Test ID	1	Test Date	2014-05-14
Tester(s)	Fredric Eidsvik	David Lindenberg	

Test Purpose
Test of shoulder pitch to know what pitches will give for different results in height from one meter away from the target.

Methodology
The hand "Rhand" should be on 0.6 to hold the gun The hand should be on 0 to fire the gun The test begins at 1.4 pitch.

Observed Results
1.4 = 20 cm 1.3 = 25 cm 1.2 = 30 cm 1.1 = 35 cm 1.0 = 40 cm 0.9 = 50 cm 0.8 = 60 cm 0.7 = 70 cm 0.6 = 80 cm 0.5 = 90 cm 0.4 = 100 cm 0.3 = 125 cm

Conclusion
This is what we could use if we wanted to hardcode the autoaim.
Verdict: Try to find a nice algorithm to make the robot auto aim

Any appendices can be attached on the next pages.