Conceptual Bootcamp

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Agenda

- Probability Theory
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 - Iterated Expectation and Variance
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- Matrix Properties
- Useful Resources

Change of Variables

If Z has a density $f_Z(z)$ and Y = G(Z), the density of Y is given as

$$f_Y(y) = f_Z(G^{-1}(y))|\det(dG^{-1})|$$

where dG^{-1} is the derivative (matrix of partial derivatives) of G^{-1} evaluated at y.

Recall

$$f_Y(y) = f_Z(G^{-1}(y))|\det(dG^{-1})|$$

Let
$$G(\sigma) = \log(\sigma) \Rightarrow G^{-1}(\sigma) = e^{\sigma}$$

$$dG^{-1} = e^{\sigma}$$

$$f_{\sigma}(\sigma) \propto \frac{1}{e^{\sigma}} |e^{\sigma}| = 1$$

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Expectation of a Random Variable

- Discrete
 - Suppose X is a discrete random variable taking on values $x_1, x_2, ...$ with probabilities $p_1, p_2, ...$ Then the expected value of X and a function of X, f(X) is

$$\sum_{i=1}^{\infty} x_i p_i \qquad \bigg/ \qquad \sum_{i=1}^{\infty} f(x_i) p_i$$

- Continuous
 - Suppose X is a continuous random variable with probability density function g(X). Then the expected value of X and a function of X, f(X) is

$$\int_{A} xg(x)dx \qquad / \qquad \int_{A} f(x)g(x)dx$$

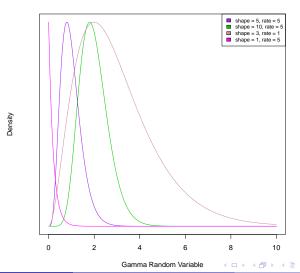
where A is the support of the random variable.

The density function of a Gamma distributed random variable X with shape parameter α and rate parameter β is

$$f_X(x) = \frac{\beta^{\alpha}}{\Gamma(\alpha)} x^{\alpha - 1} e^{-\beta x}$$

What is the expected value of X?

Gamma Densities at Various Shape and Rate Values:



$$\begin{split} E[X] &= \int_0^\infty x \frac{\beta^\alpha}{\Gamma(\alpha)} x^{\alpha - 1} e^{-\beta x} dx \\ &= \frac{\beta^\alpha}{\Gamma(\alpha)} \int_0^\infty x^{(\alpha + 1) - 1} e^{-\beta x} dx \\ &= \frac{\beta^\alpha}{\Gamma(\alpha)} \frac{\Gamma(\alpha + 1)}{\beta^{\alpha + 1}} \int_0^\infty \frac{\beta^{\alpha + 1}}{\Gamma(\alpha + 1)} x^{(\alpha + 1) - 1} e^{-\beta x} dx \\ &= \frac{\Gamma(\alpha + 1)}{\Gamma(\alpha)\beta} = \frac{\alpha\Gamma(\alpha)}{\Gamma(\alpha)\beta} = \frac{\alpha}{\beta} \end{split}$$

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Iterated Expectation and Iterated Variances

Assume that you have two random variables X and Y, such that X is integrable i.e. $E[|X|] < \infty$ and Y not necessarily integrable, but on the same probability space (Ω, \mathcal{F}, P) then:

$$E[X] = E[E[X|Y]]$$

and

$$V[X] = E[V[X|Y]] + V[E[X|Y]]$$

Iterated Expectation and Variance Example

Assume that you are told that $Y \sim N(\mu, \sigma^2)$ and $X|Y \sim N(my, t^2)$. Using **Iterated Expectation** and **Variances** we can find the marginal distribution of X:

$$E[X] = E[E[X|Y]] = E[my] = mE[y] = m\mu$$

$$V[X] = E[V[X|Y]] + V[E[X|Y]] =$$

$$E[t^{2}] + V[my] =$$

$$t^{2} + m^{2}V[y] =$$

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Hence $X \sim N(m\mu, t^2 + m^2\sigma^2)$

