# Checking Assumptions: Residuals and Influential Observations Merlise Clyde

STA721 Linear Models

Duke University

October 3, 2013

#### Outline

#### Topics

- Distribution of Residuals
- Leverage
- Standardized Residuals
- Cook's Distance
- Example: Stackloss data

Readings: Christensen Chapter 13

Linear Model:

$$\mathbf{Y} = \mu + \epsilon$$

Linear Model:

$$\mathbf{Y} = \boldsymbol{\mu} + \boldsymbol{\epsilon}$$

Assumptions:

Linear Model:

$$\mathbf{Y} = \boldsymbol{\mu} + \boldsymbol{\epsilon}$$

Assumptions:

$$\mu \in \mathcal{C}(\mathbf{X}) \;\;\Leftrightarrow\;\; \mu = \mathbf{X}\boldsymbol{\beta}$$

Linear Model:

$$\mathbf{Y} = \boldsymbol{\mu} + \boldsymbol{\epsilon}$$

Assumptions:

$$\begin{array}{ccc} \boldsymbol{\mu} \in \mathcal{C}(\mathbf{X}) & \Leftrightarrow & \boldsymbol{\mu} = \mathbf{X}\boldsymbol{\beta} \\ & \boldsymbol{\epsilon} & \sim & \mathsf{N}(\mathbf{0}_n, \sigma^2 \mathbf{I}_n) \end{array}$$

Linear Model:

$$\mathsf{Y} = \mu + \epsilon$$

Assumptions:

$$\mu \in C(\mathbf{X}) \Leftrightarrow \mu = \mathbf{X}\boldsymbol{\beta}$$
 $\epsilon \sim N(\mathbf{0}_n, \sigma^2 \mathbf{I}_n)$ 

What could go wrong?

Wrong mean



Linear Model:

$$\mathbf{Y} = \mu + \epsilon$$

Assumptions:

$$\mu \in C(\mathbf{X}) \Leftrightarrow \mu = \mathbf{X}\boldsymbol{\beta}$$
 $\epsilon \sim N(\mathbf{0}_n, \sigma^2 \mathbf{I}_n)$ 

What could go wrong?

- Wrong mean
- Wrong covariance



Linear Model:

$$\mathbf{Y} = \boldsymbol{\mu} + \boldsymbol{\epsilon}$$

Assumptions:

$$egin{aligned} oldsymbol{\mu} \in \mathcal{C}(\mathbf{X}) & \Leftrightarrow & oldsymbol{\mu} = \mathbf{X}oldsymbol{eta} \ & \epsilon & \sim & \mathsf{N}(\mathbf{0}_n, \sigma^2 \mathbf{I}_n) \end{aligned}$$

What could go wrong?

- Wrong mean
- Wrong covariance
- ullet Wrong distribution for  $\epsilon$



$$e = \mathbf{Y} - \mathbf{X}\hat{\boldsymbol{\beta}}$$

$$e = \mathbf{Y} - \mathbf{X}\hat{\boldsymbol{\beta}}$$
$$= (\mathbf{I}_n - \mathbf{P}_{\mathbf{X}})\mathbf{Y}$$

$$e = \mathbf{Y} - \mathbf{X}\hat{\boldsymbol{\beta}}$$
$$= (\mathbf{I}_n - \mathbf{P}_{\mathbf{X}})\mathbf{Y}$$

$$\mathsf{E}[\mathsf{e}] = (\mathsf{I}_n - \mathsf{P}_{\mathsf{X}})\mu$$

$$e = \mathbf{Y} - \mathbf{X}\hat{\boldsymbol{\beta}}$$
$$= (\mathbf{I}_n - \mathbf{P}_{\mathbf{X}})\mathbf{Y}$$

$$E[e] = (I_n - P_X)\mu$$
$$= 0_n \text{ if } \mu \in C(X)$$

Residuals (MLE of  $\epsilon$ ) are

$$e = \mathbf{Y} - \mathbf{X}\hat{\boldsymbol{\beta}}$$
$$= (\mathbf{I}_n - \mathbf{P}_{\mathbf{X}})\mathbf{Y}$$

$$E[e] = (I_n - P_X)\mu$$
$$= 0_n \text{ if } \mu \in C(X)$$

Mean will not be zero if we have left out terms

Under model with constant variances  $Cov[\mathbf{Y}] = \sigma^2 \mathbf{I}_n$ 

Under model with constant variances  $Cov[\mathbf{Y}] = \sigma^2 \mathbf{I}_n$ 

$$Cov = [e] = Cov[(I - P_X)Y]$$

Under model with constant variances  $Cov[Y] = \sigma^2 I_n$ 

$$Cov = [e] = Cov[(I - P_X)Y]$$
$$= (I - P_X)^T Cov[Y](I - P_X)$$

Under model with constant variances  $Cov[\mathbf{Y}] = \sigma^2 \mathbf{I}_n$ 

$$Cov = [e] = Cov[(I - P_X)Y]$$

$$= (I - P_X)^T Cov[Y](I - P_X)$$

$$= \sigma^2 (I - P_X)^T (I - P_X)$$

Under model with constant variances  $Cov[\mathbf{Y}] = \sigma^2 \mathbf{I}_n$ 

$$Cov = [\mathbf{e}] = Cov[(\mathbf{I} - P_{\mathbf{X}})\mathbf{Y}]$$

$$= (\mathbf{I} - P_{\mathbf{X}})^{T}Cov[\mathbf{Y}](\mathbf{I} - P_{\mathbf{X}})$$

$$= \sigma^{2}(\mathbf{I} - P_{\mathbf{X}})^{T}(\mathbf{I} - P_{\mathbf{X}})$$

$$= \sigma^{2}(\mathbf{I} - P_{\mathbf{X}})$$

Under model with constant variances  $Cov[Y] = \sigma^2 I_n$ 

$$Cov = [\mathbf{e}] = Cov[(\mathbf{I} - P_{\mathbf{X}})\mathbf{Y}]$$

$$= (\mathbf{I} - P_{\mathbf{X}})^{T}Cov[\mathbf{Y}](\mathbf{I} - P_{\mathbf{X}})$$

$$= \sigma^{2}(\mathbf{I} - P_{\mathbf{X}})^{T}(\mathbf{I} - P_{\mathbf{X}})$$

$$= \sigma^{2}(\mathbf{I} - P_{\mathbf{X}})$$

$$\mathbf{e} \sim N(\mathbf{0}, \sigma^{2}(\mathbf{I} - P_{\mathbf{X}}))$$

Under model with constant variances  $Cov[Y] = \sigma^2 I_n$ 

$$Cov = [\mathbf{e}] = Cov[(\mathbf{I} - P_{\mathbf{X}})\mathbf{Y}]$$

$$= (\mathbf{I} - P_{\mathbf{X}})^{T}Cov[\mathbf{Y}](\mathbf{I} - P_{\mathbf{X}})$$

$$= \sigma^{2}(\mathbf{I} - P_{\mathbf{X}})^{T}(\mathbf{I} - P_{\mathbf{X}})$$

$$= \sigma^{2}(\mathbf{I} - P_{\mathbf{X}})$$

$$\mathbf{e} \sim N(\mathbf{0}, \sigma^{2}(\mathbf{I} - P_{\mathbf{X}}))$$

ullet P<sub>X</sub> is the "hat" matrix (sometimes called  $oldsymbol{H}=[h_{ij}])$ 

