



原油操作建议



dnn神经网络



黄金线路直播



手写平板电脑



python趣



鼠标手写输入




水光针的危害



python项

TensorFlow人工智能引擎入门教程之十 最强网络 RSNN深度残差网络 平均准确率96-99%



蓝莓对冲基金

★★★★★

11483 馆藏 33861

2016-05-15 蓝莓对冲... 阅 6

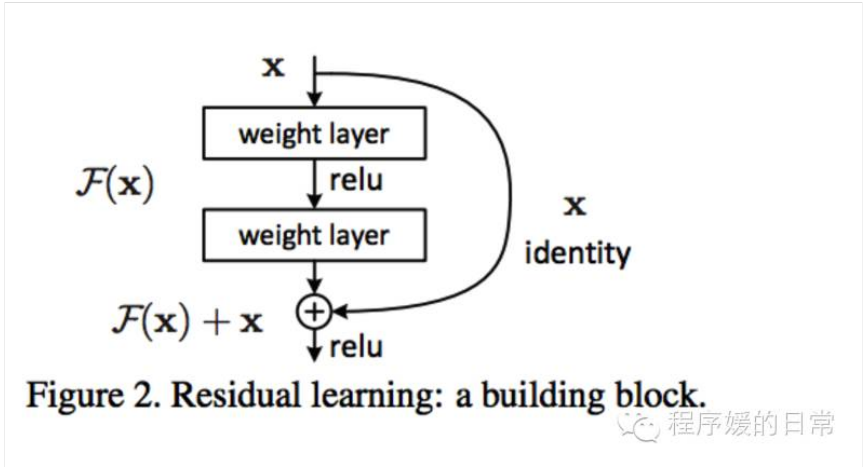
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在第六届 ImageNet 图像识别挑战赛上，微软研究院在多个类别的比赛中取得了第一名的成绩。比赛结果显示，微软的技术水平远远超越了 Google、Intel、高通、腾讯以及一众创业公司和科研实验室。

这个叫做「图像识别的深度残差学习」的获胜项目由微软研究员何恺明、张祥雨、任少卿和孙剑共同完成。根据微软博客显示，有关该成果的细节将会在后续的论文中详细介绍。

该技术的显著意义主要在于其复杂性。

<http://arxiv.org/pdf/1512.03385v1.pdf>



因为传统的 多层网络 随着层数增多，导致残差 加大。所以为了防止这个问题，我们把多个网络看成一个单元，单元计算后将上次的产生的残差 记入 并记入下一次单元计算，举个例子，小明 拿出100块 买了一件1 元的 2 元的 6元的 东西，但是 老板没有1块零钱，但是小明可能会继续买，所以 买了1 2 6 元 后 当做10元 我买了3次，那么实际上相当于 每一次 老板还欠小明1块，总共3 块，所以把这个3块 加入到下一次计算的里面呢，比如小明 下次买了个2元 5元 的东西 那么实际上 就是3 2 5 记入下一次 网络，总之 我的理解就是 把每一次计算后 得到的残差 作为 作为一层网络 来替代，也就是说 把残差用网络替代，就好像 我们用wx+b 替代y 一样，实际的值 与 真实的值 有误差 所以 如果我们把这个误差 记入下一次wx+b来替代，最后是不是可以保证 中间每一层 wx+b 被 抵消消除了。大概是这样的，这是我的理解，网上也没有任何资料指出，个人看官方论文有感，如果有什么不对请指正。

看看官方samples的 关键代码。他使用3 3 3 的卷积核，三次卷积之后 产生的残差 记入 下一次 卷积，看net+conv 然后继续wx+b 参数了残差之后 继续把新产生的残差记入 下次wx+b

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```
# Loop through all res blocks
for block_i, block in enumerate(blocks):
    for repeat_i in range(block.num_repeats):
        name = 'block_%d/repeat_%d' % (block_i, repeat_i)
        conv = conv2d(net, block.bottleneck_size, k_h=1, k_w=1,
                        padding='VALID', stride_h=1, stride_w=1,
                        activation=activation,
                        name=name + '/conv_in')

        conv = conv2d(conv, block.bottleneck_size, k_h=3, k_w=3,
                        padding='SAME', stride_h=1, stride_w=1,
                        activation=activation,
                        name=name + '/conv_bottleneck')

        conv = conv2d(conv, block.num_filters, k_h=1, k_w=1,
                        padding='VALID', stride_h=1, stride_w=1,
                        activation=activation,
                        name=name + '/conv_out')

    net = conv + net
try:
    # upscale to the next block size
    next_block = blocks[block_i + 1]
    net = conv2d(net, next_block.num_filters, k_h=1, k_w=1,
                  padding='SAME', stride_h=1, stride_w=1, bias=False,
                  name='block_%d/conv_upscale' % block_i)
except IndexError:
    pass
```



2015 MSRE大赛第一名 准确率最高的深度学习网络，也是至今为止准确率最高的网络 幸运的是 在 好的训练集情况下 大概 结果 对大多数训练得到的准确率96-99.9之间。rsnn152

152的太长了，这里贴出一个rsnn50 准确率 92-99

