

Finite Difference Method in Option Pricing

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Goals for Today

1. Introduction of the model
2. Finite difference method
 - a. Explicit scheme
 - b. Implicit scheme
3. Empirical results
4. Conclusion



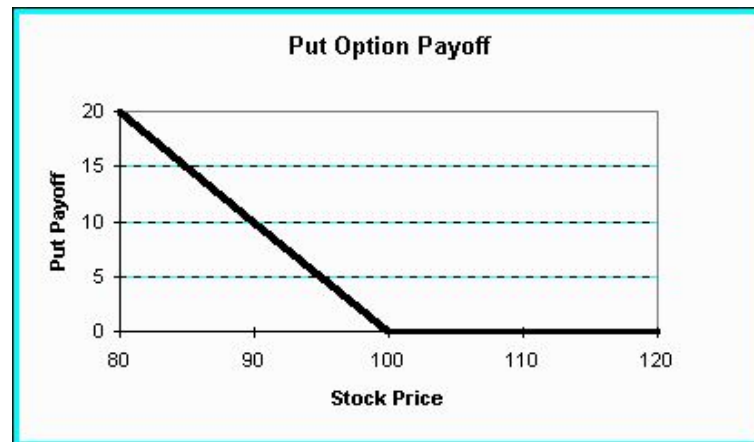
Introduction of the Model

What is an option?

Call (put) option is a contract that gives its holder the right to buy (sell) a specific quantity of a specified financial asset (underlying asset) at a specified price (strike/exercise price) on or before a specified date (expiration/maturity date).

$$V_T = \begin{cases} (S_T - X)^+, & \text{for call;} \\ (X - S_T)^+, & \text{for put.} \end{cases}$$

Problem: How much does these guys worth NOW?



Black-Scholes PDE (1973)

In Black-Scholes world:

- Underlier price follows a Geometric Brownian Motion.
- Risk free rate and underlier volatility are constant.
- Trading is continuous.
- No transaction costs, no taxes.

$$\frac{\partial v}{\partial t} + \frac{1}{2}\sigma^2 S^2 \frac{\partial^2 v}{\partial S^2} + (r - q)S \frac{\partial v}{\partial S} - rv = 0,$$

subject to the terminal condition:

$$v(S_T, T) = \begin{cases} (S_T - X)^+, & \text{call;} \\ (X - S_T)^+, & \text{put.} \end{cases}$$

Analytical Solution


Introduce the change-of-variable transformation

$$\tau = T - t$$

$$u = Ce^{r\tau}$$

$$x = \ln\left(\frac{S}{K}\right) + \left(r - \frac{1}{2}\sigma^2\right)\tau$$

Then the Black-Scholes PDE becomes a heat equation

$$\frac{\partial u}{\partial \tau} = \frac{1}{2}\sigma^2 \frac{\partial^2 u}{\partial x^2}$$


Analytical Solution

For European vanilla options, the solution to the Black-Scholes PDE is

$$v(S_t, t) = \begin{cases} e^{-q(T-t)} S_t N(d_1) - X e^{-r(T-t)} N(d_2), & \text{call;} \\ X e^{-r(T-t)} N(-d_2) - e^{-q(T-t)} S_t N(-d_1), & \text{put} \end{cases}$$

where

$$d_1 = \frac{\ln(S_t/X) + (r - q + \sigma^2/2)(T - t)}{\sigma \sqrt{T - t}},$$

$$d_2 = d_1 - \sigma \sqrt{T - t},$$

$$N(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^x e^{-y^2/2} dy.$$

Finite Difference Method

Domain Discretization

(S_n^i, t_n) , $i = 0, 1, \dots, I$, $n = 0, 1, \dots, N$, Where $S_n^i = ih$, $t_n = n\Delta t$

The domain $S \geq 0$ is truncated to $S \in [0, S_{max}]$

$$S_{max} = S_n^I = Ih \quad \text{and} \quad T = N\Delta t.$$

Option values at grid points are $v_n^i = v(S_n^i, t_n)$

(For put option) Boundary conditions are:

$$V_N^i = (X - ih)^+ \quad \text{At } t = T$$

$$V_N^0 = X e^{-r(T-n\Delta t)} \quad \text{At } S = 0; \quad V_n^I = 0 \quad \text{At } S = S_{max}$$