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Bayes' Rule

Given two events A and B, with marginal probabilities P(A) and P(B), we have that

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$

Given two random variables θ and X,

$$f(\theta|x) = \frac{f(x|\theta)f(\theta)}{\int_{\theta} f(x|\theta)f(\theta)d\theta} \qquad / \qquad f(\theta|x) = \frac{f(x|\theta)f(\theta)}{\sum_{\theta} f(x|\theta)f(\theta)d\theta}$$

Bayes' Rule Example

A random woman over the age of 50 tests positive for breast cancer during her mammogram. It is known that 1 percent of women over 50 have breast cancer, 90 percent of women who have breast cancer test positive on mammograms, and 8 percent of women who do not have breast cancer falsely test positive. What is the posterior probability that the woman has breast cancer?

Let C^+ and C^- represent the event that the woman has breast cancer and the event that woman does not have breast cancer respectively.

$$P(C^{+}|+) = \frac{P(+|C^{+})P(C^{+})}{P(+)} = \frac{.9(.01)}{.9(.01) + .08(.99)}$$

$$\approx 0.102$$

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The Central Limit Theorem

Assume that X_1, \ldots, X_n be a random sample of size n that is an IID sequence drawn from distributions with finite expectation (μ) and variance (σ^2) . Then:

$$S_n = \frac{\sum_{i=1}^n X_i}{n}$$

$$S_n \stackrel{d}{\Longrightarrow} N(\mu, \frac{\sigma^2}{n})$$

Central Limit Theorem Example

Assume that you have $X_1, \ldots, X_{1000} \sim \operatorname{Poisson}(\lambda)$, what is the approximate distribution of $S_n = \frac{\sum_{i=1}^{n=100} X_i}{100}$?

Since n is large (usually > 30), and based on the poisson distribution we know that $E[S_{100}] = \lambda$ and $V[S_{100}] = \frac{\lambda}{100}$. Then invoking the Central Limit Theorem:

$$S_{100} \overset{\text{Approx}}{\sim} \mathrm{N}(\lambda, \frac{\lambda}{100})$$

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- Any matrix with the same number of rows and columns is called a square matrix.
- Let $A = [a_{ij}]$ be a matrix. The transpose of A, written as A' or A^T is the matrix $A^T = [b_{ii}]$, where $b_{ij} = a_{ji}$
- If $A = A^T$, then A is called symmetric. Note that only square matrices can be symmetric.
- If A is a square matrix $[a_{ij}]$ and $a_{ij} = 0$ for $i \neq j$, then A is a diagonal matrix.
- Let A be a square $n \times n$ matrix. A is nonsingular if there exists a matrix A^{-1} such that $A^{-1}A = I_n = AA^{-1}$.

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- A matrix P is nonsingular if and only if the columns of A are linearly independent (i.e. no column is a linear combination of the other columns)
- A square matrix P is orthogonal if $P^T = P^{-1}$
- C(X) denotes the column space of a matrix X which is the space spanned by the linearly independent columns in the matrix.
- N(X) denotes the null space of a matrix which are all non-zero column vectors A that satisfy the equation $XA = \vec{0}$
- r(X) denotes the rank of a matrix i.e. the number of linear independent columns in a matrix.

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Matrix Properties Continued

- The Basis for a space N is a collection of linearly independent vectors that span N.
- A symmetric matrix A is positive definite if for any non-zero vector $v \in \mathbb{R}^n$, $v^T A v > 0$
- A matrix P is idempotent if $P \cdot P = P$

Useful Resources

- Plane Answers to Complex Questions Christensen 2011
- Statistical Inference Casella & Berger 2002
- Wikipedia, Stack Exchange, Google, Bing(jk...), Yandex (really jk...), Baidu (do you even have to ask?)