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TensorFlow人工智能引擎入门教程之七 DNN深度神经网络的原理 以及 使用



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DNN 深度神经网络，就是把原有的多层神经网络 扩展到深度学习里面，加上了BP 反馈，是的整理上 loss 收敛 直至不变，同时也有dropout 前面 有很多这个词 出现，dropout 是指 随机用一定概率 把一些 节点失效，进行参与训练 放置数据整理上陷入overfitting 局部最优解。

OK 我们现在打开前面的AlexNet的网络

DNN ,就是去掉C 之后 使用全连接层+dropout下降+relu激活 一层一层的WX+B的 网络模式

```
import input_data mnist = input_data.read_data_sets("/tmp/data/", one_hot=True) import tensorflow as tf
# Parameters learning_rate = 0.001 training_iters = 100000 batch_size = 128 display_step = 10
# Network Parameters n_input = 784 # MNIST data input (img shape: 28*28) n_classes = 10 # MNIST total classes (0-9 digits) dropout = 0.75 # Dropout, probability to keep units
# tf Graph input x = tf.placeholder(tf.float32, [None, n_input]) y = tf.placeholder(tf.float32, [None, n_classes]) keep_prob = tf.placeholder(tf.float32) # Create model
def conv2d(img, w, b):
    return tf.nn.conv2d(img, w, [1, 1, 1, 1], padding='SAME', b=b)
def max_pool(img, k):
    return tf.nn.max_pool(img, [k, k, 1, 1], [1, 1, 1, 1], padding='SAME')
def conv_ne_t(X, weights, biases, dropout):
    # Convolution Layer
    conv1 = conv2d(X, weights['wc1'], biases['bc1'])
    # Max Pooling (down-sampling)
    conv1 = max_pool(conv1, k=2)
    # Apply Dropout
    conv1 = tf.nn.dropout(conv1, dropout)
    # Convolution Layer
    conv2 = conv2d(conv1, weights['wc2'], biases['bc2'])
    # Max Pooling (down-sampling)
    conv2 = max_pool(conv2, k=2)
    # Apply Dropout
    conv2 = tf.nn.dropout(conv2, dropout)
    # Fully connected layer
    dense1 = tf.reshape(conv2, [-1, weights['wd1'].get_shape().as_list()[0]])
    # Reshape conv2 output to fit dense layer input
    dense1 = tf.nn.relu(tf.add(tf.matmul(dense1, weights['wd1']), biases['bd1']))
    # Relu activation
    dense1 = tf.nn.dropout(dense1, dropout)
    # Apply Dropout
    # Output
    out = tf.add(tf.matmul(dense1, weights['out']), biases['out'])
    return out
# Store layers weight & bias
weights = {
    'wc1': tf.Variable(tf.random_normal([5, 5, 1, 32])), # 5x5 conv, 1 input, 32 outputs
    'wc2': tf.Variable(tf.random_normal([5, 5, 32, 64])), # 5x5 conv, 32 inputs, 64 outputs
    'wd1': tf.Variable(tf.random_normal([7*7*64, 1024])), # fully connected, 7*7*64 inputs, 1024 outputs
    'out': tf.Variable(tf.random_normal([1024, n_classes])), # 1024 input, 10 outputs (class prediction)
}
biases = {
    'bc1': tf.Variable(tf.random_normal([32])),
    'bc2': tf.Variable(tf.random_normal([64])),
    'bd1': tf.Variable(tf.random_normal([1024])),
    'out': tf.Variable(tf.random_normal([n_classes]))
}
# Construct model
pred = conv_net(x, weights, biases, keep_prob)
# Define loss and optimizer
cost = tf.reduce_mean(tf.nn.softmax_cross_entropy_with_logits(pred, y))
optimizer = tf.train.AdamOptimizer(learning_rate=learning_rate).minimize(cost)
# Evaluate model
correct_pred = tf.equal(tf.argmax(pred, 1), tf.argmax(y, 1))
accuracy = tf.reduce_mean(tf.cast(correct_pred, tf.float32))
# Initializing the variables
init = tf.initialize_all_variables()
# Launch the graph
with tf.Session() as sess:
    sess.run(init)
    step = 1
    # Keep training until reach max iterations
    while step * batch_size < training_iters:
        batch_xs, batch_ys = mnist.train.next_batch(batch_size)
        # Fit training using batch data
        sess.run(optimizer, feed_dict={x: batch_xs, y: batch_ys, keep_prob: dropout})
        if step % display_step == 0:
            # Calculate batch accuracy
            acc = sess.run(accuracy, feed_dict={x: batch_xs, y: batch_ys, keep_prob: 1.})
            # Calculate batch loss
            loss = sess.run(cost, feed_dict={x: batch_xs, y: batch_ys, keep_prob: 1.})
            print "Iter " + str(step*batch_size) + ", Minibatch Loss = " + "{:.6f}".format(loss) + ", Training Accuracy = " + "{:.5f}".format(acc)
            step += 1
        print "Optimization Finished!"
    # Calculate accuracy for 256 mnist test images
    print "Testing Accuracy:", sess.run(accuracy, feed_dict={x: mnist.test.images[:256], y: mnist.test.labels[:256], keep_prob: 1.})
```

