

Microeconometría I

Maestría en Econometría

Lecture 4

Agenda

1 M-Estimation

- Introduction
- Identification, Uniform Convergence, and Consistency
- Asymptotic Normality

2 Two-Step M-Estimation

- Consistency
- Asymptotic Normality of Two-Step M-Estimators
- Estimating the Asymptotic Variance
- Adjustments for when we cannot ignore the first-stage estimation

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M-Estimation

- M-estimation methods include maximum likelihood, nonlinear least squares, least absolute deviations, quasi-maximum likelihood, and many other procedures used by econometricians.
- In a nonlinear regression model, we have a random variable, y , and we would like to model $E(y|x)$ as a function of the explanatory variables x , a K -vector.
- We already know how to estimate models of $E(y|x)$ when the model is linear in its parameters: OLS produces consistent, asymptotically normal estimators.
- What happens if the regression function is nonlinear in its parameters?

- Generally, let $m(x; \theta)$ be a parametric model for $E(y|x)$, where m is a known function of x and θ , and θ is a $P \times 1$ parameter vector.
- This is a parametric model because $m(x; \theta)$ is assumed to be known up to a finite number of parameters.
- The dimension of the parameters, P , can be less than or greater than K . The parameter space, Θ , is a subset of \mathbb{R}^P
- This is the set of values of y that we are willing to consider in the regression function. Unlike in linear models, for nonlinear models the asymptotic analysis requires explicit assumptions on the parameter space

- An example of a nonlinear regression function is the logistic function, $m(x; \theta) = \exp(x\theta)/[1 + \exp(x\theta)]$. The logistic function is nonlinear in θ .
- We say that we have a correctly specified model for the conditional mean, $E(y|x)$, if, for some $\theta_o \in \Theta$,

$$E(y \mid \mathbf{x}) = m(\mathbf{x}, \theta_o) \quad (1)$$

- We introduce the subscript “o” on theta to distinguish the parameter vector appearing in $E(y|x)$ from other candidates for that vector.
- Often, the value θ_o is called **the true value of theta**.

M-Estimation

- Equation (1) is the most general way of thinking about what nonlinear least squares is intended to do: estimate models of conditional expectations.
- As a statistical matter, equation (1) is equivalent to a model with an additive, unobservable error with a zero conditional mean:

$$y = m(\mathbf{x}, \theta_o) + u, \quad E(u \mid \mathbf{x}) = 0, \quad (2)$$

- Given equation (1), we obtain equation (2) by defining the error to be $u \equiv y - m(\mathbf{x}, \theta_o)$.
- We formalize the first nonlinear least squares (NLS) assumption as follows:
Assumption NLS.1: For some $\theta_o \in \Theta$, $E(y \mid \mathbf{x}) = m(\mathbf{x}, \theta_o)$.

M-Estimation

- If we let $\mathbf{w} \equiv (\mathbf{x}, y)$, then θ_o indexes a feature of the population distribution of \mathbf{w} , namely, the conditional mean of y given \mathbf{x} .
- More generally, let \mathbf{w} be an M -vector of random variables with some distribution in the population.
- We let \mathcal{W} denote the subset of \mathbb{R}^M representing the possible values of \mathbf{w} .
- Let θ_o denote a parameter vector describing some feature of the distribution of \mathbf{w} (i.e. a conditional mean).
- We assume that θ_o belongs to a known parameter space $\Theta \subset \mathbb{R}^P$.
- We assume that our data come as a random sample of size N from the population; we label this random sample $\{\mathbf{w}_i : i = 1, 2, \dots\}$, where each \mathbf{w}_i is an M -vector.

- What allows us to estimate θ_o when it indexes $E(y|x)$? It is the fact that θ_o is the value of θ that minimizes the expected squared error between y and $m(x; \theta)$.
- That is, θ_o solves the population problem

$$\min_{\theta \in \Theta} E \{ [y - m(\mathbf{x}, \theta)]^2 \}, \quad (3)$$

where the expectation is over the joint distribution of (\mathbf{x}, y) .

- Because θ_o solves the population problem in expression (3), the analogy principle suggests estimating θ_o by solving the sample analogue.

