

Planning Problem

Plan

1	2	3
0	7	4
3	6	8

Init

0	1	2
3	4	5
6	7	8

Goal

LatPlan

1	2	3
0	7	4
3	6	8

1	2	3
3	7	4
0	6	8

1	2	3
3	7	4
6	0	8

1	2	3
3	0	4
6	7	8

1	0	3
3	7	4
6	2	8

1	7	3
3	0	4
6	2	8

1	7	3
3	4	0
6	2	8

1	7	0
3	4	5
6	2	8

1	0	2
3	4	5
6	7	8

0	1	2
3	4	5
6	7	8