# **Range Optimization Report**

# 1. Overview of Optimum Values

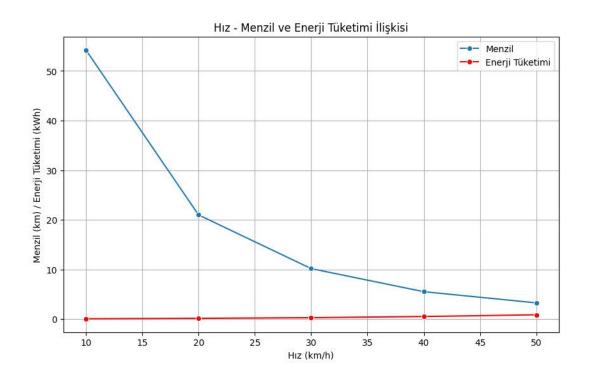
- Optimal Torque: 150 Nm and 260.33 Nm are identified as efficient torque levels.
- **Optimal Speed:** 10 km/h is the speed with the lowest energy consumption.
- **Estimated Range:** At both torque levels, the highest range (54.22 km) is achieved at 10 km/h.

These findings highlight that the vehicle achieves maximum energy efficiency at low speeds (e.g., 10 km/h) and low torque levels.

# 2. Dataset Summary

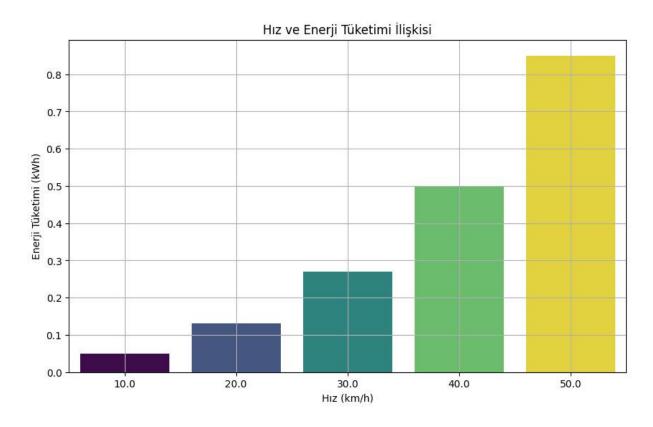
Parameter Torque (Nm) Speed (km/h) Range (km) Energy Consumption (kWh)

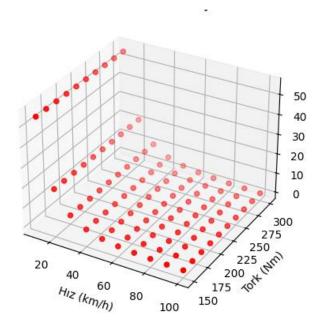
Count	5	5	5	5
Mean	150.0	30.0	18.824	0.36
Min	150.0	10.0	3.25	0.05
Max	150.0	50.0	54.22	0.85



# 3. Key Findings

- **Energy Efficiency:** Maximum range is achieved at 10-20 km/h.
- **Speed Impact:** As speed increases, energy consumption rises rapidly, reducing the range significantly.
- **Optimization at Higher Speeds:** For speeds above 30 km/h, aerodynamic improvements are recommended.
- Regenerative Braking and Steady Driving: These strategies can improve range.





#### 4. Recommendations

#### 1. Efficient Usage at Low Speeds and Torque

- 10 km/h and 150 Nm: This combination offers the lowest energy consumption and the maximum range, making it ideal for urban driving.
- **City Driving:** Maintaining low speeds in urban conditions can help minimize range loss.

#### 2. Energy Optimization at Medium Speeds (20-30 km/h)

- **Aerodynamic Enhancements:** Reducing air resistance can improve efficiency, especially at higher speeds.
- **Transmission Optimization:** More efficient torque and motor control strategies could reduce energy consumption at 30 km/h.

#### 3. Strategies for High Speeds (>50 km/h)

- **Regenerative Braking:** Recovering energy during braking can increase range.
- **Speed Management Systems:** Implementing speed limiters can optimize range for necessary high-speed driving scenarios.

#### 4. Torque Optimization

- **260.33 Nm Torque:** Suitable for high-demand situations like hill climbing or acceleration. However, lower torque levels can be more efficient on flat roads.
- **High Torque and Low Speed:** This combination can be beneficial under challenging conditions such as steep slopes.

#### **5. Driving Style Optimization**

• **Avoid Sudden Accelerations and Braking:** Smooth acceleration and maintaining a steady speed can improve energy management and range.

### 5. Future Development Areas

- 1. **Additional Data Analysis:** Further investigation of trends in energy consumption across different speed and torque levels.
- 2. **Scenario Comparisons:** Comparing results under varying conditions to enhance reliability.
- 3. **Machine Learning Models:** Using regression or classification models to predict energy consumption.
- 4. **Error Analysis:** Evaluating potential errors in range and energy consumption predictions.
- 5. **Impact of Additional Parameters:** Investigating how factors like vehicle weight, aerodynamics, and driving conditions affect the range.