M-Estimation

- In other words, we replace the population moment $E \{[(y - m(\mathbf{x}, \boldsymbol{\theta}))]^2\}$ with the sample average.
- The NLS estimator of $\boldsymbol{\theta}_0$, $\hat{\boldsymbol{\theta}}$, solves

$$\min_{\boldsymbol{\theta} \in \Theta} N^{-1} \sum_{i=1}^N [y_i - m(\mathbf{x}_i, \boldsymbol{\theta})]^2 \quad (4)$$

For now, we assume that a solution to this problem exists.

- The NLS objective function in expression (3) is a special case of a more general class of estimators. Let $q(\mathbf{w}, \boldsymbol{\theta})$ be a function of the random vector \mathbf{w} and the parameter vector $\boldsymbol{\theta}$.

M-Estimation

- An M-estimator of θ_o solves the problem

$$\min_{\theta \in \Theta} N^{-1} \sum_{i=1}^N q(\mathbf{w}_i, \theta), \quad (5)$$

assuming that a solution, call it $\hat{\theta}$, exists. The estimator clearly depends on the sample $\{\mathbf{w}_i : i = 1, 2, \dots\}$, but we suppress that fact in the notation.

- The parameter vector θ_o is assumed to uniquely solve the population problem

$$\min_{\theta \in \Theta} E[q(\mathbf{w}, \theta)], \quad (6)$$

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M-Estimation

- How do we translate the fact that θ_o solves the population problem (6) into consistency of the M-estimator $\hat{\theta}$ that solves problem (5)?
- Heuristically, the argument is as follows. Since for each $\theta \in \Theta$, $\{q(\mathbf{w}_i, \theta) : i = 1, 2, \dots\}$ is just an i.i.d. sequence, the law of large numbers implies that

$$N^{-1} \sum_{i=1}^N q(\mathbf{w}_i, \theta) \xrightarrow{P} E[q(\mathbf{w}, \theta)], \quad (7)$$

under very weak finite moment assumptions.

- Since $\hat{\theta}$ minimizes the function on the left hand side of (7) and θ_o minimizes the function on the right, it seems plausible that $\hat{\theta} \xrightarrow{P} \theta_o$.

M-Estimation

- There are essentially two issues to address.
- The first is identifiability of θ_o , which is purely a population issue.
- The second is the sense in which the convergence in equation (7) happens across different values of θ in Θ .
- For nonlinear regression, we showed how θ_o solves the population problem (3). However, we did not argue that θ_o is always the unique solution to problem (3).
- Whether or not this is the case depends on the distribution of \mathbf{x} and the nature of the regression function:
Assumption NLS.2: $E \left\{ [m(\mathbf{x}, \theta_o) - m(\mathbf{x}, \theta)]^2 \right\} > 0$, all $\theta \in \Theta, \theta \neq \theta_o$
- Assumption NLS.2 plays the same role as the assumption of no multicollinearity in OLS.

M-Estimation

- For the general M-estimation case, we assume that $q(\mathbf{w}, \theta)$ has been chosen so that θ_o is a solution to problem (6).
- Identification requires that θ_o be the unique solution:

$$E[q(\mathbf{w}, \theta_o)] < E[q(\mathbf{w}, \theta)], \quad \text{all } \theta \in \Theta, \quad \theta \neq \theta_o, \quad (8)$$

- The second component for consistency of the M-estimator is convergence of the sample average $N^{-1} \sum_{i=1}^N q(\mathbf{w}_i, \theta)$ to its expected value.
- It is not enough to simply invoke the usual weak law of large numbers at each $\theta \in \Theta$.

- Instead, uniform convergence in probability is sufficient. Mathematically,

$$\max_{\theta \in \Theta} \left| N^{-1} \sum_{i=1}^N q(\mathbf{w}_i, \theta) - \mathbb{E}[q(\mathbf{w}, \theta)] \right| \xrightarrow{P} 0, \quad (9)$$

- Uniform convergence clearly implies pointwise convergence, but the converse is not true: it is possible for equation (7) to hold but equation (9) to fail.
- To state a formal result concerning uniform convergence, we need to be more careful in stating assumptions about the function $q(\cdot, \cdot)$ and the parameter space Θ .
- Technically, we should assume that $q(\cdot, \theta)$ is a Borel measurable function on \mathcal{W} for each $\theta \in \Theta$.

