

# Transfer Learning: Introduction & Application

Yun Gu

Department of Automation  
Shanghai Jiao Tong University  
Shanghai, CHINA

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# Outline

## 1 Overview of Transfer Learning

## 2 Categorization

- Three Research Issues
- Different Settings

## 3 Applications

- Image Annotation
- Image Classification
- Deep Learning

## 4 Conclusion

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# What is Transfer Learning?[Pan and Yang, 2010]

## Naive View (Transfer Learning)

*Transfer Learning (i.e. Knowledge Transfer, Domain Adaption) aims at applying knowledge learned **previously** to solve **new** problems faster or with better solutions.*

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- What to “Transfer” ?
- How to “Transfer” ?
- When to “Transfer” ?
- Machine Learning Scheme.
- Relationship with other ML tech?

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In Top-Level Conference: 7 papers in CVPR 2014 are related with Transfer Learning;

In Top-Level Journal: M.Guilaumin, et.al, "ImageNet Auto-Annotation with Segmentation Propagation", IJCV,2014

# What is Transfer Learning? (Cont.)



Supervised Classification



Semi-supervised Learning



Transfer Learning

**Figure :** Supervised classification uses labeled examples of elephants and rhinos; semi-supervised learning uses additional unlabeled examples of elephants and rhinos; transfer learning uses additional labeled datasets[Raina et al., 2007].

# Motivation

Why we need Transfer Learning[Tang et al., 2012]?

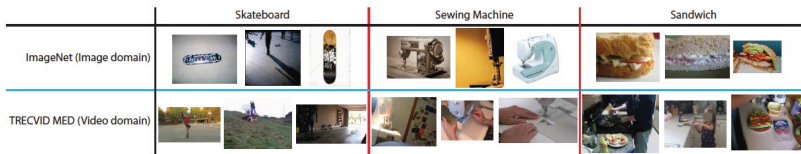
- **Labeled data are expensive and limited.**
- **Related data are cheap and sufficient.**



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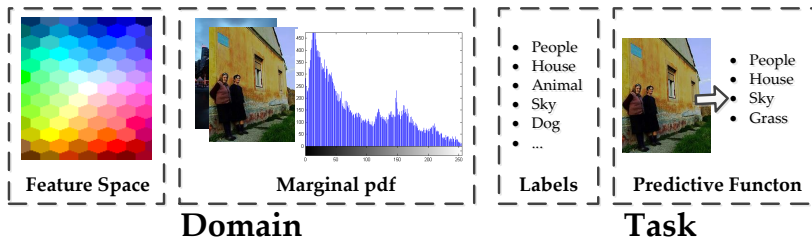
**Figure :** Object detector for static image is easy to obtain. However, the labeled data for video task are limited and expensive.

# Terminologies

- **Domain:** A domain  $\mathcal{D} = \{\mathcal{X}, P(X)\}$  consists of two components: a feature space  $\mathcal{X}$  and a marginal prob distribution  $P(X), X \in \mathcal{X}$ .
- **Task:** Given a specific domain, a task  $\mathcal{T} = \{\mathcal{Y}, f(\cdot)\}$  also consists of two components: a label space  $\mathcal{Y}$  and the predictive function  $f(\cdot) = P(y|x)$ . *The predictive is unknown for us but can be learned from training data, which consists of data pair  $(x_i, y_i)$ .*

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# Terminologies (Cont.)

- **Source/Target Domain Data:** a set of labeled data  $D_S$  and  $D_T$

$$D_S = \{(x_{S_1}, y_{S_1}) \dots (x_{S_{n_S}}, y_{S_{n_S}})\}, D_T = \{(x_{T_1}, y_{T_1}) \dots (x_{T_{n_T}}, y_{T_{n_T}})\}$$

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## Definition (Transfer Learning)

