i) Resposta a Perturbação escterna $f_p = 0$ $a(t) = e^{-w \varepsilon t} (A_{g} \operatorname{sen}_{ub} \sqrt{1-\varepsilon^{2}t} + B_{g} \operatorname{aev}_{ub} \sqrt{1-\varepsilon^{2}t})$ $a(t) = e^{-w \varepsilon t} (A_{g} \operatorname{sen}_{ub} \sqrt{1-\varepsilon^{2}t} + B_{g} \operatorname{aev}_{ub} \sqrt{1-\varepsilon^{2}t})$ Derivando as equações (I) e (II) em relação ao tempo

$$\frac{1}{4}(t) = -w_0 \mathcal{E}^{-14}(A_{q} \operatorname{sen} w_0 \sqrt{1 - \mathcal{E}^2}t + B_{q} \operatorname{cos} w_0 \sqrt{1 - \mathcal{E}^2}t) \\
+ e^{-w_0 \mathcal{E}^2}(A_{q} w_0 \sqrt{1 - \mathcal{E}^2}t \operatorname{cos} w_0 \sqrt{1 - \mathcal{E}^2}t - B_{q} w_0 \sqrt{1 - \mathcal{E}^2}t \operatorname{sen} w_0 \sqrt{1 - \mathcal{E}^2}t) \\
+ e^{-w_0 \mathcal{E}^2}(A_{q} \operatorname{sen} w_0 \sqrt{1 - \mathcal{E}^2}t + B_{q} \operatorname{cos} w_0 \sqrt{1 - \mathcal{E}^2}t - B_{q} w_0 \sqrt{1 - \mathcal{E}^2}t \operatorname{sen} w_0 \sqrt{1 - \mathcal{E}^2}t \\
- e^{-w_0 \mathcal{E}^2}(A_{q} w_0 \sqrt{1 - \mathcal{E}^2}t \operatorname{cos} w_0 \sqrt{1 - \mathcal{E}^2}t - B_{q} w_0 \sqrt{1 - \mathcal{E}^2}t \operatorname{sen} w_0 \sqrt{1 - \mathcal{E}^2}t \\
- e^{-w_0 \mathcal{E}^2}(A_{q} w_0 \sqrt{1 - \mathcal{E}^2}t \operatorname{cos} w_0 \sqrt{1 - \mathcal{E}^2}t - B_{q} w_0 \sqrt{1 - \mathcal{E}^2}t \operatorname{sen} w_0 \sqrt{1 - \mathcal{E}^2}t \\
- e^{-w_0 \mathcal{E}^2}(A_{q} w_0 \sqrt{1 - \mathcal{E}^2}t \operatorname{cos} w_0 \sqrt{1 - \mathcal{E}^2}t - B_{q} w_0 \sqrt{1 - \mathcal{E}^2}t \operatorname{sen} w_0 \sqrt{1 - \mathcal{E}^2}t \\
- e^{-w_0 \mathcal{E}^2}(A_{q} w_0 \sqrt{1 - \mathcal{E}^2}t \operatorname{cos} w_0 \sqrt{1 - \mathcal{E}^2}t - B_{q} w_0 \sqrt{1 - \mathcal{E}^2}t \operatorname{sen} w_0 \sqrt{1 - \mathcal{E}^2}t \\
- e^{-w_0 \mathcal{E}^2}(A_{q} w_0 \sqrt{1 - \mathcal{E}^2}t - B_{q} w_0 \sqrt{1 - \mathcal{E}^2}t - B_{q} w_0 \sqrt{1 - \mathcal{E}^2}t \operatorname{sen} w_0 \sqrt{1 - \mathcal{E}^2}t \\
- e^{-w_0 \mathcal{E}^2}(A_{q} w_0 \sqrt{1 - \mathcal{E}^2}t - B_{q} w_0 \sqrt{1 - \mathcal{E}^2}t - B_{q} w_0 \sqrt{1 - \mathcal{E}^2}t \operatorname{sen} w_0 \sqrt{1 - \mathcal{E}^2}t \\
- e^{-w_0 \mathcal{E}^2}(A_{q} w_0 \sqrt{1 - \mathcal{E}^2}t - B_{q} w_0 \sqrt{1 - \mathcal{E}^2}t - B_{q} w_0 \sqrt{1 - \mathcal{E}^2}t \operatorname{sen} w_0 \sqrt{1 - \mathcal{E}^2}t - B_{q} w_0 \operatorname{sen} w$$

