Homework of Motion Planning for Mobile Robots

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Abstract

Corridor-based and Bezier-based Minimum Snap Trajectory Optimization.
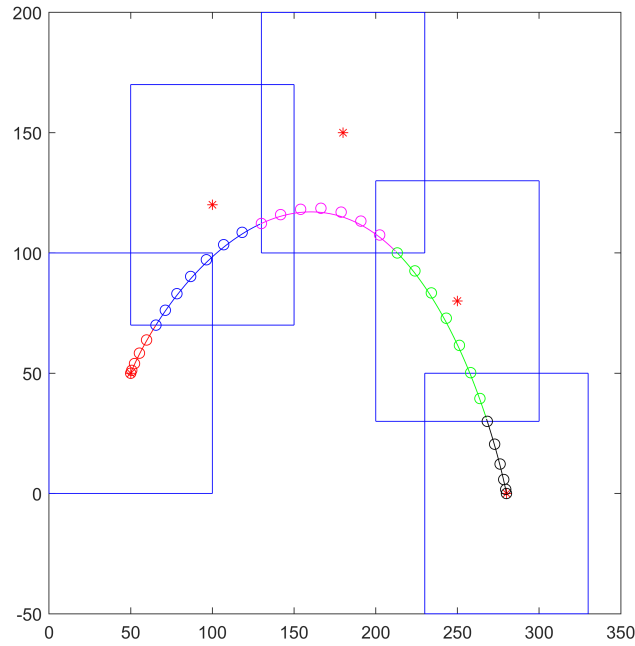
Keywords: Trajectory Generation

1. MATLAB

Figure 1: hw 6 simulation resutls

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