

Homework of Motion Planning for Mobile Robots

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Abstract

This is the homework of the chapter 1

Keywords: ROS, Ubuntu, rviz

1. Introduction

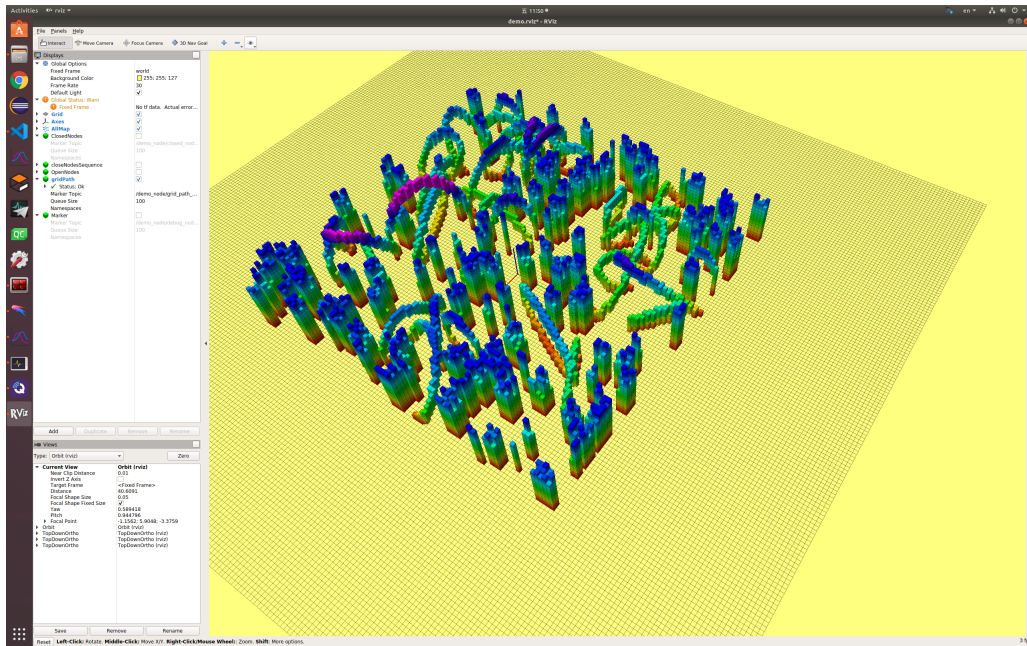


Figure 1: Rviz

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