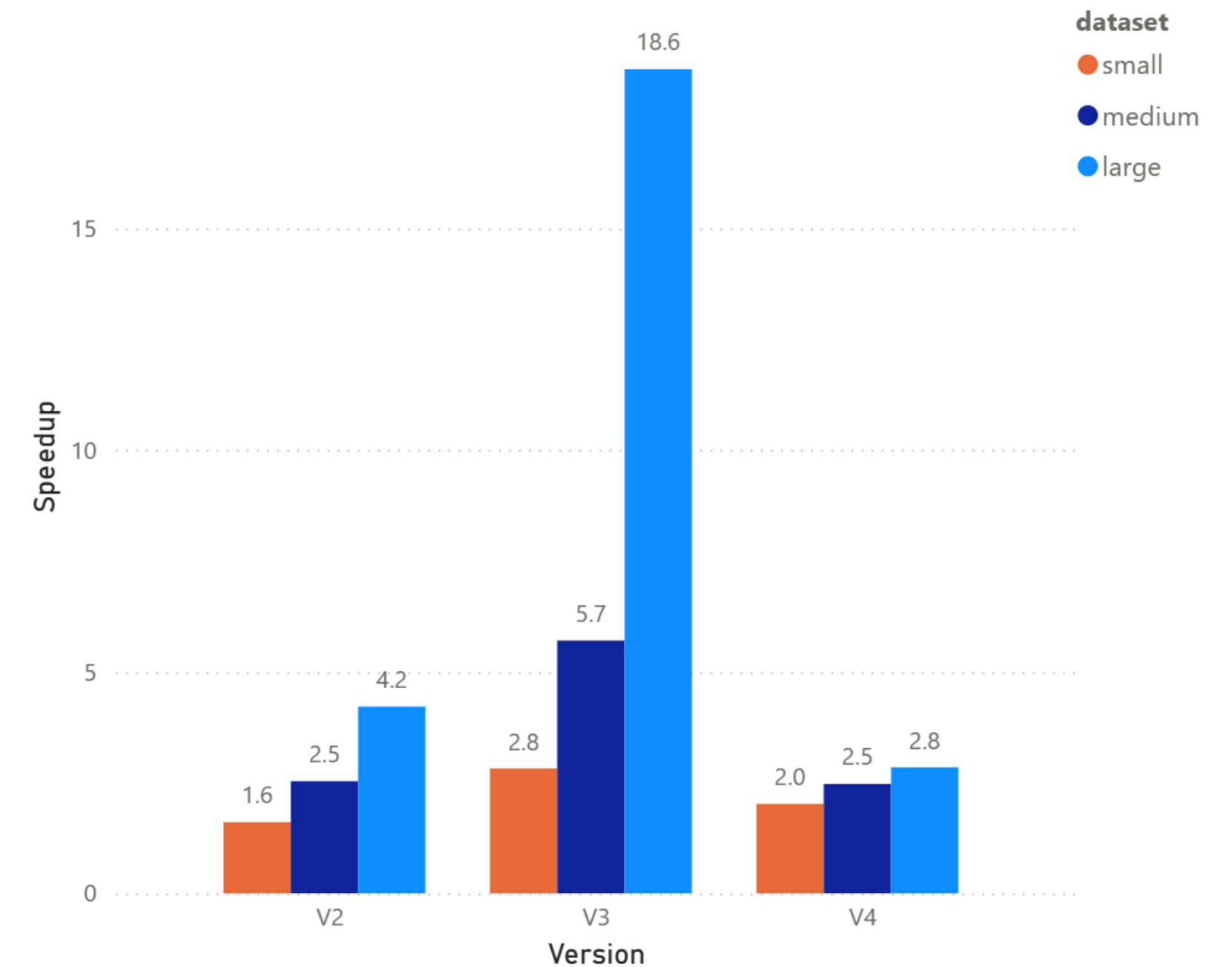
frame 29

Comparison of Results

Speedup



Speedup Comparison



CUDA Brought Tracking Time down from **5.2s** to **0.28s** while **OpenACC** brought it down to **1.84s**. *

