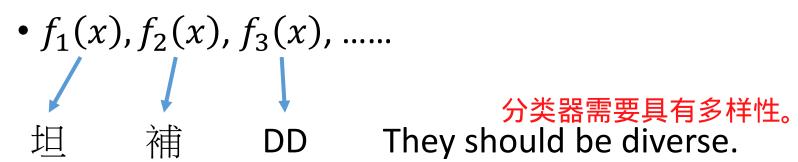
## Ensemble

#### Introduction

- We are almost at the end of the semester/final competition.
  - https://inclass.kaggle.com/c/ml2016-cyber-securityattack-defender/leaderboard
  - https://www.kaggle.com/c/outbrain-clickprediction/leaderboard
  - https://www.kaggle.com/c/transfer-learning-on-stackexchange-tags/leaderboard
- You already developed some algorithms and codes.
   Lazy to modify them.
- Ensemble: improving your machine with little modification

#### Framework of Ensemble

Get a set of classifiers



#### 集合

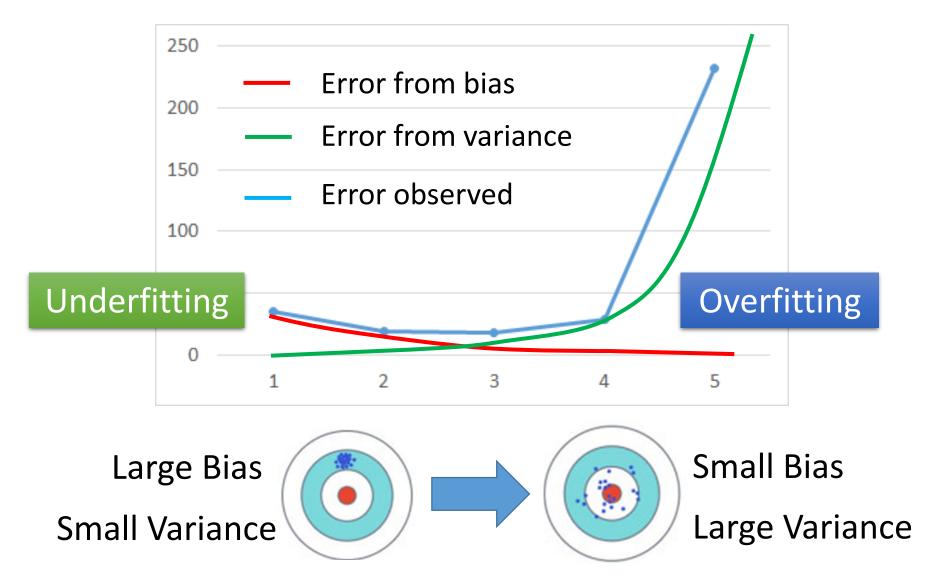
- Aggregate the classifiers (properly)
  - 在打王時每個人都有該站的位置

