Formal Methods in Software Developement Branch and Bound

Mădălina Erașcu

West University of Timișoara Faculty of Mathematics and Informatics

Based on slides of the lecture Satisfiability Checking (Erika Ábrahám), RTWH Aachen

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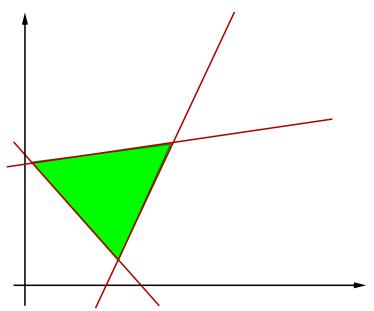
Integer linear systems

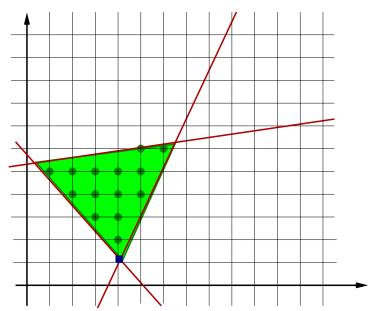
Definition

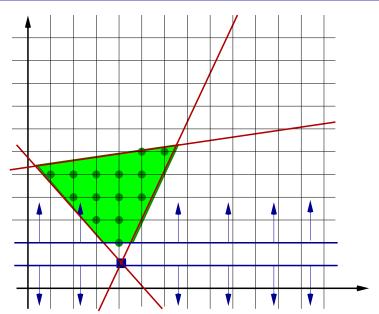
An integer linear system S is a linear system Ax = 0, $\bigwedge_{i=1}^{m} I_i \leq s_i \leq u_i$, with the additional integrality requirement that all variables are of type integer.

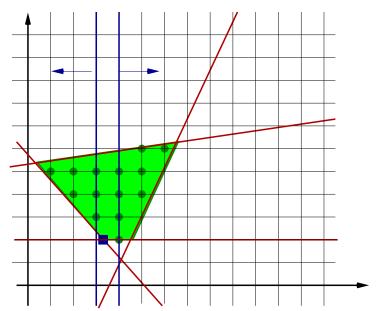
Definition (relaxed system)

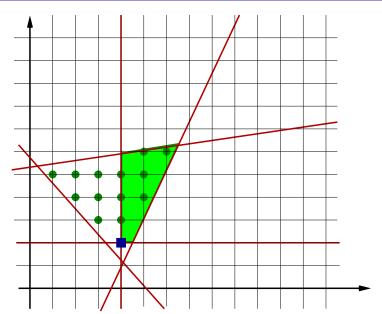
Given an integer linear system S, its relaxation relaxed(S) is S without the integrality requirement.











Input: An integer linear system *S*

Output: SAT if S is satisfiable, UNSAT otherwise

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procedure Branch-and-Bound(S) {
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	else {
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Input: An integer linear system S
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procedure Branch-and-Bound(5) {
  res = LP(relaxed(S)); /*LP could be Fourier-Motzkin*/
 if (res==UNSAT) return UNSAT;
  else if (res is integral) return SAT;
  else {
    Select a variable v that is assigned a non-integral value r;
    if (Branch-and-Bound(S \cup (v < |r|))==SAT) return SAT;
    else if (Branch-and-Bound(S \cup (v \ge \lceil r \rceil))==SAT) return SAT;
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Input: An integer linear system S
Output: SAT if S is satisfiable, UNSAT otherwise
procedure Branch-and-Bound(5) {
  res = LP(relaxed(S)); /*LP could be Fourier-Motzkin*/
 if (res==UNSAT) return UNSAT;
  else if (res is integral) return SAT;
  else {
    Select a variable v that is assigned a non-integral value r;
    if (Branch-and-Bound(S \cup (v < |r|))==SAT) return SAT;
    else if (Branch-and-Bound(S \cup (v \ge \lceil r \rceil))==SAT) return SAT;
    else return UNSAT:
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Example

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Example

- Let $x_1, ..., x_4$ be the variables of S. Assume that LP returns the solution (1, 0.7, 2.5, 3);
- Branch-and-Bound algorithm chooses between x_2 and x_3 ; assume we choose x_2 ;
- S (the linear system solved at the current recursion level) is then augmented with the constraint $x_2 \leq 0$ and sent for solving at a deeper recursion level. If no solution is found in this branch, S is augmented instead with $x_2 \geq 1$ and, once again, is sent to a deeper recursion level. If both these calls do not return integral values, UNSAT is returned. If one call returns SAT, then the same is performed for x_3 .

- The algorithm is incomplete: there are cases for which it will branch forever.
- Example: $1 \le 3x 3y \le 2$ has unbounded real solutions but no integer solutions \rightarrow the algorithm loops forever.
- The algorithm can be made complete for formulae with the small-model property: if there is a solution, then there is also a solution within a (computable) finite bound.
- The algorithm can be extended to mixed integer linear programming, where some of the variables are integer-valued while the others are real-valued.

- Branch: Split the search space
- Bound: Exclude unsatisfiable sub-spaces
- We have seen: Depth-first search
- Also possible: Breadth-first search

Optimizations:

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- Bounds can be tightened: $2x_1 + x_2 \le 2$, $x_2 \ge 4$, $x_1 \le 3$ From the first two constraints we get $x_1 \le -1$
- Assume a constraint $\sum_i a_i x_i \leq b$ with $l_i \leq x_i \leq u_i$. If $a_k > 0$, we have $x_k \leq (b - \sum_{i \neq k} a_i l_i)/a_k$. If $a_k < 0$, we have $x_k \geq (b - \sum_{i \neq k} a_i u_i)/a_k$.