

Application Note for small size Monochrome EPD with iTC (OTP LUT)

Description	Interface for the small size Mono EPD with the iTC		
Date	2022/06/06		
Doc. No.			
Revision	02		

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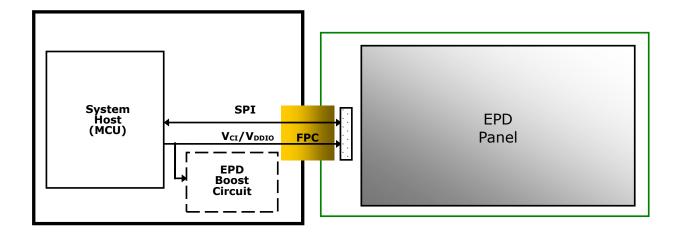
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1. General Description

1.1 Overview

The document introduces how to drive the small size EPD with OTP LUT. The "Small size" includes 1.54", 2.13", 2.66", 2.7", 2.87", 2.9" HR(High-resolution), 3.7", 4.2" and 4.37". The EPD use single driver and that embedded T-con. The major control interface of the driver is SPI. The host sends both the setting commands and the display image to driver through the SPI bus.

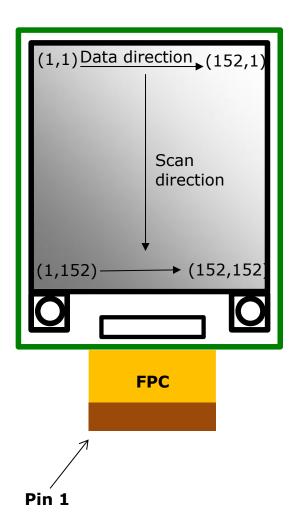


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1.2 Panel drawing

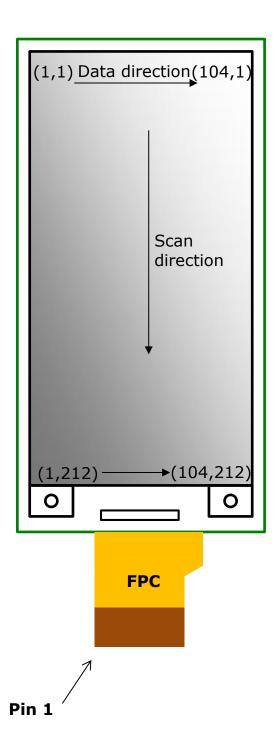
1.54-inch EPD



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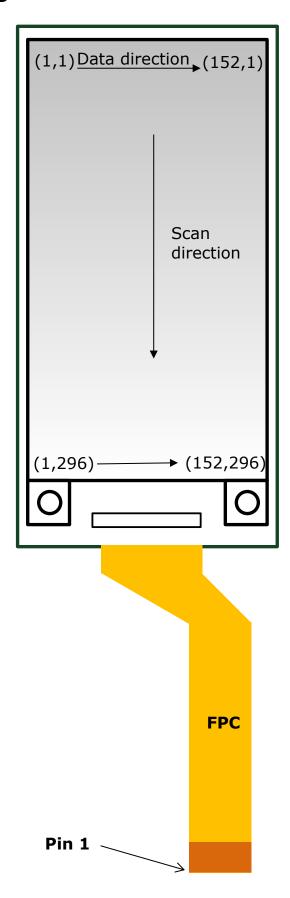
2.13-inch EPD



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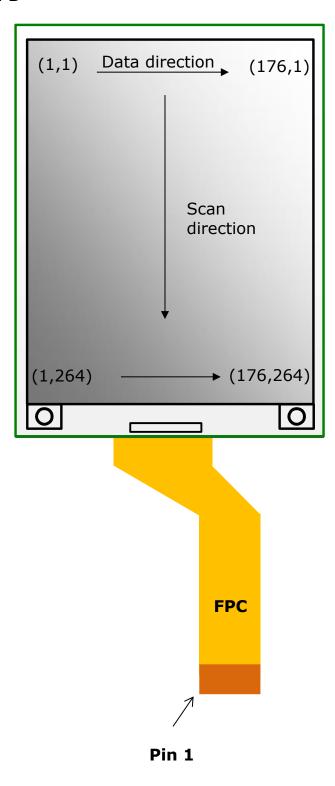
2.66-inch EPD