Under model with constant variances  $Cov[\mathbf{Y}] = \sigma^2 \mathbf{I}_n$ 

$$Cov = [\mathbf{e}] = Cov[(\mathbf{I} - P_{\mathbf{X}})\mathbf{Y}]$$

$$= (\mathbf{I} - P_{\mathbf{X}})^{T}Cov[\mathbf{Y}](\mathbf{I} - P_{\mathbf{X}})$$

$$= \sigma^{2}(\mathbf{I} - P_{\mathbf{X}})^{T}(\mathbf{I} - P_{\mathbf{X}})$$

$$= \sigma^{2}(\mathbf{I} - P_{\mathbf{X}})$$

$$\mathbf{e} \sim N(\mathbf{0}, \sigma^{2}(\mathbf{I} - P_{\mathbf{X}}))$$

- $P_X$  is the "hat" matrix (sometimes called  $H = [h_{ij}]$ )
- diagonal elements of  $P_X$  are denoted as  $h_{ii}$

Under model with constant variances  $Cov[Y] = \sigma^2 I_n$ 

$$Cov = [\mathbf{e}] = Cov[(\mathbf{I} - P_{\mathbf{X}})\mathbf{Y}]$$

$$= (\mathbf{I} - P_{\mathbf{X}})^{T}Cov[\mathbf{Y}](\mathbf{I} - P_{\mathbf{X}})$$

$$= \sigma^{2}(\mathbf{I} - P_{\mathbf{X}})^{T}(\mathbf{I} - P_{\mathbf{X}})$$

$$= \sigma^{2}(\mathbf{I} - P_{\mathbf{X}})$$

$$\mathbf{e} \sim N(\mathbf{0}, \sigma^{2}(\mathbf{I} - P_{\mathbf{X}}))$$

- $P_X$  is the "hat" matrix (sometimes called  $H = [h_{ij}]$ )
- diagonal elements of  $P_X$  are denoted as  $h_{ii}$
- leverage of the *i*th observation is  $h_{ii}$



Under model with constant variances  $Cov[Y] = \sigma^2 I_n$ 

$$Cov = [\mathbf{e}] = Cov[(\mathbf{I} - P_{\mathbf{X}})\mathbf{Y}]$$

$$= (\mathbf{I} - P_{\mathbf{X}})^{T}Cov[\mathbf{Y}](\mathbf{I} - P_{\mathbf{X}})$$

$$= \sigma^{2}(\mathbf{I} - P_{\mathbf{X}})^{T}(\mathbf{I} - P_{\mathbf{X}})$$

$$= \sigma^{2}(\mathbf{I} - P_{\mathbf{X}})$$

$$\mathbf{e} \sim N(\mathbf{0}, \sigma^{2}(\mathbf{I} - P_{\mathbf{X}}))$$

- $P_X$  is the "hat" matrix (sometimes called  $H = [h_{ij}]$ )
- diagonal elements of  $P_X$  are denoted as  $h_{ii}$
- leverage of the *i*th observation is h<sub>ii</sub>

$$\mathsf{var}(e_i) = \sigma^2(1 - h_i)$$



Let  $\mathbf{X} = [\mathbf{1}_n \mathbf{Z}]$  and  $\mathsf{P_1} = \mathbf{1} (\mathbf{1}^T \mathbf{1})^{-1} \mathbf{1}^T$  denote the projection on  $C(\mathbf{1})$ 

Let 
$$\mathbf{X} = [\mathbf{1}_n\mathbf{Z}]$$
 and  $\mathsf{P_1} = \mathbf{1}(\mathbf{1}^T\mathbf{1})^{-1}\mathbf{1}^T$  denote the projection on  $\mathcal{C}(\mathbf{1})$ 

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon}$$

Let 
$$\mathbf{X} = [\mathbf{1}_n\mathbf{Z}]$$
 and  $\mathsf{P_1} = \mathbf{1}(\mathbf{1}^T\mathbf{1})^{-1}\mathbf{1}^T$  denote the projection on  $\mathcal{C}(\mathbf{1})$ 

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon} \\
= \mathbf{1}_{n}\alpha_{0} + \mathbf{Z}\boldsymbol{\alpha} + \boldsymbol{\epsilon}$$

Let 
$$\mathbf{X} = [\mathbf{1}_n\mathbf{Z}]$$
 and  $\mathsf{P_1} = \mathbf{1}(\mathbf{1}^T\mathbf{1})^{-1}\mathbf{1}^T$  denote the projection on  $\mathcal{C}(\mathbf{1})$ 

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon} 
= \mathbf{1}_{n}\alpha_{0} + \mathbf{Z}\boldsymbol{\alpha} + \boldsymbol{\epsilon} 
= \mathbf{1}_{n}\alpha_{0} + P_{1}\mathbf{Z}\boldsymbol{\alpha} + (\mathbf{I}_{n} - P_{1})\mathbf{Z}\boldsymbol{\alpha} + \boldsymbol{\epsilon}$$

Let 
$$\mathbf{X} = [\mathbf{1}_n\mathbf{Z}]$$
 and  $\mathsf{P_1} = \mathbf{1}(\mathbf{1}^T\mathbf{1})^{-1}\mathbf{1}^T$  denote the projection on  $\mathcal{C}(\mathbf{1})$ 

