

# Project CHANDRA

BRIDGING THE GAP BETWEEN HUMAN & ROBOT INTERACTION

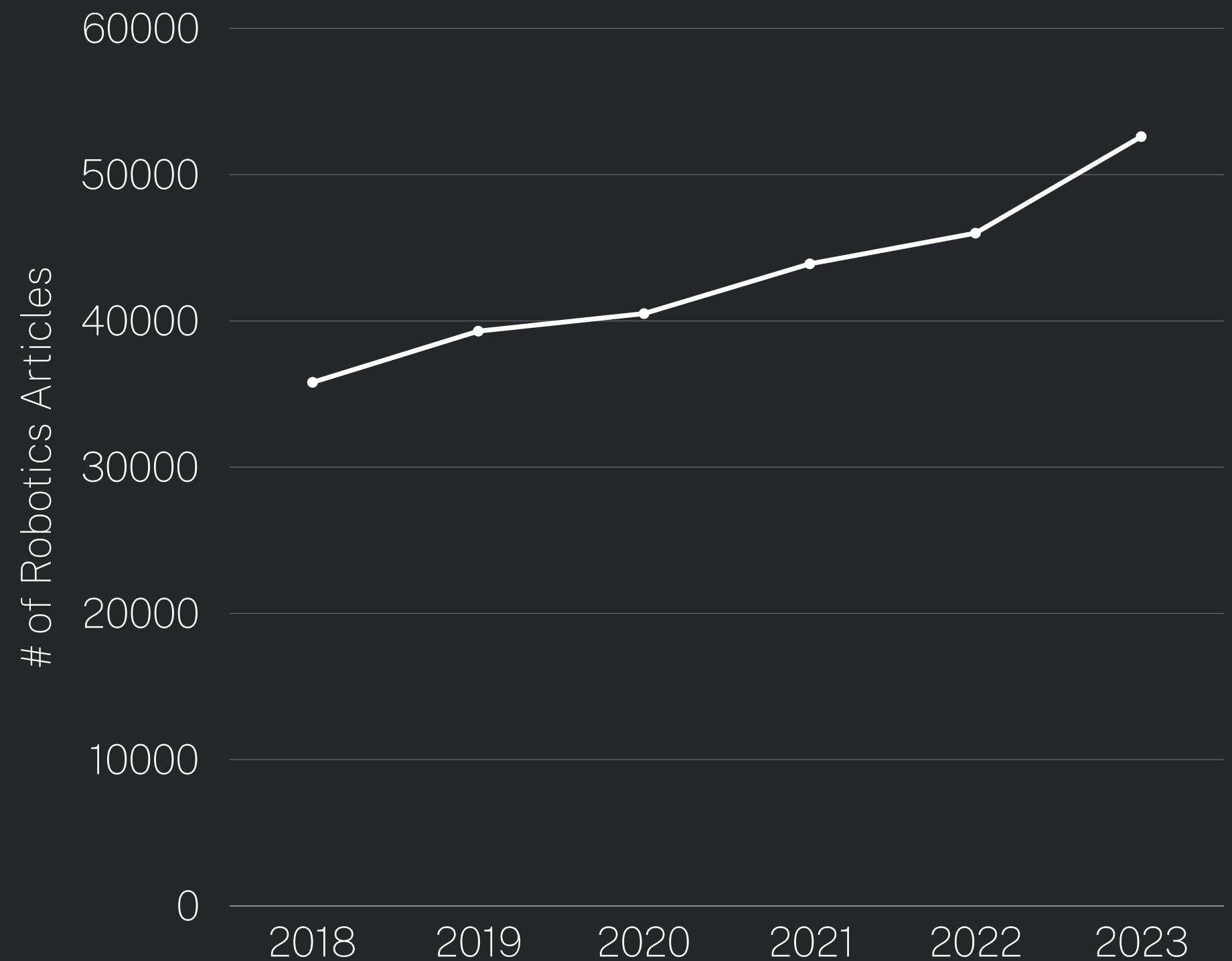
Interacting  
with robots  
is very  
difficult.

Every roboticist will tell you this...



# More research every year...

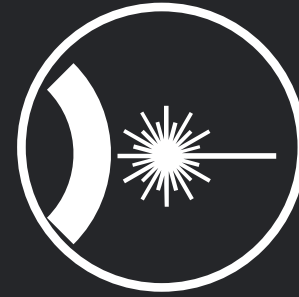
still not smart or affordable enough  
to have robots in the common  
household.