$$\begin{bmatrix} \dot{q}_{0} \\ \dot{\alpha}_{0} \end{bmatrix} = \begin{bmatrix} -M_{q} & -M_{q} \\ -\left(\frac{L_{\alpha}}{V_{e}} + \frac{q}{V_{e}V_{e}}\right) \end{bmatrix} \begin{bmatrix} \dot{q}_{0} \\ \dot{\alpha}_{0} \end{bmatrix}$$

$$\begin{bmatrix} L_{\alpha} + \frac{q}{V_{e}V_{e}} \end{bmatrix} \begin{bmatrix} \dot{q}_{0} \\ \dot{\gamma}_{0} \end{bmatrix} = \begin{bmatrix} -M_{q} & -M_{q} \\ -\left(\frac{L_{\alpha}}{V_{e}} + \frac{q}{V_{e}V_{e}}\right) \end{bmatrix} \begin{bmatrix} \dot{q}_{0} \\ \dot{\gamma}_{0} \end{bmatrix} = \begin{bmatrix} -M_{q} & -M_{q} \\ -\left(\frac{L_{\alpha}}{V_{e}} + \frac{q}{V_{e}V_{e}}\right) \end{bmatrix} \begin{bmatrix} \dot{q}_{0} \\ \dot{\gamma}_{0} \end{bmatrix} = \begin{bmatrix} -M_{q} & -M_{q} \\ V_{e}V_{e} \end{bmatrix} \begin{bmatrix} \dot{q}_{0} \\ V_{e}V_{e} \end{bmatrix} = \begin{bmatrix} -M_{q} & -M_{q} \\ V_{e}V_{e} \end{bmatrix} \begin{bmatrix} \dot{q}_{0} \\ V_{e}V_{e} \end{bmatrix} \begin{bmatrix} \dot{q}_{0} \\ V_{e}V_{e} \end{bmatrix} = \begin{bmatrix} -M_{q} & -M_{q} \\ -\left(\frac{M_{q}}{V_{e}} + \frac{M_{q}}{V_{e}}\right) \end{bmatrix} \begin{bmatrix} \dot{q}_{0} \\ -\left(\frac{M_{q}}{V_{e}} + \frac{M_{q}}{V_{e}} + \frac{M_{q}}{V_{e}}\right) \end{bmatrix} \begin{bmatrix} \dot{q}_{0} \\ -\left(\frac{M_{q}}{V_{e}} + \frac{M_{q}}{V_{e}} + \frac{M_{q}}{V_{e}}\right) \end{bmatrix} \begin{bmatrix} \dot{q}_{0} \\ -\left(\frac{M_{q}}{V_{e}} + \frac{M_{q}}{V_{e}} + \frac{M_{q}}{V_{e}} + \frac{M_{q}}{V_{e}} \end{bmatrix} \begin{bmatrix} \dot{q}_{0} \\ -\left(\frac{M_{q}}{V_{e}} + \frac{M_{q}}{V_{e}} + \frac{M_{q}}{V_{e}} + \frac{M_{q}}{V_{e}} \end{bmatrix} \begin{bmatrix} \dot{q}_{0} \\ -\left(\frac{M_{q}}{V_{e}} + \frac{M_{q}}{V_{e}} + \frac{M_{q}}{V_{e}} + \frac{M_{q}}{V_{e}} \end{bmatrix} \begin{bmatrix} \dot{q}_{0} \\ -\left(\frac{M_{q}}{V_{e}} + \frac{M_{q}}{V_{e}} + \frac{M_{q}}{V_{e}} + \frac{M_{q}}{V_{e}} \end{bmatrix} \begin{bmatrix} \dot{q}_{0} \\ -\left(\frac{M_{q$$

On sija Bg= go Ag = jo + wo & go Wo VI-E Ax = io + wo & xo Wo VI-E