- The next assumption concerning q is practically more important.
- We assume that, for each $\mathbf{w} \in \mathcal{W}$, $q(\mathbf{w}, \cdot)$ is a continuous function over the parameter space Θ .
- We can now state a theorem concerning uniform convergence appropriate for the random sampling environment. This result, known as the **uniform weak law of large numbers (UWLLN)**, dates back to LeCam (1953).

Theorem 1 (Uniform Weak Law of Large Numbers): Let \mathbf{w} be a random vector taking values in $\mathcal{W} \subset \mathbb{R}^M$, let Θ be a subset of \mathbb{R}^P and let $q : \mathcal{W} \times \Theta \rightarrow \mathbb{R}$ be a real valued function. Assume that (a) Θ is compact; (b) for each $\theta \in \Theta$, $q(\cdot, \theta)$ is Borel measurable on \mathcal{W} ; (c) for each $\mathbf{w} \in \mathcal{W}$, $q(\mathbf{w}, \cdot)$ is continuous on Θ ; and (d) $|q(\mathbf{w}, \theta)| \leq b(\mathbf{w})$ for all $\theta \in \Theta$, where b is a nonnegative function on \mathcal{W} such that $E[b(\mathbf{w})] < \infty$. Then equation (9) holds.

- **Theorem 2 (Consistency of M-Estimators):** Under the assumptions of Theorem 1, assume that the identification assumption (8) holds. Then a random vector, $\hat{\theta}$, solves problem (5), and $\hat{\theta} \xrightarrow{P} \theta_o$.
- **Lemma 1:** Suppose that $\hat{\theta} \xrightarrow{P} \theta_o$, and assume that $r(\mathbf{w}, \theta)$ satisfies the same assumptions on $q(\mathbf{w}, \theta)$ in Theorem 2. Then

$$N^{-1} \sum_{i=1}^N r(\mathbf{w}_i, \hat{\theta}) \xrightarrow{P} E[r(\mathbf{w}, \theta_o)], \quad (10)$$

That is $N^{-1} \sum_{i=1}^N r(\mathbf{w}_i, \hat{\theta})$ is a consistent estimator of $E[r(\mathbf{w}, \theta_o)]$.

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M-Estimation

- The simplest asymptotic normality proof proceeds as follows.
- Assume that θ_o is in the interior of Θ , which means that Θ must have nonempty interior (this assumption is true in most applications). Then, since $\hat{\theta} \xrightarrow{P} \theta_o$, $\hat{\theta}$ is in the interior of Θ with probability approaching one.
- If $q(\mathbf{w}, \cdot)$ is continuously differentiable on the interior of Θ , then (with probability approaching one) $\hat{\theta}$ solves the first-order condition

$$\sum_{i=1}^N \mathbf{s}(\mathbf{w}_i, \hat{\theta}) = \mathbf{0}, \quad (11)$$

where $\mathbf{s}(\mathbf{w}, \theta)$ is the $P \times 1$ vector of partial derivatives of $q(\mathbf{w}, \theta)$: $\mathbf{s}(\mathbf{w}, \theta)' = \nabla_{\theta} q(\mathbf{w}, \theta) \equiv [\partial q(\mathbf{w}, \theta)/\partial \theta_1, \partial q(\mathbf{w}, \theta)/\partial \theta_2, \dots, \partial q(\mathbf{w}, \theta)/\partial \theta_P]$. (That is, $\mathbf{s}(\mathbf{w}, \theta)$ is the transpose of the gradient of $q(\mathbf{w}, \theta)$).

- We call $\mathbf{s}(\mathbf{w}, \theta)$ **the score of the objective function** $q(\mathbf{w}, \theta)$.