OpenACC shows poor scaling

* on large dataset

Comparison of Results

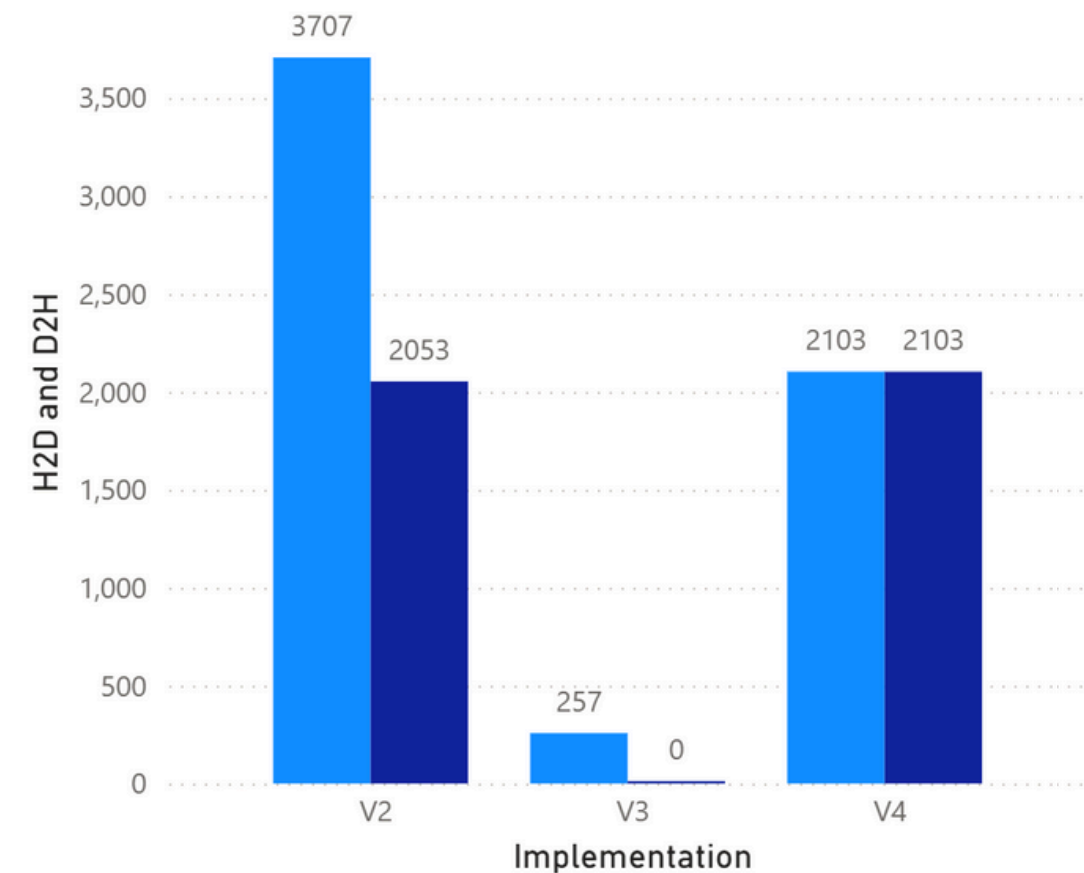
Memory Transfer

The amount of data (MBs), and the time taken transferring that data (ms) from Host to Device and Device to Host **decrease** significantly from our CUDA optimization

Total Data Transfer (MB)

