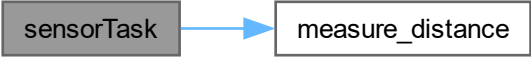


sensorTask



```
graph LR; A[sensorTask] --> B[measure_distance]
```

The diagram consists of two rectangular boxes connected by a horizontal blue arrow. The left box is filled with a dark gray color and contains the text 'sensorTask'. The right box is white with a thin gray border and contains the text 'measure_distance'. The arrow points from the right side of the first box to the left side of the second box.

measure_distance