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon}$$

$$= \mathbf{1}_{n}\alpha_{0} + \mathbf{Z}\boldsymbol{\alpha} + \boldsymbol{\epsilon}$$

$$= \mathbf{1}_{n}\alpha_{0} + P_{1}\mathbf{Z}\boldsymbol{\alpha} + (\mathbf{I}_{n} - P_{1})\mathbf{Z}\boldsymbol{\alpha} + \boldsymbol{\epsilon}$$

$$= \mathbf{1}_n \alpha_0^* + (\mathbf{Z} - \mathbf{1}_n \mathbf{\bar{Z}}^T) \alpha + \epsilon$$



$$\mathsf{P}_{\boldsymbol{X}} \ = \ \mathsf{P}_{\boldsymbol{1}} + \mathsf{P}_{\boldsymbol{Z} - \boldsymbol{1}\boldsymbol{\bar{Z}}^{\mathcal{T}}}$$

$$\mathsf{P}_{\boldsymbol{\mathsf{X}}} \ = \ \mathsf{P}_{\boldsymbol{\mathsf{1}}} + \mathsf{P}_{\boldsymbol{\mathsf{Z}} - \mathbf{1}\boldsymbol{\bar{\mathsf{Z}}}^{\mathsf{T}}}$$

$$h_{ii} = \frac{1}{n} + (z_i - \bar{\mathbf{Z}})^T ((\mathbf{Z} - \mathbf{1}\bar{\mathbf{Z}}^T)^T (\mathbf{Z} - \mathbf{1}\bar{\mathbf{Z}}^T))^{-1} (z_i - \bar{\mathbf{Z}})$$

$$P_{\mathbf{X}} = P_{\mathbf{1}} + P_{\mathbf{Z} - \mathbf{1}\bar{\mathbf{Z}}^T}$$

$$h_{ii} = \frac{1}{n} + (z_i - \bar{\mathbf{Z}})^T \left( (\mathbf{Z} - \mathbf{1}\bar{\mathbf{Z}}^T)^T (\mathbf{Z} - \mathbf{1}\bar{\mathbf{Z}}^T) \right)^{-1} (z_i - \bar{\mathbf{Z}})$$

$$= \frac{1}{n} + \frac{D_i^2}{n-1}$$

Let  $z_i^T$  denote the vector of explanatory variables for the *i*th case

$$P_{\mathbf{X}} = P_{\mathbf{1}} + P_{\mathbf{Z} - \mathbf{1}\bar{\mathbf{Z}}^T}$$

$$h_{ii} = \frac{1}{n} + (z_i - \bar{\mathbf{Z}})^T \left( (\mathbf{Z} - \mathbf{1}\bar{\mathbf{Z}}^T)^T (\mathbf{Z} - \mathbf{1}\bar{\mathbf{Z}}^T) \right)^{-1} (z_i - \bar{\mathbf{Z}})$$

$$= \frac{1}{n} + \frac{D_i^2}{n-1}$$

Leverage is a function of the estimated Mahalanobis distance  $D_i^2$  of  $z_i$  from  $\bar{\mathbf{Z}}$ 

#### Residual Plots

Under normality and constant variance assumptions, the residuals  ${\bf e}$  and fitted values  $\hat{{\bf Y}}$  are jointly normal but independent.

#### Residual Plots

Under normality and constant variance assumptions, the residuals  ${\bf e}$  and fitted values  $\hat{{\bf Y}}$  are jointly normal but independent. Under the correct model

Under normality and constant variance assumptions, the residuals  $\boldsymbol{e}$  and fitted values  $\hat{\boldsymbol{Y}}$  are jointly normal but independent. Under the correct model

•  $E[e] = \mathbf{0}_n$ : scatter plots of residuals versus any combination of terms in the mean function will have a constant mean of  $\mathbf{0}$ 

Under normality and constant variance assumptions, the residuals  $\boldsymbol{e}$  and fitted values  $\hat{\boldsymbol{Y}}$  are jointly normal but independent. Under the correct model

- $E[e] = 0_n$ : scatter plots of residuals versus any combination of terms in the mean function will have a constant mean of 0
- $var(e_i) = \sigma^2(1 h_{ii})$ , so even if fitted model is correct, the variances are not constant. Lower variability for points with high leverage with  $h_{ii} \approx 1$

Under normality and constant variance assumptions, the residuals  $\boldsymbol{e}$  and fitted values  $\hat{\boldsymbol{Y}}$  are jointly normal but independent. Under the correct model

- $E[e] = 0_n$ : scatter plots of residuals versus any combination of terms in the mean function will have a constant mean of 0
- $\text{var}(e_i) = \sigma^2(1 h_{ii})$ , so even if fitted model is correct, the variances are not constant. Lower variability for points with high leverage with  $h_{ii} \approx 1$
- The residuals are correlated, but this correlation is usually not visible in residual plots

Under normality and constant variance assumptions, the residuals  $\boldsymbol{e}$  and fitted values  $\hat{\boldsymbol{Y}}$  are jointly normal but independent. Under the correct model

- $E[e] = 0_n$ : scatter plots of residuals versus any combination of terms in the mean function will have a constant mean of 0
- $\text{var}(e_i) = \sigma^2(1 h_{ii})$ , so even if fitted model is correct, the variances are not constant. Lower variability for points with high leverage with  $h_{ii} \approx 1$
- The residuals are correlated, but this correlation is usually not visible in residual plots

When the model is not correct we hope to see structure in the residual plots to help us re-model the data



Under normality and constant variance assumptions, the residuals  $\boldsymbol{e}$  and fitted values  $\hat{\boldsymbol{Y}}$  are jointly normal but independent. Under the correct model

- $E[e] = 0_n$ : scatter plots of residuals versus any combination of terms in the mean function will have a constant mean of 0
- $\text{var}(e_i) = \sigma^2(1 h_{ii})$ , so even if fitted model is correct, the variances are not constant. Lower variability for points with high leverage with  $h_{ii} \approx 1$
- The residuals are correlated, but this correlation is usually not visible in residual plots

When the model is not correct we hope to see structure in the residual plots to help us re-model the data Use standardized residuals



Since  $var(e_i) = \sigma^2(1 - h_{ii})$  has non-constant variance

Since  $var(e_i) = \sigma^2(1 - h_{ii})$  has non-constant variance

• Divide by standard deviation:

$$\frac{e_i}{\sigma\sqrt{1-h_{ii}}}$$

(constant variance)

Since  $var(e_i) = \sigma^2(1 - h_{ii})$  has non-constant variance

• Divide by standard deviation:

$$\frac{e_i}{\sigma\sqrt{1-h_{ii}}}$$

(constant variance)