```
name: "ResNet-50" input: "data" input_dim: 1 output_dim: 3 input_dim: 224 input_dim: 224 layer { bottom: "data" top: "conv1" name: "conv1" type: "Convolution" convolution_param { num_output: 64 kernel_size: 7 pad: 3 stride: 2 } } layer { bottom: "conv1" top: "conv1" name: "bn_conv1" type: "BatchNorm" batch_norm_param { use_global_stats: true } } layer { bottom: "conv1" top: "conv1" name: "scale_conv1" type: "Scale" scale_param { bias_term: true } } layer { bottom: "conv1" top: "conv1" name: "conv1_relu" type: "ReLU" } layer { bottom: "conv1" top: "pool1" name: "pool1" type: "Pooling" pooling_param { kernel_size: 3 stride: 2 pool: MAX } } layer { bottom: "pool1" top: "res2a_branch1" name: "res2a_branch1" type: "Convolution" convolution_param { num_output: 256 kernel_size: 1 pad: 0 stride: 1 bias_term: false } } layer { bottom: "res2a_branch1" top: "res2a_branch1" name: "bn2a_branch1" type: "BatchNorm" batch_norm_param { use_global_stats: true } } layer { bottom: "res2a_branch1" top: "res2a_branch1" name: "scale2a_branch1" type: "Scale" scale_param { bias_term: true } } layer { bottom: "pool1" top: "res2a_branch2a" name: "res2a_branch2a" type: "Convolution" convolution_param { num_output: 64 kernel_size: 1 pad: 0 stride: 1 bias_term: false } } layer { bottom: "res2a_branch2a" top: "res2a_branch2a" name: "bn2a_branch2a" type: "BatchNorm" batch_norm_param { use_global_stats: true } } layer { bottom: "res2a_branch2a" top: "res2a_branch2a" name: "scale2a_branch2a" type: "Scale" scale_param { bias_term: true } } layer { bottom: "res2a_branch2a" top: "res2a_branch2a" name: "res2a_branch2a_relu" type: "ReLU" } layer { bottom: "res2a_branch2a" top: "res2a_branch2b" name: "res2a_branch2b" type: "Convolution" convolution_param { num_output: 64 kernel_size: 3 pad: 1 stride: 1 bias_term: false } } layer { bottom: "res2a_branch2b" top: "res2a_branch2b" name: "bn2a_branch2b" type: "BatchNorm" batch_norm_param { use_global_stats: true } } layer { bottom: "res2a_branch2b" top: "res2a_branch2b" name: "scale2a_branch2b" type: "Scale" scale_param { bias_term: true } } layer { bottom: "res2a_branch2b" top: "res2a_branch2b" name: "res2a_branch2b_relu" type: "ReLU" } layer { bottom: "res2a_branch2b" top: "res2a_branch2c" name: "res2a_branch2c" type: "Convolution" convolution_param { num_output: 256 kernel_size: 1 pad: 0 stride: 1 bias_term: false } } layer { bottom: "res2a_branch2c" top: "res2a_branch2c" name: "bn2a_branch2c" type: "BatchNorm" batch_norm_param { use_global_stats: true } } layer { bottom: "res2a_branch2c" top: "res2a_branch2c" name: "scale2a_branch2c" type: "Scale" scale_param { bias_term: true } } layer { bottom: "res2a_branch1" bottom: "res2a_branch2c" top: "res2a" name: "res2a" type: "Eltwise" } layer { bottom: "res2a" top: "res2a" name: "res2a_relu" type: "ReLU" } layer { bottom: "res2a" top: "res2b_branch2a" name: "res2b_branch2a" type: "Convolution" convolution_param { num_output: 64 kernel_size: 1 pad: 0 stride: 1 bias_term: false } } layer { bottom: "res2b_branch2a" top: "res2b_branch2a" name: "bn2b_branch2a" type: "BatchNorm" batch_norm_param { use_global_stats: true } } layer { bottom: "res2b_branch2a" top: "res2b_branch2a" name: "scale2b_branch2a" type: "Scale" scale_param { bias_term: true } } layer { bottom: "res2b_branch2a" top: "res2b_branch2a" name: "res2b_branch2a_relu" type: "ReLU" } layer { bottom: "res2b_branch2a" top: "res2b_branch2b" name: "res2b_branch2b" type: "Convolution" convolution_param { num_output: 64 kernel_size: 3 pad: 1 stride: 1 bias_term: false } } layer { bottom: "res2b_branch2b" top: "res2b_branch2b" name: "bn2b_branch2b" type: "BatchNorm" batch_norm_param { use_global_stats: true } } layer { bottom: "res2b_branch2b" top: "res2b_branch2b" name: "scale2b_branch2b" type: "Scale" scale_param { bias_term: true } } layer { bottom: "res2a" bottom: "res2b_branch2b" top: "res2b" name: "res2b" type: "Eltwise" } layer { bottom: "res2b" top: "res2b" name: "res2b_relu" type: "ReLU" } layer { bottom: "res2b" top: "res2b_branch2c" name: "res2b_branch2c" type: "Convolution" convolution_param { num_output: 256 kernel_size: 1 pad: 0 stride: 1 bias_term: false } } layer { bottom: "res2b_branch2c" top: "res2b_branch2c" name: "bn2b_branch2c" type: "BatchNorm" batch_norm_param { use_global_stats: true } } layer { bottom: "res2b_branch2c" top: "res2b_branch2c" name: "scale2b_branch2c" type: "Scale" scale_param { bias_term: true } } layer { bottom: "res2a" bottom: "res2b_branch2c" top: "res2b" name: "res2b" type: "Eltwise" } layer { bottom: "res2b" top: "res2b" name: "res2b_relu" type: "ReLU" } layer { bottom: "res2b" top: "res2b" name: "res2b_relu" type: "ReLU" }
```

http://www.360doc.com/content/16/0515/08/1317564_559243426.shtml


