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TensorFlow人工智能引擎入门教程之七 DNN深度 神经网络 的原理 以及 使用



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DNN 深度神经网络,就是把原有的多层神经网络扩展到深度学习里面,加上了BP 反 馈,是的整理上 loss 收敛 直至不变,同时也有dropout 前面 有很多这个词 出现, dropout 是指 随机用一定概率 把一些 节点失效,进行参与训练 放置数据整理上陷入overfitting 局部 最优解。

OK 我们现在打开前面的AlexNet的网络

DNN,就是去掉C之后 使用全连接层+dropout下降+relu激活 一层一层的WX+B的 网 络模式

import input_data mnist = input_data.read_data_sets("/tmp/data/", one_hot=True) import tensorflo w as tf # Parameters learning_rate = 0.001 training_iters = 100000 batch_size = 128 display_step = 10 # Network Parameters n_input = 784 # MNIST data input (img shape: 28*28) n_classes = 10 # MNIS T total classes (0-9 digits) dropout = 0.75 # Dropout, probability to keep units # tf Graph input x = tf.placeholder(tf.float32, [None, n_input]) y = tf.placeholder(tf.float32, [None, n_classes]) keep_prob = t f.placeholder(tf.float32) #dropout (keep probability) # Create model def conv2d(img, w, b): f.nn.relu(tf.nn.bias_add(tf.nn.conv2d(img, w, strides=[1, 1, 1, 1], padding='SAME'),b)) def max_pool(im $g, k): \quad \textbf{return } tf.nn.max_pool(img, \, ksize=[1, \, k, \, k, \, 1], \, strides=[1, \, k, \, k, \, 1], \, padding='SAME') \quad \textbf{def } conv_ne$ t(_X, _weights, _biases, _dropout): # Reshape input picture _X = tf.reshape(_X, shape=[-1, 28, 28, 1]) # Convolution Layer conv1 = conv2d(_X, _weights['wc1'], _biases['bc1']) # Max Pooling (downsampling) conv1 = max_pool(conv1, k=2) # Apply Dropout conv1 = tf.nn.dropout(conv1, _drop # Convolution Layer conv2 = conv2d(conv1, _weights['wc2'], _biases['bc2']) # Max Poolin g (down-sampling) conv2 = max_pool(conv2, k=2) # Apply Dropout conv2 = tf.nn.dropout(con # Fully connected layer dense1 = tf.reshape(conv2, [-1, _weights['wd1'].get_shap e().as_list()[0]]) # Reshape conv2 output to fit dense layer input dense1 = tf.nn.relu(tf.add(tf.matmul(d ense1, _weights['wd1']), _biases['bd1'])) # Relu activation dense1 = tf.nn.dropout(dense1, _dropou t) # Apply Dropout # Output, class prediction out = tf.add(tf.matmul(dense1, _weights['out']), _bia ses['out']) return out # Store layers weight & bias weights = { 'wc1': tf.Variable(tf.random_norma l([5, 5, 1, 32])), # 5x5 conv, 1 input, 32 outputs 'wc2': tf.Variable(tf.random_normal([5, 5, 32, 64])), # 5 'wd1': tf.Variable(tf.random_normal([7*7*64, 1024])), # fully connecte x5 conv, 32 inputs, 64 outputs d, 7*7*64 inputs, 1024 outputs 'out': tf.Variable(tf.random_normal([1024, n_classes])) # 1024 input s, 10 outputs (class prediction) } biases = { 'bc1': tf.Variable(tf.random_normal([32])), ble(tf.random_normal([64])), 'bd1': tf.Variable(tf.random_normal([1024])), 'out': tf.Variable(tf.rando oss and optimizer cost = tf.reduce_mean(tf.nn.softmax_cross_entropy_with_logits(pred, y)) optimizer = t f.train.AdamOptimizer(learning_rate=learning_rate).minimize(cost) # Evaluate model correct_pred = tf.e qual(tf.argmax(pred,1), tf.argmax(y,1)) accuracy = tf.reduce_mean(tf.cast(correct_pred, tf.float32)) # Ini tializing the variables init = tf.initialize_all_variables() # Launch the graph with tf.Session() as sess: while step * batch_size < training_it s.run(init) step = 1 # Keep training until reach max iterations batch_xs, batch_ys = mnist.train.next_batch(batch_size) # Fit training using batch data sess.run(optimizer, feed_dict={x: batch_xs, y: batch_ys, keep_prob: dropout}) y_step == 0: # Calculate batch accuracy acc = sess.run(accuracy, feed_dict={x: batch_x # Calculate batch loss s, y: batch_ys, keep_prob: 1.}) loss = sess.run(cost, feed dict={x: b print "Iter " + str(step*batch_size) + ", Minibatch Los atch_xs, y: batch_ys, keep_prob: 1.}) s= " + "{:.6f}".format(loss) + ", Training Accuracy= " + "{:.5f}".format(acc) step += 1 print "Opti # Calculate accuracy for 256 mnist test images print "Testing Accuracy:", sess.r un(accuracy, feed_dict={x: mnist.test.images[:256], y: mnist.test.labels[:256], keep_prob: 1.})