• (Internally) Standardized residuals

$$r_i = \frac{e_i}{\hat{\sigma}\sqrt{1 - h_{ii}}}$$

where  $\hat{\sigma}$  is root MSE



Since  $var(e_i) = \sigma^2(1 - h_{ii})$  has non-constant variance

• Divide by standard deviation:

$$\frac{e_i}{\sigma\sqrt{1-h_{ii}}}$$

(constant variance)

• (Internally) Standardized residuals

$$r_i = \frac{e_i}{\hat{\sigma}\sqrt{1 - h_{ii}}}$$

where  $\hat{\sigma}$  is root MSE



• 
$$\sum_i h_{ij} = 1$$

$$\mathbf{1}^T \mathsf{P}_{\mathbf{X}} = \mathbf{1}^T \mathsf{P}_{\mathbf{1}} + \mathbf{1}^T \mathsf{P}_{\mathbf{Z} - \mathbf{1}\bar{\mathbf{Z}}^T}$$

$$= \mathbf{1}^T \mathbf{1} (\mathbf{1}^T \mathbf{1})^{-1} \mathbf{1}^T + \mathbf{0}^T$$

• 
$$\sum_i h_{ij} = 1$$

$$\mathbf{1}^{T} \mathsf{P}_{\mathsf{X}} = \mathbf{1}^{T} \mathsf{P}_{1} + \mathbf{1}^{T} \mathsf{P}_{\mathsf{Z} - 1\bar{\mathsf{Z}}^{T}}$$
  
=  $\mathbf{1}^{T} \mathbf{1} (\mathbf{1}^{T} \mathbf{1})^{-1} \mathbf{1}^{T} + \mathbf{0}^{T}$   
=  $\mathbf{1}^{T}$ 

$$= \mathbf{1}^T \mathbf{1} (\mathbf{1}^T \mathbf{1})^{-1} \mathbf{1}^T + \mathbf{0}^T$$
$$= \mathbf{1}^T$$

$$\bullet \sum_{i} h_{ij} = 1$$

$$\mathbf{1}^{T} \mathsf{P}_{\mathsf{X}} = \mathbf{1}^{T} \mathsf{P}_{1} + \mathbf{1}^{T} \mathsf{P}_{\mathsf{Z} - 1\bar{\mathsf{Z}}^{T}}$$
$$= \mathbf{1}^{T} \mathbf{1} (\mathbf{1}^{T} \mathbf{1})^{-1} \mathbf{1}^{T} + \mathbf{0}^{T}$$
$$= \mathbf{1}^{T}$$

$$P_{\mathbf{X}} = P_{\mathbf{X}}^2$$

$$\bullet \sum_{i} h_{ij} = 1$$

$$\mathbf{1}^{T} \mathsf{P}_{\mathsf{X}} = \mathbf{1}^{T} \mathsf{P}_{1} + \mathbf{1}^{T} \mathsf{P}_{\mathsf{Z} - 1\bar{\mathsf{Z}}^{T}}$$
$$= \mathbf{1}^{T} \mathbf{1} (\mathbf{1}^{T} \mathbf{1})^{-1} \mathbf{1}^{T} + \mathbf{0}^{T}$$
$$= \mathbf{1}^{T}$$

$$P_{\mathbf{X}} = P_{\mathbf{X}}^{2}$$

$$h_{ii} = \sum_{j} h_{ij} h_{ji}$$

$$\bullet \sum_i h_{ij} = 1$$

$$\mathbf{1}^T \mathsf{P}_{\mathbf{X}} = \mathbf{1}^T \mathsf{P}_{\mathbf{1}} + \mathbf{1}^T \mathsf{P}_{\mathbf{Z} - \mathbf{1}\bar{\mathbf{Z}}^T}$$
$$= \mathbf{1}^T \mathbf{1} (\mathbf{1}^T \mathbf{1})^{-1} \mathbf{1}^T + \mathbf{0}^T$$
$$= \mathbf{1}^T$$

$$P_{\mathbf{X}} = P_{\mathbf{X}}^{2}$$

$$h_{ii} = \sum_{j} h_{ij} h_{ji}$$

$$= \sum_{i} h_{jj}^{2}$$

$$\bullet \sum_{i} h_{ij} = 1$$

$$\mathbf{1}^{T} \mathsf{P}_{\mathbf{X}} = \mathbf{1}^{T} \mathsf{P}_{\mathbf{1}} + \mathbf{1}^{T} \mathsf{P}_{\mathbf{Z} - \mathbf{1} \bar{\mathbf{Z}}^{T}}$$
$$= \mathbf{1}^{T} \mathbf{1} (\mathbf{1}^{T} \mathbf{1})^{-1} \mathbf{1}^{T} + \mathbf{0}^{T}$$
$$= \mathbf{1}^{T}$$

$$P_{\mathbf{X}} = P_{\mathbf{X}}^{2}$$

$$h_{ii} = \sum_{j} h_{ij} h_{ji}$$

$$= \sum_{j} h_{jj}^{2}$$

$$= h_{ii}^{2} + \sum_{i \neq i} h_{jj}^{2}$$

$$\bullet \sum_i h_{ij} = 1$$

$$\mathbf{1}^T \mathsf{P}_{\mathsf{X}} = \mathbf{1}^T \mathsf{P}_{\mathsf{1}} + \mathbf{1}^T \mathsf{P}_{\mathsf{Z} - \mathsf{1}\bar{\mathsf{Z}}^T} \\ = \mathbf{1}^T \mathbf{1} (\mathbf{1}^T \mathbf{1})^{-1} \mathbf{1}^T + \mathbf{0}^T \\ = \mathbf{1}^T$$

$$P_{\mathbf{X}} = P_{\mathbf{X}}^{2}$$

$$h_{ii} = \sum_{j} h_{ij} h_{ji}$$

$$= \sum_{j} h_{jj}^{2}$$

$$= h_{ii}^{2} + \sum_{j \neq i} h_{jj}^{2}$$

$$h_{ii}(1 - h_{ii}) \geq 0$$

$$\hat{Y}_i = h_{ii}Y_i + \sum_{j \neq i} h_{ij}Y_j$$

$$\hat{Y}_i = h_{ii}Y_i + \sum_{j \neq i} h_{ij}Y_j$$

$$\hat{Y}_i = h_{ii}Y_i + \sum_{j \neq i} h_{ij}Y_j$$

• 
$$\sum_{j} h_{ij} = 1$$

$$\hat{Y}_i = h_{ii}Y_i + \sum_{j \neq i} h_{ij}Y_j$$

- $\sum_i h_{ij} = 1$
- $\sum_i h_{ij}^2 = 1$

$$\hat{Y}_i = h_{ii} Y_i + \sum_{j \neq i} h_{ij} Y_j$$

- $\sum_{i} h_{ij} = 1$
- $\sum_{i} h_{ij}^{2} = 1$

$$\mathbf{1}^T \mathsf{P}_{\mathbf{X}} \ = \ \mathbf{1}^T (\mathsf{P}_{\mathbf{1}} + \mathsf{P}_{\mathbf{X}}) (\mathsf{P}_{\mathbf{1}} + \mathsf{P}_{\mathbf{X}})^T$$