```

ale3d_branch2c" type: "Scale" scale_param { bias_term: true } } layer { bottom: "res3c" bottom: "res3d_b
ranch2c" top: "res3d" name: "res3d" type: "Eltwise" } layer { bottom: "res3d" top: "res3d" name: "res3
d_relu" type: "ReLU" } layer { bottom: "res3d" top: "res4a_branch1" name: "res4a_branch1" type: "Conv
olution" convolution_param { num_output: 1024 kernel_size: 1 pad: 0 stride: 2 bias_term: false } } layer {
bottom: "res4a_branch1" top: "res4a_branch1" name: "bn4a_branch1" type: "BatchNorm" batch_norm
m_param { use_global_stats: true } } layer { bottom: "res4a_branch1" top: "res4a_branch1" name: "scale4
a_branch1" type: "Scale" scale_param { bias_term: true } } layer { bottom: "res3d" top: "res4a_branch2a"
name: "res4a_branch2a" type: "Convolution" convolution_param { num_output: 256 kernel_size: 1 pa
d: 0 stride: 2 bias_term: false } } layer { bottom: "res4a_branch2a" top: "res4a_branch2a" name: "bn4a_br
anch2a" type: "BatchNorm" batch_norm_param { use_global_stats: true } } layer { bottom: "res4a_branch
2a" top: "res4a_branch2a" name: "scale4a_branch2a" type: "Scale" scale_param { bias_term: true } } laye
r { bottom: "res4a_branch2a" top: "res4a_branch2a" name: "res4a_branch2a_relu" type: "ReLU" } layer {
bottom: "res4a_branch2a" top: "res4a_branch2b" name: "res4a_branch2b" type: "Convolution" convolu
tion_param { num_output: 256 kernel_size: 3 pad: 1 stride: 1 bias_term: false } } layer { bottom: "res4a_br
anch2b" top: "res4a_branch2b" name: "bn4a_branch2b" type: "BatchNorm" batch_norm_param { use_g
lobal_stats: true } } layer { bottom: "res4a_branch2b" top: "res4a_branch2b" name: "scale4a_branch2b" t
ype: "Scale" scale_param { bias_term: true } } layer { bottom: "res4a_branch2b" top: "res4a_branch2b" na
me: "res4a_branch2b_relu" type: "ReLU" } layer { bottom: "res4a_branch2b" top: "res4a_branch2c" nam
e: "res4a_branch2c" type: "Convolution" convolution_param { num_output: 1024 kernel_size: 1 pad: 0 st
ride: 1 bias_term: false } } layer { bottom: "res4a_branch2c" top: "res4a_branch2c" name: "bn4a_branch2
c" type: "BatchNorm" batch_norm_param { use_global_stats: true } } layer { bottom: "res4a_branch2c" to
p: "res4a_branch2c" name: "scale4a_branch2c" type: "Scale" scale_param { bias_term: true } } layer { bot
tom: "res4a_branch1" bottom: "res4a_branch2c" top: "res4a" name: "res4a" type: "Eltwise" } layer { bott
om: "res4a" top: "res4a" name: "res4a_relu" type: "ReLU" } layer { bottom: "res4a" top: "res4b_branch2
a" name: "res4b_branch2a" type: "Convolution" convolution_param { num_output: 256 kernel_size: 1 pa
d: 0 stride: 1 bias_term: false } } layer { bottom: "res4b_branch2a" top: "res4b_branch2a" name: "bn4b_b
ranch2a" type: "BatchNorm" batch_norm_param { use_global_stats: true } } layer { bottom: "res4b_branc
h2a" top: "res4b_branch2a" name: "scale4b_branch2a" type: "Scale" scale_param { bias_term: true } } laye
r { bottom: "res4b_branch2a" top: "res4b_branch2a" name: "res4b_branch2a_relu" type: "ReLU" } layer {
bottom: "res4b_branch2a" top: "res4b_branch2b" name: "res4b_branch2b" type: "Convolution" conv
olution_param { num_output: 256 kernel_size: 3 pad: 1 stride: 1 bias_term: false } } layer { bottom: "res4
b_branch2b" top: "res4b_branch2b" name: "bn4b_branch2b" type: "BatchNorm" batch_norm_param { u
se_global_stats: true } } layer { bottom: "res4b_branch2b" top: "res4b_branch2b" name: "scale4b_branc
h2b" type: "Scale" scale_param { bias_term: true } } layer { bottom: "res4b_branch2b" top: "res4b_branch2
b" name: "res4b_branch2b_relu" type: "ReLU" } layer { bottom: "res4b_branch2b" top: "res4b_branch2c"
name: "res4b_branch2c" type: "Convolution" convolution_param { num_output: 1024 kernel_size: 1 pa
d: 0 stride: 1 bias_term: false } } layer { bottom: "res4b_branch2c" top: "res4b_branch2c" name: "bn4b_b
ranch2c" type: "BatchNorm" batch_norm_param { use_global_stats: true } } layer { bottom: "res4b_branc
h2c" top: "res4b_branch2c" name: "scale4b_branch2c" type: "Scale" scale_param { bias_term: true } } laye
r { bottom: "res4a" bottom: "res4b_branch2c" top: "res4b" name: "res4b" type: "Eltwise" } layer { botto
m: "res4b" top: "res4b" name: "res4b_relu" type: "ReLU" } layer { bottom: "res4b" top: "res4c_branch2a"
name: "res4c_branch2a" type: "Convolution" convolution_param { num_output: 256 kernel_size: 1 pa
d: 0 stride: 1 bias_term: false } } layer { bottom: "res4c_branch2a" top: "res4c_branch2a" name: "bn4c_br