**We want to give robots a voice  
interface.**

— Project TLDR

# Our goals



## **Cutting-edge**

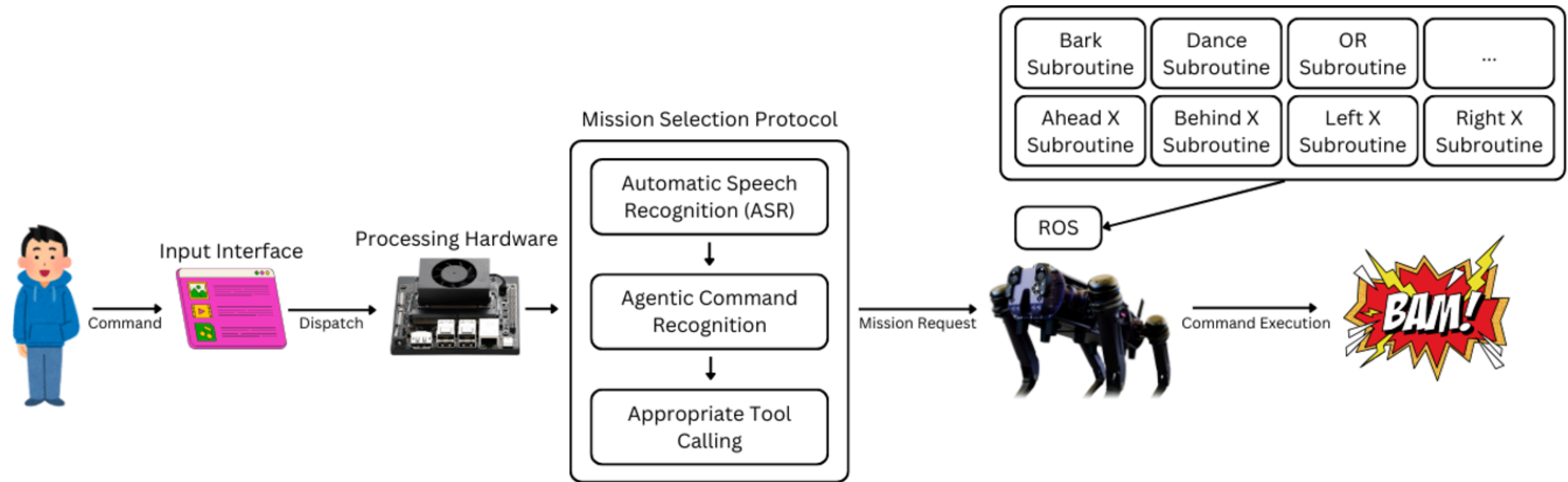
We want to use the latest advanced in voice detection and natural language technologies.



## **Seamless**

We want interactions to be natural, fast and seamless.

# Our solution



# Main benefits



## **It's Intuitive**

Simply saying things in natural language is more intuitive than any tools short of brain interfaces.



## **It's Efficient**

Talking is very efficient and require less attention than manual control schemes.



