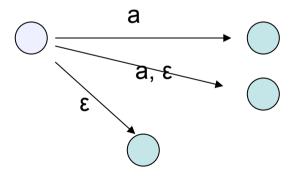
### NFA with ε moves

- · Let ε denote the null string.
- Extend the transition function  $f: Q \times (\Sigma \cup \{\epsilon\}) \rightarrow P(Q)$

- E.g., 
$$f(a) = \{q1, q2\}$$
;  $f(\epsilon) = \{q2, q3\}$ 

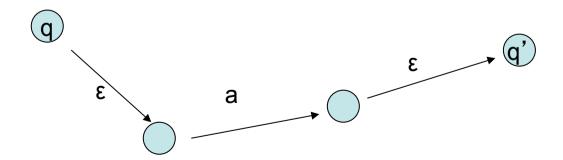


• Are NFA with  $\epsilon$  moves more powerful than NFA and DNA? No.

Lemma. Given an NFA  $M_{\epsilon}$  with  $\epsilon$  moves, we can construct another NFA M without  $\epsilon$  moves accepting the same language.

**Idea**. M uses the same set of states as  $M_{\epsilon}$ .

For every pair of states (q, q'), M has a transition from q to q' labeled with a in  $\Sigma$  if and only if in  $M_s$ , there is a path from q to q' labeled with all  $\epsilon$  except one a.



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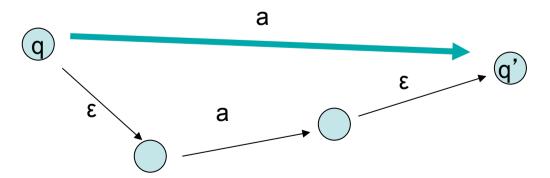
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### Week 1: finite automata

 Summary: Finite automata, deterministic versus nondeterministic computation, languages, limitation of finite automata, regular expressions.

#### Reading:

- Sipser, Chapter 1 (and Chapter 0 for those not confident in discrete math); or
- Hopcroft, Motwani & Ullman (1st edition or 2nd edition),
   Chapter 2 & 3.2

## Non-computational models

Given a language (decision problem) L, we can reason whether there is a finite automaton (pda, or Turing machine) accepting L.

In fact, languages can be characterised by some noncomputation-based models.

- Regular expressions
  - Theorem. A language L is accepted by a DFA if and only if L = L(R) of some regular expression R.

Today's lecture

- Right (Left) Linear grammars Probably exercise
  - Theorem. A language L is accepted by a DFA if and only if L = L(G) of some right linear grammar R.

## Equivalence

- · DFA
- · NFA
- · NFA with ε moves
- Regular expressions

## Regular Expressions

- · A simple way to define a set of strings (a language).
- For example, (0 U 1)0\* denotes the set { 0, 1, 00, 10, 000, 100, 0000, 1000, ...}
- A recursive definition: R is a regular expression over an alphabet  $\Sigma$  if R is
  - a for some a in  $\Sigma$ ,  $\epsilon$ ,  $\emptyset$ ,
  - (R<sub>1</sub> U R<sub>2</sub>), (R<sub>1</sub> o R<sub>2</sub>), or R<sub>1</sub>\*, where R<sub>1</sub> and R<sub>2</sub> are regular expressions.
- More examples: 0\*10\*, (0U1)\*1

### Languages

A regular expression R defines a language L(R).

```
• R = a: L(R) = \{a\}.

• R = \epsilon: L(R) = \{\epsilon\} (i.e., the set of null string).

• R = \emptyset: L(R) is empty.

• R = (R_1 \cup R_2): L(R) = \{w \mid w \text{ is in } L(R_1) \text{ or } L(R_2)\}.

• R = (R_1 \cup R_2): L(R) = \{w \mid w = xy \text{ where } x \text{ is in } L(R_1) \text{ and } y \text{ is in } L(R_2)\}.

• R = R_1^*: L(R) = \{w \mid w \text{ is in } L(R_1)^*\}.
```

Def.  $w = \varepsilon$  or  $w_1 w_2 w_3 ... w_n$ , where  $n \ge 1$  and each  $w_i$  is in  $L(R_1)$ .

## Examples

```
· (O1*)*:
```

For convenience: we let R+ be shorthand for RR\*.

- · (O1<sup>+</sup>)\*:
- 1\* ∅ :
- e\*

## Regular Expressions & DFA

Theorem. Let L be a language accepted by a DFA M. Then there exists a regular expression R such that L(R) = L.