on large dataset

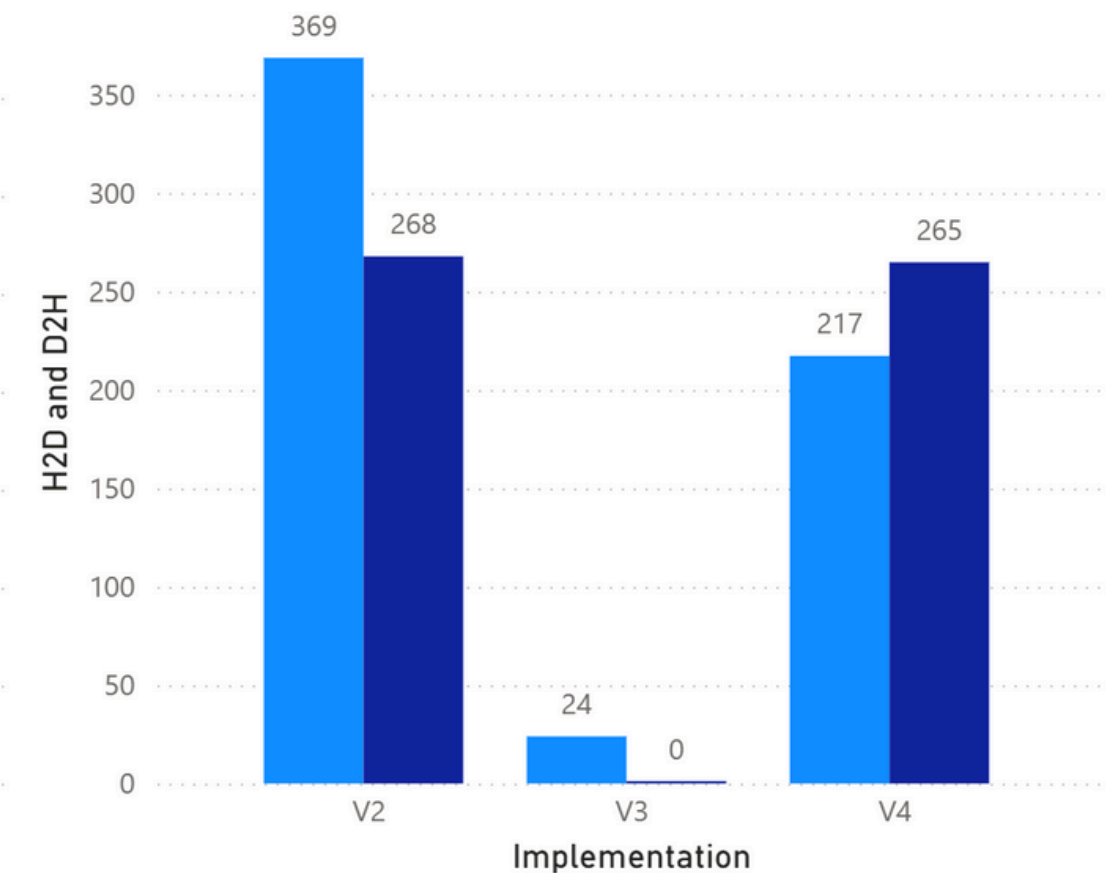
● H2D ● D2H



Total Data Transfer Time (ms)