Explicit Scheme

P A R E N T A L

A D V I S O R Y

E X P L I C I T C O N T E N T

Explicit Scheme

Evaluate the PDE at (S_{n+1}^i, t_{n+1})

$$\left. \frac{\partial v}{\partial t} \right|_{(S_{n+1}^i, t_{n+1})} + \frac{1}{2} \sigma^2 S^2 \left. \frac{\partial^2 v}{\partial S^2} \right|_{(S_{n+1}^i, t_{n+1})} + r S \left. \frac{\partial v}{\partial S} \right|_{(S_{n+1}^i, t_{n+1})} - r v \Big|_{(S_{n+1}^i, t_{n+1})} = 0$$

Use backward time, and centered space

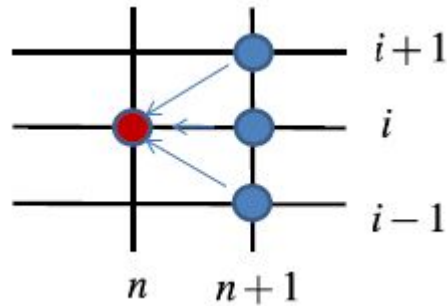
$$\frac{v_{n+1}^i - v_n^i}{\Delta t} + \frac{1}{2} \sigma^2 i^2 h^2 \frac{v_{n+1}^{i+1} - 2v_{n+1}^i + v_{n+1}^{i-1}}{h^2} + r i h \frac{v_{n+1}^{i+1} - v_{n+1}^{i-1}}{2h} - r v_{n+1}^i + O(\Delta t + h^2) = 0.$$

Explicit Scheme

Dropping the truncation error, and re-arranging the terms, we get

$$V_n^i = \frac{1}{2} (\sigma^2 i^2 - r i) \Delta t V_{n+1}^{i-1} + (1 - \sigma^2 i^2 \Delta t - r \Delta t) V_{n+1}^i + \frac{1}{2} (\sigma^2 i^2 + r i) \Delta t V_{n+1}^{i+1}.$$

The stencil is like:



Stability

We have $V_n^i = a_i V_{n+1}^{i-1} + b_i V_{n+1}^i + c_i V_{n+1}^{i+1}$

A sufficient condition:

$$a_i \geq 0, b_i \geq 0, c_i \geq 0 \text{ for all } i.$$



Stable? $V_n^i = \frac{1}{2} (\sigma^2 i^2 - ri) \Delta t V_{n+1}^{i-1} + (1 - \sigma^2 i^2 \Delta t - r \Delta t) V_{n+1}^i + \frac{1}{2} (\sigma^2 i^2 + ri) \Delta t V_{n+1}^{i+1}.$

$1 - \sigma^2 i^2 \Delta t - r \Delta t$ and $\frac{1}{2} (\sigma^2 i^2 - ri)$ are likely to be negative

Problem!!!

–How?

Approximate $v(S_{n+1}^i, t_{n+1})$ by v_n^i



Explicit Scheme (II)

Evaluate the PDE at (S_{n+1}^i, t_{n+1})

$$\frac{v_{n+1}^i - v_n^i}{\Delta t} + \frac{1}{2} \sigma^2 i^2 h^2 \frac{v_{n+1}^{i+1} - 2v_{n+1}^i + v_{n+1}^{i-1}}{h^2} + r i h \frac{v_{n+1}^{i+1} - v_{n+1}^{i-1}}{2h} - r v_n^i + O(\Delta t) + O(\Delta t + h^2) = 0$$

Dropping the truncation error, and re-arranging the terms, we get

$$V_n^i = \frac{1}{1 + r\Delta t} \left[\frac{1}{2} (\sigma^2 i^2 - r i) \Delta t V_{n+1}^{i-1} + (1 - \sigma^2 i^2 \Delta t) V_{n+1}^i + \frac{1}{2} (\sigma^2 i^2 + r i) \Delta t V_{n+1}^{i+1} \right]$$

Stable?
$$V_n^i = \frac{1}{1+r\Delta t} \left[\frac{1}{2} (\sigma^2 i^2 - ri) \Delta t V_{n+1}^{i-1} + (1 - \sigma^2 i^2 \Delta t) V_{n+1}^i + \frac{1}{2} (\sigma^2 i^2 + ri) \Delta t V_{n+1}^{i+1} \right]$$

We now requires $1 - \sigma^2 i^2 \Delta t > 0$

(Also need to notice the possibility that $\sigma^2 i < r$)

--How?