- If $q(\mathbf{w}, \boldsymbol{\theta})$ is twice continuously differentiable, then each row of the left-hand side of equation (11) can be expanded about $\boldsymbol{\theta}_o$ in a mean-value expansion:

$$\sum_{i=1}^N \mathbf{s}(\mathbf{w}_i, \hat{\boldsymbol{\theta}}) = \sum_{i=1}^N \mathbf{s}(\mathbf{w}_i, \boldsymbol{\theta}_o) + \left(\sum_{i=1}^N \ddot{\mathbf{H}}_i \right) (\hat{\boldsymbol{\theta}} - \boldsymbol{\theta}_o), \quad (12)$$

- The notation $\ddot{\mathbf{H}}_i$ denotes the $P \times P$ Hessian of the objective function, $q(\mathbf{w}_i, \boldsymbol{\theta})$, with respect to $\boldsymbol{\theta}$, but with each row of $\mathbf{H}(\mathbf{w}_i, \boldsymbol{\theta}) \equiv \partial^2 q(\mathbf{w}_i, \boldsymbol{\theta}) / \partial \boldsymbol{\theta} \partial \hat{\boldsymbol{\theta}}' \equiv \nabla_{\boldsymbol{\theta}}^2 q(\mathbf{w}_i, \boldsymbol{\theta})$ evaluated at a different mean value.

M-Estimation

- Combining equations (11) and (12) and multiplying through by $1/\sqrt{N}$ gives

$$\mathbf{0} = N^{-1/2} \sum_{i=1}^N \mathbf{s}(\mathbf{w}_i, \boldsymbol{\theta}_o) + \left(N^{-1} \sum_{i=1}^N \ddot{\mathbf{H}}_i \right) \sqrt{N} (\hat{\boldsymbol{\theta}} - \boldsymbol{\theta}_o), \quad (13)$$

- Using **Lemma 1** we get $N^{-1} \sum_{i=1}^N \ddot{\mathbf{H}}_i \xrightarrow{p} E[\mathbf{H}(\mathbf{w}, \boldsymbol{\theta}_o)]$.
- If $\mathbf{A}_o \equiv E[\mathbf{H}(\mathbf{w}, \boldsymbol{\theta}_o)]$ is nonsingular, then $N^{-1} \sum_{i=1}^N \ddot{\mathbf{H}}_i$ is nonsingular w.p.a. 1 and $\left(N^{-1} \sum_{i=1}^N \ddot{\mathbf{H}}_i \right)^{-1} \xrightarrow{p} \mathbf{A}_o^{-1}$.
- Therefore, we can write

$$\sqrt{N} (\hat{\boldsymbol{\theta}} - \boldsymbol{\theta}_o) = \left(N^{-1} \sum_{i=1}^N \ddot{\mathbf{H}}_i \right)^{-1} \left[-N^{-1/2} \sum_{i=1}^N \mathbf{s}_i(\boldsymbol{\theta}_o) \right], \quad (14)$$

where $\mathbf{s}_i(\boldsymbol{\theta}_o) \equiv \mathbf{s}(\mathbf{w}_i, \boldsymbol{\theta}_o)$.

M-Estimation

- Since $o_p(1) \cdot O_p(1) = o_p(1)$ we have,

$$\sqrt{N}(\hat{\theta} - \theta_o) = \mathbf{A}_o^{-1} \left[-N^{-1/2} \sum_{i=1}^N \mathbf{s}_i(\theta_o) \right] + o_p(1), \quad (15)$$

- This is an important equation. It shows that $\sqrt{N}(\theta - \theta_o)$ inherits its limiting distribution from the average of the scores, evaluated at θ_o . The matrix \mathbf{A}_o^{-1} simply acts as linear transformation.
- Absorbing this linear transformation into $\mathbf{s}_i(\theta_o)$, we can write

$$\sqrt{N}(\hat{\theta} - \theta_o) = N^{-1/2} \sum_{i=1}^N \mathbf{e}_i(\theta_o) + o_p(1), \quad (16)$$

where $\mathbf{e}_i(\theta_o) \equiv -\mathbf{A}_o^{-1} \mathbf{s}_i(\theta_o)$; this is sometimes called the **influence function representation** of θ , where $\mathbf{e}(\mathbf{w}, \theta)$ is the influence function.