anch2a" type: "BatchNorm" batch_norm_param { use_global_stats: true } } layer { bottom: "res4c_branch
2a" top: "res4c_branch2a" name: "scale4c_branch2a" type: "Scale" scale_param { bias_term: true } } laye
r { bottom: "res4c_branch2a" top: "res4c_branch2a" name: "res4c_branch2a_relu" type: "ReLU" } layer {
bottom: "res4c_branch2a" top: "res4c_branch2b" name: "res4c_branch2b" type: "Convolution" convolu
tion_param { num_output: 256 kernel_size: 3 pad: 1 stride: 1 bias_term: false } } layer { bottom: "res4c_br
anch2b" top: "res4c_branch2b" name: "bn4c_branch2b" type: "BatchNorm" batch_norm_param { use_g
lobal_stats: true } } layer { bottom: "res4c_branch2b" top: "res4c_branch2b" name: "scale4c_branch2b" t
ype: "Scale" scale_param { bias_term: true } } layer { bottom: "res4c_branch2b" top: "res4c_branch2b" na
me: "res4c_branch2b_relu" type: "ReLU" } layer { bottom: "res4c_branch2b" top: "res4c_branch2c" nam
e: "res4c_branch2c" type: "Convolution" convolution_param { num_output: 1024 kernel_size: 1 pad: 0 st
ride: 1 bias_term: false } } layer { bottom: "res4c_branch2c" top: "res4c_branch2c" name: "bn4c_branch2
c" type: "BatchNorm" batch_norm_param { use_global_stats: true } } layer { bottom: "res4c_branch2c" to
p: "res4c_branch2c" name: "scale4c_branch2c" type: "Scale" scale_param { bias_term: true } } layer { bot
tom: "res4b" bottom: "res4c_branch2c" top: "res4c" name: "res4c" type: "Eltwise" } layer { bottom: "res4
c" top: "res4c" name: "res4c_relu" type: "ReLU" } layer { bottom: "res4c" top: "res4d_branch2a" name: "r
es4d_branch2a" type: "Convolution" convolution_param { num_output: 256 kernel_size: 1 pad: 0 strid
e: 1 bias_term: false } } layer { bottom: "res4d_branch2a" top: "res4d_branch2a" name: "bn4d_branch2a"
type: "BatchNorm" batch_norm_param { use_global_stats: true } } layer { bottom: "res4d_branch2a" to
p: "res4d_branch2a" name: "scale4d_branch2a" type: "Scale" scale_param { bias_term: true } } layer { bot
tom: "res4d_branch2a" top: "res4d_branch2a" name: "res4d_branch2a_relu" type: "ReLU" } layer { botto
m: "res4d_branch2a" top: "res4d_branch2b" name: "res4d_branch2b" type: "Convolution" convolutio
n_param { num_output: 256 kernel_size: 3 pad: 1 stride: 1 bias_term: false } } layer { bottom: "res4d_branc
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bal_stats: true } } layer { bottom: "res4d_branch2b" top: "res4d_branch2b" name: "scale4d_branch2b" ty
pe: "Scale" scale_param { bias_term: true } } layer { bottom: "res4d_branch2b" top: "res4d_branch2b" na
me: "res4d_branch2b_relu" type: "ReLU" } layer { bottom: "res4d_branch2b" top: "res4d_branch2c" nam
e: "res4d_branch2c" type: "Convolution" convolution_param { num_output: 1024 kernel_size: 1 pad: 0 st
ride: 1 bias_term: false } } layer { bottom: "res4d_branch2c" top: "res4d_branch2c" name: "bn4d_branc
h2c" type: "BatchNorm" batch_norm_param { use_global_stats: true } } layer { bottom: "res4d_branch2c"
top: "res4d_branch2c" name: "scale4d_branch2c" type: "Scale" scale_param { bias_term: true } } layer { b
ottom: "res4c" bottom: "res4d_branch2c" top: "res4d" name: "res4d" type: "Eltwise" } layer { bottom: "r
es4d" top: "res4d" name: "res4d_relu" type: "ReLU" } layer { bottom: "res4d" top: "res4e_branch2a" nam
e: "res4e_branch2a" type: "Convolution" convolution_param { num_output: 256 kernel_size: 1 pad: 0 stri
de: 1 bias_term: false } } layer { bottom: "res4e_branch2a" top: "res4e_branch2a" name: "bn4e_branch2
a" type: "BatchNorm" batch_norm_param { use_global_stats: true } } layer { bottom: "res4e_branch2a" to
p: "res4e_branch2a" name: "scale4e_branch2a" type: "Scale" scale_param { bias_term: true } } layer { bot
tom: "res4e_branch2a" top: "res4e_branch2a" name: "res4e_branch2a_relu" type: "ReLU" } layer { botto
m: "res4e_branch2a" top: "res4e_branch2b" name: "res4e_branch2b" type: "Convolution" convolutio
n_param { num_output: 256 kernel_size: 3 pad: 1 stride: 1 bias_term: false } } layer { bottom: "res4e_branc
h2b" top: "res4e_branch2b" name: "bn4e_branch2b" type: "BatchNorm" batch_norm_param { use_glo
bal_stats: true } } layer { bottom: "res4e_branch2b" top: "res4e_branch2b" name: "scale4e_branch2b" ty
pe: "Scale" scale_param { bias_term: true } } layer { bottom: "res4e_branch2b" top: "res4e_branch2b" na
me: "res4e_branch2b_relu" type: "ReLU" } layer { bottom: "res4e_branch2b" top: "res4e_branch2c" nam
e: "res4e_branch2c" type: "Convolution" convolution_param { num_output: 1024 kernel_size: 1 pad: 0 st

```