先去掉卷积部分 以及 maxpool部分

下面遵循 WX+B 即可 输入时候[Batchsize,768]

那么 W 应该 需要是[768 ,n] 接下来应该是[n,m]在接下来应该是[m,p]

也就是满足矩阵乘法

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下面来看看我们定义的

```
def dnn(X, _weights, _biases, _dropout):
    # Reshape input picture

    _X = tf.nn.dropout(X, _dropout)  # 这里可以让dropout都不同 我就一样了
    d1 = tf.nn.relu(tf.nn.bias_add(tf.matmul(_X, _weights['wd1']), _biases['bd1']), name='d1')

    d2x = tf.nn.dropout(d1, _dropout)
    d2 = tf.nn.relu(tf.nn.bias_add(tf.matmul(d2x, _weights['wd2']), _biases['bd2']), name='d2')

    #dense1 = tf.nn.relu(tf.matmul(dense1, _weights['wd1']) + _biases['bd1'], name='fc1') # Relu activation
    #dense2 = tf.nn.relu(tf.matmul(dense1, _weights['wd2']) + _biases['bd2'], name='fc2') # Relu activation
    dout = tf.nn.dropout(d2, _dropout)
    # Output, class prediction
    out = tf.matmul(dout, _weights['out']) + _biases['out']
    return out

# Store layers weight & bias
```

修改相应的变量

```
weights = { 'wd1': tf.Variable(tf.random_normal([784,600], stddev=0.01)), 'wd2': tf.Variable(tf.random_normal([600,480], stddev=0.01)), 'out': tf.Variable(tf.random_normal([480, 10])) }
biases = { 'bd1': tf.Variable(tf.random_normal([600])), 'bd2': tf.Variable(tf.random_normal([480])), 'out': tf.Variable(tf.random_normal([10])) }
```

其实我们看出来就是三个全连接层 只不过通过dropout保证 loss一致收敛，不会陷入最优解问题，其实可能实际上的还会有norm 其他一些层 等优化，也许是tanh 或者 sigmoid 的激活函数 这是网络设计的问题，上面的就是一个简单的DNN网络 利用深度学习 比传统的多层网络有了更好的效果以及准确率