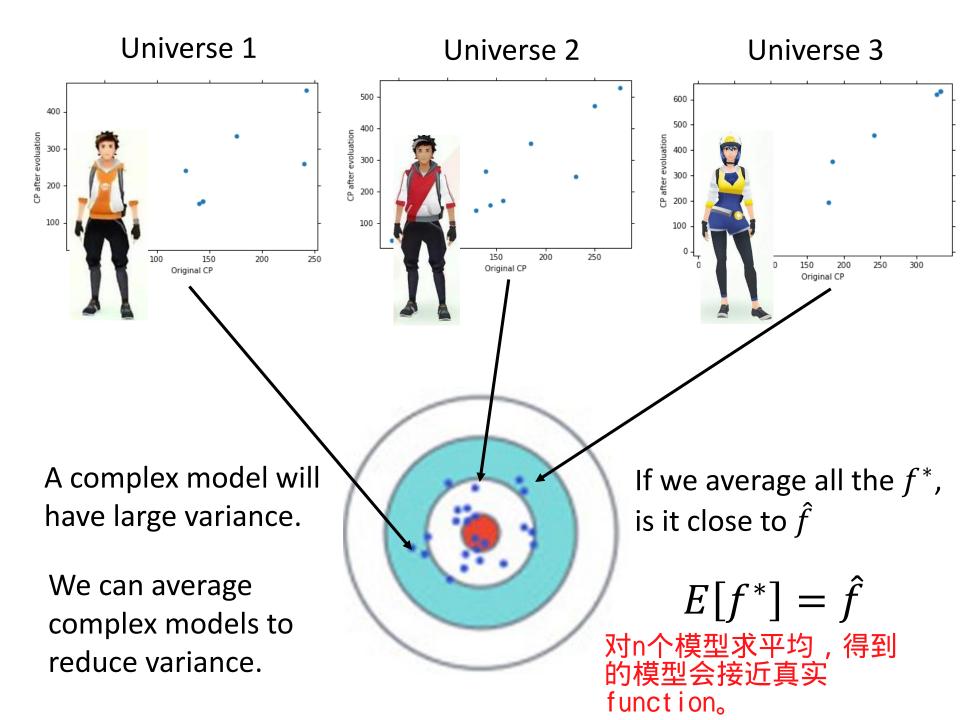
# Ensemble: Bagging

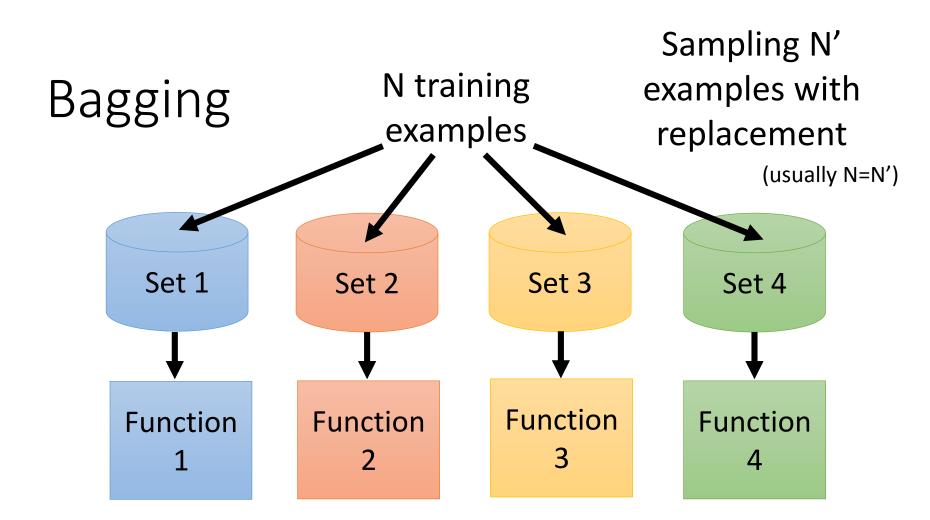
baggi ng就是打包的意思。

#### Error来自于两方面,一个来自bias,一个来自variance。

#### Review: Bias v.s. Variance





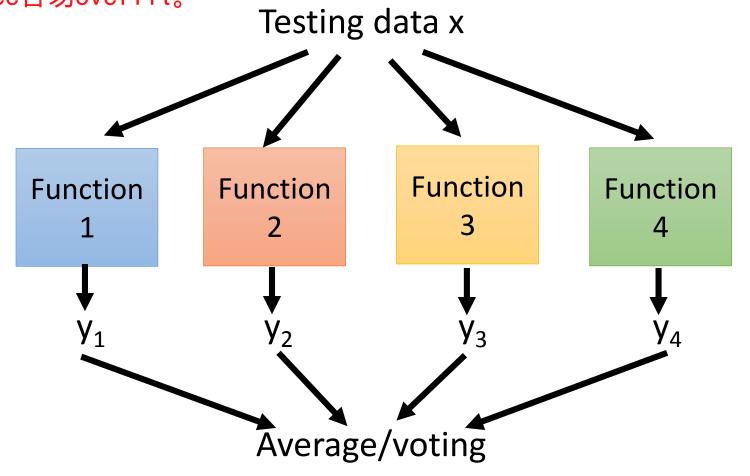


## Bagging

This approach would be helpful when your model is complex, easy to overfit.

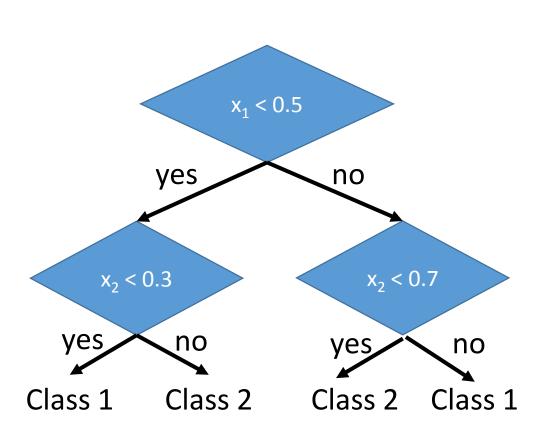
注意:模型复杂度要比较高! e.g. decision tree

容易overfit的模型:1.神经网络实际上不容易overfit。2.decision tree容易overfit。



#### **Decision Tree**

Assume each object x is represented by a 2-dim vector  $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ 



 $x_2 = 0.3$   $x_2 = 0.3$   $x_1 = 0.5$ 

The questions in training .....

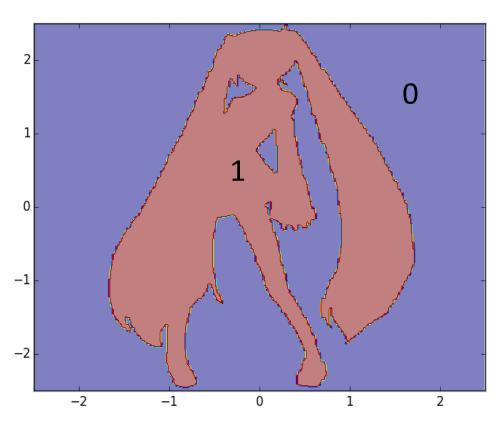
number of branches, Branching criteria, termination criteria, base hypothesis

Can have more complex questions

#### Decision tree的实际例子。

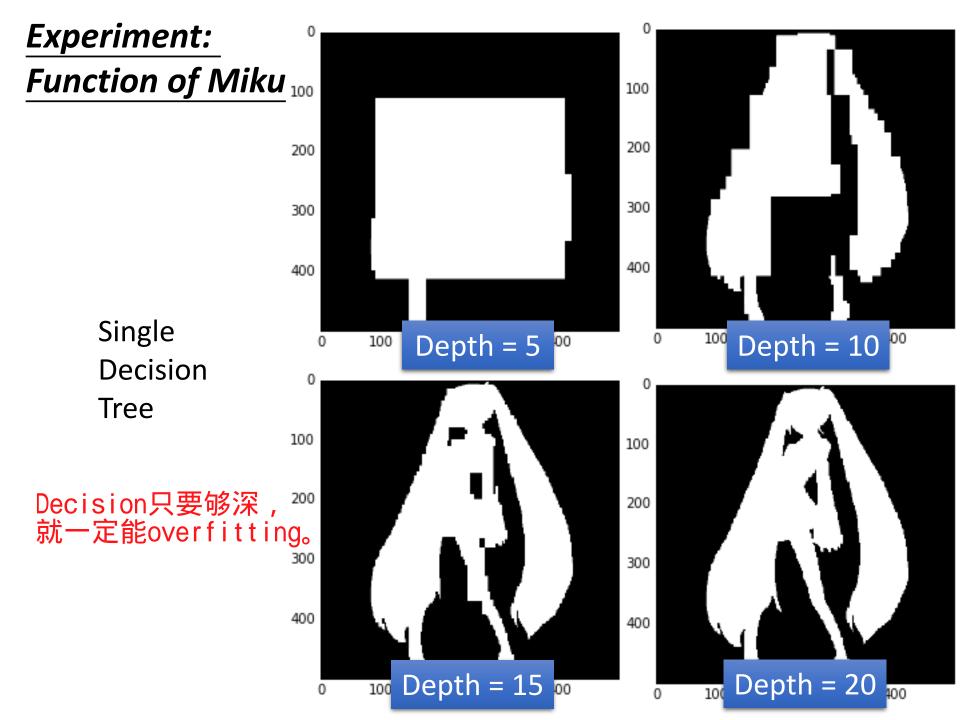
#### Experiment: Function of Miku





http://speech.ee.ntu.edu.tw/~tlkagk/courses/ MLDS\_2015\_2/theano/miku 数据下载。

(1st column: x, 2nd column: y, 3rd column: output (1 or 0))