Consider

$$\left. \frac{\partial v}{\partial S} \right|_{(S_{n+1}^i, t_{n+1})} = \frac{v_{n+1}^{i+1} - v_{n+1}^i}{h} + O(h)$$



Explicit Scheme (III)

Evaluate the PDE at (S_{n+1}^i, t_{n+1})

$$\frac{v_{n+1}^i - v_n^i}{\Delta t} + \frac{1}{2} \sigma^2 i^2 h^2 \frac{v_{n+1}^{i+1} - 2v_{n+1}^i + v_{n+1}^{i-1}}{h^2} + r i h \frac{v_{n+1}^{i+1} - v_{n+1}^i}{h} - r v_n^i + O(\Delta t) + O(\Delta t + h) = 0.$$

Dropping the truncation error, and re-arranging the terms, we get

$$V_n^i = \frac{1}{1 + r\Delta t} \left[\frac{1}{2} \sigma^2 i^2 \Delta t V_{n+1}^{i-1} + (1 - \sigma^2 i^2 \Delta t - r i \Delta t) V_{n+1}^i + \frac{1}{2} (\sigma^2 i^2 + r i) \Delta t V_{n+1}^{i+1} \right]$$

Stable? $V_n^i = \frac{1}{1+r\Delta t} \left[\frac{1}{2} \sigma^2 i^2 \Delta t V_{n+1}^{i-1} + (1 - \sigma^2 i^2 \Delta t - ri\Delta t) V_{n+1}^i + \frac{1}{2} (\sigma^2 i^2 + ri) \Delta t V_{n+1}^{i+1} \right]$

We now ONLY requires $1 - \sigma^2 i^2 \Delta t - ri\Delta t > 0$



Matrix Form

Recall the boundary condition

$$t = T \quad V_N^i = (X - ih)^+ \quad S = 0: \quad V_N^0 = X e^{-r(T-n\Delta t)} \quad S = S_{max} \quad V_n^I = 0$$

$$\begin{bmatrix} V_n^1 \\ V_n^2 \\ \vdots \\ V_n^{I-2} \\ V_n^{I-1} \end{bmatrix} = \begin{bmatrix} b_1 & c_1 & & & \\ a_2 & b_2 & c_2 & & \\ & \ddots & \ddots & & \\ & & a_{I-2} & b_{I-2} & c_{I-2} \\ & & & a_{I-1} & b_{I-1} \end{bmatrix} \begin{bmatrix} V_{n+1}^1 \\ V_{n+1}^2 \\ \vdots \\ V_{n+1}^{I-2} \\ V_{n+1}^{I-1} \end{bmatrix} + \begin{bmatrix} a_1 V_{n+1}^0 \\ 0 \\ \vdots \\ 0 \\ c_{I-1} V_{n+1}^I \end{bmatrix}$$

Matlab Implementation

```
% Explicit Scheme I
% c=(0.5*sig^2*isq+0.5*r*i)*dt;
% b=1-sig^2*isq*dt-r*dt;
% a=(0.5*sig^2*isq-0.5*r*i)*dt;
% Explicit Scheme II
c=(0.5*sig^2*isq+0.5*r*i)*dt/(1+r*dt);
b=(1-sig^2*isq*dt)/(1+r*dt);
a=(0.5*sig^2*isq-0.5*r*i)*dt/(1+r*dt);
% Explicit Scheme III
% c=(0.5*sig^2*isq+r*i)*dt/(1+r*dt);
% b=(1-sig^2*isq*dt-r*i*dt)/(1+r*dt);
% a=(0.5*sig^2*isq)*dt/(1+r*dt);

for n=N:-1:1
    VGrid(i,n)=a.*VGrid(i-1,n+1)+b.*VGrid(i,n+1)+c.*VGrid(i+1,n+1);
end;
```