$$\hat{Y}_i = h_{ii} Y_i + \sum_{j \neq i} h_{ij} Y_j$$

- $\sum_{i} h_{ij} = 1$
- $\sum_{i} h_{ij}^{2} = 1$

$$\mathbf{1}^T \mathsf{P}_{\mathsf{X}} = \mathbf{1}^T (\mathsf{P}_1 + \mathsf{P}_{\mathsf{X}}) (\mathsf{P}_1 + \mathsf{P}_{\mathsf{X}})^T$$
$$= \mathbf{1}^T \mathbf{1} (\mathbf{1}^T \mathbf{1})^{-1} \mathbf{1}^T + \mathbf{0}^T$$

$$\hat{Y}_i = h_{ii} Y_i + \sum_{j \neq i} h_{ij} Y_j$$

- $\sum_i h_{ij} = 1$
- $\bullet \sum_i h_{ij}^2 = 1$

$$\mathbf{1}^{T} \mathsf{P}_{\mathsf{X}} = \mathbf{1}^{T} (\mathsf{P}_{\mathsf{1}} + \mathsf{P}_{\mathsf{X}}) (\mathsf{P}_{\mathsf{1}} + \mathsf{P}_{\mathsf{X}})^{T}$$
$$= \mathbf{1}^{T} \mathbf{1} (\mathbf{1}^{T} \mathbf{1})^{-1} \mathbf{1}^{T} + \mathbf{0}^{T}$$
$$= \mathbf{1}^{T}$$

$$\hat{Y}_i = h_{ii} Y_i + \sum_{j \neq i} h_{ij} Y_j$$

If  $h_{ii} \approx 1$  then  $\hat{Y}_i \approx Y_i$ 

- $\sum_{i} h_{ij} = 1$
- $\bullet \sum_i h_{ij}^2 = 1$

$$\mathbf{1}^{T} \mathsf{P}_{\mathsf{X}} = \mathbf{1}^{T} (\mathsf{P}_{\mathsf{1}} + \mathsf{P}_{\mathsf{X}}) (\mathsf{P}_{\mathsf{1}} + \mathsf{P}_{\mathsf{X}})^{T}$$
$$= \mathbf{1}^{T} \mathbf{1} (\mathbf{1}^{T} \mathbf{1})^{-1} \mathbf{1}^{T} + \mathbf{0}^{T}$$
$$= \mathbf{1}^{T}$$

•  $h_{ij} \approx 0$  for  $i \neq j$  if  $h_{ii} \approx 1$ 



$$\hat{Y}_i = h_{ii} Y_i + \sum_{j \neq i} h_{ij} Y_j$$

- $\sum_{i} h_{ij} = 1$
- $\bullet \ \sum_i h_{ij}^2 = 1$

$$\mathbf{1}^{T} \mathsf{P}_{\mathsf{X}} = \mathbf{1}^{T} (\mathsf{P}_{1} + \mathsf{P}_{\mathsf{X}}) (\mathsf{P}_{1} + \mathsf{P}_{\mathsf{X}})^{T}$$
$$= \mathbf{1}^{T} \mathbf{1} (\mathbf{1}^{T} \mathbf{1})^{-1} \mathbf{1}^{T} + \mathbf{0}^{T}$$
$$= \mathbf{1}^{T}$$

- $h_{ij} \approx 0$  for  $i \neq j$  if  $h_{ii} \approx 1$
- $var(e_i) = \sigma^2(1 h_{ii}) \approx 0$  if  $h_{ii} \approx 1$



## Illustration

Let  $\mathbf{X}_{(i)}$  and  $\mathbf{Y}_{(i)}$  denote the design matrix and response vector with the ith row  $\mathbf{x}_i^T$  deleted

Let  $\mathbf{X}_{(i)}$  and  $\mathbf{Y}_{(i)}$  denote the design matrix and response vector with the *i*th row  $\mathbf{x}_{i}^{T}$  deleted

$$\bullet \ \hat{\boldsymbol{\beta}}_{(i)} = (\mathbf{X}_{(i)}^T \mathbf{X}_{(i)})^{-1} \mathbf{X}_{(i)}^T \mathbf{Y}_{(i)}$$

Let  $\mathbf{X}_{(i)}$  and  $\mathbf{Y}_{(i)}$  denote the design matrix and response vector with the *i*th row  $\mathbf{x}_{i}^{T}$  deleted

$$\bullet \ \hat{\boldsymbol{\beta}}_{(i)} = (\mathbf{X}_{(i)}^T \mathbf{X}_{(i)})^{-1} \mathbf{X}_{(i)}^T \mathbf{Y}_{(i)}$$

• Predicted residual  $\mathbf{e}_{(i)} = y_i - \mathbf{x}_{(i)}^T \hat{\boldsymbol{\beta}}_{(i)}$ 

Let  $\mathbf{X}_{(i)}$  and  $\mathbf{Y}_{(i)}$  denote the design matrix and response vector with the *i*th row  $\mathbf{x}_{i}^{T}$  deleted

$$\bullet \ \hat{\boldsymbol{\beta}}_{(i)} = (\mathbf{X}_{(i)}^T \mathbf{X}_{(i)})^{-1} \mathbf{X}_{(i)}^T \mathbf{Y}_{(i)}$$

- Predicted residual  $\mathbf{e}_{(i)} = y_i \mathbf{x}_{(i)}^T \hat{\boldsymbol{\beta}}_{(i)}$
- Variance  $\operatorname{var}(e_{(i)}) = \sigma^2(1 + \mathbf{x}_{(i)}^T(\mathbf{X}_{(i)}^T\mathbf{X}_{(i)})^{-1}\mathbf{x}_{(i)})$

Let  $\mathbf{X}_{(i)}$  and  $\mathbf{Y}_{(i)}$  denote the design matrix and response vector with the *i*th row  $\mathbf{x}_{i}^{T}$  deleted

$$\bullet \ \hat{\boldsymbol{\beta}}_{(i)} = (\mathbf{X}_{(i)}^T \mathbf{X}_{(i)})^{-1} \mathbf{X}_{(i)}^T \mathbf{Y}_{(i)}$$

- Predicted residual  $\mathbf{e}_{(i)} = y_i \mathbf{x}_{(i)}^T \hat{\boldsymbol{\beta}}_{(i)}$
- Variance  $\operatorname{var}(e_{(i)}) = \sigma^2(1 + \mathbf{x}_{(i)}^T(\mathbf{X}_{(i)}^T\mathbf{X}_{(i)})^{-1}\mathbf{x}_{(i)})$

# Updating Formula

How to compute without re-fitting model for each case deletion?

