

Environment

**Observer
(Goal Recognizer)**



*Recognized
Goal (s)*

**Incomplete
Domain
Model**

Observations

$[o1, o2, o3, o4, o5]$

Observed Agent



Plan Execution

$[a1, a2, a3, a4, a5]$

**Complete
Domain
Model**

*Missing
and/or Noisy
Observations*