*Given a source domain  $\mathcal{D}_S$  and learning task  $\mathcal{T}_S$ , a target domain  $\mathcal{D}_T$  and learning task  $\mathcal{T}_T$ , **transfer learning** aims to help improve the learning of the target predictive function  $f_T(\cdot)$  in  $\mathcal{D}_T$  using the knowledge in  $\mathcal{D}_S$  and  $\mathcal{T}_S$ , where  $\mathcal{D}_S \neq \mathcal{D}_T$  or  $\mathcal{T}_S \neq \mathcal{T}_T$ .*

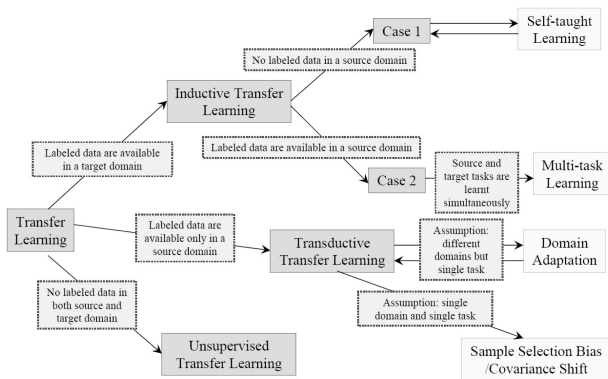
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- 1 Overview of Transfer Learning
- 2 **Categorization**
  - Three Research Issues
  - Different Settings
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# Three Research Issues

- **"What to transfer?"**  
Which part of knowledge can be transferred across domain?  
e.g. feature representation, parameter settings, latent feature distribution, etc.
- **"How to transfer?"** Specific learning algorithms to transfer the knowledge.  
e.g. TrAdaBoost (*Dai,2007*), Structural Correspondence Learning (*Blitzer,2006*),etc.
- **"When to transfer?"** Asks in which situations, transferring skills should be done. Likewise, we are interested in knowing in which situations, knowledge should not be transferred.

# Categorization of Transfer Learning



**Figure :** Different settings of Transfer Learning based on the availability of Source/Target Domain Labels.



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# Transfer Learning: Image Annotation

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**Main Idea:** Learning a new class(target) is helped by labeled examples of other related classes (source). This is actually a **Inductive Transfer Learning** scheme.

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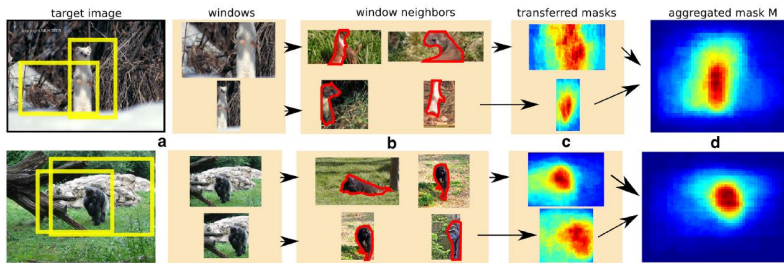
- **Parameters Transfer:** Use the parameters from the source classifier as a prior for target model.  
 e.g. Transfer  $w$  in SVM Classifier from source to target. *Aytar, ICCV 2011.*
- **Feature Transfer:** Transfer knowledge through an intermediate attributive layer shared by many classes.  
 e.g. The color or basic texture. *Lampert, CVPR 2009.*
- **Transfer between Classes:** Transfer object parts between classes, such as wheels between "car" and "bike". e.g. *Ott, CVPR 2011.*
- **From Annotated to Bounded:** Transfer from the images only annotated by tags to the localization task. e.g. *Guillaumin, CVPR 2012.*

# Auto-Annotation with Segmentation Propagation

## [Guillaumin et al., 2014]

- **Task:** Weakly-supervised segmentation on ImageNet dataset (500k images, 577 classes).
- **A new transfer scheme (Window-based Transfer):**
  - Segmented Images from PASCAL VOC 2010 (1928 images, 4203 objects).
  - Images with bounding boxes from ImageNet (60k images).
  - Images only with tags from ImageNet (440k images).
  - Images to be segmented.