Implicit Scheme

Implicit Scheme

Evaluate the PDE at (S_n^i, t_n)

$$\left. \frac{\partial v}{\partial t} \right|_{(S_n^i, t_n)} + \frac{1}{2} \sigma^2 S^2 \left. \frac{\partial^2 v}{\partial S^2} \right|_{(S_n^i, t_n)} + r S \left. \frac{\partial v}{\partial S} \right|_{(S_n^i, t_n)} - r v \Big|_{(S_n^i, t_n)} = 0.$$

Use forward time, centered space

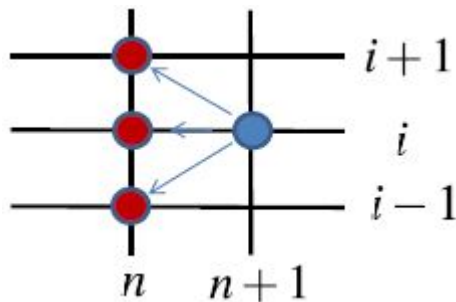
$$\frac{v_{n+1}^i - v_n^i}{\Delta t} + \frac{1}{2} \sigma^2 i^2 h^2 \frac{v_n^{i-1} - 2v_n^i + v_n^{i+1}}{h^2} + r i h \frac{v_n^{i+1} - v_n^{i-1}}{2h} - r v_n^i + O(\Delta t + h^2) = 0.$$

Implicit Scheme

Dropping the truncation error, and re-arranging the terms, we get

$$V_{n+1}^i = -\frac{1}{2}(\sigma^2 i^2 - ri)\Delta t V_n^{i-1} + (1 + \sigma^2 i^2 \Delta t + r\Delta t)V_n^i - \frac{1}{2}(\sigma^2 i^2 + ri)\Delta t V_n^{i+1}$$

The stencil is like:



Stability

We have $a_i V_n^{i-1} + b_i V_n^i + c_i V_n^{i+1} = V_{n+1}^i$, $i = 1, 2, \dots, I-1$.

In matrix form:

$$\begin{bmatrix} b_1 & c_1 & & & \\ a_2 & b_2 & c_2 & & \\ & \ddots & \ddots & \ddots & \\ & & a_{I-2} & b_{I-2} & c_{I-2} \\ & & & a_{I-1} & b_{I-1} \end{bmatrix} \begin{bmatrix} V_n^1 \\ V_n^2 \\ \vdots \\ V_n^{I-2} \\ V_n^{I-1} \end{bmatrix} = \begin{bmatrix} V_{n+1}^1 \\ V_{n+1}^2 \\ \vdots \\ V_{n+1}^{I-2} \\ V_{n+1}^{I-1} \end{bmatrix} + \begin{bmatrix} -a_1 V_n^0 \\ 0 \\ \vdots \\ 0 \\ -c_{I-1} V_n^I \end{bmatrix}$$

A sufficient condition: “ $a_i \leq 0, c_i \leq 0$ $b_i > |a_i| + |c_i|$ ”



Stability

In our scheme:

$$a_i = -\frac{1}{2}(\sigma^2 i^2 - ri)\Delta t V_n^{i-1}$$

We are then motivated to do the change:

$$\left. \frac{\partial V}{\partial S} \right|_{(S_n^i, t_n)} = \frac{V_n^{i+1} - V_n^i}{h} + O(h)$$



Implicit Scheme (II)

$$\frac{v_{n+1}^i - v_n^i}{\Delta t} + \frac{1}{2} \sigma^2 i^2 h^2 \frac{v_n^{i-1} - 2v_n^i + v_n^{i+1}}{h^2} + r i h \frac{v_n^{i+1} - v_n^i}{h} - r v_n^i + O(\Delta t + h) = 0.$$