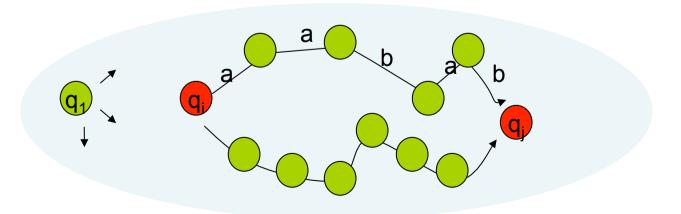
Implication: An NFA or DFA is no more powerful than a regular expression.

## Regular Expressions & DFA

Theorem. If L is accepted by a DFA M, then L = L(R) for some regular expression R.

Suppose that  $M = (Q, \Sigma, f, q_1, F)$  and  $Q = \{q_1, q_2, ..., q_n\}$ , where n denotes the number of states.

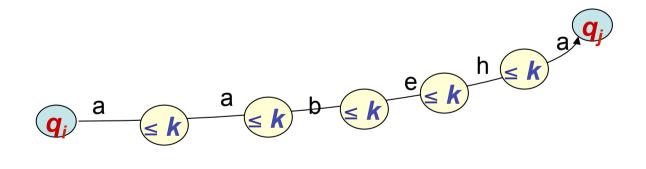
The transition function of M (i.e., f) defines a directed  $\frac{\text{graph}}{\text{graph}}$ , in which every vertex is a state and every edge is labeled with a symbol in  $\Sigma$ .



## From State $q_i$ to State $q_j$

Consider any k in [0, n], and i,j in [1,n].

Let  $S_{i,j} = \{ x \mid x \text{ is the string on a path from } q_i \text{ to } q_j \text{ in } M \}$ Let  $S_{i,j}(k) = \{ x \mid x \text{ is the string on a path from } q_i \text{ to } q_j \text{ in } M, \text{ and excluding the two ends, every state on this path has a label } q_b \text{ with } b \leq k. \}$ 

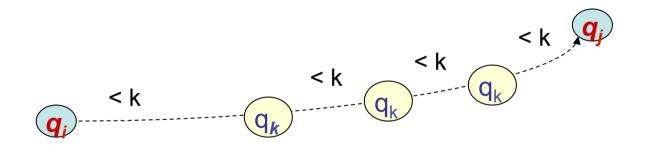


NB.  $S_{i,i}(k)$  is a set, not a regular expression.

Question: What is  $S_{i,i}(0)$ ?

### A Technical Lemma

Lemma.  $S_{i,j}(k) = S_{i,j}(k-1) \cup S_{ik}(k-1) (S_{kk}(k-1))^* S_{kj}(k-1)$ .



$$S_{1,j}(n)$$

Suppose  $q_j$  is a state in F. What does  $S_{1,j}(n) = S_{1,j}$  denote?

# $S_{1,j}(\mathbf{n})$

Suppose  $q_j$  is a state in F.

What does  $S_{1,j}(n) = S_{1,j}$  denote?

•The set of strings that M accepts using the final state  $q_{\rm i}$ .

Let L be the language accepted by M. Then L is equal to the *union* of all  $S_{1,j}(n)$ , where  $q_j$  is in F.

## Converting DFA to regular expressions

**Lemma** For any i, j, k, there is a regular expression R such that  $L(R) = S_{i,i}(k)$ .

Proof. By induction on k.

Basis: k = 0.

Let  $a_1$ ,  $a_2$ , ...,  $a_h$  be symbols in  $\Sigma$  such that  $f(q_i, a_1) = q_j$ ,  $f(q_i, a_2) = q_j$ , ...,  $f(q_i, a_h) = q_j$ .

Let R be the regular expression a<sub>1</sub> U a<sub>2</sub> U ... U a<sub>h</sub>

Then  $L(R) = \{a_1, a_2, ..., a_h\} = S_{i,j}(0)$ .

NB. If no such a exists, then  $R = \emptyset$ .

## Induction Step

Assume that the lemma is true for k-1.

Recall that 
$$S_{i,j}(k) = S_{i,j}(k-1) \cup S_{ik}(k-1) (S_{kk}(k-1))^* S_{kj}(k-1)$$
.

By <u>induction hypothesis</u>, there exist regular expressions R1, R2, R3, and R4 such that

- $L(R1) = S_{i,j}(k-1),$
- $L(R2) = S_{ik}(k-1)$ ,
- $L(R3) = S_{kk}(k-1)$ ,
- $L(R4) = S_{kj}(k-1)$ .