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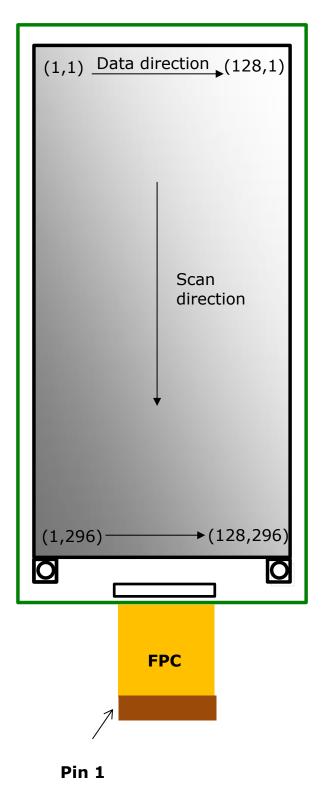
2.7-inch EPD



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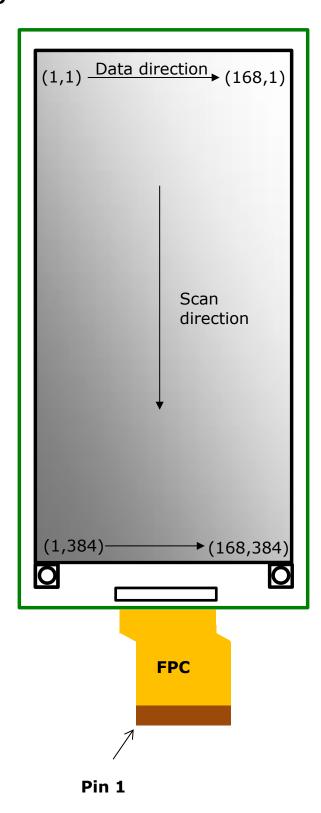
2.87-inch EPD



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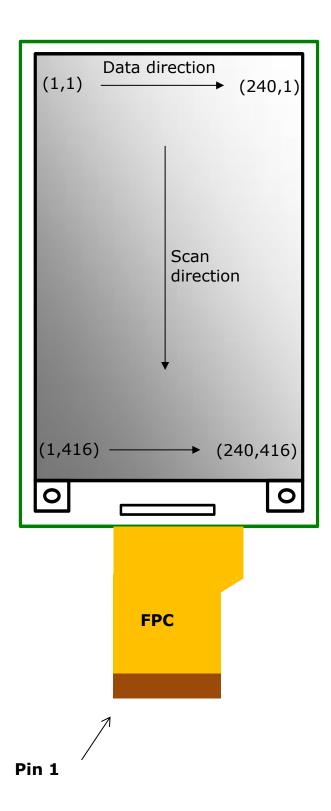
2.9-inch HR EPD



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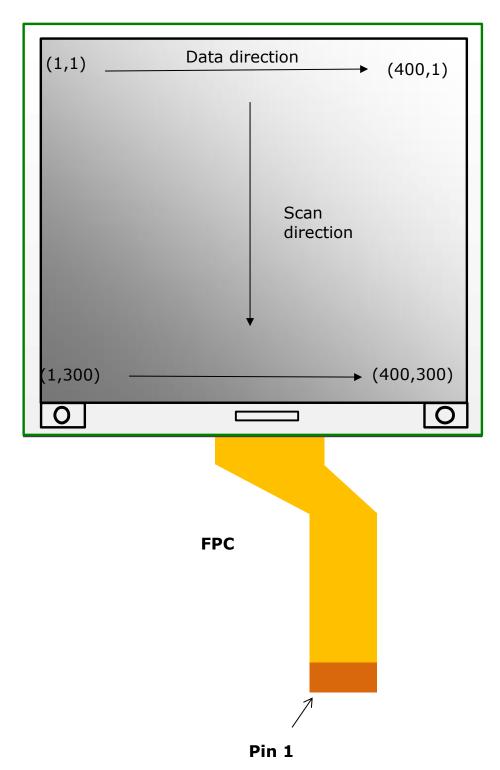
3.7-inch EPD