```

ride: 1 bias_term: false }} layer { bottom: "res4e_branch2c" top: "res4e_branch2c" name: "bn4e_branch2c" type: "BatchNorm" batch_norm_param { use_global_stats: true }} layer { bottom: "res4e_branch2c" top: "res4e_branch2c" name: "scale4e_branch2c" type: "Scale" scale_param { bias_term: true }} layer { bottom: "res4d" bottom: "res4e_branch2c" top: "res4e" name: "res4e" type: "Eltwise" } layer { bottom: "res4e" top: "res4e" name: "res4e_relu" type: "ReLU" } layer { bottom: "res4e" top: "res4f_branch2a" name: "res4f_branch2a" type: "Convolution" convolution_param { num_output: 256 kernel_size: 1 pad: 0 stride: 1 bias_term: false }} layer { bottom: "res4f_branch2a" top: "res4f_branch2a" name: "bn4f_branch2a" type: "BatchNorm" batch_norm_param { use_global_stats: true }} layer { bottom: "res4f_branch2a" top: "res4f_branch2a" name: "scale4f_branch2a" type: "Scale" scale_param { bias_term: true }} layer { bottom: "res4f_branch2a" top: "res4f_branch2a" name: "res4f_branch2a_relu" type: "ReLU" } layer { bottom: "res4f_branch2a" top: "res4f_branch2b" name: "res4f_branch2b" type: "Convolution" convolution_param { num_output: 256 kernel_size: 3 pad: 1 stride: 1 bias_term: false }} layer { bottom: "res4f_branch2b" top: "res4f_branch2b" name: "bn4f_branch2b" type: "BatchNorm" batch_norm_param { use_global_stats: true }} layer { bottom: "res4f_branch2b" top: "res4f_branch2b" name: "scale4f_branch2b" type: "Scale" scale_param { bias_term: true }} layer { bottom: "res4f_branch2b" top: "res4f_branch2b" name: "res4f_branch2b_relu" type: "ReLU" } layer { bottom: "res4f_branch2b" top: "res4f_branch2c" name: "res4f_branch2c" type: "Convolution" convolution_param { num_output: 1024 kernel_size: 1 pad: 0 stride: 1 bias_term: false }} layer { bottom: "res4f_branch2c" top: "res4f_branch2c" name: "bn4f_branch2c" type: "BatchNorm" batch_norm_param { use_global_stats: true }} layer { bottom: "res4f_branch2c" top: "res4f_branch2c" name: "scale4f_branch2c" type: "Scale" scale_param { bias_term: true }} layer { bottom: "res4e" bottom: "res4f_branch2c" top: "res4f" name: "res4f" type: "Eltwise" } layer { bottom: "res4f" top: "res4f" name: "res4f_relu" type: "ReLU" } layer { bottom: "res4f" top: "res5a_branch1" name: "res5a_branch1" type: "Convolution" convolution_param { num_output: 2048 kernel_size: 1 pad: 0 stride: 2 bias_term: false }} layer { bottom: "res5a_branch1" top: "res5a_branch1" name: "bn5a_branch1" type: "BatchNorm" batch_norm_param { use_global_stats: true }} layer { bottom: "res5a_branch1" top: "res5a_branch1" name: "scale5a_branch1" type: "Scale" scale_param { bias_term: true }} layer { bottom: "res4f" top: "res5a_branch2a" name: "res5a_branch2a" type: "Convolution" convolution_param { num_output: 512 kernel_size: 1 pad: 0 stride: 2 bias_term: false }} layer { bottom: "res5a_branch2a" top: "res5a_branch2a" name: "bn5a_branch2a" type: "BatchNorm" batch_norm_param { use_global_stats: true }} layer { bottom: "res5a_branch2a" top: "res5a_branch2a" name: "scale5a_branch2a" type: "Scale" scale_param { bias_term: true }} layer { bottom: "res5a_branch2a" top: "res5a_branch2a" name: "res5a_branch2a_relu" type: "ReLU" } layer { bottom: "res5a_branch2a" top: "res5a_branch2b" name: "res5a_branch2b" type: "Convolution" convolution_param { num_output: 512 kernel_size: 3 pad: 1 stride: 1 bias_term: false }} layer { bottom: "res5a_branch2b" top: "res5a_branch2b" name: "bn5a_branch2b" type: "BatchNorm" batch_norm_param { use_global_stats: true }} layer { bottom: "res5a_branch2b" top: "res5a_branch2b" name: "scale5a_branch2b" type: "Scale" scale_param { bias_term: true }} layer { bottom: "res5a_branch2b" top: "res5a_branch2b" name: "res5a_branch2b_relu" type: "ReLU" } layer { bottom: "res5a_branch2b" top: "res5a_branch2c" name: "res5a_branch2c" type: "Convolution" convolution_param { num_output: 2048 kernel_size: 1 pad: 0 stride: 1 bias_term: false }} layer { bottom: "res5a_branch2c" top: "res5a_branch2c" name: "bn5a_branch2c" type: "BatchNorm" batch_norm_param { use_global_stats: true }} layer { bottom: "res5a_branch2c" top: "res5a_branch2c" name: "scale5a_branch2c" type: "Scale" scale_param { bias_term: true }} layer { bottom: "res5a_branch1" bottom: "res5a_branch2c" top: "res5a" name: "res5a" type: "Eltwise" } layer { bottom: "res5a" top: "res5a" name: "res5a_relu" type: "ReLU" } layer { bottom: "res5a" top: "res5b_branch2a" name: "res5b_branch2a" type: "Convolution" convolution_param { num_output: 512 kernel_size: 1 pad: 0 stride: 1 bias_term: false }} layer { bottom: "res5b_branch2a" top: "res5b_branch2a" name: "bn5b_branch2a" type: "BatchNorm" batch_norm_param { use_global_stats: true }} layer { bottom: "res5b_branch2a" top: "res5b_branch2a" name: "scale5b_branch2a" type: "Scale" scale_param { bias_term: true }} layer { bottom: "res5b_branch2a" top: "res5b_branch2a" name: "res5b_branch2a_relu" type: "ReLU" } layer { bottom: "res5b_branch2a" top: "res5b_branch2b" name: "res5b_branch2b" type: "Convolution" convolution_param { num_output: 512 kernel_size: 3 pad: 1 stride: 1 bias_term: false }} layer { bottom: "res5b_branch2b" top: "res5b_branch2b" name: "bn5b_branch2b" type: "BatchNorm" batch_norm_param { use_global_stats: true }} layer { bottom: "res5b_branch2b" top: "res5b_branch2b" name: "scale5b_branch2b" type: "Scale" scale_param { bias_term: true }} layer { bottom: "res5b_branch2b" top: "res5b_branch2b" name: "res5b_branch2b_relu" type: "ReLU" } layer { bottom: "res5b_branch2b" top: "res5b_branch2c" name: "res5b_branch2c" type: "Convolution" convolution_param { num_output: 2048 kernel_size: 1 pad: 0 stride: 1 bias_term: false }} layer { bottom: "res5b_branch2c" top: "res5b_branch2c" name: "bn5b_branch2c" type: "BatchNorm" batch_norm_param { use_global_stats: true }} layer { bottom: "res5b_branch2c" top: "res5b_branch2c" name: "scale5b_branch2c" type: "Scale" scale_param { bias_term: true }} layer { bottom: "res5a" bottom: "res5b_branch2c" top: "res5b" name: "res5b" type: "Eltwise" } layer { bottom: "res5b" top: "res5b" name: "res5b_relu" type: "ReLU" } layer { bottom: "res5b" top: "res5c_branch2a" name: "res5c_branch2a" type: "Convolution" convolution_param { num_output: 512 kernel_size: 1 pad: 0 stride: 1 bias_term: false }} layer { bottom: "res5c_branch2a" top: "res5c_branch2a" name: "bn5c_branch2a" type: "BatchNorm" batch_norm_param { use_global_stats: true }} layer { bottom: "res5c_branch2a" top: "res5c_branch2a" name: "scale5c_branch2a" type: "Scale" scale_param { bias_term: true }} layer { bottom: "res5c_branch2a" top: "res5c_branch2a" name: "res5c_branch2a_relu" type: "ReLU" } layer { bottom: "res5c_branch2a" top: "res5c_branch2b" name: "res5c_branch2b" type: "Convolution" convolution_param { num_output: 512 kernel_size: 3 pad: 1 stride: 1 bias_term: false }} layer { bottom: "res5c_branch2b" top: "res5c_branch2b" name: "bn5c_branch2b" type: "BatchNorm" batch_norm_param { use_global_stats: true }} layer { bottom: "res5c_branch2b" top: "res5c_branch2b" name: "scale5c_branch2b" type: "Scale" scale_param { bias_term: true }} layer { bottom: "res5c_branch2b" top: "res5c_branch2b" name: "res5c_branch2b_relu" type: "ReLU" } layer { bottom: "res5c_branch2b" top: "res5c_branch2c" name: "res5c_branch2c" type: "Convolution" convolution_param { num_output: 2048 kernel_size: 1 pad: 0 stride: 1 bias_term: false }} layer { bottom: "res5c_branch2c" top: "res5c_branch2c" name: "bn5c_branch2c" type: "BatchNorm" batch_norm_param { use_global_stats: true }} layer { bottom: "res5c_branch2c" top: "res5c_branch2c" name: "scale5c_branch2c" type: "Scale" scale_param { bias_term: true }} layer { bottom: "res5b" bottom: "res5c_branch2c" top: "res5c" name: "res5c" type: "Eltwise" } layer { bottom: "res5c" top: "res5c" name: "res5c_relu" type: "ReLU" } layer { bottom: "res5c" top: "pool5" name: "pool5" type: "Pooling" pooling_param { kernel_size: 7 stride: 1 pool: AVE }} layer { bottom: "pool5" top: "fc1000" name: "fc1000" type: "InnerProduct" inner_product_param { num_output: 1000 }} layer { bottom: "fc1000" top: "prob" name: "prob" type: "Softmax" }

```

下面贴出一个非常简单的10层的残差网络，真实环境下 请用res50 res152