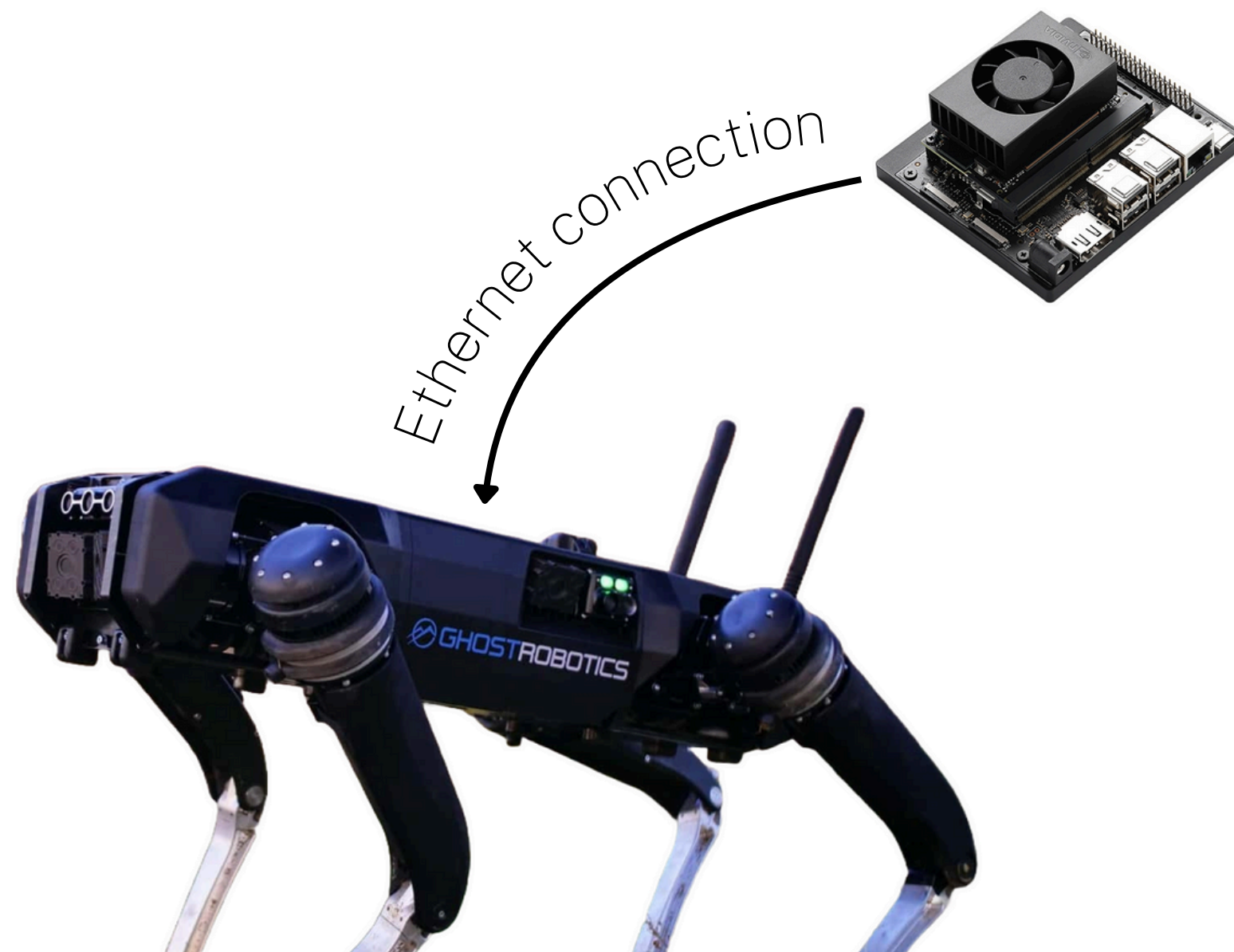
## **It's Accessible**

You don't need to have technical knowledge to talk.

**Let's get technical...**




Our non-demo tech stack.



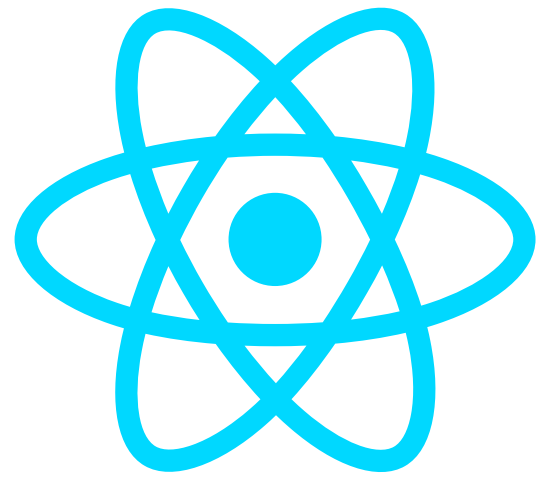
 ROS 2 reigns. Everything is a node.

 OpenAI's Whisper is the best STT.

 smolagents is good for LLM agents.

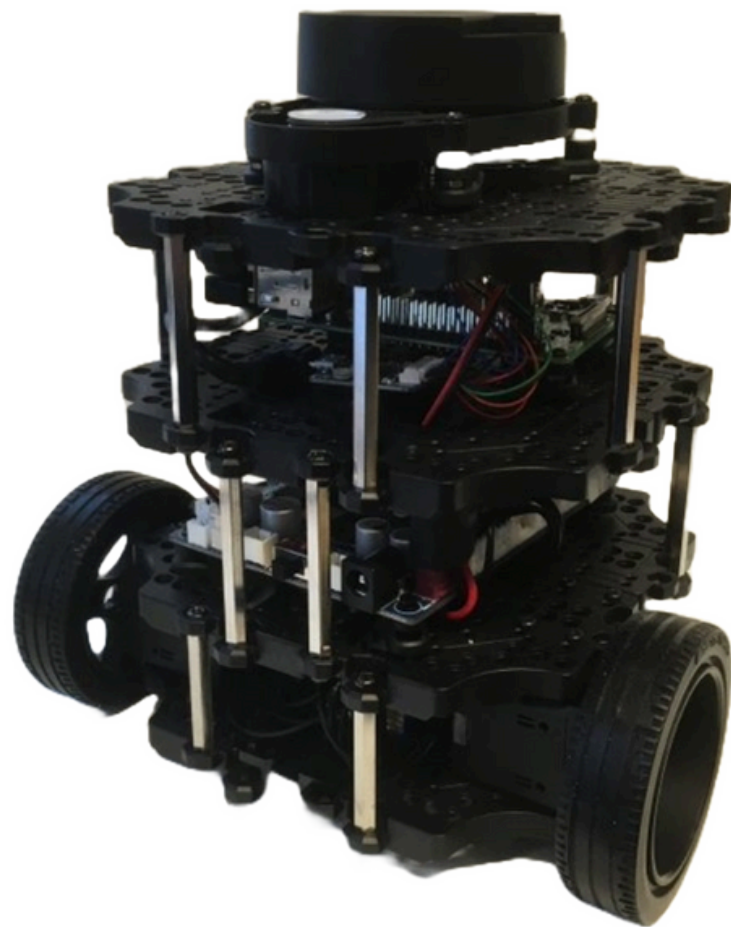
 Llama is a good local LLM family.

Our demo tech stack.



Robot (simulators) we tested on.

Turtlebot3 Burger



Mangdang Minipupper



GhostRobotics V60



# Let's look at some stats

Here's what our system can achieve.



## **1-2s latency**

Basically real-time  
inference of speech.



## **98% accuracy**

Near-perfect intent  
parsing from agent.

**Demo time!**