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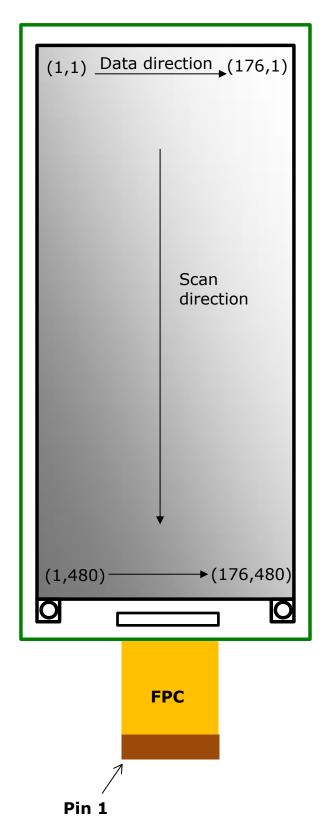
4.2-inch EPD



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4.37-inch EPD

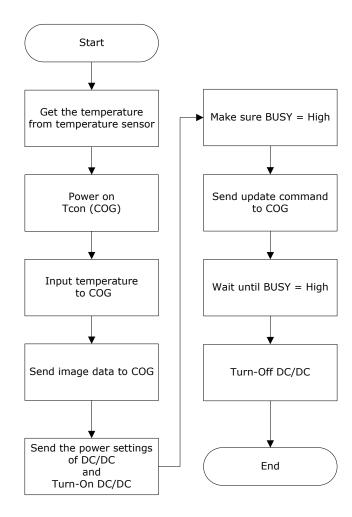


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1.3 EPD Driving Flow Chart

The flowchart below provides an overview of the necessary actions to update the EPD. The steps below refer to the detailed descriptions in the respective sections.

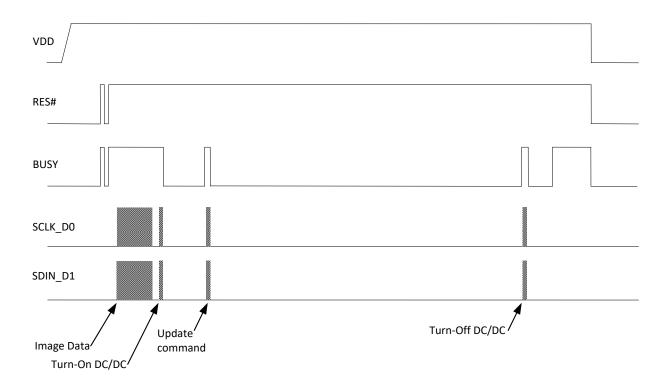


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1.4 Overall Waveform

The diagram below provides a signal control overview during an EPD update cycle.



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1.5 **SPI Timing Format**

SPI commands are used to communicate between the MCU and the COG Driver. The SPI format used differs from the standard in that two-way communications are not used, and CS is pulled high then low between clocks. When setting up the SPI timing, PDI recommends verify both the SPI command format and SPI command timing in this section.

The maximum clock speed of the display is 10MHz.

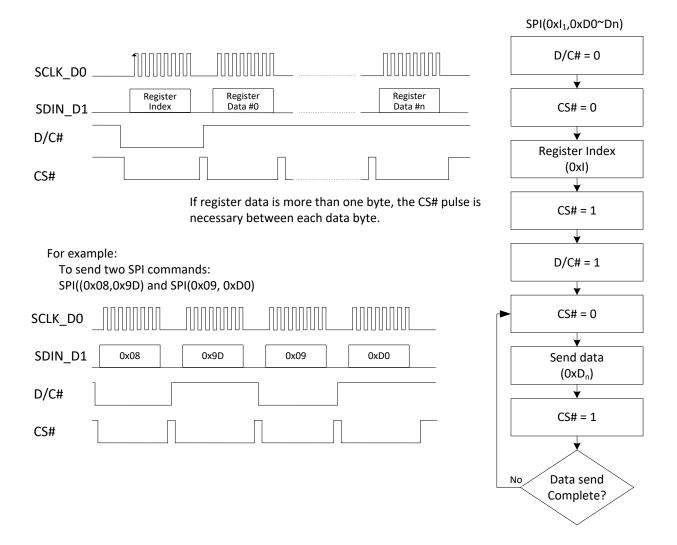
Below is a description of the SPI Format:

 $SPI(0xI, 0xD_0, 0xD_1, 0xD_2, ...)$

Where:

I is the Register Index and the length is 1 byte $D_{0\sim n}$ is the Register Data. The Data length is variable by different Register Index.

