

# Yue Meng

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## FIELD OF INTERESTS

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Generative AI, LLM, foundation models, multi-agent systems, robotics, computer vision

## EDUCATION

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- Ph.D. in Aeronautics and Astronautics** Sep. 2020 - Current  
Massachusetts Institute of Technology, MA, USA
- M.S. in Electrical and Computer Engineering** Sep. 2017 - Mar. 2019  
University of California San Diego, CA, USA
- B.E. in Department of Automation** Aug. 2013 - Jul. 2017  
Tsinghua University, Beijing, China

## ONGOING PROJECTS

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- Y. Meng**, and C. Fan, “TeLoGraF: Temporal Logic Planning via Graph-encoded Flow Matching”, under review.
- Y. Meng**, F. Chen, Y. Chen and C. Fan, “TL-LLM: Temporal Logic Grounding and Decision Making with Large Language Models”, work in progress.

## SELECTED PUBLICATIONS

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- Y. Meng**, N. Majcherczyk, W. Liu, S. Kiesel, C. Fan and F. Pecora, “Reliable and Efficient Multi-Agent Coordination via Graph Neural Network Variational Autoencoders”, in *IEEE Int. Conf. on Robotics and Automation (ICRA)*, 2025.
- Y. Meng**, and C. Fan, “Diverse Controllable Diffusion Policy with Signal Temporal Logic”, in *IEEE Robotics and Automation Letters (RA-L)*, 2024 [\[PDF\]](#)
- Y. Meng**, S. Vemprala, R. Bonatti, C. Fan, and A. Kapoor, “ConBaT: Control Barrier Transformer for Safe Policy Learning”, in *IEEE Int. Conf. on Robotics and Automation (ICRA)*, 2024 [\[PDF\]](#)
- Y. Meng**, and C. Fan, “Signal Temporal Logic Neural Predictive Control”, in *IEEE Robotics and Automation Letters (RA-L)*, 2023 [\[PDF\]](#)
- Y. Meng**, and C. Fan, “Hybrid Systems Neural Control with Region-of-Attraction Planner”, in *5th Annual Conference on Learning for Dynamics and Control (L4DC)*, 2023 [\[PDF\]](#)
- Y. Meng**, D. Sun, Z. Qiu, M. Waez and C. Fan, “Learning Density Distribution of Reachable States for Autonomous Systems”, in *5th Conference on Robot Learning (CoRL)*, 2021 [\[PDF\]](#)
- Y. Meng**, R. Panda, C. Lin, P. Sattigeri, L. Karlinsky, K. Saenko, A. Oliva and R. Feris, “AdaFuse: Adaptive Temporal Fusion Network for Efficient Action Recognition,” in *Int. Conf. on Learning Representations (ICLR)*, 2021 [\[PDF\]](#)
- Y. Meng**, C. Lin, R. Panda, P. Sattigeri, L. Karlinsky, K. Saenko, A. Oliva and R. Feris, “AR-Net: Adaptive Frame Resolution for Efficient Action Recognition,” in *European Conf. on Computer Vision (ECCV)*, 2020 (acceptance rate 27.0%) [\[PDF\]](#)
- C. Li, **Y. Meng**, S. Chan and Y. Chen, “Learning 3D-aware Egocentric Spatial-Temporal Interaction via Graph Convolutional Networks,” in *ICRA*, 2020 [\[PDF\]](#)
- Q. Feng, **Y. Meng**, M. Shan, and N. Atanasov, “Localization and Mapping using Instance-specific Mesh Models,” in *IEEE/RSJ Int. Conf. on Intelligent Robots and Systems (IROS)*, 2019 [\[PDF\]](#)
- Y. Meng**, Y. Lu, A. Raj, S. Sunarjo, G. Bansal, R. Guo, T. Javidi, and D. Bharadia, “SIGNet: Semantic Instance Aided Unsupervised 3D Geometry Perception,” in *IEEE Conf. on Computer Vision and Pattern Recognition (CVPR)*, 2019 (acceptance rate 25.2%) [\[PDF\]](#)
- Y. Meng**, L. Li, F. Wang, K. Li, and Z. Li, “Analysis of Cooperative Driving Strategies for Nonsignalized Intersections,” *IEEE Transactions on Vehicular Technology (TVT)*, 67 (4), [\[PDF\]](#)

## **AWARDS AND HONORS**

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Amazon Robotics Fellowship, 2023 - 2024

Study & Sports Scholarship of Tsinghua University, 2014, 2015

## **RESEARCH EXPERIENCE**

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**Research Assistant**, Massachusetts Institute of Technology, Cambridge, MA Sep. 2020 - Current  
Advisor: Chuchu Fan, Department of Aeronautics and Astronautics

- Temporal logic decision making using Large Language Models (LLM).
- Neural controller synthesis for Signal Temporal Logic specifications.
- Neural certificates (CLF, CBF) and policy learning for control systems.
- Learning-based reachability distribution estimation via solving Liouville PDE.

**Applied Research Intern**, Amazon Robotics, MA, USA May 2024 - Aug. 2024

Mentor: Nathalie Majcherczyk, Applied Scientist

- Learning multi-agent coordination using Graph Neural Network (GNN).

**Research Intern**, Microsoft Corporation, WA, USA May 2022 - Aug. 2022

Mentor: Sai H. Vemprala, Senior Researcher

- Learning robot safety concepts from demonstrations.

**AI Resident**, IBM Thomas J. Watson Research Center, NY, USA Sep. 2019 - Aug. 2020

Mentor: Rogerio S. Feris, Research Manager

- Efficient video understanding and few-shot learning.

**Research Intern**, Honda Research Institute, CA, USA Mar. 2019 - Jun. 2019

Mentor: Yi-Ting Chen, Research Scientist

- Proposed a bird's-eye view representation for driving scene understanding.

**Research Assistant**, University of California San Diego, CA, USA Jan. 2018 - Mar. 2019

Advisor: Nikolay A. Atanasov, Electrical and Computer Engineering

- Developed semantic perception and tracking pipeline for 3D reconstruction.

**Research Assistant**, University of California San Diego, CA, USA Sep. 2018 - Dec. 2018

Advisor: Dinesh Bharadia, Tara Javidi, Electrical and Computer Engineering

- Proposed semantic unsupervised learning framework for depth and flow estimation.

**Research Assistant**, Tsinghua University, Beijing, China Sep. 2015 - Jun. 2017

Advisor: Li Li, Department of Automation

- Designed a traffic simulation platform and analyzed cooperative driving strategies at intersections

## **PROFESSIONAL EXPERIENCE**

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**Software Engineering Intern**, Google Geo, Mountain View, CA, USA Jun. 2019 - Sep. 2019

- Improved user-photo timestamp correction by using image content-based annotation.

**Software Engineering Intern**, Google Ads, New York, NY, USA Jun. 2018 - Sep. 2018

- Migrated Ads prediction modules from Sibyl to Tensorflow platform.

**System Development Intern**, TuSimple, Beijing, China Jul. 2017 - Sep. 2017

- Implemented Faster-RCNN for cameras on bus and optimized the pipeline by 40%.

## **TEACHING EXPERIENCE**

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**Teaching Assistant**, University of California, San Diego, CA, USA Jan. 2019 - Mar. 2019

Course: Stochastic Processes in Dynamic Systems I

## **TECHNICAL SKILLS**

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**Programming:** Python, C++, Matlab, Julia, C#

**Tools:** Pytorch, Tensorflow, JAX, Linux, ROS, PyBullet, Git, AWS, Docker, Kubernetes, L<sup>A</sup>T<sub>E</sub>X