- **THEOREM 3 (Asymptotic Normality of M-Estimators):** In addition to the assumptions in Theorem 2, assume (a) θ_o is in the interior of Θ ; (b) $\mathbf{s}(\mathbf{w}, \cdot)$ is continuously differentiable on the interior of Θ for all $\mathbf{w} \in \mathcal{W}$; (c) Each element of $\mathbf{H}(\mathbf{w}, \theta)$ is bounded in absolute value by a function $b(\mathbf{w})$, where $E[b(\mathbf{w})] < \infty$; (d) $\mathbf{A}_o \equiv E[\mathbf{H}(\mathbf{w}, \theta_o)]$ is positive definite; (e) $E[\mathbf{s}(\mathbf{w}, \theta_o)] = \mathbf{0}$; and (f) each element of $\mathbf{s}(\mathbf{w}, \theta_o)$ has finite second moment. Then

$$\sqrt{N}(\hat{\theta} - \theta_o) \xrightarrow{d} \text{Normal}(0, \mathbf{A}_o^{-1} \mathbf{B}_o \mathbf{A}_o^{-1}), \quad (17)$$

where $\mathbf{A}_o \equiv E[\mathbf{H}(\mathbf{w}, \theta_o)]$ and $\mathbf{B}_o \equiv E[\mathbf{s}(\mathbf{w}, \theta_o) \mathbf{s}(\mathbf{w}, \theta_o)'] = \text{Var}[\mathbf{s}(\mathbf{w}, \theta_o)]$

- Thus,

$$\text{Avar}(\hat{\theta}) = \mathbf{A}_o^{-1} \mathbf{B}_o \mathbf{A}_o^{-1} / N, \quad (18)$$

Two-Step M-Estimators

- Sometimes applications of M-estimators involve a first-stage estimation (an example is OLS with generated regressors).
- Let $\hat{\gamma}$ be a preliminary estimator, usually based on the random sample $\{\mathbf{w}_i : i = 1, 2, \dots, N\}$.
- A two-step M-estimator θ of θ_0 solves the problem

$$\min_{\theta \in \Theta} \sum_{i=1}^N q(\mathbf{w}_i, \theta; \hat{\gamma}), \quad (19)$$

where q is now defined on $\mathcal{W} \times \Theta \times \Gamma$, and Γ is a subset of \mathbb{R}^J .

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Two-Step M-Estimators

- For the general two-step M-estimator, when will $\hat{\theta}$ be consistent for θ_o ?
- In practice, the important condition is the identification assumption.
- To state the identification condition, we need to know about the asymptotic behavior of $\hat{\gamma}$.
- A general assumption is that $\hat{\gamma} \xrightarrow{P} \gamma^*$, where γ^* is some element in Γ .
- The identification condition for the two-step M-estimator is

$$E[q(\mathbf{w}, \theta_o; \gamma^*)] < E[q(\mathbf{w}, \theta; \gamma^*)] \text{ all } \theta \in \Theta, \quad \theta \neq \theta_o, \quad (20)$$

Two-Step M-Estimators

- The consistency argument is essentially the same as that underlying Theorem 2. If $q(\mathbf{w}_i, \boldsymbol{\theta}; \gamma)$ satisfies the UWLLN over $\Theta \times \Gamma$ then expression (19) can be shown to converge to $E[q(\mathbf{w}, \boldsymbol{\theta}; \gamma^*)]$ uniformly over Θ . Along with identification, this result can be shown to imply consistency of $\hat{\boldsymbol{\theta}}$ for $\boldsymbol{\theta}_0$.

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Two-Step M-Estimators

- With the two-step M-estimator, there are two cases worth distinguishing.
- The first occurs when the asymptotic variance of $\sqrt{N}(\hat{\theta} - \theta_o)$ does not depend on the asymptotic variance of $\sqrt{N}(\hat{\gamma} - \gamma^*)$.
- The second occurs when the asymptotic variance of $\sqrt{N}(\hat{\theta} - \theta_o)$ should be adjusted to account for the first-stage estimation of γ^* .
- We first derive conditions under which we can ignore the first-stage estimation error.