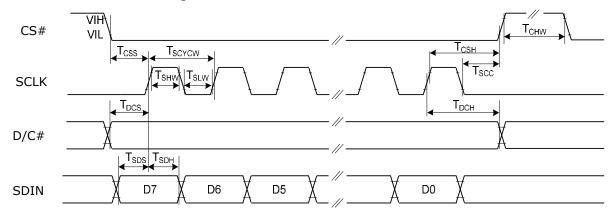
SPI command signals and flowchart:



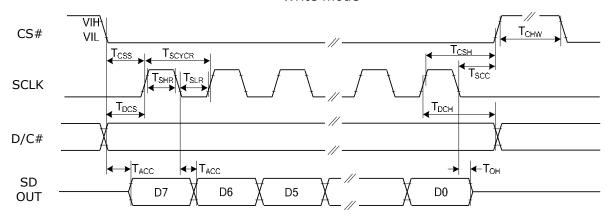
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SPI command timing



Write mode



Read mode

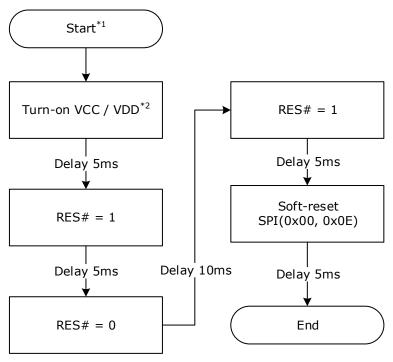
Item	Symbol	Min.	Тур.	Max.	Unit	Remark
Chip Select Setup Time	t _{CSS}	60	-	-	ns	
Chip Select Hold Time	t _{CSH}	65	-	-	ns	
Chip Select Setup Time	t _{SCC}	20	-	-	ns	
Chip Select Setup Time	t _{CHW}	40	-	-	ns	
Serial Clock Cycle (Write)	t _{SCYCW}	100	-	-	ns	
SCLK "H" Pulse Width (Write)	t _{SHW}	35	-	-	ns	
SCLK "L" Pulse Width (Write)	t_SLW	35	-	-	ns	
Serial Clock Cycle (Read)	t_{SCYCR}	350	-	-	ns	
SCLK "H" Pulse Width (Read)	t_{SHR}	175	-	-	ns	
SCLK "L" Pulse Width (Read)	t _{SLR}	175	-	-	ns	
DC Setup Time	t _{DCS}	30	-	-	ns	
DC Hold Time	t _{DCH}	30	-	-	ns	
Data Setup Time	t _{SDS}	30	-	-	ns	
Data Hold Time	t _{SDH}	30	-	-	ns	
Access Time	t _{ACC}	-	-	250	ns	
Output Disable Time	t _{OH}	15	-	-	ns	

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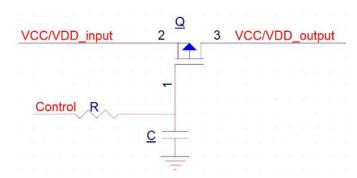
2. Power on COG driver

This flowchart describes power sequence for driver chip.



Note:

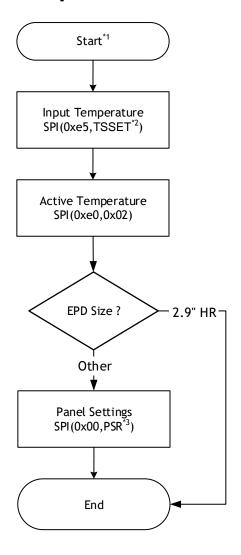
- 1. Start
 - Initial State:
 - VCC/VDD, RES#, CS#, SDIN, SCLK = 0
- 2. In order to the inrush current will cause other issue. It is recommended to add soft-start when VCC/VDD is turned on. (as the circuit below)



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3. Set environment temperature and PSR



NOTE:

- 1. **start:** Follow the end of the power on sequence
- 2. **TSSET:** is the temperature value and unit is degree of Celsius.