on large dataset

● H2D ● D2H



Comparison of Results

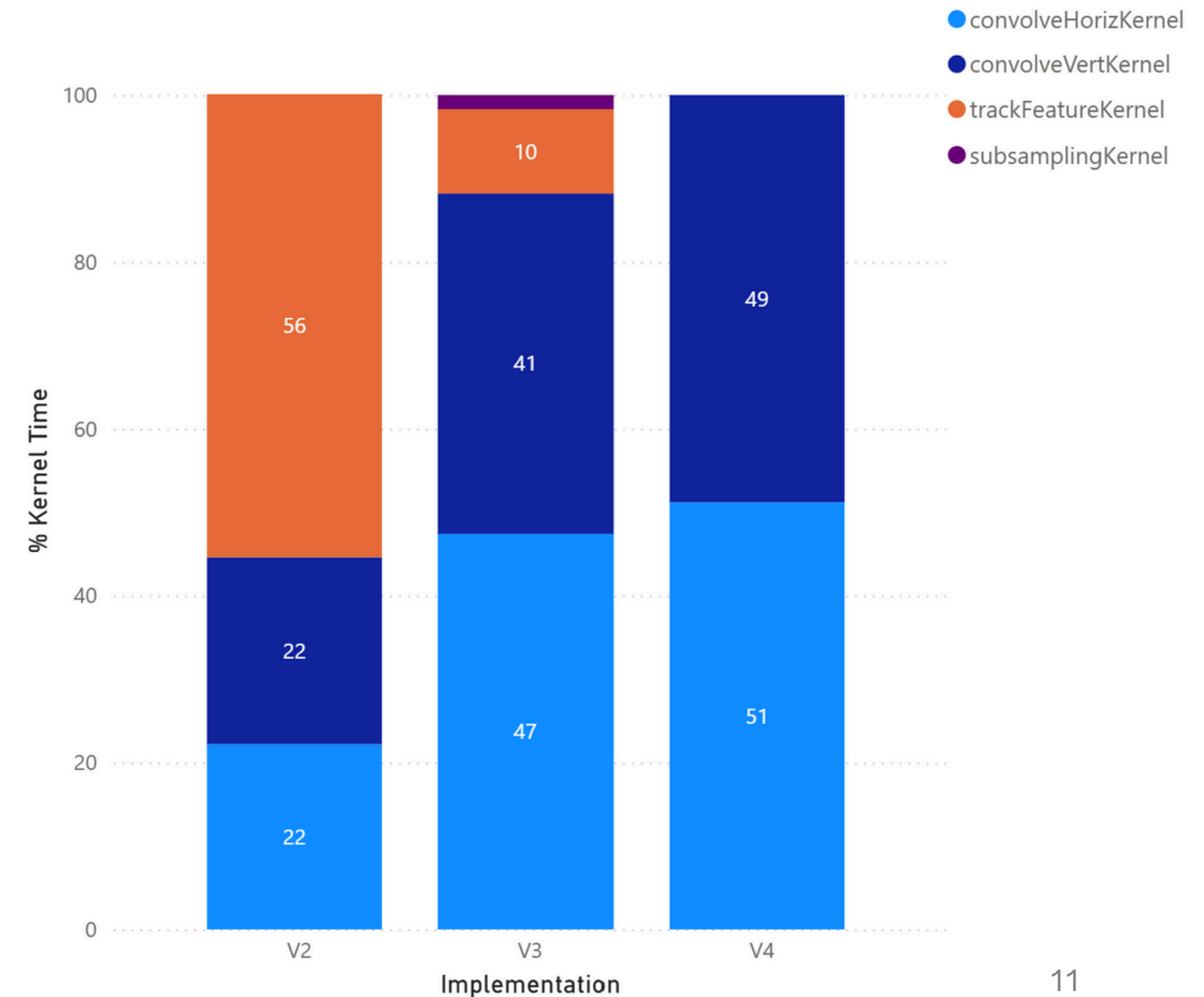
Kernel Breakdown

Before Optimisation:
Tracking Dominates

After Optimisation:
Convolutions Dominate

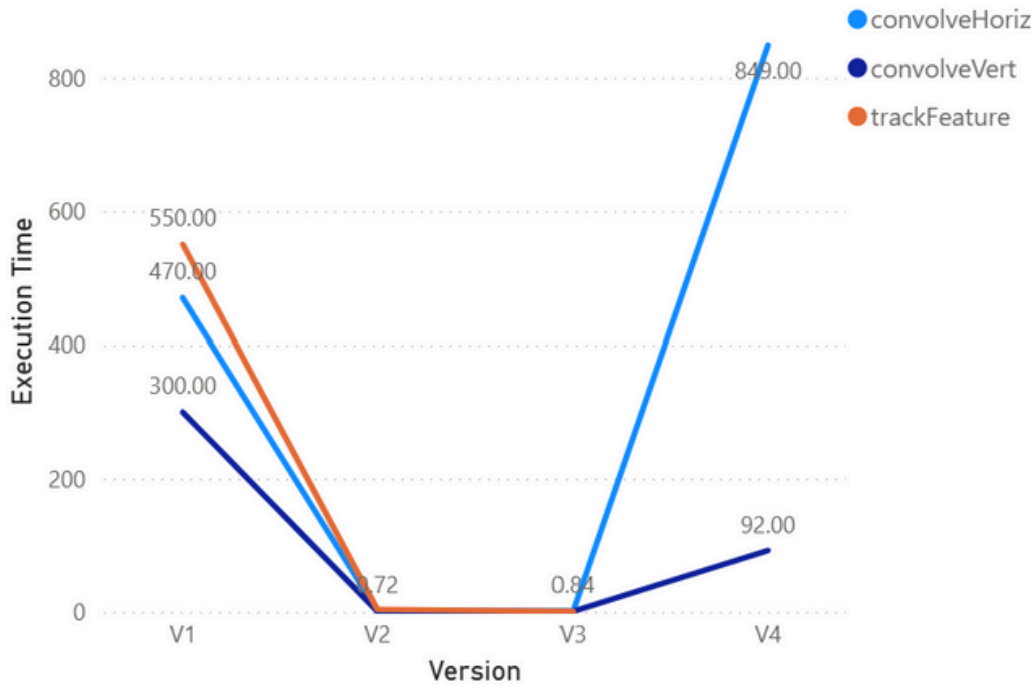
This aligns with the CPU baseline!

