

Formal Methods in Software Development

Branch and Bound

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Based on slides of the lecture Satisfiability Checking (Erika Ábrahám), RTWH Aachen

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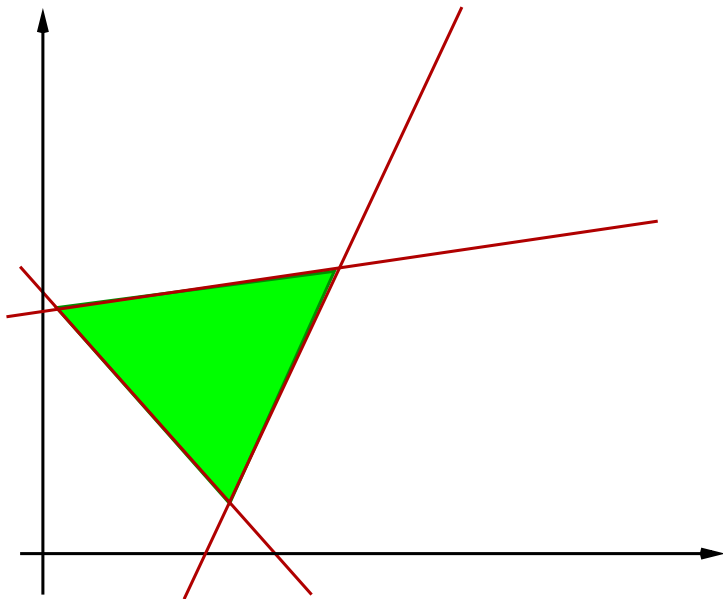
Definition

An **integer linear system** S is a linear system $Ax = 0$, $\bigwedge_{i=1}^m l_i \leq s_i \leq u_i$, with the additional **integrality requirement** that all variables are of type integer.

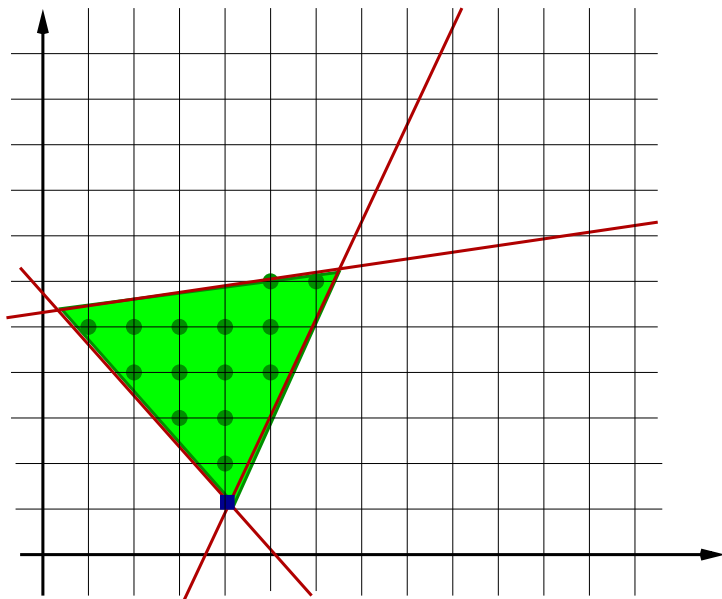
Definition (relaxed system)

Given an integer linear system S , its **relaxation** $\text{relaxed}(S)$ is S without the integrality requirement.