先去掉卷积部分 以及 maxpool部分

下面遵循 WX+B 即可 输入时候[Batchsize,768]

那么 W 应该 需要是[768,n]接下来应该是[n,m]在接下来应该是[m,p]

也就是满足矩阵乘法

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下面来看看我们定义的

```
edef dnn(_X, _weights, _biases, _dropout):

# Reshape input picture

_X = tf.nn.dropout(_X, _dropout)#//这里可以让dropout都不同 我就一样了
d1 = tf.nn.relu(tf.nn.bias_add(tf.matmul(_X,_weights['wd1']),_biases['bd1']), name="d1")

d2x = tf.nn.dropout(d1, _dropout)
d2 = tf.nn.relu(tf.nn.bias_add(tf.matmul(d2x,_weights['wd2']),_biases['bd2']), name="d2")

#dense1 = tf.nn.relu(tf.matmul(dense1, _weights['wd1']) + _biases['bd1'], name='fc1') # Relu activation

#lense2 = tf.nn.dropout(d2,_dropout)
# Output, class prediction
out = tf.matmul(dout, _weights['out']) + _biases['out']
return out

# Store layers weight & bias
```

修改相应的变量

 $weights = \{ \quad 'wd1': tf.Variable(tf.random_normal([784,600], stddev=0.01)), \quad 'wd2': tf.Variable(tf.random_normal([600,480], stddev=0.01)), \quad 'out': tf.Variable(tf.random_normal([480, 10])) \} \ biases = \{ \quad 'bd 1': tf.Variable(tf.random_normal([600])), \quad 'bd2': tf.Variable(tf.random_normal([480])), \quad 'out': tf.Variable(tf.random_normal([10])), \} \\$

其实我们看出来了就是三个全连接层只不过通过dropout保证 loss一致收敛,不会陷入最优解问题,其实可能实际上的还会有norm 其他一些层等优化,也许是tanh 或者 sigmoid 的激活函数 这是网络设计的问题,上面的就是一个简单的DNN网络 利用深度学习 比传统的多层网络有了更好的效果以及准确率

看上面Nonex768 768X600 600X480 480X10 = None x 10

ok 下面贴出全部的代码

import input_data mnist = input_data.read_data_sets("/tmp/data/", one_hot=True) import tensorflow a s tf # Parameters learning_rate = 0.001 training_iters = 200000 batch_size = 64 display_step = 20 # Ne twork Parameters n_input = 784 # MNIST data input (img shape: 28*28) n_classes = 10 # MNIST tota I classes (0-9 digits) dropout = 0.8 # Dropout, probability to keep units # tf Graph input x = tf.placehold er(tf.float32, [None, n_input]) y = tf.placeholder(tf.float32, [None, n_classes]) keep_prob = tf.placeholde r(tf.float32) # dropout (keep probability) def init_weights(shape): return tf.Variable(tf.random_norma l(shape, stddev=0.01)) # Create custom model def conv2d(name, l_input, w, b): return tf.nn.relu(tf.n n.bias_add(tf.nn.conv2d(l_input, w, strides=[1, 1, 1, 1], padding='SAME'),b), name=name) def max_poo l(name, l_input, k): return tf.nn.max_pool(l_input, ksize=[1, k, k, 1], strides=[1, k, k, 1], padding='SAM E', name=name) def norm(name, l_input, lsize=4): return tf.nn.lrn(l_input, lsize, bias=1.0, alpha=0.00 1 / 9.0, beta=0.75, name=name) def dnn(_X, _weights, _biases, _dropout): # Reshape input picture _X = tf.nn.dropout(_X, _dropout)#//这里可以让dropout都不同 我就一样了 d1 = tf.nn.relu(tf.nn.bia s_add(tf.matmul(_X,_weights['wd1']),_biases['bd1']), name="d1") $d2x = tf.nn.dropout(d1, _dropout)$ d2 = tf.nn.relu(tf.nn.bias_add(tf.matmul(d2x,_weights['wd2']),_biases['bd2']), name="d2") ${\tt e1} = {\tt tf.nn.relu(tf.matmul(dense1, _weights['wd1']) + _biases['bd1'], name='fc1') \# Relu \ activation}$ nse2 = tf.nn.relu(tf.matmul(dense1, _weights['wd2']) + _biases['bd2'], name='fc2') # Relu activation ut =tf.nn.dropout(d2,_dropout) # Output, class prediction out = tf.matmul(dout, _weights['ou m_normal([784,600], stddev=0.01)), 'wd2': tf.Variable(tf.random_normal([600,480], stddev=0.01)), 'out': tf.Variable(tf.random_normal([480, 10])) } biases = { 'bd1': tf.Variable(tf.random_normal([60 'bd2': tf.Variable(tf.random_normal([480])), 'out': tf.Variable(tf.random_normal([10])), } # Constr uct model pred = dnn(x, weights, biases, keep_prob) # Define loss and optimizer cost = tf.reduce_mea n(tf.nn.softmax_cross_entropy_with_logits(pred, y)) optimizer = tf.train.AdamOptimizer(learning_rate=lea $rning_rate). minimize(cost) \ \# \ Evaluate \ model \ correct_pred = tf. equal(tf.argmax(pred,1), tf.argmax(y,1)) \ according to the property of the property$ curacy = tf.reduce_mean(tf.cast(correct_pred, tf.float32)) # Initializing the variables init = tf.initialize_al Lourniables() # Launch the graph with tf.Session() as sess: sess.run(init) step = 1 # Keep trainin g until reach max iterations while step * batch_size < training_iters: batch_xs, batch_ys = mnist.t rain.next_batch(batch_size) # Fit training using batch data sess.run(optimizer, feed_dict={x: ba tch_xs, y: batch_ys, keep_prob: dropout}) if step % display_step == 0: # Calculate batch ac acc = sess.run(accuracy, feed_dict={x: batch_xs, y: batch_ys, keep_prob: 1.}) curacy culate batch loss loss = sess.run(cost, feed_dict={x: batch_xs, y: batch_ys, keep_prob: 1.}) print "Iter " + str(step*batch_size) + ", Minibatch Loss= " + "{:.6f}".format(loss) + ", Training Acc
" + "{:.5f}".format(acc) step += 1 print "Optimization Finished!" # Calculate a uracv= " + "{:.5f}".format(acc) st.images[:256], y: mnist.test.labels[:256], keep_prob: 1.})