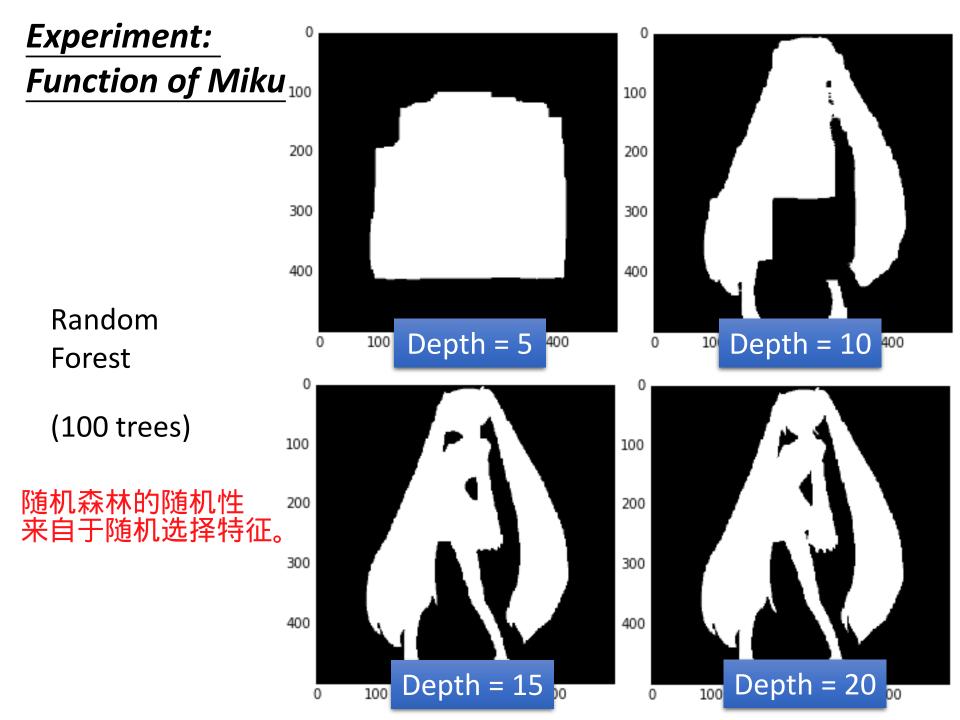
由于decision tree非常容易过拟合, 因此在dicision tree上做bagging是· 不错的选择。 Kandom Forest

train	f <sub>1</sub>	f <sub>2</sub>	f <sub>3</sub>	f <sub>4</sub>
X <sup>1</sup>	0	X	0	X
$x^2$	0	X	X	0
$x^3$	X	0	0	X
$x^4$	X	0	X	0

- Decision tree:
  - Easy to achieve 0% error rate on training data
    - If each training example has its own leaf ....
- Random forest: Bagging of decision tree
  - Resampling training data is not sufficient
  - Randomly restrict the features/questions used in each split
- Out-of-bag validation for bagging
  - Using RF =  $f_2+f_4$  to test  $x^1$
  - Using RF =  $f_2+f_3$  to test  $x^2$
  - Using RF =  $f_1+f_4$  to test  $x^3$
  - Using RF =  $f_1+f_3$  to test  $x^4$

bagging不需要特别地准备 validation数据。

Out-of-bag (OOB) error
Good error estimation
of testing set



Boosting是提升的意思。

# Ensemble: Boosting

Improving Weak Classifiers

Bagging是一群很强(复杂度高)的模型的集合。 Boosting相反,是一群弱的模型的集合。

#### Boosting

# Training data: $\{(x^1, \hat{y}^1), \dots, (x^n, \hat{y}^n), \dots, (x^N, \hat{y}^N)\}$ $\hat{y} = \pm 1 \text{ (binary classification)}$

- Guarantee: 这里说的error指的是training上的。
  - If your ML algorithm can produce classifier with error rate smaller than 50% on training data
  - You can obtain 0% error rate classifier after boosting.
- Framework of boosting
  - Obtain the first classifier  $f_1(x)$
  - Find another function  $f_2(x)$  to help  $f_1(x)$ 
    - However, if  $f_2(x)$  is similar to  $f_1(x)$ , it will not help a lot.
    - We want  $f_2(x)$  to be complementary with  $f_1(x)$  (How?)
  - Obtain the second classifier  $f_2(x)$
  - ..... Finally, combining all the classifiers
- The classifiers are learned sequentially.

#### How to obtain different classifiers?

#### 两种方法

- Training on different training data sets
- How to have different training data sets
  - Re-sampling your training data to form a new set
  - Re-weighting your training data to form a new set
  - In real implementation, you only have to change the cost/objective function

#### re-weighting实际上可以看作是re-sampling

$$(x^1, \hat{y}^1, u^1)$$
  $u^1 = 1$  0.4

$$(x^2, \hat{y}^2, u^2)$$
  $u^2 = 1$  2.1

$$(x^3, \hat{y}^3, u^3)$$
  $u^3 = 1$  0.7

$$L(f) = \sum_{n} l(f(x^n), \hat{y}^n)$$

$$L(f) = \sum_{n} u^{n} l(f(x^{n}), \hat{y}^{n})$$

#### Idea of Adaboost

- Idea: training  $f_2(x)$  on the new training set that fails  $f_1(x)$
- How to find a new training set that fails  $f_1(x)$ ?

 $\varepsilon_1$ : the error rate of  $f_1(x)$  on its training data

$$\varepsilon_1 = \frac{\sum_n u_1^n \delta(f_1(x^n) \neq \hat{y}^n)}{Z_1} \qquad Z_1 = \sum_n u_1^n \qquad \varepsilon_1 < 0.5$$

Changing the example weights from  $u_1^n$  to  $u_2^n$  such that

$$\frac{\sum_{n} u_{2}^{n} \delta(f_{1}(x^{n}) \neq \hat{y}^{n})}{Z_{2}} = 0.5$$
 The performance of  $f_{1}$  for new weights would be random.