Two-Step M-Estimators

- first derive conditions under which we can ignore the first-stage estimation error.
- Using arguments similar to those used to derive the asymptotic normality of M-estimators, it can be shown that, under standard regularity conditions,

$$\sqrt{N} \left(\hat{\boldsymbol{\theta}} - \boldsymbol{\theta}_o \right) = \mathbf{A}_o^{-1} \left(-N^{-1/2} \sum_{i=1}^N \mathbf{s}_i(\boldsymbol{\theta}_o; \hat{\gamma}) \right) + o_p(1), \quad (21)$$

where now $\mathbf{A}_o = E[\mathbf{H}(\mathbf{w}, \boldsymbol{\theta}_o; \gamma^*)]$.

- In obtaining the score and the Hessian, we take derivatives only with respect to $\boldsymbol{\theta}$; γ^* simply appears as an extra argument.

Two-Step M-Estimators

- Now if,

$$N^{-1/2} \sum_{i=1}^N \mathbf{s}_i(\boldsymbol{\theta}_o; \hat{\boldsymbol{\gamma}}) = N^{-1/2} \sum_{i=1}^N \mathbf{s}_i(\boldsymbol{\theta}_o; \boldsymbol{\gamma}^*) + o_p(1), \quad (22)$$

- Then $\sqrt{N}(\hat{\boldsymbol{\theta}} - \boldsymbol{\theta}_o)$ behaves the same asymptotically whether we used $\hat{\boldsymbol{\gamma}}$ or its plim in defining the M-estimator.
- When does equation (22) hold?

Two-Step M-Estimators

- Assuming that $\sqrt{N}(\hat{\gamma} - \gamma^*) = O_p(1)$ (which is standard).
- A mean value expansion similar to (12) gives

$$N^{-1/2} \sum_{i=1}^N \mathbf{s}_i(\boldsymbol{\theta}_0; \hat{\gamma}) = N^{-1/2} \sum_{i=1}^N \mathbf{s}_i(\boldsymbol{\theta}_0; \gamma^*) + \mathbf{F}_0 \sqrt{N}(\hat{\gamma} - \gamma^*) + o_p(1), \quad (23)$$

where \mathbf{F}_0 is the $P \times J$ matrix $\mathbf{F}_0 \equiv E[\nabla_{\gamma} \mathbf{s}(\mathbf{w}, \boldsymbol{\theta}_0; \gamma^*)]$.

- Therefore if

$$E[\nabla_{\gamma} \mathbf{s}(\mathbf{w}, \boldsymbol{\theta}_0; \gamma^*)] = \mathbf{0}, \quad (24)$$

then equation (22) holds.

- And the asymptotic variance of the two-step M-estimator is the same as if γ^* were plugged in.

Two-Step M-Estimators

- There are many problems for which assumption (24) does not hold.
- These problems include some the methods for correcting for endogeneity in Probit and Tobit models.
- In such cases we need to make an adjustment to the asymptotic variance of $\sqrt{N}(\hat{\theta} - \theta_o)$.
- Assume

$$\sqrt{N}(\hat{\gamma} - \gamma^*) = N^{-1/2} \sum_{i=1}^N \mathbf{r}_i(\gamma^*) + o_p(1), \quad (25)$$

where $\mathbf{r}_i(\gamma^*)$ is a $J \times 1$ vector with $E[\mathbf{r}_i(\gamma^*)] = \mathbf{0}$.

Two-Step M-Estimators

- Now using equation (23) we can write

$$\sqrt{N} \left(\hat{\theta} - \theta_o \right) = \mathbf{A}_o^{-1} N^{-1/2} \sum_{i=1}^N [-\mathbf{g}_i(\theta_o; \gamma^*)] + o_p(1), \quad (26)$$

where $\mathbf{g}_i(\theta_o; \gamma^*) \equiv \mathbf{s}_i(\theta_o; \gamma^*) + \mathbf{F}_o \mathbf{r}_i(\gamma^*)$.