看上面NoneX768 768X600 600X480 480X10 = None x 10

ok 下面贴出全部的代码

```
import input_data
mnist = input_data.read_data_sets("/tmp/data/", one_hot=True)
import tensorflow as tf

# Parameters
learning_rate = 0.001
training_iters = 200000
batch_size = 64
display_step = 20
n_classes = 10
n_input = 784
img_shape = 28*28
dropout = 0.8
keep_prob = tf.placeholder(tf.float32)

# Graph input
x = tf.placeholder(tf.float32, [None, n_input])
y = tf.placeholder(tf.float32, [None, n_classes])

# dropout (keep probability)
def init_weights(shape):
    return tf.Variable(tf.random_normal(shape, stddev=0.01))

# Create custom model
def conv2d(name, l_input, w, b):
    return tf.nn.conv2d(l_input, w, [1, 1, 1, 1], padding='SAME', b=b, name=name)

def max_pool(name, l_input, k):
    return tf.nn.max_pool(l_input, [1, k, k, 1], [1, k, k, 1], padding='SAME', name=name)

def norm(name, l_input, lsize=4):
    return tf.nn.l2_normalize(l_input, lsize, bias=1.0, alpha=0.001 / 9.0, beta=0.75, name=name)

def dnn(X, _weights, _biases, _dropout):
    # Reshape input picture
    _X = tf.nn.dropout(X, _dropout)  # 这里可以让dropout都不同 我就一样了
    d1 = tf.nn.relu(tf.nn.bias_add(tf.matmul(_X, _weights['wd1']), _biases['bd1']), name='d1')
    d2x = tf.nn.dropout(d1, _dropout)
    d2 = tf.nn.relu(tf.nn.bias_add(tf.matmul(d2x, _weights['wd2']), _biases['bd2']), name='d2')
    dense1 = tf.nn.relu(tf.matmul(dense1, _weights['wd1']) + _biases['bd1'], name='fc1') # Relu activation
    dense2 = tf.nn.relu(tf.matmul(dense1, _weights['wd2']) + _biases['bd2'], name='fc2') # Relu activation
    dout = tf.nn.dropout(d2, _dropout)
    # Output, class prediction
    out = tf.matmul(dout, _weights['out']) + _biases['out']
    return out

# Store layers weight & bias
weights = { 'wd1': tf.Variable(tf.random_normal([784,600], stddev=0.01)), 'wd2': tf.Variable(tf.random_normal([600,480], stddev=0.01)), 'out': tf.Variable(tf.random_normal([480, 10])) }
biases = { 'bd1': tf.Variable(tf.random_normal([600])), 'bd2': tf.Variable(tf.random_normal([480])), 'out': tf.Variable(tf.random_normal([10])) }

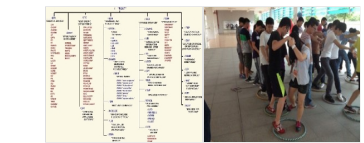
# Construct model
pred = dnn(x, weights, biases, keep_prob)
# Define loss and optimizer
cost = tf.reduce_mean(tf.nn.softmax_cross_entropy_with_logits(pred, y))
optimizer = tf.train.AdamOptimizer(learning_rate=learning_rate).minimize(cost)
# Evaluate model
correct_pred = tf.equal(tf.argmax(pred, 1), tf.argmax(y, 1))
accuracy = tf.reduce_mean(tf.cast(correct_pred, tf.float32))

# Initializing the variables
init = tf.initialize_all_variables()

# Launch the graph
with tf.Session() as sess:
    sess.run(init)
    step = 1
    # Keep training until reach max iterations
    while step * batch_size < training_iters:
        batch_xs, batch_ys = mnist.train.next_batch(batch_size)
        # Fit training using batch data
        sess.run(optimizer, feed_dict={x: batch_xs, y: batch_ys, keep_prob: 1.0})
        # Calculate batch accuracy
        acc = sess.run(accuracy, feed_dict={x: batch_xs, y: batch_ys, keep_prob: 1.0})
        # Calculate batch loss
        loss = sess.run(cost, feed_dict={x: batch_xs, y: batch_ys, keep_prob: 1.0})
        print "Iter " + str(step*batch_size) + ", Minibatch Loss= " + "{:.6f}".format(loss) + ", Training Accuracy= " + "{:.5f}".format(acc)
        step += 1
    print "Optimization Finished!"
    # Calculate accuracy for 256 mnist test images
    print "Testing Accuracy:", sess.run(accuracy, feed_dict={x: mnist.test.images[:256], y: mnist.test.labels[:256], keep_prob: 1.0})
```