Training  $f_2(x)$  based on the new weights  $u_2^n$ 

- Idea: training  $f_2(x)$  on the new training set that fails  $f_1(x)$
- How to find a new training set that fails  $f_1(x)$ ?

$$(x^{1}, \hat{y}^{1}, u^{1}) \quad u^{1} = 1 \qquad \qquad u^{1} = 1/\sqrt{3}$$

$$(x^{2}, \hat{y}^{2}, u^{2}) \quad u^{2} = 1 \qquad \qquad u^{2} = \sqrt{3}$$

$$(x^{3}, \hat{y}^{3}, u^{3}) \quad u^{3} = 1 \qquad \qquad u^{3} = 1/\sqrt{3}$$

$$(x^{4}, \hat{y}^{4}, u^{4}) \quad u^{4} = 1 \qquad \qquad u^{4} = 1/\sqrt{3}$$

$$\varepsilon_{1} = 0.25$$

$$f_{1}(x)$$

$$\varepsilon_{2} < 0.5$$

要使答错的比重增大才可能使错误率变成0.5。

- Idea: training  $f_2(x)$  on the new training set that fails  $f_1(x)$
- How to find a new training set that fails  $f_1(x)$ ?

```
If x^n misclassified by f_1 (f_1(x^n) \neq \hat{y}^n)
u_2^n \leftarrow u_1^n \text{ multiplying } d_1 \text{ increase}
If x^n correctly classified by f_1 (f_1(x^n) = \hat{y}^n)
u_2^n \leftarrow u_1^n \text{ devided by } d_1 \text{ decrease}
```

 $f_2$  will be learned based on example weights  $u_2^n$ 

What is the value of  $d_1$ ?

$$\varepsilon_{1} = \frac{\sum_{n} u_{1}^{n} \delta(f_{1}(x^{n}) \neq \hat{y}^{n})}{Z_{1}} \qquad Z_{1} = \sum_{n} u_{1}^{n}$$

$$\frac{\sum_{n} u_{2}^{n} \delta(f_{1}(x^{n}) \neq \hat{y}^{n})}{Z_{2}} = 0.5 \qquad f_{1}(x^{n}) \neq \hat{y}^{n} \quad u_{2}^{n} \leftarrow u_{1}^{n} \text{ multiplying } d_{1}$$

$$= \sum_{f_{1}(x^{n}) \neq \hat{y}^{n}} u_{1}^{n} d_{1} \qquad = \sum_{f_{1}(x^{n}) \neq \hat{y}^{n}} u_{2}^{n} + \sum_{f_{1}(x^{n}) = \hat{y}^{n}} u_{2}^{n}$$

$$= \sum_{n} u_{1}^{n} d_{1} \qquad = \sum_{f_{1}(x^{n}) \neq \hat{y}^{n}} u_{1}^{n} d_{1} + \sum_{f_{1}(x^{n}) = \hat{y}^{n}} u_{1}^{n} d_{1}$$

$$= \sum_{f_{1}(x^{n}) \neq \hat{y}^{n}} u_{1}^{n} d_{1} + \sum_{f_{1}(x^{n}) = \hat{y}^{n}} u_{1}^{n} d_{1}$$

$$\frac{\sum_{f_{1}(x^{n}) \neq \hat{y}^{n}} u_{1}^{n} d_{1} + \sum_{f_{1}(x^{n}) = \hat{y}^{n}} u_{1}^{n} d_{1}}{\sum_{f_{1}(x^{n}) \neq \hat{y}^{n}} u_{1}^{n} d_{1}} = 2$$

$$\begin{split} \varepsilon_{1} &= \frac{\sum_{n} u_{1}^{n} \delta(f_{1}(x^{n}) \neq \hat{y}^{n})}{Z_{1}} \qquad Z_{1} = \sum_{n} u_{1}^{n} \\ &\frac{\sum_{n} u_{2}^{n} \delta(f_{1}(x^{n}) \neq \hat{y}^{n})}{Z_{2}} = 0.5 \quad \frac{f_{1}(x^{n}) \neq \hat{y}^{n}}{f_{1}(x^{n}) = \hat{y}^{n}} \quad u_{2}^{n} \leftarrow u_{1}^{n} \text{ multiplying } d_{1} \\ &\frac{\sum_{f_{1}(x^{n}) \neq \hat{y}^{n}} u_{1}^{n} d_{1} + \sum_{f_{1}(x^{n}) = \hat{y}^{n}} u_{1}^{n} / d_{1}}{\sum_{f_{1}(x^{n}) \neq \hat{y}^{n}} u_{1}^{n} d_{1}} = 2 \quad \frac{\sum_{f_{1}(x^{n}) = \hat{y}^{n}} u_{1}^{n} / d_{1}}{\sum_{f_{1}(x^{n}) \neq \hat{y}^{n}} u_{1}^{n} d_{1}} = 1 \\ &\sum_{f_{1}(x^{n}) \neq \hat{y}^{n}} u_{1}^{n} d_{1} = \sum_{f_{1}(x^{n}) \neq \hat{y}^{n}} u_{1}^{n} d_{1} \quad \frac{1}{d_{1}} \sum_{f_{1}(x^{n}) = \hat{y}^{n}} u_{1}^{n} = d_{1} \sum_{f_{1}(x^{n}) \neq \hat{y}^{n}} u_{1}^{n} \\ &\varepsilon_{1} = \frac{\sum_{f_{1}(x^{n}) \neq \hat{y}^{n}} u_{1}^{n}}{Z_{1}} \quad Z_{1}(1 - \varepsilon_{1}) \quad Z_{1}\varepsilon_{1} \\ &\sum_{f_{1}(x^{n}) \neq \hat{y}^{n}} u_{1}^{n} \quad Z_{1}(1 - \varepsilon_{1}) / d_{1} = Z_{1}\varepsilon_{1} d_{1} \\ &\int_{f_{1}(x^{n}) \neq \hat{y}^{n}} u_{1}^{n} & J_{1}(1 - \varepsilon_{1}) / J_{1} = J_{1}\varepsilon_{1} \\ &\int_{f_{1}(x^{n}) \neq \hat{y}^{n}} u_{1}^{n} & J_{1}(1 - \varepsilon_{1}) / J_{2} \\ &\sum_{f_{1}(x^{n}) \neq \hat{y}^{n}} u_{1}^{n} & J_{1}(1 - \varepsilon_{1}) / J_{2} & J_{1}\varepsilon_{1} \\ &\int_{f_{1}(x^{n}) \neq \hat{y}^{n}} u_{1}^{n} & J_{1}(1 - \varepsilon_{1}) / J_{2} & J_{1}\varepsilon_{1} \\ &\int_{f_{1}(x^{n}) \neq \hat{y}^{n}} u_{1}^{n} & J_{1}(1 - \varepsilon_{1}) / J_{2} & J_{1}\varepsilon_{1} \\ &\int_{f_{1}(x^{n}) \neq \hat{y}^{n}} u_{1}^{n} & J_{1}(1 - \varepsilon_{1}) / J_{2} & J_{1}\varepsilon_{1} \\ &\int_{f_{1}(x^{n}) \neq \hat{y}^{n}} u_{1}^{n} & J_{1}(1 - \varepsilon_{1}) / J_{2} & J_{1}\varepsilon_{1} \\ &\int_{f_{1}(x^{n}) \neq \hat{y}^{n}} u_{1}^{n} & J_{1}(1 - \varepsilon_{1}) / J_{2} & J_{1}\varepsilon_{1} \\ &\int_{f_{1}(x^{n}) \neq \hat{y}^{n}} u_{1}^{n} & J_{1}(1 - \varepsilon_{1}) / J_{2} & J_{1}\varepsilon_{1} \\ &\int_{f_{1}(x^{n}) \neq \hat{y}^{n}} u_{1}^{n} & J_{1}(1 - \varepsilon_{1}) / J_{2}(1 - \varepsilon_{1})$$