Kernel Breakdown Summary
on medium dataset

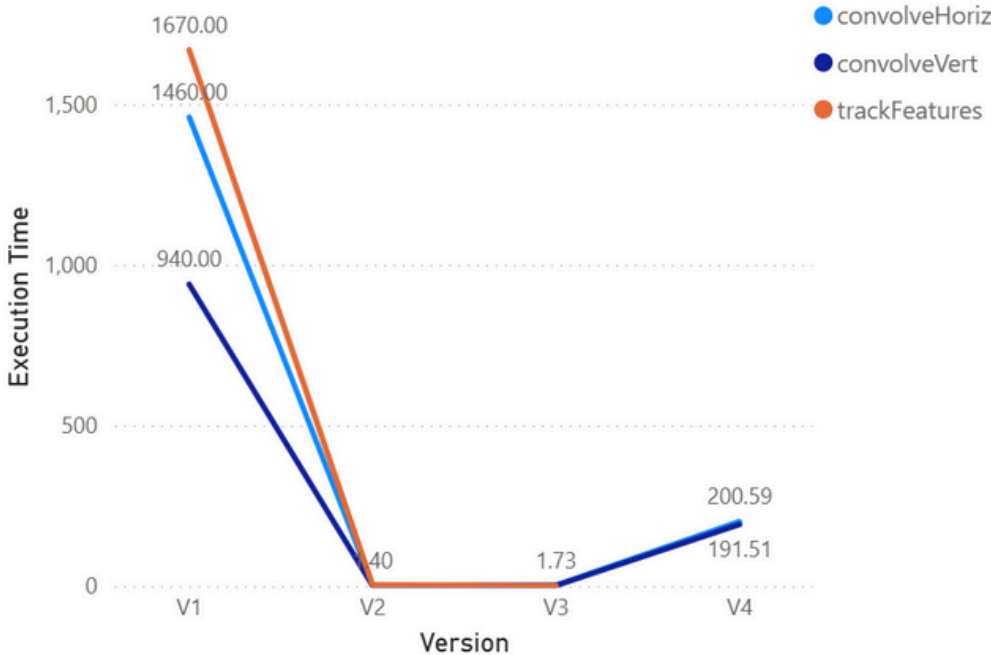


Comparison of Results

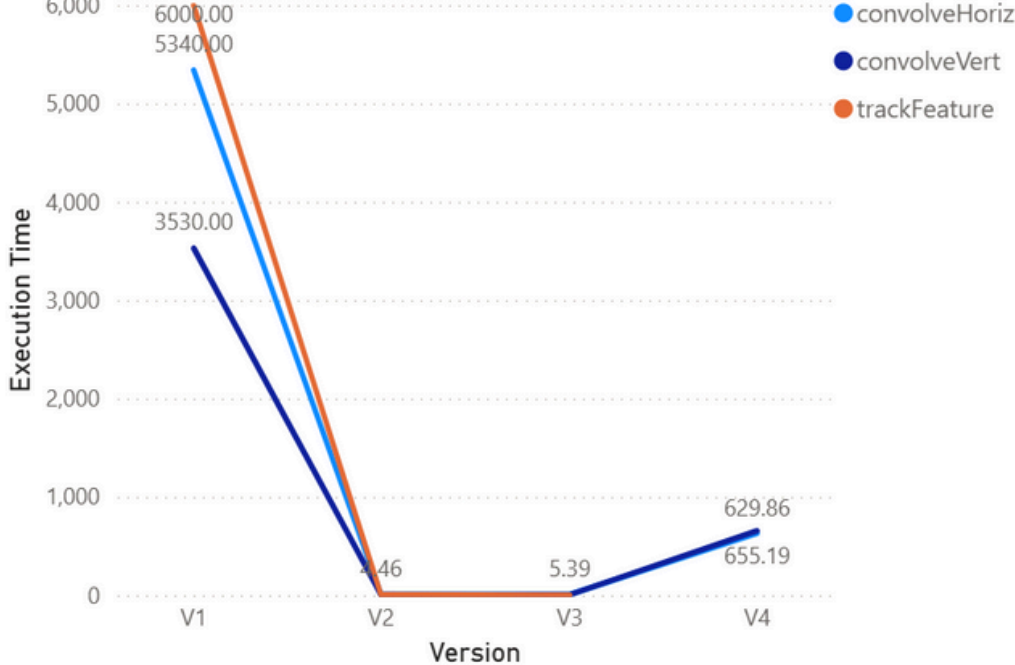
Kernel Execution Time



Kernel Execution Time



Kernel Execution Time



Successfully parallelised our bottlenecks:

Horizontal Convolution: 5340 ms	→	5.39 ms
Vertical Convolution: 3530 ms		4.93 ms
Feature Tracking: 6000 ms		0.39 ms

Key Takeaways

- Highly Suitable for Parallelisation
- Scales well for large workloads
- $\text{CUDA} > \text{OpenACC?}$
- Sequential Dependencies Constraints