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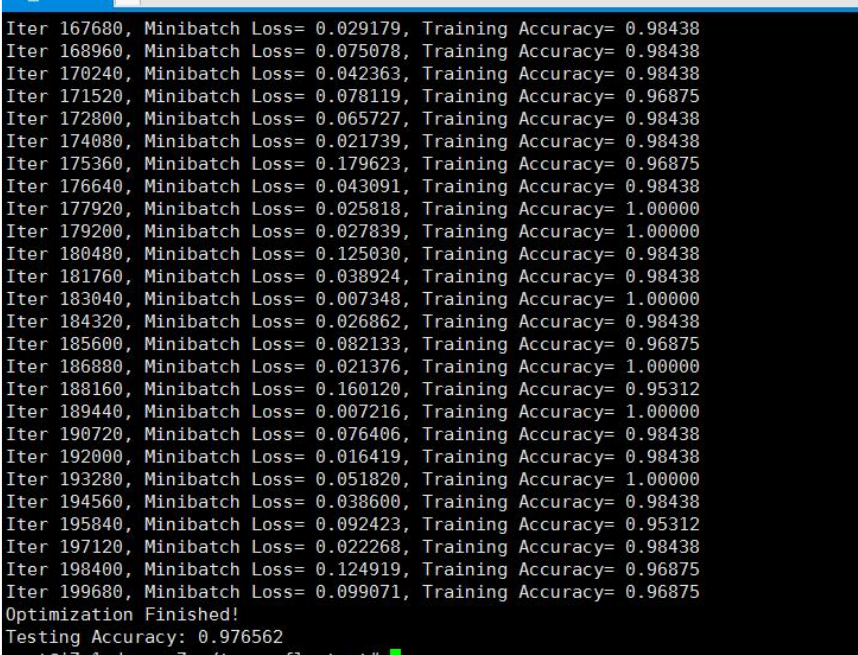
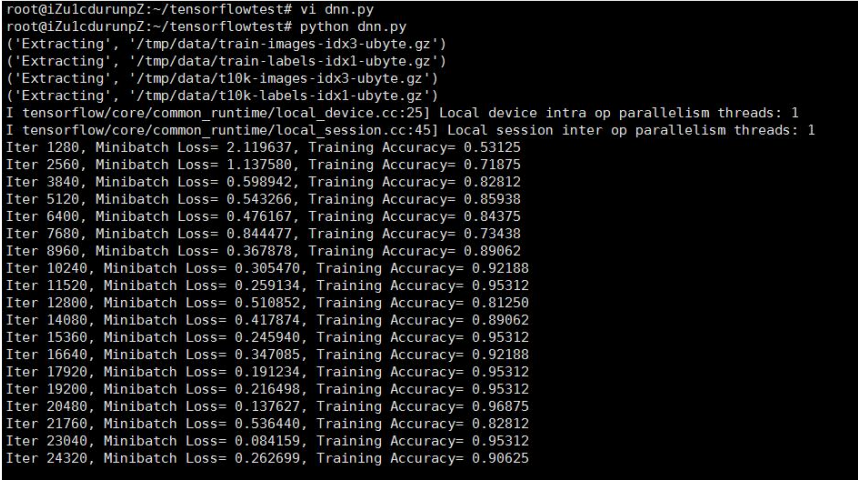
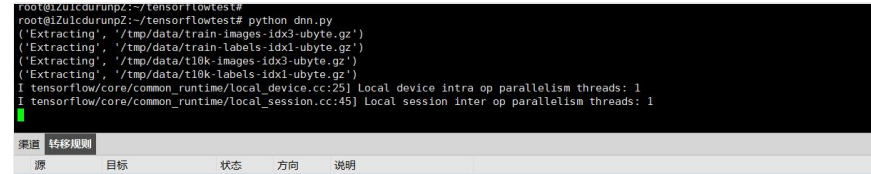


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