#### Algorithm for AdaBoost

- Giving training data
  - $\{(x^1, \hat{y}^1, u_1^1), \cdots, (x^n, \hat{y}^n, u_1^n), \cdots, (x^N, \hat{y}^N, u_1^N)\}$ 
    - $\hat{y} = \pm 1$  (Binary classification),  $u_1^n = 1$  (equal weights)
- For t = 1, ..., T:
  - Training weak classifier  $f_t(x)$  with weights  $\{u_t^1, \dots, u_t^N\}$
  - $\varepsilon_t$  is the error rate of  $f_t(x)$  with weights  $\{u_t^1, \dots, u_t^N\}$
  - For n = 1, ..., N:

• If 
$$x^n$$
 is misclassified classified by  $f_t(x)$ :
•  $u^n_{t+1} = u^n_t \times d_t = u^n_t \times \exp(\alpha_t)$   $d_t = \sqrt{(1 - \varepsilon_t)/\varepsilon_t}$ 

- $u_{t+1}^n = u_t^n/d_t = u_t^n \times \exp(-\alpha_t)$   $\alpha_t = \ln\sqrt{(1-\varepsilon_t)/\varepsilon_t}$

$$u_{t+1}^n \leftarrow u_t^n \times exp(-\hat{y}^n + (y^n)\alpha_t)$$

## Algorithm for AdaBoost

- We obtain a set of functions:  $f_1(x), ..., f_t(x)$ , ...,  $f_T(x)$
- How to aggregate them?
  - Uniform weight:

• 
$$H(x) = sign(\sum_{t=1}^{T} f_t(x))$$

- Non-uniform weight:
  - $H(x) = sign(\sum_{t=1}^{T} \alpha_t f_t(x))$

Smaller error  $\varepsilon_t$ , larger weight for final voting

$$\alpha_t = \ln \sqrt{(1 - \varepsilon_t)/\varepsilon_t} \qquad \qquad \epsilon^t = 0.1 \qquad \epsilon^t = 0.4$$

$$u_{t+1}^n = u_t^n \times \exp(-\hat{y}^n f_t(x^n) \alpha_t) \qquad \alpha^t = 1.10 \qquad \alpha^t = 0.20$$

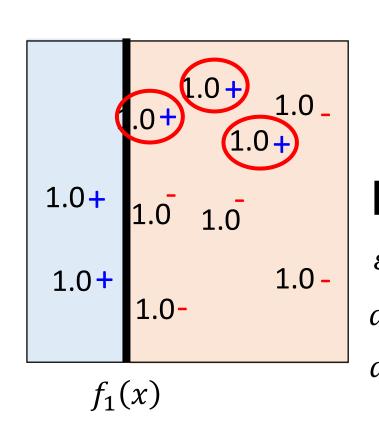
$$u_{t+1}^n = u_t^n \times exp(-\hat{y}^n f_t(x^n) \alpha_t) \quad \alpha^t = 1.10 \quad \alpha^t = 0.20$$

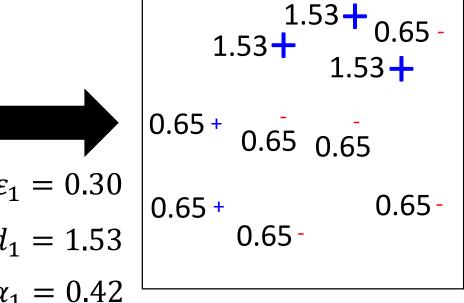
#### 假定我们就用3个弱分类器。

T=3, weak classifier = decision stump

• t=1

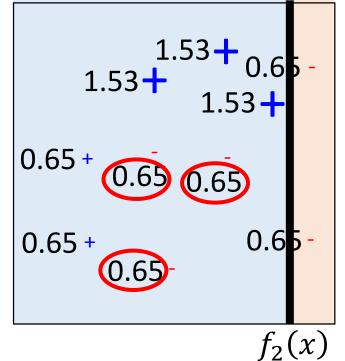
decision stump不是决策树,它就是在二维平面上垂直或者水平切一刀,按照这个切痕为界限分类。





T=3, weak classifier = decision stump

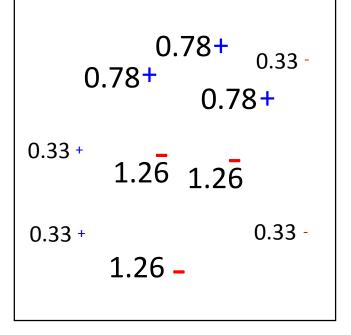
• t=2 
$$\alpha_1 = 0.42$$





$$d_2 = 0.21$$
 $d_2 = 1.94$ 

$$\alpha_2 = 0.66$$



T=3, weak classifier = decision stump

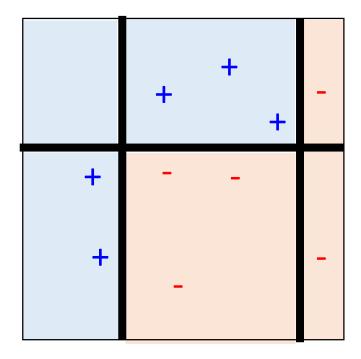
• t=3 
$$a_1 = 0.42$$
  $a_2 = 0.66$ 

$$f_{3}(x) = 0.78 + 0.33 - 0.78 + 0.33 - 0.33 + 0.33 - 0.3$$

$$\varepsilon_3 = 0.13$$
$$d_3 = 2.59$$
$$\alpha_3 = 0.95$$

$$f_3(x)$$
:

• Final Classifier:  $H(x) = sign(\sum_{t=1}^{T} \alpha_t f_t(x))$  系数相当于投票的权重。



# Warning of Math

$$H(x) = sign\left(\sum_{t=1}^{T} \alpha_t f_t(x)\right) \quad \alpha_t = ln\sqrt{(1 - \varepsilon_t)/\varepsilon_t}$$

As we have more and more  $f_t$  (T increases), H(x) achieves smaller and smaller error rate on training data.

