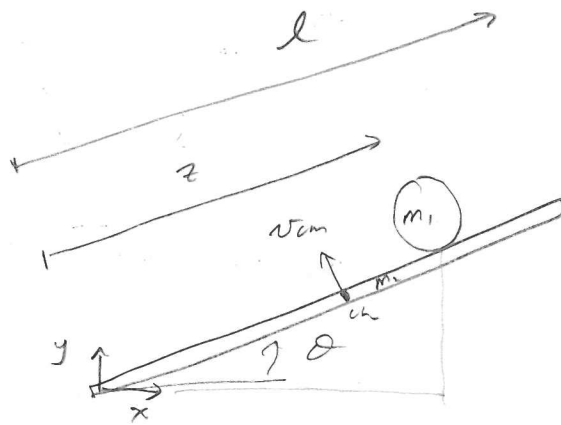


V.1



$$K = \frac{1}{2} m_2 \dot{v}_{cm, beam}^T J_{cm, beam}^T \dot{v}_{cm, beam} + \frac{1}{2} \omega_{beam}^T J_{beam} \omega_{beam}$$

$$+ \frac{1}{2} m_2 \dot{v}_{ball}^T \dot{v}_{ball} + \frac{1}{2} \omega_{ball}^T J_{ball} \omega_{ball}$$

→ Assume zero
- move without rolling

Position of ball

$$P_{ball} = \begin{pmatrix} z \cos \theta \\ z \sin \theta \\ 0 \end{pmatrix}$$

position of cm of beam

$$P_{cm, beam} = \begin{pmatrix} \frac{1}{2} z \cos \theta \\ \frac{1}{2} z \sin \theta \\ 0 \end{pmatrix}$$

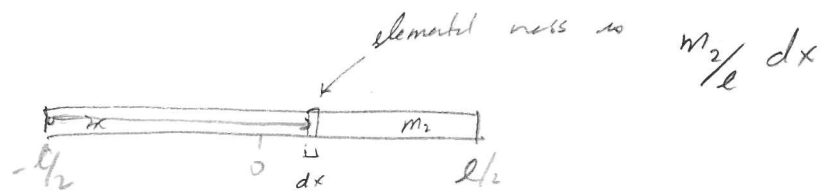
$$\therefore \dot{v}_{ball} = \begin{pmatrix} \dot{z} \cos \theta - z \dot{\theta} \sin \theta \\ \dot{z} \sin \theta + z \dot{\theta} \cos \theta \\ 0 \end{pmatrix}, \quad \dot{v}_{cm, beam} = \begin{pmatrix} -\dot{\theta} \frac{1}{2} z \sin \theta \\ \dot{\theta} \frac{1}{2} z \cos \theta \\ 0 \end{pmatrix}$$

The angular velocity of the beam is

$$\omega_{beam} = \begin{pmatrix} 0 \\ 0 \\ \dot{\theta} \end{pmatrix}$$

Therefore we only need to know the (3,3) element of J_{beam}

Let J_z be the (3,3) element



$$J = \int (r^T r I - r r^T) dm$$

where $r = \begin{pmatrix} x \\ 0 \\ 0 \end{pmatrix}$ and $dm = \frac{m_2}{l} dx$

Note that

$$r^T r I - r r^T = \begin{pmatrix} x^2 & 0 & 0 \\ 0 & x^2 & 0 \\ 0 & 0 & x^2 \end{pmatrix} - \begin{pmatrix} x^2 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & x^2 & 0 \\ 0 & 0 & x^2 \end{pmatrix}$$

\therefore The (3,3) element is

$$J_2 = \int_{x=-l/2}^{l/2} x^2 \left(\frac{m_2}{l} \right) dx$$

$$= \frac{m_2}{l} \int_{-l/2}^{l/2} x^2 dx = \frac{m_2}{l} \left[\frac{x^3}{3} \right]_{-l/2}^{l/2} = \frac{m_2}{3l} \left[\frac{l^3}{8} + \frac{l^3}{8} \right]$$

$$= \frac{m_2 l^2}{12}$$

$$\therefore K = \frac{1}{2} m_2 \left[\left(-\dot{\theta} \frac{l}{2} \sin \theta \right)^2 + \left(\dot{\theta} \frac{l}{2} \cos \theta \right)^2 \right] + \frac{1}{2} \left(\frac{m_2 l^2}{12} \right) \dot{\theta}^2$$

$$+ \frac{1}{2} m_1 \left[\left(\dot{z} \cos \theta - z \dot{\theta} \sin \theta \right)^2 + \left(\dot{z} \sin \theta + z \dot{\theta} \cos \theta \right)^2 \right]$$

$$= \frac{1}{2} m_2 \frac{l^2}{4} \dot{\theta}^2 + \frac{1}{2} m_2 \frac{l^2}{12} \dot{\theta}^2$$

$$+ \frac{1}{2} m_1 \left[\dot{z}^2 \cos^2 \theta - 2z \dot{z} \dot{\theta} \sin \theta \cos \theta + z^2 \dot{\theta}^2 \sin^2 \theta \right. \\ \left. + \dot{z}^2 \sin^2 \theta + 2z \dot{z} \dot{\theta} \sin \theta \cos \theta + z^2 \dot{\theta}^2 \cos^2 \theta \right]$$

$$= \frac{1}{2} \frac{m_2}{3} \ell^2 \dot{\theta}^2 + \frac{1}{2} m_1 (\dot{z}^2 + z^2 \dot{\theta}^2)$$

$$= \frac{1}{2} m_1 \dot{z}^2 + \frac{1}{2} \left(\frac{m_2 \ell^2}{3} + m_1 z^2 \right) \dot{\theta}^2$$