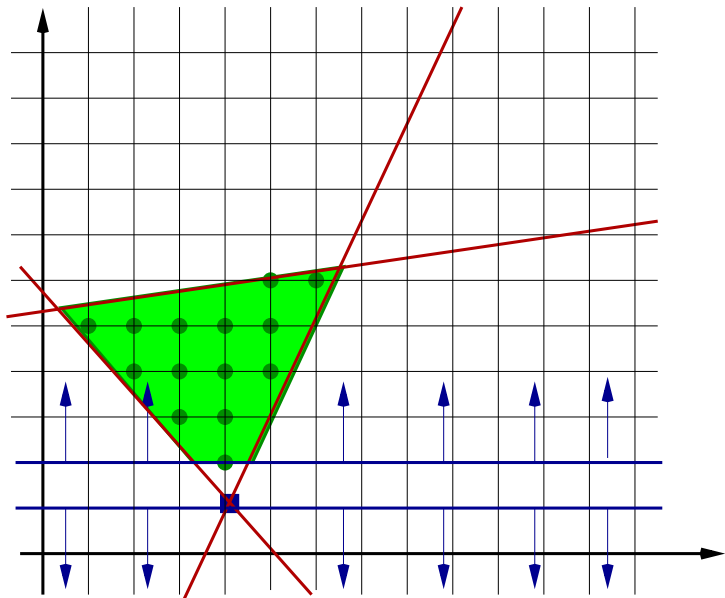
Geometric interpretation



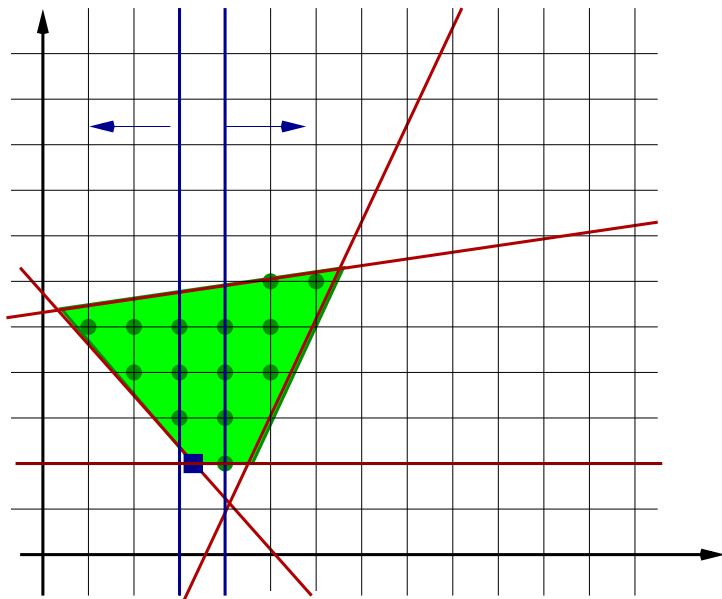
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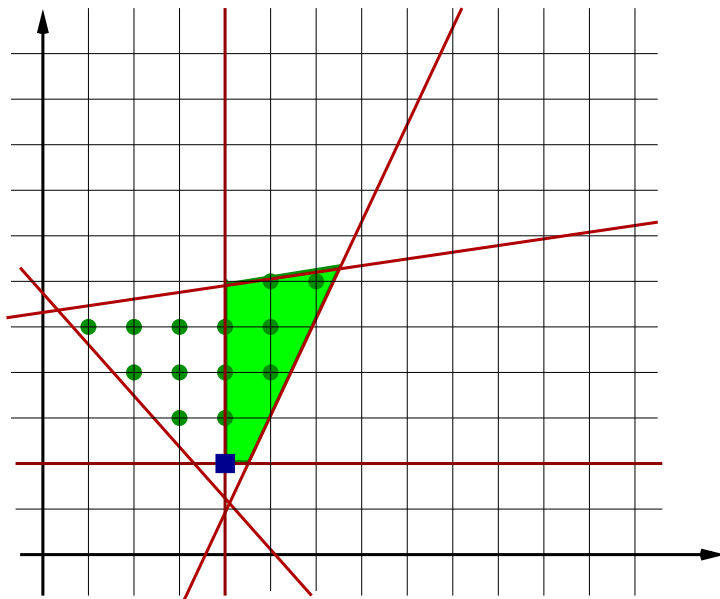
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- Branch-and-Bound algorithm, chooses, in line 7 between x_2 and x_3 ; assume we choose x_2 ;
- In line 8, S (the linear system solved at the current recursion level) is then augmented with the constraint $x_2 \leq 0$ and sent for solving at a deeper recursion level. If no solution is found in this branch, S is augmented instead with $x_2 \geq 1$ and, once again, is sent to a deeper recursion level. If both these calls do not return integral values, UNSAT is returned. If one call returns SAT, then the same is performed for x_3 .

- The algorithm is **incomplete**.
- Example: $1 \leq 3x - 3y \leq 2$ has unbounded real solutions but no integer solutions \rightarrow the algorithm loops forever.
- The algorithm can be made complete for formulae with the small-model property: if there is a solution, then there is also a solution within a (computable) finite bound.
- The algorithm can be extended to **mixed integer linear programming**, where some of the variables are integer-valued while the others are real-valued.

Branch and bound

- Branch: Split the search space
- Bound: Exclude unsatisfiable sub-spaces
- We have seen: Depth-first search
- Also possible: Breadth-first search

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From the first two constraints we get $x_1 \leq -1$
- Assume a constraint $\sum_i a_i x_i \leq b$ with $l_i \leq x_i \leq u_i$.
If $a_k > 0$, we have $x_k \leq (b - \sum_{i \neq k} a_i l_i) / a_k$.
If $a_k < 0$, we have $x_k \geq (b - \sum_{i \neq k} a_i u_i) / a_k$.