#### Error Rate of Final Classifier

• Final classifier:  $H(x) = sign(\sum_{t=1}^{T} \alpha_t f_t(x))$ 

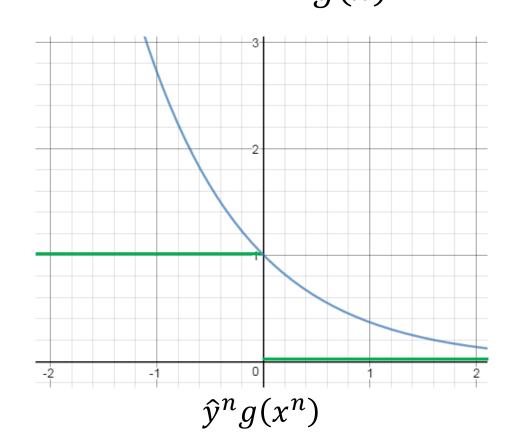
• 
$$\alpha_t = ln\sqrt{(1-\varepsilon_t)/\varepsilon_t}$$

**Training Data Error Rate** 

$$=\frac{1}{N}\sum_{n}\delta(H(x^{n})\neq\hat{y}^{n})$$

$$= \frac{1}{N} \sum_{n} \underline{\delta(\hat{y}^n g(x^n) < 0)}$$

$$\leq \frac{1}{N} \sum_{n} \underline{exp(-\hat{y}^n g(x^n))}$$



**Training Data Error Rate** 

$$\leq \frac{1}{N} \sum_{n} exp(-\hat{y}^n g(x^n)) = \frac{1}{N} Z_{T+1}$$

$$g(x) = \sum_{t=1}^{T} \alpha_t f_t(x)$$
$$\alpha_t = \ln \sqrt{(1 - \varepsilon_t)/\varepsilon_t}$$

 $Z_t$ : the summation of the weights of training data for training  $f_t$ 

What is 
$$Z_{T+1} = ?$$
  $Z_{T+1} = \sum_{n} u_{T+1}^{n}$ 

$$u_1^n = 1$$

$$u_{t+1}^n = u_t^n \times exp(-\hat{y}^n f_t(x^n) \alpha_t)$$

$$u_{t+1}^n = u_t^n \times exp(-\hat{y}^n f_t(x^n) \alpha_t)$$

$$Z_{T+1} = \sum_{n} \prod_{t=1}^{T} exp(-\hat{y}^n f_t(x^n) \alpha_t)$$

$$= \sum_{n} exp\left(-\hat{y}^n \sum_{t=1}^{T} f_t(x^n) \alpha_t\right)$$

**Training Data Error Rate** 

$$\leq \frac{1}{N} \sum_{n} exp(-\hat{y}^n g(x^n)) = \frac{1}{N} Z_{T+1}$$

$$g(x) = \sum_{t=1}^{T} \alpha_t f_t(x)$$
$$\alpha_t = \ln \sqrt{(1 - \varepsilon_t)/\varepsilon_t}$$

 $Z_1 = N$  (equal weights)

$$Z_{t} = \underline{Z_{t-1}\varepsilon_{t}}exp(\alpha_{t}) + \underline{Z_{t-1}(1-\varepsilon_{t})}exp(-\alpha_{t})$$

Misclassified portion in  $Z_{t-1}$  Correctly classified portion in  $Z_{t-1}$ 

$$= Z_{t-1}\varepsilon_t\sqrt{(1-\varepsilon_t)/\varepsilon_t} + Z_{t-1}(1-\varepsilon_t)\sqrt{\varepsilon_t/(1-\varepsilon_t)}$$

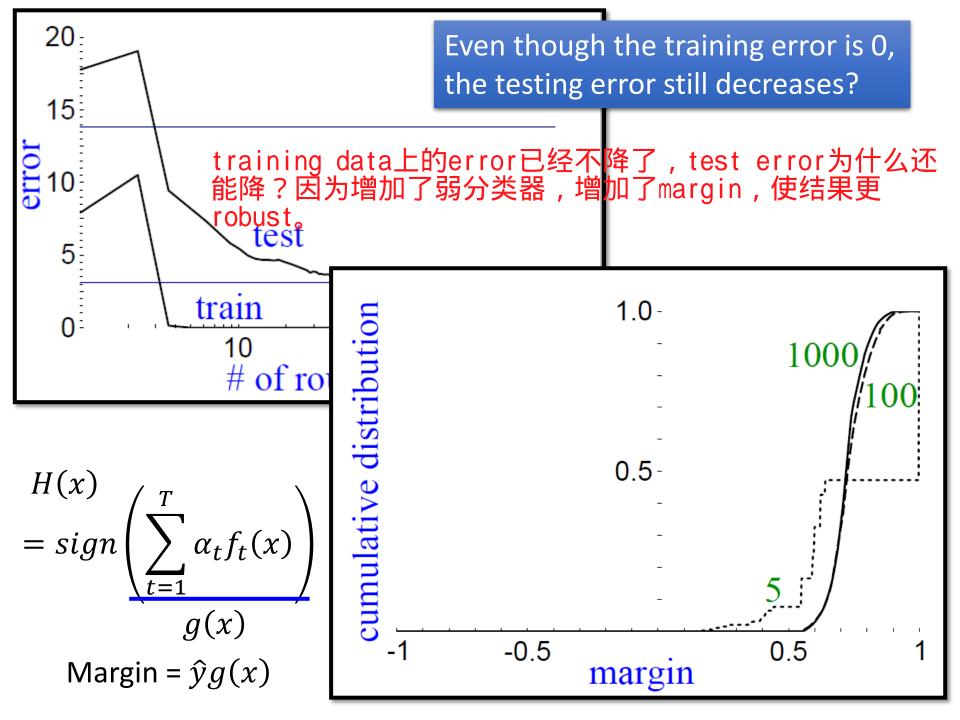
$$= Z_{t-1} \times 2\sqrt{\varepsilon_t(1-\varepsilon_t)} \qquad Z_T$$

$$Z_{T+1} = N \prod_{t=1}^{I} 2\sqrt{\varepsilon_t (1 - \varepsilon_t)}$$

Training Data Error Rate 
$$\leq \prod_{t=1}^{r} 2\sqrt{\epsilon_t(1-\epsilon_t)}$$