# Window Transfer



**Figure :** Examples of window-level segmentation transfer: From segmented to bounded.

# Segmentation Propagation

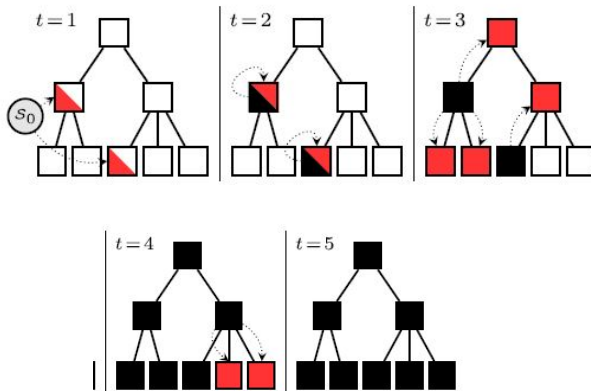
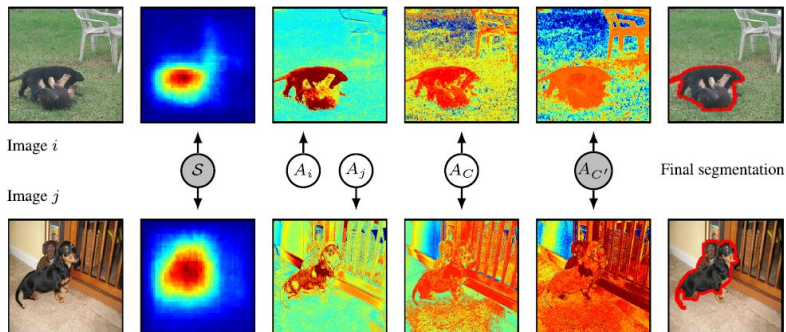


Figure : *white:*"unsegmented";*red:*"being segmented";*black:*"already segmented"

# Class-wise Cosegmentation



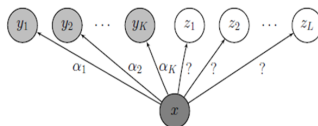


# Transfer Learning: Image Classification

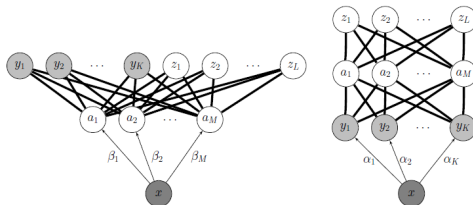
Shaoyong Jia

# TL for Image Classification [Lampert et al., 2009]

- **Problem:** Object classification when training and test classes are disjoint.



- **Proposal:** Transfer learning for object detection by between class attributes.

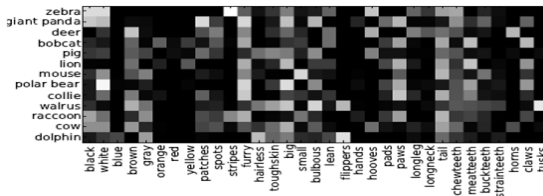


# Transfer Learning for Image Classification (Cont.)

- **Attribute:** Human-specified high-level description, which consists of arbitrary semantic attributes, like shape, color or even geographic information.



- The class-attribute matrices



# Transfer Learning for Image Classification (Cont.)

- **Dataset:** Animals with Attributes of over 30475 animal images, 85 semantic attributes and 50 classes with at minimum of 92 images for any class<sup>1</sup>.

- Base package (1M) including the class/attribute table: [AwA-base.tar.bz2](#) (everybody needs this)
  - Color Histogram features (124M): [AwA-features-cq.tar.bz2](#)
  - Local Self-Similarity features (30M): [AwA-features-lss.tar.bz2](#)
  - PyramidHOG (PHOG) features (28M): [AwA-features-phog.tar.bz2](#)
  - SIFT features (44M): [AwA-features-sift.tar.bz2](#)
  - colorSIFT features (44M): [AwA-features-rgsift.tar.bz2](#)
  - SURF features (49M): [AwA-features-surf.tar.bz2](#)
  - DECAF features (122M): [AwA-features-decaf.tar.bz2](#) (NEW!)
  - Source code (30K) illustrating DAP and IAP methods: [AwA-code.tar.bz2](#)
- Addendum: new [attributes.py](#) script that work with recent versions of Shogun
- Example Images (15M): [AwA-examples.tar.bz2](#) (3 example per class, e.g. for illustrative use in publications)
  - Full Image Set in JPEG format: *not directly downloadable for copyright reasons*  
 please ask at <chl(at)ist.ac.at>.