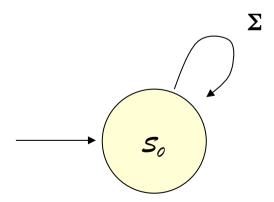
Then  $R = R1 \cup (R2 (R3)^* R4)$  is a regular expression such that  $L(R) = S_{i,i}(k)$ .

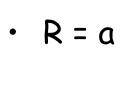
## From regular Expressions to NFA

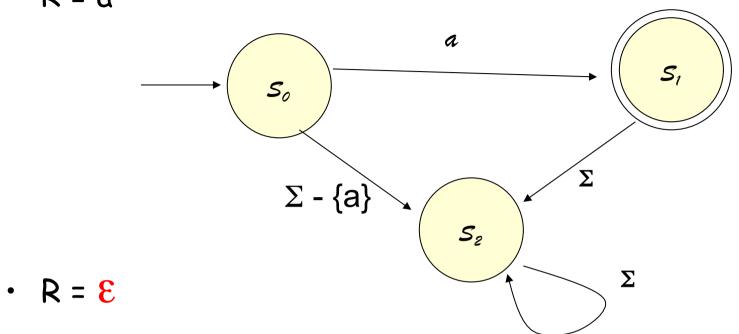
Theorem. Let r be a regular expression. Then there exists an NFA with  $\varepsilon$  moves M such that L(M) = L(R).

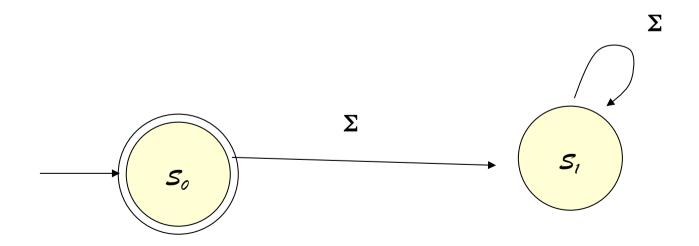
Proof. By induction on the structure of R.

• R = ∅:





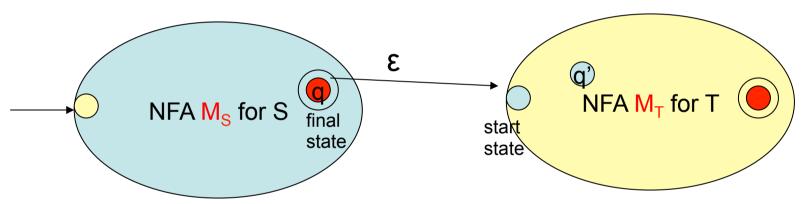




### Induction Step

Consider a regular expression R. Assume the theorem is true for all sub-expressions of R.

Case 1. R= S T

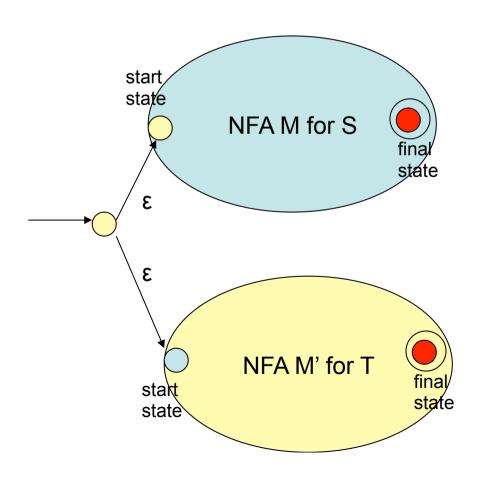


Combine the two NFA to make a bigger NFA for R.

- For each final state q of  $M_S$ , add an  $\epsilon$  transition to the start state of  $M_T$ .
- New final states: All final states of  $M_{\mathsf{T}}$  remain final states. What about the final states of  $M_{\mathsf{S}}$ ?

#### Case 2. R = S U T

Create a new start state, which has a  $\epsilon$  transition to the start states of  $M_S$  and  $M_T$ .



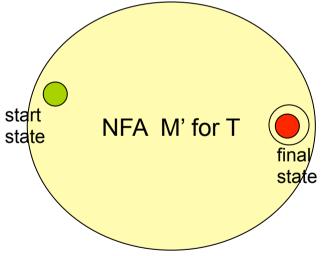
What are the new final states?

Final states of  $M_S$  and  $M_T$ .

#### Case 3. R = T\*

Create a new start state, which is also a new final state, and has an  $\epsilon$  move to the original start state.

Each original final state has an  $\epsilon$  transition to the original start state.



### Case 3. R = T\*

Create a new start state, which is also a new final state, and has an  $\epsilon$  move to the original start state.

Each original final state has an  $\epsilon$  transition to the original start state.