Smaller and smaller

# End of Warning



## Large Margin?

$$H(x) = sign\left(\sum_{t=1}^{T} \alpha_t f_t(x)\right)$$

$$g(x)$$

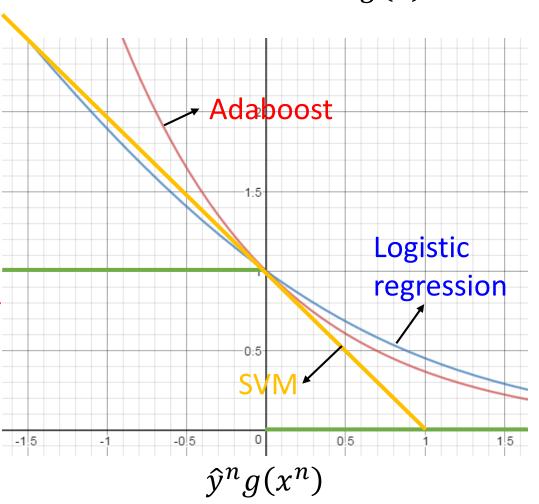
Training Data Error Rate =

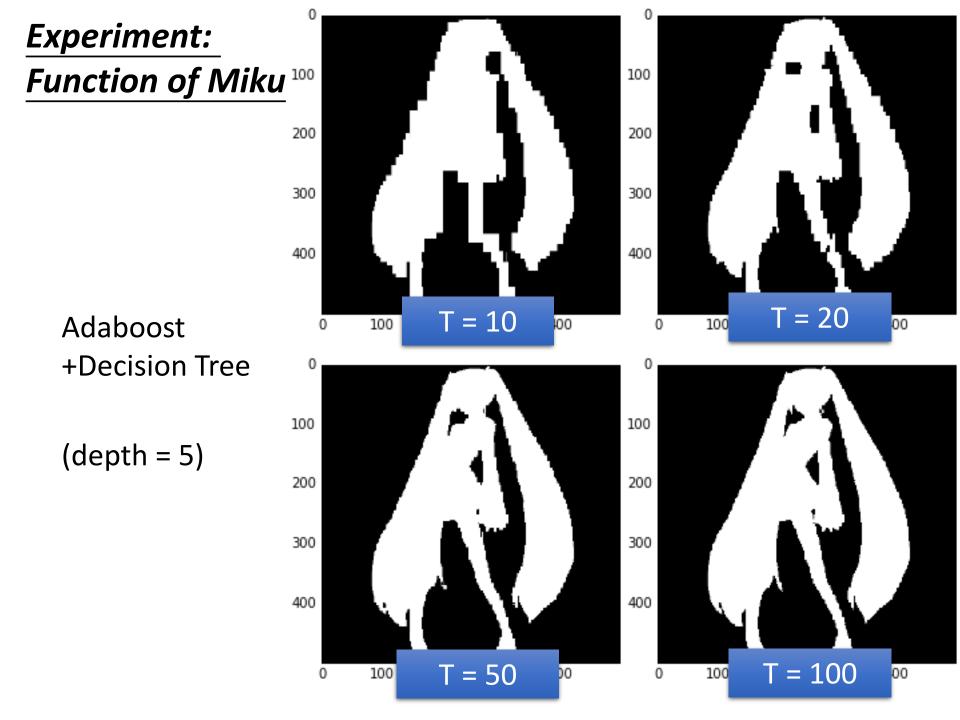
$$=\frac{1}{N}\sum_{n}\delta(H(x^{n})\neq\hat{y}^{n})$$

$$\leq \frac{1}{N} \sum_{n} exp(-\hat{y}^{n} g(x^{n}))$$

$$= \prod_{t=1}^{T} 2\sqrt{\epsilon_t (1 - \epsilon_t)}$$

Getting smaller and smaller as T increase





#### To learn more ...

#### Introduction of Adaboost:

• Freund; Schapire (1999). "A Short Introduction to Boosting"

#### Multiclass/Regression

- Y. Freund, R. Schapire, "A Decision-Theoretic Generalization of on-Line Learning and an Application to Boosting", 1995.
- Robert E. Schapire and Yoram Singer. Improved boosting algorithms using confidence-rated predictions. In Proceedings of the Eleventh Annual Conference on Computational Learning Theory, pages 80–91, 1998.

#### Gentle Boost

• Schapire, Robert; Singer, Yoram (1999). "Improved Boosting Algorithms Using Confidence-rated Predictions".

## General Formulation of Boosting

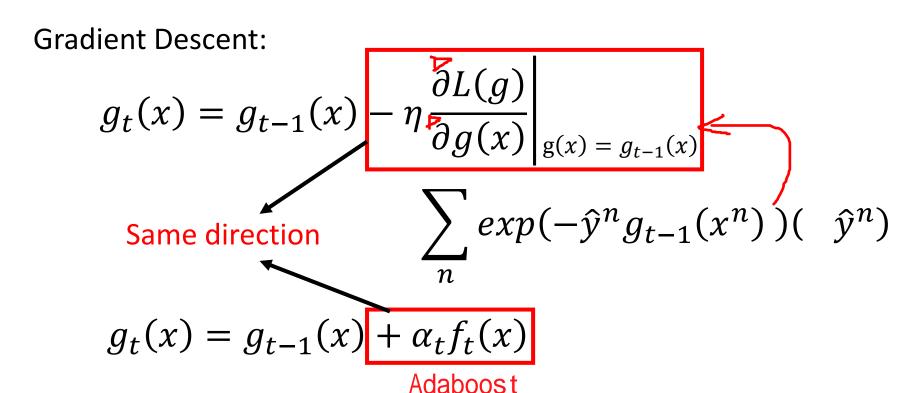
- Initial function  $g_0(x) = 0$
- For t = 1 to T:
  - Find a function  $f_t(x)$  and  $\alpha_t$  to improve  $g_{t-1}(x)$ 
    - $g_{t-1}(x) = \sum_{i=1}^{t-1} \alpha_i f_i(x)$
  - $g_t(x) = g_{t-1}(x) + \alpha_t f_t(x)$
- Output:  $H(x) = sign(g_T(x))$

What is the learning target of g(x)?