```

import tensorflow as tf from collections import namedtuple from math import sqrt import input_data d
ef conv2d(x, n_filters, k_h=5, k_w=5, stride_h=2, stride_w=2, stddev=0.02,
activation=lambda x: x, bias=True, padding='SAME', name='Conv2D'):
    with tf.variable_scope(name):
        w = tf.get_variable('w', [k_h, k_w, x.get_shape()[-1], n_filters],
initializer=tf.truncated_normal_initializer(stddev=stddev))
        conv = tf.nn.conv2d(x, w, strides=[1, stride_h, stride_w, 1], padding=padding)
        if bias:
            b = tf.get_variable('b', [n_filters],
initializer=tf.truncated_normal_initializer(stddev=stddev))
            conv = conv + b
        return activation(conv)
def linear(x, n_units, scope=None, stddev=0.02, activation=lambda x: x):
    shape = x.get_shape().as_list()
    with tf.variable_scope(scope or "Linear"):
        matrix = tf.get_variable("Matrix", [shape[1], n_units], tf.float32,
tf.random_normal_initializer(stddev=stddev))
        return activation(tf.matmul(x, matrix))
%% def residual_network
k(x, n_outputs, activation=tf.nn.relu):
    %% LayerBlock = namedtuple('LayerBlock', ['num_repeats', 'num_filters', 'bottleneck_size'])
    blocks = [LayerBlock(3, 128, 32), LayerBlock(3, 256, 64), LayerBlock(3, 512, 128), LayerBlock(3, 1024, 256)]
    %% input_shape = x.get_shape().as_list()
    if len(input_shape) == 2:
        ndim = int(sqrt(input_shape[1]))
        i = ndim * ndim
        if i != input_shape[1]:
            raise ValueError('input_shape should be square')
        x = tf.reshape(x, [-1, ndim, ndim, 1])
        %% # First convolution expands to 64 channels and downsamples
        net = conv2d(x, 64, k_h=7, k_w=7, name='conv1', activation=activation)
        %% # Max pool and downsampling
        net = tf.nn.max_pool(net, [1, 3, 3, 1], strides=[1, 2, 2, 1], padding='SAME')
        %% # Setup first chain of resnets
        net = conv2d(net, blocks[0].num_filters, k_h=1, k_w=1, stride_h=1, stride_w=1, padding='VALID', name='conv2')
        %% # Loop through all res blocks
        for block_i, block in enumerate(blocks):
            for repeat_i in range(block.num_repeats):
                name = 'block_%d/repeat_%d' % (block_i, repeat_i)
                conv = conv2d(net, block.num_filters, k_h=1, k_w=1, padding='VALID', stride_h=1, stride_w=1,
activation=activation, name=name + '/conv_in')
                conv = conv2d(conv, block.bottleneck_size, k_h=3, k_w=3, padding='SAME', stride_h=1, stride_w=1,
activation=activation, name=name + '/conv_bottleneck')
                conv = conv2d(conv, block.num_filters, k_h=1, k_w=1, padding='VALID', stride_h=1, stride_w=1,
activation=activation, name=name + '/conv_out')
                net = conv + net
            try:
                # upscale to the next block size
                next_block = blocks[block_i + 1]
                net = conv2d(net, next_block.num_filters, k_h=1, k_w=1, padding='VALID', stride_h=1, stride_w=1,
activation=activation, name='block_%d/conv_upscale' % block_i)
            except IndexError:
                pass