# **Updating Formula**

How to compute without re-fitting model for each case deletion?

$$\mathbf{X}_{(i)}^{\mathsf{T}}\mathbf{X}_{(i)} = \mathbf{X}^{\mathsf{T}}\mathbf{X} + \frac{(\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{x}_{i}\mathbf{x}_{i}^{\mathsf{t}}(\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}}{1 - \mathbf{x}_{i}^{\mathsf{T}}(\mathbf{X}^{\mathsf{X}})^{-1}\mathbf{x}_{i}}$$

How to compute without re-fitting model for each case deletion?

$$\mathbf{X}_{(i)}^{\mathsf{T}}\mathbf{X}_{(i)} = \mathbf{X}^{\mathsf{T}}\mathbf{X} + \frac{(\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{x}_{i}\mathbf{x}_{i}^{\mathsf{t}}(\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}}{1 - \mathbf{x}_{i}^{\mathsf{T}}(\mathbf{X}^{\mathsf{X}})^{-1}\mathbf{x}_{i}}$$

How to compute without re-fitting model for each case deletion?

$$\mathbf{X}_{(i)}^{\mathsf{T}}\mathbf{X}_{(i)} = \mathbf{X}^{\mathsf{T}}\mathbf{X} + \frac{(\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{x}_{i}\mathbf{x}_{i}^{\mathsf{t}}(\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}}{1 - \mathbf{x}_{i}^{\mathsf{T}}(\mathbf{X}^{\mathsf{X}})^{-1}\mathbf{x}_{i}}$$

$$\hat{\boldsymbol{\beta}}_{(i)} = (\mathbf{X}_{(i)}^T \mathbf{X}_{(i)})^{-1} \mathbf{X}_{(i)}^T \mathbf{Y}_{(i)}$$

How to compute without re-fitting model for each case deletion?

$$\mathbf{X}_{(i)}^{\mathsf{T}}\mathbf{X}_{(i)} = \mathbf{X}^{\mathsf{T}}\mathbf{X} + \frac{(\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{x}_{i}\mathbf{x}_{i}^{\mathsf{t}}(\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}}{1 - \mathbf{x}_{i}^{\mathsf{T}}(\mathbf{X}^{\mathsf{X}})^{-1}\mathbf{x}_{i}}$$

$$\hat{\boldsymbol{\beta}}_{(i)} = (\mathbf{X}_{(i)}^T \mathbf{X}_{(i)})^{-1} \mathbf{X}_{(i)}^T \mathbf{Y}_{(i)}$$
$$= (\mathbf{X}_{(i)}^T \mathbf{X}_{(i)})^{-1} (\mathbf{X}^T \mathbf{Y} - \mathbf{x}_i y_i)$$

How to compute without re-fitting model for each case deletion?

$$\mathbf{X}_{(i)}^{T}\mathbf{X}_{(i)} = \mathbf{X}^{T}\mathbf{X} + \frac{(\mathbf{X}^{T}\mathbf{X})^{-1}\mathbf{x}_{i}\mathbf{x}_{i}^{t}(\mathbf{X}^{T}\mathbf{X})^{-1}}{1 - \mathbf{x}_{i}^{T}(\mathbf{X}^{\mathbf{X}})^{-1}\mathbf{x}_{i}}$$

$$\hat{\boldsymbol{\beta}}_{(i)} = (\mathbf{X}_{(i)}^T \mathbf{X}_{(i)})^{-1} \mathbf{X}_{(i)}^T \mathbf{Y}_{(i)}$$

$$= (\mathbf{X}_{(i)}^T \mathbf{X}_{(i)})^{-1} (\mathbf{X}^T \mathbf{Y} - \mathbf{x}_i y_i)$$
some algebra

How to compute without re-fitting model for each case deletion?

$$\mathbf{X}_{(i)}^{T}\mathbf{X}_{(i)} = \mathbf{X}^{T}\mathbf{X} + \frac{(\mathbf{X}^{T}\mathbf{X})^{-1}\mathbf{x}_{i}\mathbf{x}_{i}^{t}(\mathbf{X}^{T}\mathbf{X})^{-1}}{1 - \mathbf{x}_{i}^{T}(\mathbf{X}^{X})^{-1}\mathbf{x}_{i}}$$

$$\hat{\boldsymbol{\beta}}_{(i)} = (\mathbf{X}_{(i)}^{T} \mathbf{X}_{(i)})^{-1} \mathbf{X}_{(i)}^{T} \mathbf{Y}_{(i)} 
= (\mathbf{X}_{(i)}^{T} \mathbf{X}_{(i)})^{-1} (\mathbf{X}^{T} \mathbf{Y} - \mathbf{x}_{i} y_{i}) 
\text{some algebra} 
= \hat{\boldsymbol{\beta}} + \frac{\mathbf{X}^{T} \mathbf{X} \mathbf{x}_{i} e_{i}}{1 - h_{i:}}$$

How to compute without re-fitting model for each case deletion?

$$\mathbf{X}_{(i)}^{T}\mathbf{X}_{(i)} = \mathbf{X}^{T}\mathbf{X} + \frac{(\mathbf{X}^{T}\mathbf{X})^{-1}\mathbf{x}_{i}\mathbf{x}_{i}^{t}(\mathbf{X}^{T}\mathbf{X})^{-1}}{1 - \mathbf{x}_{i}^{T}(\mathbf{X}^{X})^{-1}\mathbf{x}_{i}}$$

$$\hat{\boldsymbol{\beta}}_{(i)} = (\mathbf{X}_{(i)}^{T} \mathbf{X}_{(i)})^{-1} \mathbf{X}_{(i)}^{T} \mathbf{Y}_{(i)} 
= (\mathbf{X}_{(i)}^{T} \mathbf{X}_{(i)})^{-1} (\mathbf{X}^{T} \mathbf{Y} - \mathbf{x}_{i} y_{i}) 
\text{some algebra} 
= \hat{\boldsymbol{\beta}} + \frac{\mathbf{X}^{T} \mathbf{X} \mathbf{x}_{i} e_{i}}{1 - h_{i:}}$$