下面我们来运行测试看看

```
root@iZulcdurunpZ:-/tensorflowtest# vi dnn.py
root@iZulcdurunpZ:-/tensorflowtest# python dnn.py
('Extracting', '/tmp/data/train-images-idx3-ubyte.gz')
('Extracting', '/tmp/data/train-labels-idx1-ubyte.gz')
('Extracting', '/tmp/data/tlok-images-idx3-ubyte.gz')
('Extracting', '/tmp/data/tlok-images-idx3-ubyte.gz')
('Extracting', '/tmp/data/tlok-labels-idx1-ubyte.gz')
('Ex
```

```
Iter 167680, Minibatch Loss= 0.029179, Training Accuracy= 0.98438
Iter 168960, Minibatch Loss= 0.075078, Training Accuracy= 0.98438
Iter 170240, Minibatch Loss= 0.042363, Training Accuracy= 0.98438
Iter 171520, Minibatch Loss= 0.078119, Training Accuracy= 0.96875
Iter 172800, Minibatch Loss= 0.065727, Training Accuracy= 0.98438
Iter 174080, Minibatch Loss= 0.021739, Training Accuracy= 0.98438
Iter 175360, Minibatch Loss= 0.179623, Training Accuracy= 0.96875
Iter 176640, Minibatch Loss= 0.043091, Training Accuracy= 0.98438
 Iter 177920, Minibatch Loss= 0.025818, Training Accuracy= 1.00000
Iter 179200, Minibatch Loss= 0.027839, Training Accuracy= 1.00000
Iter 180480, Minibatch Loss= 0.125030, Training Accuracy= 0.98438
Iter 181760, Minibatch Loss= 0.038924, Training Accuracy= 0.98438
 Iter
          183040, Minibatch Loss= 0.007348, Training Accuracy= 1.00000
Iter 184320, Minibatch Loss= 0.026862, Training Accuracy= 0.98438
Iter 185600, Minibatch Loss= 0.082133, Training Accuracy= 0.96875
Iter 186880, Minibatch Loss= 0.021376, Training Accuracy= 1.00000
Iter 188160, Minibatch Loss= 0.160120, Training Accuracy= 0.95312
Iter 189440, Minibatch Loss= 0.007216, Training Accuracy= 1.00000
Iter 190720, Minibatch Loss= 0.076406, Training Accuracy= 0.98438
Iter 192000, Minibatch Loss= 0.016419, Training Accuracy= 0.98438
Iter 193280, Minibatch Loss= 0.051820, Training Accuracy= 1.00000
Iter 194560, Minibatch Loss= 0.038600, Training Accuracy= 0.98438
          195840, Minibatch Loss= 0.092423, Training Accuracy= 0.95312
 Iter
          197120, Minibatch Loss= 0.022268, Training Accuracy= 0.98438
 Iter
Iter 198400, Minibatch Loss= 0.124919, Training Accuracy= 0.96875
Iter 199680, Minibatch Loss= 0.099071, Training Accuracy= 0.96875
 Optimization Finished!
 Testing Accuracy: 0.976562
```

有人问我 图片文件夹 怎么读取。。。数据怎么读取。。。。。。可以看看input的代码 ,,,这是python的知识。。。不属于tensorflow 不过tensorflow也带了一些record 读 取。后面比如数据推荐系统就可能会使用哪个电影文件的 ,那时候我在使用下。

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