- Since $\mathbf{g}_i(\theta_o; \gamma^*)$ has zero mean, the standardized partial sum in equation (26) can be assumed to satisfy the central limit theorem.
- Define the $P \times P$ matrix

$$\mathbf{D}_o \equiv E \left[\mathbf{g}_i(\theta_o; \gamma^*) \mathbf{g}_i(\theta_o; \gamma^*)' \right] = \text{Var} [\mathbf{g}_i(\theta_o; \gamma^*)], \quad (27)$$

- Then

$$\text{Avar} \sqrt{N} \left(\hat{\theta} - \theta_o \right) = \mathbf{A}_o^{-1} \mathbf{D}_o \mathbf{A}_o^{-1}, \quad (28)$$

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Two-Step M-Estimators

- We first consider estimating the asymptotic variance of $\hat{\boldsymbol{\theta}}$ in the case where there are no nuisance parameters.
- Under regularity conditions that ensure uniform convergence of the Hessian, the estimator

$$N^{-1} \sum_{i=1}^N \mathbf{H}(\mathbf{w}_i, \hat{\boldsymbol{\theta}}) \equiv N^{-1} \sum_{i=1}^N \hat{\mathbf{H}}_i, \quad (29)$$

is consistent for \mathbf{A}_o , by Lemma 1.

- By Lemma 1, under standard regularity conditions we have

$$N^{-1} \sum_{i=1}^N \mathbf{s}(\mathbf{w}_i, \hat{\boldsymbol{\theta}}) \mathbf{s}(\mathbf{w}_i, \hat{\boldsymbol{\theta}})' \equiv N^{-1} \sum_{i=1}^N \hat{\mathbf{s}}_i \hat{\mathbf{s}}_i' \xrightarrow{P} \mathbf{B}_o. \quad (30)$$

Two-Step M-Estimators

- Combining equations (29) and (30) we can consistently estimate $\text{Avar} \sqrt{N} (\hat{\theta} - \theta_o)$ by

$$\text{Avar} \sqrt{N} (\hat{\theta} - \theta_o) = \hat{\mathbf{A}}^{-1} \hat{\mathbf{B}} \hat{\mathbf{A}}^{-1}, \quad (31)$$

- The asymptotic standard errors are obtained from the matrix

$$\hat{\mathbf{V}} \equiv \widehat{\text{Avar}(\hat{\theta})} = \hat{\mathbf{A}}^{-1} \hat{\mathbf{B}} \hat{\mathbf{A}}^{-1} / N. \quad (32)$$

- Which can be expressed as

$$\left(\sum_{i=1}^N \hat{\mathbf{H}}_i \right)^{-1} \left(\sum_{i=1}^N \hat{\mathbf{s}}_i \hat{\mathbf{s}}_i' \right) \left(\sum_{i=1}^N \hat{\mathbf{H}}_i \right)^{-1}. \quad (33)$$

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Two-Step M-Estimators

- When assumption (24) is violated, the asymptotic variance estimator of $\hat{\theta}$ must account for the asymptotic variance of $\hat{\gamma}$.
- We need to estimate equation (28).
- We already know how to consistently estimate \mathbf{A}_o using equation (29).
- Estimation of \mathbf{D}_o is also straightforward.
- First we need to estimate \mathbf{F}_o ,

$$\hat{\mathbf{F}} = N^{-1} \sum_{i=1}^N \nabla_{\gamma} \mathbf{s}_i(\hat{\theta}; \hat{\gamma}), \quad (34)$$

Two-Step M-Estimators

- Next, replace $\mathbf{r}_i(\gamma^*)$ with $\hat{\mathbf{r}}_i \equiv \mathbf{r}_i(\hat{\gamma})$.
- Then

$$\hat{\mathbf{D}} \equiv N^{-1} \sum_{i=1}^N \hat{\mathbf{g}}_i \hat{\mathbf{g}}_i' \xrightarrow{P} \mathbf{D}_o, \quad (35)$$

where $\hat{\mathbf{g}}_i = \hat{\mathbf{s}}_i + \mathbf{F} \hat{\mathbf{r}}_i$.

- The asymptotic variance of the two-step M-estimator is,

$$\left(\sum_{i=1}^N \hat{\mathbf{H}}_i \right)^{-1} \left(\sum_{i=1}^N \hat{\mathbf{g}}_i \hat{\mathbf{g}}_i' \right) \left(\sum_{i=1}^N \hat{\mathbf{H}}_i \right)^{-1}. \quad (36)$$