                net = tf.nn.avg_pool(net, [1, net.get_shape()[-1], net.get_shape()[-1], 1], [1, 1, 1, 1], padding='VALID')
                net = tf.reshape(net, [-1, net.get_shape()[-1] * net.get_shape()[-1] * net.get_shape()[-1]])
                net = linear(net, n_outputs, activation=tf.nn.softmax)
        %% return net
def rsnn():
    """Test the resnet on MNIST."""
    mnist = input_data.read_data_sets('/tmp/data/', one_hot=True)
    x = tf.placeholder(tf.float32, [None, 784])
    y = tf.placeholder(tf.float32, [None, 10])
    y_pred = residual_network(x, 10)
    %% Define loss/evaluation/training functions
    cross_entropy = -tf.reduce_sum(y * tf.log(y_pred))
    optimizer = tf.train.AdamOptimizer().minimize(cross_entropy)
    %% Monitor accuracy
    correct_prediction = tf.equal(tf.argmax(y_pred, 1), tf.argmax(y, 1))
    accuracy = tf.reduce_mean(tf.cast(correct_prediction, 'float'))
    %% We now create a new session to actually perform the initialization the # variables:
    sess = tf.Session()
    sess.run(tf.initialize_all_variables())
    %% We'll train in minibatches and report accuracy:
    batch_size = 50
    n_epochs = 5
    for epoch_i in range(n_epochs):
        # Training
        train_accuracy = 0
        for batch_i in range(mnist.train.num_examples // batch_size):
            batch_xs, batch_ys = mnist.train.next_batch(batch_size)
            train_accuracy += sess.run([optimizer, accuracy], feed_dict={x: batch_xs, y: batch_ys})
        train_accuracy /= (mnist.train.num_examples // batch_size)
        # Validation
        valid_accuracy = 0
        for batch_i in range(mnist.validation.num_examples // batch_size):
            batch_xs, batch_ys = mnist.validation.next_batch(batch_size)
            valid_accuracy += sess.run(accuracy, feed_dict={x: batch_xs, y: batch_ys})
        valid_accuracy /= (mnist.validation.num_examples // batch_size)
        print('epoch:', epoch_i, 'train:', train_accuracy, 'valid:', valid_accuracy)
    if __name__ == '__main__':
        rsnn()

```

```

root@iZulcdurupZ:~/tensorflowtest# vi rsnn.py
root@iZulcdurupZ:~/tensorflowtest# python rsnn.py
('Extracting', '/tmp/data/train-images-idx3-ubyte.gz')
('Extracting', '/tmp/data/train-labels-idx1-ubyte.gz')
('Extracting', '/tmp/data/t10k-images-idx3-ubyte.gz')
('Extracting', '/tmp/data/t10k-labels-idx1-ubyte.gz')
I tensorflow/core/common_runtime/local_device.cc:25] Local device intra op parallelism threads: 1
I tensorflow/core/common_runtime/local_session.cc:45] Local session inter op parallelism threads: 1

```

下面是迭代一次的准确率

```

root@iZulcdurupZ:~/tensorflowtest# python rsnn.py
('Extracting', '/tmp/data/train-images-idx3-ubyte.gz')
('Extracting', '/tmp/data/train-labels-idx1-ubyte.gz')
('Extracting', '/tmp/data/t10k-images-idx3-ubyte.gz')
('Extracting', '/tmp/data/t10k-labels-idx1-ubyte.gz')
I tensorflow/core/common_runtime/local_device.cc:25] Local device intra op parallelism threads: 1
I tensorflow/core/common_runtime/local_session.cc:45] Local session inter op parallelism threads: 1
('epoch:', 0, 'train:', 0.86889090818099002, 'valid:', 0.9667999887943269)

```

这里我就不等他迭代完成了。。。。

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