Minimize 
$$L(g) = \sum_{n} l(\hat{y}^n, g(x^n)) = \sum_{n} exp(-\hat{y}^n g(x^n))$$

#### **Gradient Boosting**

- Find g(x), minimize  $L(g) = \sum_{n} exp(-\hat{y}^{n}g(x^{n}))$ 
  - If we already have  $g(x) = g_{t-1}(x)$ , how to update g(x)?



## **Gradient Boosting**

$$f_t(x) = \sum_{n} exp(-\hat{y}^n g_t(x^n))(\hat{y}^n)$$
Same direction

We want to find  $f_t(x)$  maximizing

$$\sum_{n} \frac{exp(-\hat{y}^n g_{t-1}(x^n))}{example \text{ weight } u_t^n} \frac{\text{Minimize Error}}{(\hat{y}^n) f_t(x^n)}$$

$$\begin{split} u^n_t &= exp \Big( -\hat{y}^n g_{t-1}(x^n) \Big) = exp \left( -\hat{y}^n \sum_{i=1}^{t-1} \alpha_i \, f_i(x^n) \right) \\ &= \prod_{i=1}^{t-1} exp \Big( -\hat{y}^n \alpha_i f_i(x^n) \Big) \quad \text{Exactly the weights we obtain in Adaboost} \end{split}$$

## **Gradient Boosting**

• Find g(x), minimize  $L(g) = \sum_{n} exp(-\hat{y}^{n}g(x^{n}))$ 

$$g_t(x) = g_{t-1}(x) + \alpha_t f_t(x)$$

 $\alpha_t$  is something like learning rate

Find  $\alpha_t$  minimzing  $L(g_{t+1})$ 

$$L(g) = \sum_{n} exp(-\hat{y}^{n}(g_{t-1}(x) + \alpha_{t}f_{t}(x)))$$

$$= \sum_{n} exp(-\hat{y}^{n}g_{t-1}(x))exp(-\hat{y}^{n}\alpha_{t}f_{t}(x))$$

$$= \sum_{n} exp(-\hat{y}^{n}g_{t-1}(x^{n}))exp(\alpha_{t})$$

$$+ \sum_{\hat{y}^{n}=f_{t}(x)} exp(-\hat{y}^{n}g_{t-1}(x^{n}))exp(-\alpha_{t})$$

Find  $\alpha_t$  such that  $\frac{\partial L(g)}{\partial \alpha_t} = 0$   $\alpha_t = \frac{\ln \sqrt{(1-\varepsilon_t)/\varepsilon_t}}{2}$ 

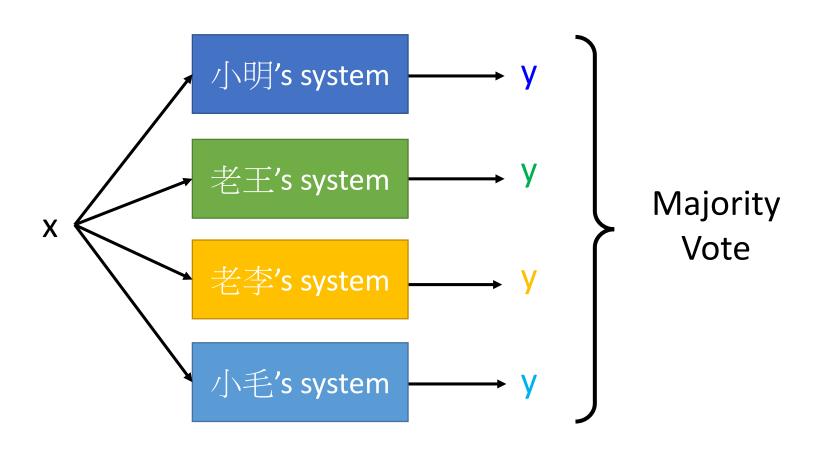
Adaboost!

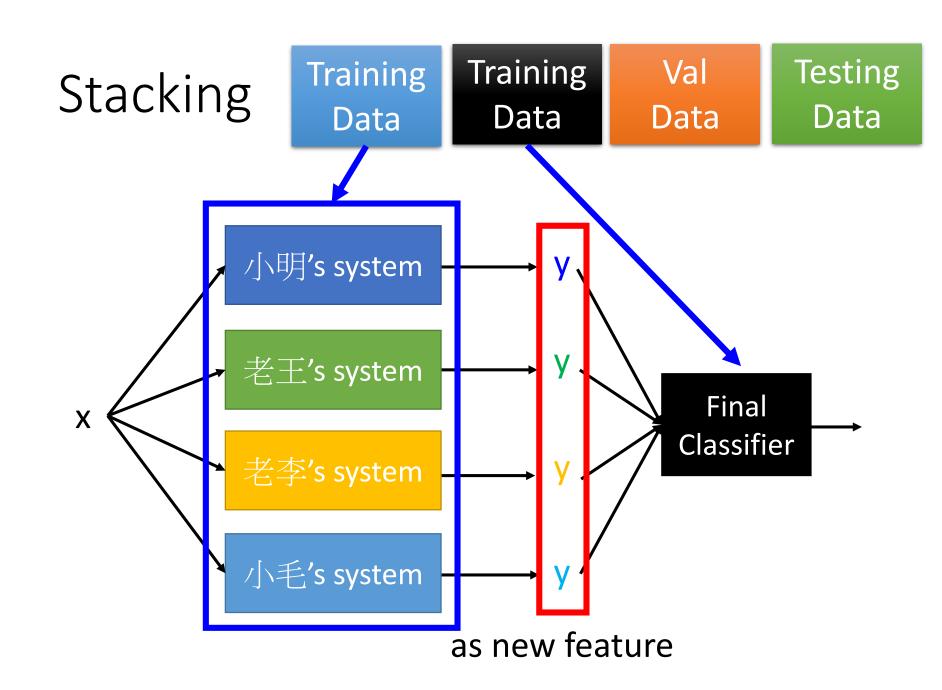
#### Cool Demo

 http://arogozhnikov.github.io/2016/07/05/gradient \_boosting\_playground.html

# Ensemble: Stacking

## Voting





# 2017 新年快樂 Happy New Year