The highest bit of the data represents positive/negative in temperature.

if it's positive, the data = (temperature value)

if it's negative, the data = (2's complement of temperature value)

example:

temperature value data 25°C 0x19 5°C 0x05 -5°C 0xFB

3. **PSR**: there are 2 bytes' data to send.

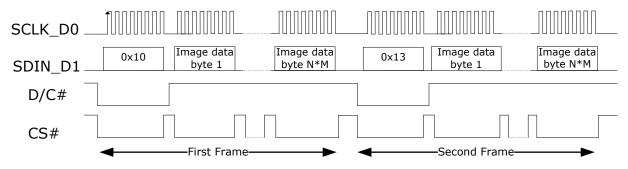
3.7", 4.2", 4.37" : 0x0F,0x89 Other Size : 0xCF,0x8D

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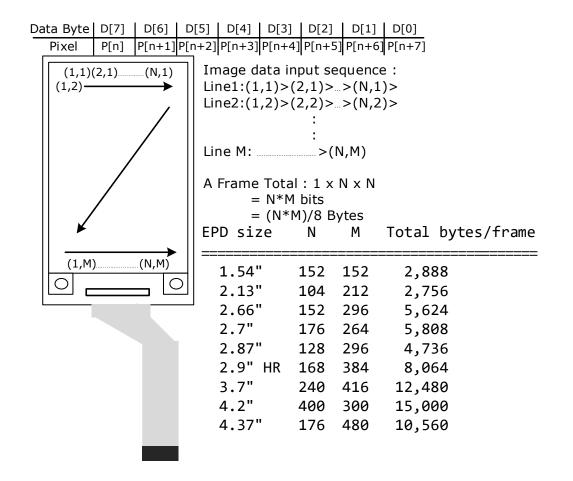
4. Input image to the EPD

This section describes how to send the image data into the COG driver which will update the display. EDP need to receive both First and Second frame data each updating. The index of the first frame is **0x10** and the second frame is **0x13**.



Note 1: n=(N*M)/8

The data of image frame, one bit represents 1 pixel. (e.g. the first byte represents the $1^{st} \sim 8^{th}$ pixels of the first line, the second byte represents the $9^{th} \sim 16^{th}$ pixels of the first line, and so on).



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First Frame

The frame is the "black" frame. The data "1" represents the black color pixel and the data "0" represents the white color pixel.

Data	Pixel Color
1	Black
0	White

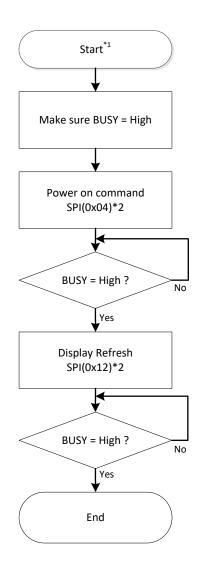
Second Frame

The second frame need to be fed K bytes 0x00. (K: reference Total bytes/frame on previous page.)

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5. Send updating command



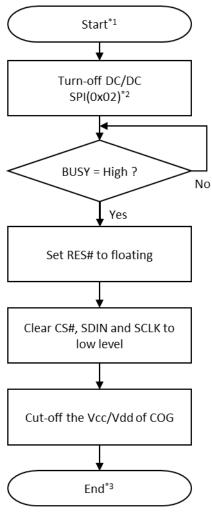
Note:

- 1. Start
 - Follow the end of the input image sequence
- 2. This register does not have data, just need send the index.

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5. Turn-off DC/DC



Note:

- 1. Start
 - Follow the end of the send updating command
- 2. This register does not have data, just need send the index.
- 3. Finished the all of the steps for update the EPD

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Revision History

Version	Date	Page (New)	Section	Description
01	2018/7/11			First issue
02	2022/6/6			Add EPD 2.9" HR(High-resolution)/3.7"/4.37". Modify SPI timing spec and "PSR" data.

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Glossary of Acronyms

EPD Electrophoretic Display (e-Paper Display)

EPD Panel EPD

TCon Timing Controller

FPL Front Plane Laminate (e-Paper Film)

SPI Serial Peripheral Interface

COG Chip on Glass

PDI, PDi Pervasive Displays Incorporated

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