Dropping the truncation error, and re-arranging the terms, we get



$$-\frac{1}{2} \sigma^2 i^2 \Delta t V_n^{i-1} + (1 + \sigma^2 i^2 \Delta t + r \Delta t (1 + i)) V_n^i - \frac{1}{2} (\sigma^2 i^2 + r i) \Delta t V_n^{i+1} = V_{n+1}^i$$

Matlab Implementation

```
a= -0.5*(sig^2*isq - r*i)*dt;  
b=(1 + sig^2*isq*dt + r*dt);  
c= -0.5*(sig^2*isq + r*i)*dt;  
  
% Set up sparse tri-diagonal matrix of coefficients  
CoeffMatrix=spdiags([c, b, a],-1:1, I-1, I-1)';  
ishift=1;  
for n=N:-1:1 % backward time recursive  
    RhsB=VGrid(i+ishift,n+1); % set up right hand side vector  
    RhsB(1) =RhsB(1) -a(1) *VGrid(0+ishift,n);  
    RhsB(I-1)=RhsB(I-1)-c(I-1)*VGrid(I+ishift,n);  
    VGrid(i+ishift,n)=CoeffMatrix\RhsB; % solve linear system  
end;
```

No Loop

But need to solve a matrix



Empirical Results

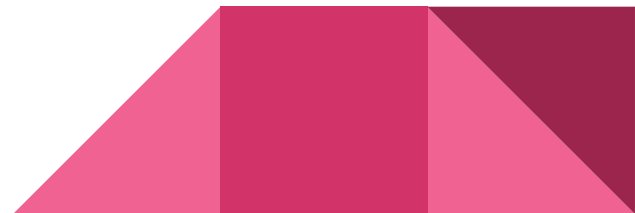
Problem

The case: $S_0 = \$100$, $X = \$98$, $r = 0.02$, $T = 0.2$, $\sigma = 20\%$

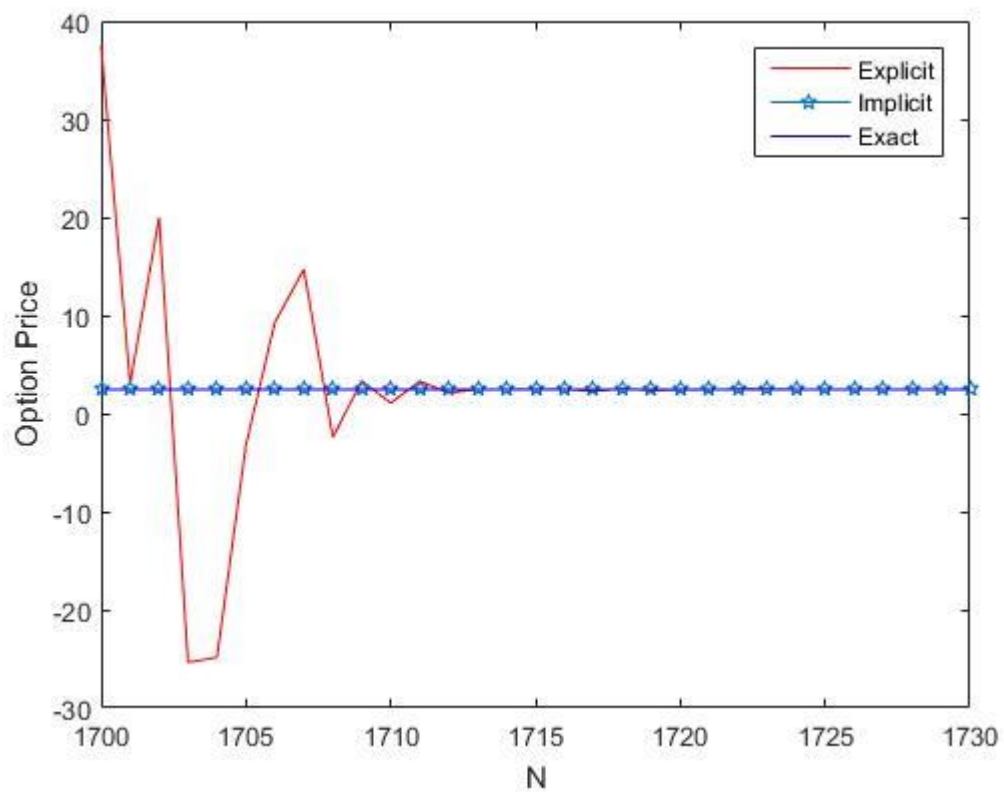
$$S_{max} = 3X, \Delta S = 0.5$$

$$\Delta t = T/N, N = 1700, 1701, \dots, 1730$$

Why use these N values?