<sup>1</sup>Website Link: <http://attributes.kyb.tuebingen.mpg.de/>

# Transfer Learning for Image Classification (Cont.)

- **Implementation:** Use a probabilistic model to reflect the graphical.

DAP

- Image-attribute stage:

$$p(\alpha|x) = \prod_{m=1}^M p(\alpha_m|x)$$

- Attribute-class stage:

$$p(z|\alpha) = \frac{p(z)}{p(\alpha^z)} [\alpha = \alpha^z]$$

- Image-class stage:

$$p(z|x) = \sum_{\alpha \in \{0,1\}^M} p(z|\alpha) p(\alpha|x) = \frac{p(z)}{p(\alpha^z)} \prod_{m=1}^M p(\alpha_m^z|x)$$

- Decision rule:

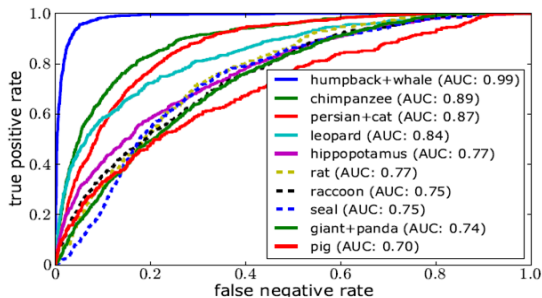
$$f(x) = \underset{l=1,\dots,L}{\operatorname{argmax}} \prod_{m=1}^M \frac{p(\alpha_m^{z_l}|x)}{p(\alpha_m^{z_l})}$$

IAP

- Image-attribute stage:  $p(\alpha_m|x) = \sum_{k=1}^K p(\alpha_m|y_k) p(y_k|x)$
- Other stages are in the same way in DAP:

# Transfer Learning for Image Classification (Cont.)

- Experimental design: 6180 images of 10 classes for test while 24295 images of 40 classes for training.
- Results: Accuracy of 40.5% for DAP while 27.8% for IAP .



**Figure :** Note: Detection performance of object classification with disjoint training and test classes(DAP method):ROC-curves and area under curve(AUC) for the 10 Animals with Attributes test classes.

# Transfer Learning for Image Classification (Cont.)



Figure : Note: The five images with highest posterior score for each test class.

# Transfer Learning: Combined with Deep Learning

Haoyang Xue



# The Characteristics of Deep Learning

- Advantages**
- Outstanding classification performance in large-scale visual recognition challenge
- Flaws**
- Numerous parameters;
  - A large scale number of annotated samples needed;
  - Time consuming.

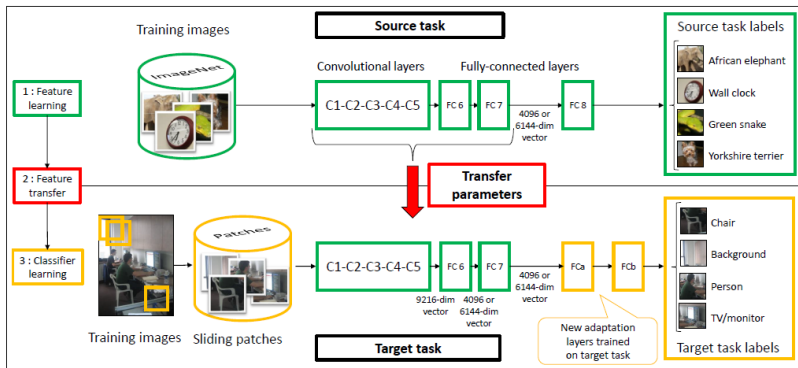
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- Solution**
- The multilayer networks of a training set include many intermediate features or presentations.(Avoid training large part of the network for a new task)
  - Can we just transfer the middle presentations of a pre-trained network on one dataset to new dataset for new target task?(Avoid collecting a large scale of training data)