Predicted residual

$$e_{(i)} = y_i - \mathbf{x}_i^T \hat{\boldsymbol{\beta}}(i) = \frac{e_i}{1 - h_{ii}}$$

Predicted residual

$$e_{(i)} = y_i - \mathbf{x}_i^T \hat{\boldsymbol{\beta}}(i) = \frac{e_i}{1 - h_{ii}}$$

with variance

$$\operatorname{var}(e_{(i)}) = \frac{\sigma^2}{1 - h_{ii}}$$

Predicted residual

$$e_{(i)} = y_i - \mathbf{x}_i^T \hat{\boldsymbol{\beta}}(i) = \frac{e_i}{1 - h_{ii}}$$

with variance

$$\operatorname{var}(e_{(i)}) = \frac{\sigma^2}{1 - h_{ii}}$$

Standardized predicted residual is

$$\frac{e_{(i)}}{\sqrt{\mathsf{var}(e_{(i)})}} = \frac{e_i/(1-h_{ii})}{\sigma/\sqrt{1-h_{ii}}} = \frac{e_i}{\sigma\sqrt{1-h_{ii}}}$$

Predicted residual

$$e_{(i)} = y_i - \mathbf{x}_i^T \hat{\boldsymbol{\beta}}(i) = \frac{e_i}{1 - h_{ii}}$$

with variance

$$\operatorname{var}(e_{(i)}) = \frac{\sigma^2}{1 - h_{ii}}$$

Standardized predicted residual is

$$\frac{e_{(i)}}{\sqrt{\mathsf{var}(e_{(i)})}} = \frac{e_i/(1-h_{ii})}{\sigma/\sqrt{1-h_{ii}}} = \frac{e_i}{\sigma\sqrt{1-h_{ii}}}$$

Same as before!



Estimate  $\hat{\sigma}_{(i)}^2$  using data with case i deleted

Estimate  $\hat{\sigma}_{(i)}^2$  using data with case i deleted

$$SSE_{(i)} = SSE - \frac{e_i^2}{1 - hii}$$

Estimate  $\hat{\sigma}_{(i)}^2$  using data with case *i* deleted

$$SSE_{(i)} = SSE - \frac{e_i^2}{1 - hii}$$

$$\hat{\sigma}_{(i)}^2 = MSE_{(i)} = \frac{SSE_{(i)}}{n - p - 1}$$

Estimate  $\hat{\sigma}_{(i)}^2$  using data with case *i* deleted

$$SSE_{(i)} = SSE - \frac{e_i^2}{1 - hii}$$

$$\hat{\sigma}_{(i)}^2 = MSE_{(i)} = \frac{SSE_{(i)}}{n - p - 1}$$

Externally Standardized residuals

Estimate  $\hat{\sigma}_{(i)}^2$  using data with case *i* deleted

$$SSE_{(i)} = SSE - \frac{e_i^2}{1 - hii}$$

$$\hat{\sigma}_{(i)}^2 = MSE_{(i)} = \frac{SSE_{(i)}}{n - p - 1}$$

Externally Standardized residuals

$$t_{i} = \frac{e_{(i)}}{\sqrt{\hat{\sigma}_{(i)}^{2}/(1-h_{ii})}} = \frac{y_{i} - \mathbf{x}_{i}^{T}\hat{\boldsymbol{\beta}}_{(i)}}{\sqrt{\hat{\sigma}_{(i)}^{2}/(1-h_{ii})}}$$

Estimate  $\hat{\sigma}_{(i)}^2$  using data with case *i* deleted

$$SSE_{(i)} = SSE - \frac{e_i^2}{1 - hii}$$

$$\hat{\sigma}_{(i)}^2 = MSE_{(i)} = \frac{SSE_{(i)}}{n - p - 1}$$

Externally Standardized residuals

$$t_{i} = \frac{e_{(i)}}{\sqrt{\hat{\sigma}_{(i)}^{2}/(1-h_{ii})}} = \frac{y_{i} - \mathbf{x}_{i}^{T}\hat{\boldsymbol{\beta}}_{(i)}}{\sqrt{\hat{\sigma}_{(i)}^{2}/(1-h_{ii})}}$$

May still miss extreme points with high leverage, but will pick up unusual  $y_i$ s



$$H_0$$
:  $\mu_i = \mathbf{x}_i^T \boldsymbol{\beta}$  versus  $H_a$ :  $\mu_i = \mathbf{x}_i^T \boldsymbol{\beta} + \alpha_i$ 

$$H_0$$
:  $\mu_i = \mathbf{x}_i^T \boldsymbol{\beta}$  versus  $H_a$ :  $\mu_i = \mathbf{x}_i^T \boldsymbol{\beta} + \alpha_i$ 

• Show that t-test for testing  $H_0$ :  $\alpha_i = 0$  is equal to  $t_i$  (HW)

$$H_0$$
:  $\mu_i = \mathbf{x}_i^T \boldsymbol{\beta}$  versus  $H_a$ :  $\mu_i = \mathbf{x}_i^T \boldsymbol{\beta} + \alpha_i$ 

- Show that t-test for testing  $H_0$ :  $\alpha_i = 0$  is equal to  $t_i$  (HW)
- if p-value is small declare the *i*th case to be an outlier:  $E[Y_i]$  not given by  $\mathbf{X}\boldsymbol{\beta}$  but  $\mathbf{X}\boldsymbol{\beta} = \delta_i\alpha_i$

$$H_0$$
:  $\mu_i = \mathbf{x}_i^T \boldsymbol{\beta}$  versus  $H_a$ :  $\mu_i = \mathbf{x}_i^T \boldsymbol{\beta} + \alpha_i$ 

- Show that t-test for testing  $H_0$ :  $\alpha_i = 0$  is equal to  $t_i$  (HW)
- if p-value is small declare the *i*th case to be an outlier:  $\mathsf{E}[Y_i]$  not given by  $\mathsf{X}\beta$  but  $\mathsf{X}\beta=\delta_i\alpha_i$
- control for multiple testing



$$H_0$$
:  $\mu_i = \mathbf{x}_i^T \boldsymbol{\beta}$  versus  $H_a$ :  $\mu_i = \mathbf{x}_i^T \boldsymbol{\beta} + \alpha_i$ 