Result

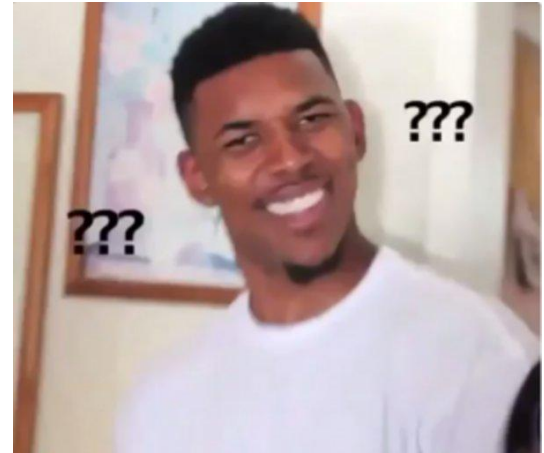


Stability--Explicit Scheme

```
>> FD_eds_put(100, 98, 0.02, 0.2, 0.2, 1730, 0.5)
Coeff a, Of 587 elements, 0 violated the positivity condition.
Coeff b, Of 587 elements, 122 violated the positivity condition.
Coeff c, Of 587 elements, 0 violated the positivity condition.
At S0=100 exact value=2.457 FD value=2.4691
```

What if $\Delta S = 0.49$?

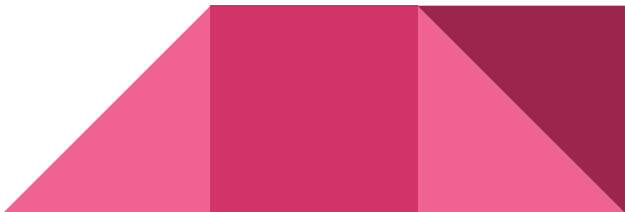
```
>> FD_eds_put(100, 98, 0.02, 0.2, 0.2, 1730, 0.49)
Coeff a, Of 599 elements, 0 violated the positivity condition.
Coeff b, Of 599 elements, 134 violated the positivity condition.
Coeff c, Of 599 elements, 0 violated the positivity condition.
At S0=100 exact value=2.457 FD value=-1.59523486575866e+18
```



Stability--Explicit Scheme

```
>> FD_eds_put(100, 98, 0.02, 0.2, 0.2, 3000, 0.5)
Coeff a, Of 587 elements, 0 violated the positivity condition.
Coeff b, Of 587 elements, 0 violated the positivity condition.
Coeff c, Of 587 elements, 0 violated the positivity condition.
At S0=100 exact value=2.457 FD value=2.4558
```

```
>> FD_eds_put(100, 98, 0.02, 0.2, 0.2, 3000, 0.49)
Coeff a, Of 599 elements, 0 violated the positivity condition.
Coeff b, Of 599 elements, 0 violated the positivity condition.
Coeff c, Of 599 elements, 0 violated the positivity condition.
At S0=100 exact value=2.457 FD value=2.4709
```



Stability--Implicit Scheme

```
>> FD_ids_put(100, 98, 0.02, 0.2, 0.2, 1730, 0.5)
```

```
At S0=100 exact value=2.457 FD value=2.4554
```

```
>> FD_ids_put(100, 98, 0.02, 0.2, 0.2, 1730, 0.49)
```

```
At S0=100 exact value=2.457 FD value=2.4705
```




Conclusion

Explicit vs Implicit

Explicit schemes

- Advantages:
 - There is no need to solve a system of equations.
 - Easy for implementation in software.
- Disadvantage: Bad stability and conditional convergence

Implicit schemes

- Advantage: Good stability and convergence.
 - Disadvantage: Need to solve a system of equations.
- 



Q&A



Thank you!