# Learning and Transferring Mid-Level Image Representations using Convolutional Neural Networks[Oquab et al., 2013]

- In this paper, the author propose an approach to re-use a pre-trained CNN network to a new dataset and estimate its performance in target tasks.
- A pre-trained CNN network on the source dataset(ImageNet) for classification task.
- A adaptation layer is then trained with the data in the new dataset(Pascal VOC)to solve the differences between two tasks.
- The new network is applied to the object classification task on VOC2007 and VOC2012 test set.

# The Main Framework



# The Performance

	plane	bike	bird	boat	btl	bus	car	cat	chair	cow	table	dog	horse	moto	pers	plant	sheep	sofa	train	tv	mAP
INRIA [32]	77.5	63.6	56.1	71.9	33.1	60.6	78.0	58.8	53.5	42.6	54.9	45.8	77.5	64.0	85.9	36.3	44.7	50.6	79.2	53.2	59.4
NUS-PSL [44]	82.5	79.6	64.8	73.4	54.2	75.0	77.5	79.2	46.2	62.7	41.4	74.6	85.0	76.8	91.1	53.9	61.0	67.5	83.6	70.6	70.5
PRE-1000C	88.5	81.5	87.9	82.0	47.5	75.5	90.1	87.2	61.6	75.7	67.3	85.5	83.5	80.0	95.6	60.8	76.8	58.0	90.4	77.9	77.7

Table 1: Per-class results for object classification on the VOC2007 test set (average precision %).

	plane	bike	bird	boat	btl	bus	car	cat	chair	cow	table	dog	horse	moto	pers	plant	sheep	sofa	train	tv	mAP
NUS-PSL [49]	97.3	84.2	80.8	85.3	60.8	89.9	86.8	89.3	75.4	77.8	75.1	83.0	87.5	90.1	95.0	57.8	79.2	73.4	94.5	80.7	82.2
NO PRETRAIN	85.2	75.0	69.4	66.2	48.8	82.1	79.5	79.8	62.4	61.9	49.8	75.9	71.4	82.7	93.1	59.1	69.7	49.3	80.0	76.7	70.9
PRE-1000C	93.5	78.4	87.7	80.9	57.3	85.0	81.6	89.4	66.9	73.8	62.0	89.5	83.2	87.6	95.8	61.4	79.0	54.3	88.0	78.3	78.7
PRE-1000R	93.2	77.9	83.8	80.0	55.8	82.7	79.0	84.3	66.2	71.7	59.5	83.4	81.4	84.8	95.2	59.8	74.9	52.9	83.8	75.7	76.3
PRE-1512	94.6	82.9	88.2	84.1	60.3	89.0	84.4	90.7	72.1	86.8	69.0	92.1	93.4	88.6	96.1	64.3	86.6	62.3	91.1	79.8	82.8

Table 2: Per-class results for object classification on the VOC2012 test set (average precision %).

- A simple transfer learning procedure yields state-of-the-art results on challenging benchmark datasets of much smaller size.

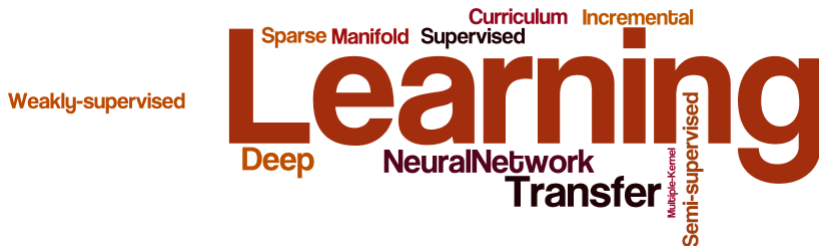
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# Conclusion

**Transfer Learning** is still a hot topic in various fields.

- Image Annotation/Classification;
- Text Classification;
- Recommendation;
- Software Engineering;
- etc.



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Thank you.  
Q&A.