- Show that t-test for testing  $H_0$ :  $\alpha_i = 0$  is equal to  $t_i$  (HW)
- if p-value is small declare the *i*th case to be an outlier:  $\mathsf{E}[Y_i]$  not given by  $\mathsf{X}\beta$  but  $\mathsf{X}\beta = \delta_i\alpha_i$
- control for multiple testing
- Extreme case  $\mu = \mathbf{X}\boldsymbol{\beta} + \mathbf{I}_n \boldsymbol{\alpha}$  all points have their own mean!



$$H_0$$
:  $\mu_i = \mathbf{x}_i^T \boldsymbol{\beta}$  versus  $H_a$ :  $\mu_i = \mathbf{x}_i^T \boldsymbol{\beta} + \alpha_i$ 

- Show that t-test for testing  $H_0$ :  $\alpha_i = 0$  is equal to  $t_i$  (HW)
- if p-value is small declare the *i*th case to be an outlier:  $\mathsf{E}[Y_i]$  not given by  $\mathsf{X}\beta$  but  $\mathsf{X}\beta = \delta_i\alpha_i$
- control for multiple testing
- Extreme case  $\mu = \mathbf{X}\boldsymbol{\beta} + \mathbf{I}_n \boldsymbol{\alpha}$  all points have their own mean!



Cook's Distance measure of how much predictions change with *i*th case deleted

Cook's Distance measure of how much predictions change with *i*th case deleted

$$D_i = \frac{\|\mathbf{Y}_{(i)} - \mathbf{Y}\|^2}{p\hat{\sigma}^2} = \frac{(\hat{\boldsymbol{\beta}}_{(i)} - \hat{\boldsymbol{\beta}})^T \mathbf{X}^T \mathbf{X} (\hat{\boldsymbol{\beta}}_{(i)} - \hat{\boldsymbol{\beta}})}{p\hat{\sigma}^2}$$

Cook's Distance measure of how much predictions change with *i*th case deleted

$$D_{i} = \frac{\|\mathbf{Y}_{(i)} - \mathbf{Y}\|^{2}}{p\hat{\sigma}^{2}} = \frac{(\hat{\beta}_{(i)} - \hat{\beta})^{T}\mathbf{X}^{T}\mathbf{X}(\hat{\beta}_{(i)} - \hat{\beta})}{p\hat{\sigma}^{2}}$$
$$= \frac{r_{i}^{2}}{p} \frac{h_{ii}}{1 - h_{ii}}$$

Cook's Distance measure of how much predictions change with *i*th case deleted

$$D_{i} = \frac{\|\mathbf{Y}_{(i)} - \mathbf{Y}\|^{2}}{p\hat{\sigma}^{2}} = \frac{(\hat{\beta}_{(i)} - \hat{\beta})^{T}\mathbf{X}^{T}\mathbf{X}(\hat{\beta}_{(i)} - \hat{\beta})}{p\hat{\sigma}^{2}}$$
$$= \frac{r_{i}^{2}}{p} \frac{h_{ii}}{1 - h_{ii}}$$

Flag cases where  $D_i > 1$  or large relative to other cases

Cook's Distance measure of how much predictions change with *i*th case deleted

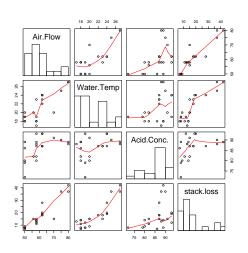
$$D_{i} = \frac{\|\mathbf{Y}_{(i)} - \mathbf{Y}\|^{2}}{p\hat{\sigma}^{2}} = \frac{(\hat{\beta}_{(i)} - \hat{\beta})^{T}\mathbf{X}^{T}\mathbf{X}(\hat{\beta}_{(i)} - \hat{\beta})}{p\hat{\sigma}^{2}}$$
$$= \frac{r_{i}^{2}}{p} \frac{h_{ii}}{1 - h_{ii}}$$

Flag cases where  $D_i > 1$  or large relative to other cases Influential

Cases

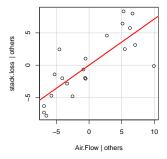


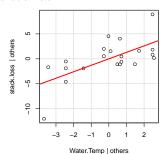
### Stackloss Data

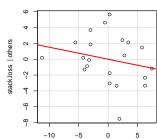


#### Stackloss Added Variable Plot

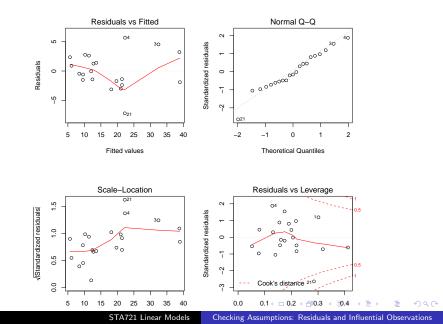
#### Added-Variable Plots







## Stackloss Data



#### Case 21

- Leverage 0.285
- Cooks'd Distance .69
- p-value  $t_{21}$  is 0.0042
- Bonferonni adjusted p-value is 0.0024
- Other points? Masking?
- Refit without Case 21

Others have suggested that cases (1, 3, 4, 21) are outliers

• For suspicious cases, check data sources

- For suspicious cases, check data sources
- Check that points are not outliers because of wrong mean function or distributional assumptions

- For suspicious cases, check data sources
- Check that points are not outliers because of wrong mean function or distributional assumptions
- Influential cases report results with and without cases (results may change)

- For suspicious cases, check data sources
- Check that points are not outliers because of wrong mean function or distributional assumptions
- Influential cases report results with and without cases (results may change)
- Outlier test suggests alternative population; if not influential may in keep analysis, but will inflate  $\hat{\sigma}^2$  and interval estimates

- For suspicious cases, check data sources
- Check that points are not outliers because of wrong mean function or distributional assumptions
- Influential cases report results with and without cases (results may change)
- Outlier test suggests alternative population; if not influential may in keep analysis, but will inflate  $\hat{\sigma}^2$  and interval estimates
- Document steps reproducibility!
- Robust Regression Methods

- For suspicious cases, check data sources
- Check that points are not outliers because of wrong mean function or distributional assumptions
- Influential cases report results with and without cases (results may change)
- Outlier test suggests alternative population; if not influential may in keep analysis, but will inflate  $\hat{\sigma}^2$  and interval estimates
- Document steps reproducibility!
- Robust Regression Methods

Are there outliers in the Stackloss Data?

